ICS 233 – Fall 2010 Computer Architecture and Assembly Language Programming Assignment 3

Gaussian elimination is a well-known technique for solving simultaneous linear systems of equations. Variables are eliminated one by one until there is only one left, and the discovered values of variables are back-substituted to obtain the values of other variables. In practice, the linear equations are represented as an augmented matrix A[N][N+1] with N rows and N+1 columns. The matrix is converted to an upper triangular matrix. Then back substitutions are used to produce the solution vector. Pseudo-code for *Gaussian* elimination is shown below.

Pseudo-code for the *solve* procedure is shown below. This procedure is called after Gaussian elimination. It receives as input the upper triangular converted matrix *A*, and produces as output the solution vector *Sol*.

```
procedure Solve(int N, float A[N][N+1], float Sol[N]) {
  for (i=N-1; i>=0; i--) {
    Sol[i] = A[i][N];
    for (j=i+1; j<N; j++) {
        Sol[i] = Sol[i] - A[i][j] * Sol[j];
        }
        Sol[i] = Sol[i]/A[i][i];
    }
}</pre>
```

Write a MIPS assembly language program to perform Gaussian Elimination of floating-point matrices of size N by N+1, and to produce a solution vector of N floating-point elements (Maximum value of N is 10). Ask the user to input the matrix values. One large array A should be defined in the data segment, but you can operate on a subset of the array elements. Perform Gaussian elimination on A and produce a solution vector. All arithmetic operations should be done using the floating-point instructions. Display the solution vector, where each number is displayed on a separate line. A sample run is show below:

```
Enter Matrix Size N (range 2 to 10): 3
Matrix Input (3 rows by 4 values):
. . .
Solution Vector (5 values):
. . .
```