

Dr. Samir H. Abdul-Jauwad Electrical Engineering Department College of Engineering Sciences King Fahd University of Petroleum & Minerals Dhahran – Saudi Arabia

Gaussian Lowpass Filter

$$H(u,v) = e^{-D^2(u,v)/2\sigma^2}$$

- D(u,v): distance from the origin of FT
- Parameter: σ=D₀ (cutoff frequency)
- The inverse FT of the Gaussian filter is also a Gaussian



abc

FIGURE 4.17 (a) Perspective plot of a GLPF transfer function. (b) Filter displayed as an image. (c) Filter radial cross sections for various values of D_0 .





a b

FIGURE 4.19

(a) Sample text of poor resolution
(note broken
characters in
magnified view).
(b) Result of
filtering with a
GLPF (broken
character
segments were
joined).

Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



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FIGURE 4.20 (a) Original image (1028 × 732 pixels). (b) Result of filtering with a GLPF with $D_0 = 100$. (c) Result of filtering with a GLPF with $D_0 = 80$. Note reduction in skin fine lines in the magnified sections of (b) and (c).



a b c

FIGURE 4.21 (a) Image showing prominent scan lines. (b) Result of using a GLPF with $D_0 = 30$. (c) Result of using a GLPF with $D_0 = 10$. (Original image courtesy of NOAA.)

Sharpening (Highpass) Filtering



 Image sharpening can be achieved by a highpass filtering process, which attenuates the low-frequency components without disturbing high-frequency information.

 $H_{hv}(u,v) = 1 - H_{lv}(u,v)$

• Zero-phase-shift filters: radially symmetric and completely specified by a cross section.



Ideal Filter (Highpass)

$$H(u,v) = \begin{cases} 0 \text{ if } D(u,v) \le D_0 \\ 1 \text{ if } D(u,v) > D_0 \end{cases}$$

• This filter is the opposite of the ideal lowpass filter.



Butterworth Filter (Highpass)

$$H(u,v) = \frac{1}{1 + [D_0 / D(u,v)]^{2n}}$$

 High-frequency emphasis: Adding a constant to a highpass filter to preserve the low-frequency components.

Gaussian Highpass Filter

$$H(u,v) = 1 - e^{-D^2(u,v)/2\sigma^2}$$

- D(u,v): distance from the origin of FT
- Parameter: σ=D₀ (cutoff frequency)

Laplacian (recap)



$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

$$\frac{\partial^2 f}{\partial^2 x^2} = f(x+1,y) + f(x-1,y) - 2f(x,y)$$
$$\frac{\partial^2 f}{\partial^2 y^2} = f(x,y+1) + f(x,y-1) - 2f(x,y)$$
$$\nabla^2 f = [f(x+1,y) + f(x-1,y) + f(x,y+1) + f(x,y-1)] - 4f(x,y)$$

Laplacian in the FD



• It can be shown that:

$$\Im\left[\nabla^2 f(x,y)\right] = -(u^2 + v^2)F(u,v)$$

• The Laplacian can be implemented in the FD by using the filter



Laplacian in the Frequency Domain



Questions?



