King Fahd University of Petroleum & Minerals Electrical Engineering Department

EE 380 • CONTROL ENGINEERING

[MAJOR EXAMINATION #1]

OCTOBER 13, 2003

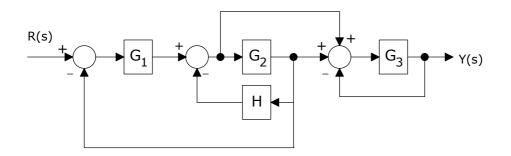
Time 8:00 - 9:30 PM

Name:		
ID #:		
Section	<mark>02- (8:00 AM)</mark>	<mark>04- (10:00 AM)</mark>

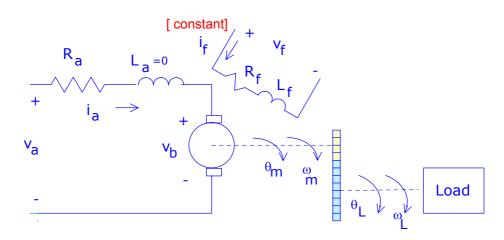
PROBLEM #	SCORE	MAXIMUM
1		20
2		30
3		25
4		25
TOTAL		100

Prof. Youssef Abdel-Magid

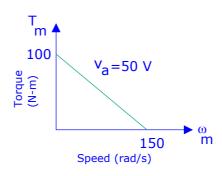
Q1. Reduce the block diagram to a single transfer function $\frac{Y(s)}{R(s)}$ using block diagram reduction techniques.



Q2. Consider the armature-controlled dc motor, and the torque-speed curve shown, find the transfer function that relates the output torque to the input armature voltage $\frac{T_L(s)}{V_a(s)}$.



 $J_m = 2 \text{ kg-m}^2$; $J_L = 18 \text{ kg-m}^2$; $b_m = 2 \text{ N-m s/rad}$; $b_L = 36 \text{ N-m s/rad}$; $n = \frac{50}{150}$



Q4. A control system is described by the following state and output equations

$$\dot{\boldsymbol{x}}(t) = A\boldsymbol{x}(t) + B\boldsymbol{u}(t) = \begin{bmatrix} 0 & 2 \\ -1 & -3 \end{bmatrix} \boldsymbol{x}(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \boldsymbol{u}(t)$$
$$\boldsymbol{y}(t) = C\boldsymbol{x}(t) = \begin{bmatrix} 1 & 0 \end{bmatrix} \boldsymbol{x}(t)$$

(a) Find the transfer function of the system. $\begin{bmatrix} 1 \end{bmatrix}$

(b) If the input is zero, with
$$\mathbf{x}(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$
, find the output $\mathbf{y}(t), t \ge 0$.

- Q3. Consider the closed-loop control system shown, and its signal-flow graph .
 - (a) Find the closed-loop transfer function $\frac{Y(s)}{R(s)}$ using Mason's Rule
 - (b) Find $G_c(s)$, the compensator transfer function, and $G_p(s)$, the plant transfer function directly from the signal-flow graph.
 - (c) Assign state variables on the signal-flow graph state diagram from right to left in ascending order.
 - d) Give **2** state variable representations of the system based on (c) and in controller canonical form.

