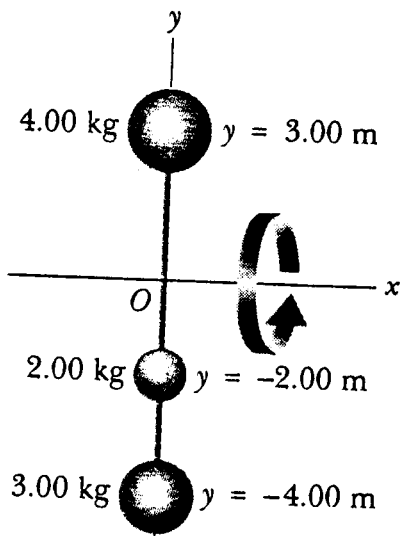


Three particles are connected by rigid rods of negligible mass lying along the y axis (Fig. P10.19). If the system rotates about the x axis with an angular speed of 2.00 rad/s , find (a) the moment of inertia about the x axis and the total rotational energy evaluated from $\frac{1}{2}I\omega^2$ and (b) the linear speed of each particle and the total energy evaluated from $\sum \frac{1}{2}m_i v_i^2$.



$$(a) \quad I = \sum m_i r_i^2 = 4 \times 9 + 2 \times 4 + 3 \times 16 = \boxed{92 \text{ kg m}^2}$$

$$(b) \quad K = \frac{1}{2} I \omega^2 = \frac{1}{2} \times 92 \times (2)^2 = \boxed{184 \text{ J}}$$

$$(c) \quad v_1 = \omega r_1 = (2)(3) = 6 \text{ m/s}$$

$$v_2 = \omega r_2 = (2)(2) = 4 \text{ m/s}$$

$$v_3 = \omega r_3 = (2)(4) = 8 \text{ m/s}$$

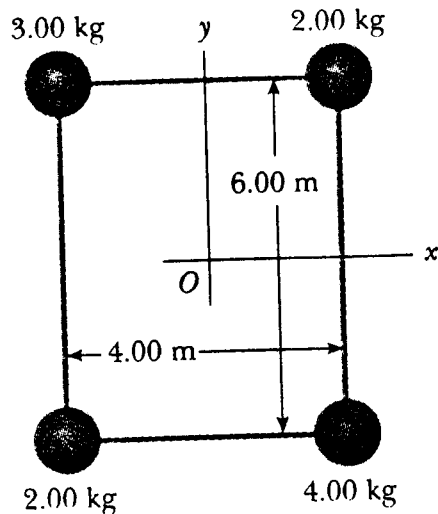
$$K_1 = \frac{1}{2} m_1 v_1^2 = 72 \text{ J}$$

$$K_2 = \frac{1}{2} m_2 v_2^2 = 16 \text{ J}$$

$$K_3 = \frac{1}{2} m_3 v_3^2 = 96 \text{ J}$$

$$\text{Sum} = 184 \text{ J}$$

The four particles in Figure P10.17 are connected by rigid rods of negligible mass. The origin is at the center of the rectangle. If the system rotates in the xy plane about the z axis with an angular speed of 6.00 rad/s, calculate (a) the moment of inertia of the system about the z axis and (b) the rotational energy of the system.

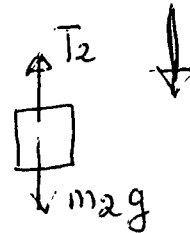
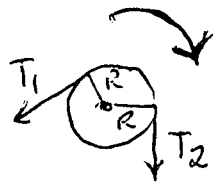
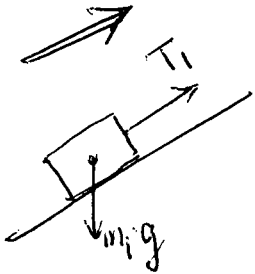
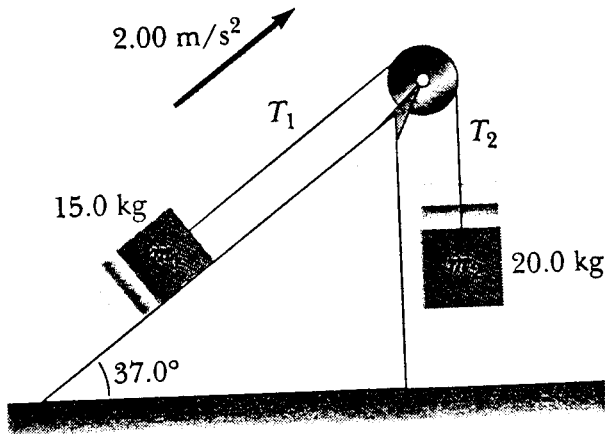


$$(a) \quad I = \sum m_i r_i^2 \quad r = \sqrt{3^2 + 2^2} = \sqrt{13} \text{ m}$$

$$I = (3 + 2 + 2 + 4) (13) = \boxed{143 \text{ kg m}^2}$$

$$(b) \quad K = \frac{1}{2} I \omega^2 = \frac{1}{2} (143) (6)^2 = \boxed{2.6 \times 10^3 \text{ J}}$$

The blocks shown in Figure 10.51 are connected by a string of negligible mass passing over a pulley of radius R and moment of inertia I . The block on the incline is moving up with a constant acceleration of magnitude a . (a) Determine T_1 and T_2 , the tensions in the two parts of the string, and (b) find the moment of inertia of the pulley.



$$T_1 - m_1 g \sin \theta = m_1 a \quad (1) \quad \Rightarrow \quad T_1 = m_1 (g \sin \theta + a) = 118 \text{ N}$$

$$-T_2 + m_2 g = m_2 a \quad (2) \quad \Rightarrow \quad T_2 = m_2 (g - a) = 156 \text{ N}$$

$$T_2 R - T_1 R = I \alpha = \frac{I a}{R} \quad (3)$$

$$(3) \Rightarrow I = \frac{(T_2 - T_1) R^2}{a} = 1.19$$