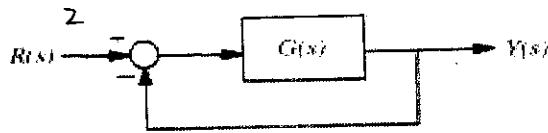


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ELECTRICAL ENGINEERING DEPARTMENT

EE380 [081]	SEC#	Quiz # 9
Name: <u>Key Solution</u>	ID: _____	Grade: _____

Consider the feedback control system. Sketch the root locus and find the break-away and break-in points. Also find the angle of departures from complex poles and angles of arrivals to the complex zeros.



Ch. Eqn: $1 + G(s) = 0$

$$1 + \frac{K(s^2 + 2s + 2)}{s(s^2 + 4)} = 0$$

where

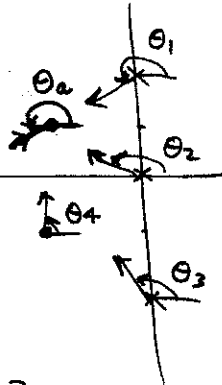
$$G(s) = \frac{K(s + 1 + j)(s + 1 - j)}{s(s + 2j)(s - 2j)}$$

$$K = -\frac{s(s^2 + 4)}{s^2 + 2s + 2}$$

$$\frac{dK}{ds} = s^4 + 4s^3 + 2s^2 + 8 = 0 \Rightarrow \frac{dK}{ds} = (s + 2)(s^3 + 2s^2 - 2s + 4) = 0 \Rightarrow \begin{cases} s = -2 \\ s \approx -3.07 \end{cases}$$

Angle of arrival: θ_a

$$[\theta_1 + \theta_2 + \theta_3] - [\theta_4 + \theta_a] = 180$$



$$225 + 135 + [180 - \tan^{-1} 3] - [90 + \theta_a] = 180$$

$$\therefore 90 + \theta_a = 360 - \tan^{-1} 3$$

$$\therefore \theta_a = 270 - \tan^{-1} 3 \approx 198.6^\circ$$

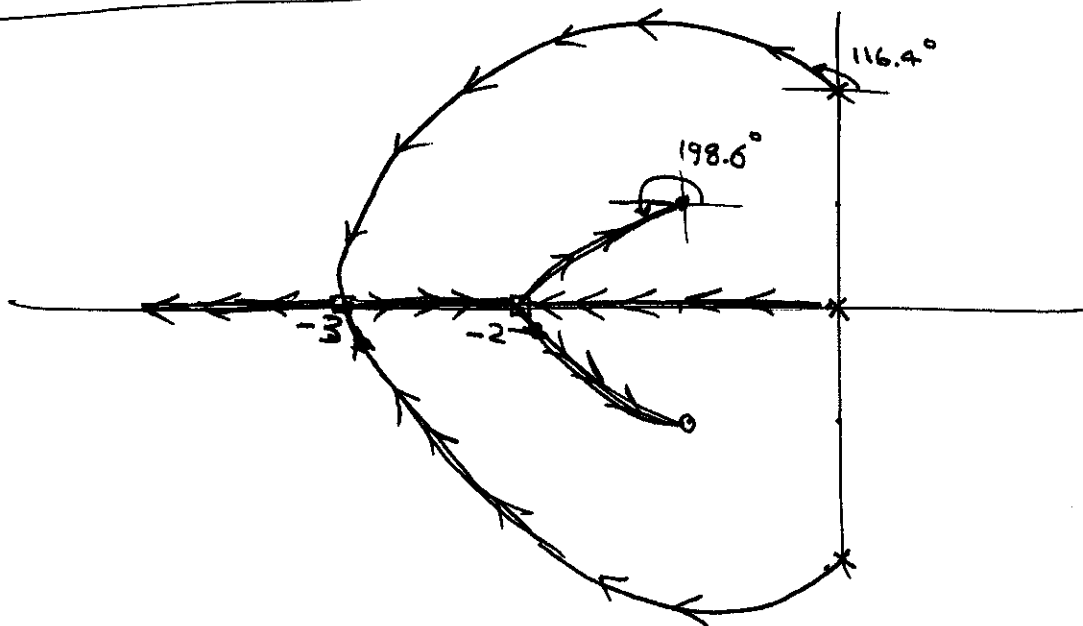
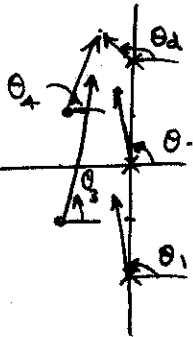
Angle of departure: θ_d

$$[\theta_1 + \theta_2 + \theta_d] - [\theta_3 + \theta_4] = 180$$

$$[90 + 90 + \theta_d] - [\tan^{-1} 3 + 45] = 180$$

$$\therefore \theta_d = \tan^{-1} 3 + 45$$

$$\theta_d = 71.4 + 45 = 116.4^\circ$$



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ELECTRICAL ENGINEERING DEPARTMENT

EE380 [081]	SEC# 4	Quiz # 9
Name: _____	ID: _____	Grade: _____

A mechanical system has the closed-loop transfer function given by

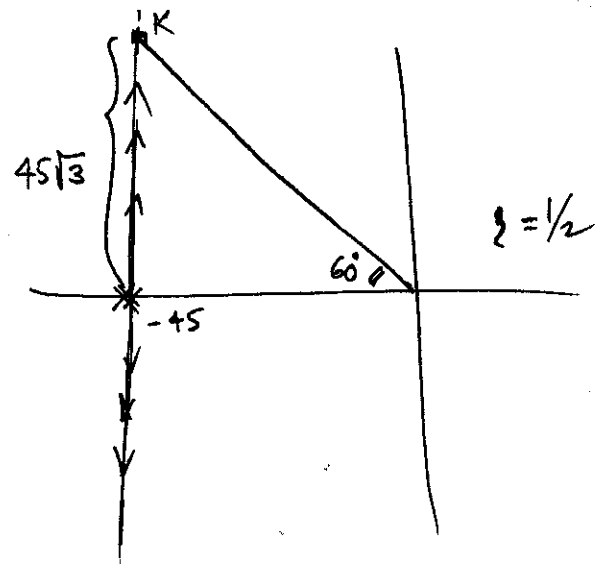
$$T(s) = \frac{K}{(s + 45)^2 + K}$$

Using the root-locus method, determine the value of the gain K so that the closed-loop system has a damping factor $\zeta = \frac{1}{2}$.

$$1 + \frac{K}{(s + 45)^2} = 0$$

$$|K| = (45\sqrt{3})(45\sqrt{3})$$

$$= 2025 \times 3 = 6075$$



For $\zeta = \frac{1}{2} = \frac{\sqrt{2}}{2}$

$$K = 45 \times 45$$

$$= 2025$$

