

**KING FAHD UNIVERSITY OF PETROLEUM & MINERALS**  
**ELECTRICAL ENGINEERING DEPARTMENT**

**EE 306 – Term 181**

**HW # 6: Induction Motors**

**Due Date: (UT-Classes, Dec. 11<sup>th</sup>, 2018; MW-Classes, Dec. 12<sup>th</sup>, 2018)**

**Key Solutions**

**Problem # 1:**

A three-phase, four-pole, 30-hp, 220-V, 60-Hz, Y-connected induction motor draws a current of 77-A from the supply line at a power factor of 0.88. At this operating condition, the motor losses are known to be the following:

Stator copper losses = 1033 W ; Rotor copper losses = 1299 W

Core loss = 485 W ; Mechanical losses (friction & windage) = 540 W

Determine:

- a) the power transferred across the air gap
- b) the internally developed torque in Newton-meters
- c) the slip expressed in percentage
- d) the mechanical power developed in watts
- e) the horsepower output
- f) the motor speed in rpm
- g) the torque at the output shaft
- h) the efficiency of operation

$$\begin{aligned} V_{\phi} &= \frac{220}{\sqrt{3}} = 127 \text{ V} \\ P_{in} &= 3 V_{\phi} I_{\phi} \cos \phi = 3 \times 127 \times 77 \times 0.88 \\ P_{in} &= 25.8 \text{ kW} \\ P_{cu1} &= 1033 \text{ W} \\ P_{cu2} &= 1299 \text{ W} \\ P_{core} &= 485 \text{ W} \\ P_{fw} &= 540 \text{ W} \\ P_g &= P_{in} - P_{cu1} - P_{core} = 25.8 \times 10^3 - 1033 - 485 \\ P_g &= 24.3 \text{ kW} \end{aligned}$$

$$\textcircled{b} \quad T_d = \frac{P_g}{\omega_s}, \quad \omega_s = \frac{2\pi n_s}{60}, \quad n_s = \frac{120 \text{ kV}}{P} = \frac{120 \times 60}{4} = 1800 \text{ rpm}$$

$$\omega_s = \frac{2\pi \times 1800}{60} = 188.5 \text{ rad/sec}$$

$$T_d = \frac{24.3 \times 10^3}{188.5}$$

$$\boxed{T_d = 128.9 \text{ N-m}}$$

$$\textcircled{c} \quad S = \frac{P_{\text{core}}}{P_g} = \frac{1299}{24.3 \times 10^3} \Rightarrow S = 0.0534$$

$$\boxed{S = 5.34\%}$$

$$\textcircled{d} \quad P_d = (1-S) \times P_g = (1-0.0534) \times 24.3 \times 10^3$$

$$\boxed{P_d = 23.0 \text{ kW}}$$

$$\textcircled{e} \quad P_o = P_d - P_{\text{fric}} = 23 \times 10^3 - 540 = 22.46 \text{ kW}$$

$$P_o = \frac{22.46 \times 10^3}{746} \Rightarrow \boxed{P_o = 30 \text{ hp}}$$

$$\textcircled{f} \quad \eta_m = (1-S) \times n_s = (1-0.0534) \times 1800 \Rightarrow \boxed{n_s = 1704 \text{ rpm}}$$

$$\textcircled{g} \quad T_o = \frac{P_o}{\omega} = \frac{22.46 \times 10^3}{1704} \Rightarrow \boxed{T_o = 132 \text{ N-m}} \quad \textcircled{h} \quad \gamma = \frac{P_o}{P_{\text{in}}} = \frac{22.46}{25.8}$$

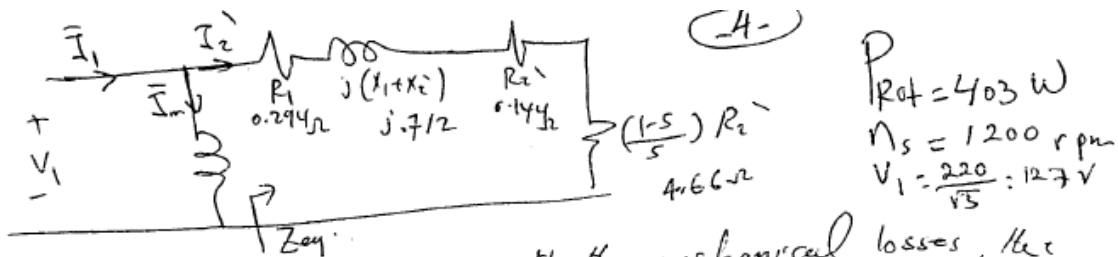
**Problem # 2:**

A 3-phase, Y-connected, 220-V, 10-HP, 60-Hz, 6-pole induction motor has the following parameters in ohms.

$$R_1 = 0.294 \Omega, R_2 = 0.144 \Omega, X_1 = 0.503 \Omega, X_2 = 0.209 \Omega, X_m = 13.25 \Omega$$

The total friction, windage and core losses may be assumed to be constant at 403 W, independent of load. For a slip of 3%, determine:

- (a) the rotor current, developed torque and developed power.
- (b) the maximum developed torque and the corresponding speed.
- (c) the starting torque and starting current.
- (d) How much resistance must be inserted in the rotor circuit to bring the motor speed at maximum torque down to 900 rpm?
- (e) the new starting torque.



Since the core loss is lumped with the mechanical losses, the core resistance will be removed from the equivalent circuit.

$$s = 0.03 \Rightarrow \frac{1-s}{s} \times R_2 = \frac{1-0.03}{0.03} \times 0.144 = 4.66 \Omega$$

$$Z_{eq} = (R_1 + \frac{R_2}{s}) + j(X_1 + X_2) = (0.294 + \frac{0.144}{0.03}) + j(0.503 + 2.09)$$

$$Z_{eq} = 5.14 \angle 7.95^\circ \Omega$$

$$V_1 = \frac{220}{\sqrt{3}} = 127 V$$

(a) 
$$\vec{I}_2 = \frac{V_1}{Z_{eq}} = \frac{127 \angle 0^\circ}{5.14 \angle 7.95^\circ} \Rightarrow$$

$$\vec{I}_2 = 24.7 \angle -7.95^\circ A$$

$$P_d = 3 I_2^2 \left( \frac{1-s}{s} \right) R_2' = 3 (24.7)^2 (4.66) \Rightarrow P_d = 8.52 \text{ kW}$$

$$n = (1-s) n_s = (1-0.03) * 1200 \Rightarrow n = 1164 \text{ rpm}$$

$$T_d = \frac{P_d}{\omega_m} = \frac{P_d}{\frac{2\pi n}{60}} = \frac{8.52 * 10^3}{\frac{2\pi (1164)}{60}} \Rightarrow T_d = 69.9 \text{ N-m}$$

$$\textcircled{b} T_{\max} = \frac{3 V_1^2}{2\omega_s} \cdot \frac{1}{[R_1 + \sqrt{R_1^2 + (X_1 + X_2')^2}]} = \frac{3 * (127)^2}{2 \left( \frac{2\pi * 1200}{60} \right)} * \frac{1}{[0.294 + \sqrt{(0.294)^2 + (0.712)^2}]}$$

$$T_{\max} = 181 \text{ N-m}$$

$$S_{\max} = \frac{R_2'}{\sqrt{R_1^2 + (X_1 + X_2')^2}} = \frac{0.144}{\sqrt{(0.294)^2 + (0.712)^2}} = 0.187$$

$$\textcircled{c} |I_{2 \text{ start}}| = \frac{V_1}{\sqrt{(R_1 + R_2')^2 + (X_1 + X_2')^2}} = \frac{127}{\sqrt{(0.438)^2 + (0.712)^2}} \quad -5^\circ$$

$$I_{2 \text{ start}} = 151.9 \angle -58.5^\circ \text{ A}$$

$$\alpha = \tan^{-1} \frac{(X_1 + X_2')}{R_1 + R_2'} = 58.5^\circ$$

$$I_m = \frac{\bar{V}_1}{jX_m} = \frac{127 \angle 0^\circ}{13.25 \angle 90^\circ} = -j9.6 \text{ A}$$

$$I_{1 \text{ start}} = I_m + I_2 = 9.6 \angle -90^\circ + 151.9 \angle -58.5^\circ$$

$$I_1 = 159.6 \angle -60.3^\circ \text{ A}$$

$$T_{d \text{ starting}} = \frac{3 I_{2 \text{ start}}^2 R_2'}{\omega_s} = \frac{3 V_1^2}{\omega_s} \cdot \frac{R_2'}{(R_1 + R_2')^2 + (X_1 + X_2')^2}$$

$$T_{d \text{ starting}} = \frac{3 (127)^2 * (0.144)}{(0.438)^2 + (0.712)^2} * \frac{1}{\frac{2\pi * 1200}{60}}$$

$$T_{\text{starting}} = 79 \text{ N}\cdot\text{m}$$

$$\textcircled{d} \quad \frac{n}{T_{\text{max}}} = 900 \text{ rpm} \Rightarrow s_{\text{max}} = \frac{n_s - n}{n_s} = \frac{1200 - 900}{1200} = 0.25$$

$$\text{at max. torque} \Rightarrow s_{\text{max}} = \frac{R_{z_{\text{new}}}}{\sqrt{R_1^2 + (X_1 + X_2)^2}} = 0.25$$

$$R_{z_{\text{new}}} = 0.25 \times \sqrt{(0.294)^2 + (0.712)^2} = 0.193 \Omega$$

$$R_{z_{\text{added}}} = R_{z_{\text{new}}} - R_1 = 0.193 - 0.144$$

$$R_{z_{\text{added}}} = 0.0486 \Omega$$

$\approx 0.05 \Omega$

$$\Rightarrow T_{\text{starting, new}} = 100 \text{ N}\cdot\text{m}$$