

Overview (Cont.): Single threaded vs. Overview (Cont.): Threads Versus Processes multithreaded code data files data files code stack registers registers registers registers stack stack stack Ş ş one process one process thread threa one thread multiple threads single-threaded multithreaded A simple way to think about a process is as an address space (containing)

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- code, data, etc.) in which there is a single thread of execution
- The thread is the active part of a process



- A process can do several things concurrently by running more than a single thread
- Each thread is a different stream of control that can execute its instructions independently
- Examples
 - A web Browser may have:
 - A thread to display images or text
 - A thread to retrieve data from the network
 - Word processor may have
 - A thread to display graphics
 - A thread to respond to keystrokes from the user
 - A thread to perform spelling and grammar checking



multiple processes

one thread per process

Overview (Cont.): Motivation

Benefits

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Responsiveness: multithreading is useful in an interactive application.
E.g., a multithreaded web browser can allow user interaction even though an image is still downloading

multiple processes

multiple threads per process

- Resource sharing: threads share memory and resources allocated to the process to which they belong, e.g. code sharing, where different threads of activity all within the same address space
- Economy: allocating memory and resources for process creation is costly but it is more economical to create and context-switch threads
- Utilization of multiprocessor architectures: threads may run in parallel on different processors; hence increase the utilization

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Multithreading Models

- Support of thread can be either at user level (user threads) or at the kernel level (kernel threads)
- User threads:
 - Supported above the kernel and managed without kernel support
 - Implemented by the thread library at the user level
 - User thread are generally fast to create and manage
 - Example of user thread libraries: Pthreads and Mach C-threads
- Kernel threads:

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- The kernel performs creation, scheduling, and management
- Supported by the OS such as Windows XP, Linux, Mac OS X, Solaris and True64 Unix
- Relationship between user threads and kernel threads
 - Many-to-one model
 - One-to-one model
 - Many-to-many model

Multithreading Models: Many-to-One

- Maps many user threads to one kernel thread
- Thread management is done by the thread library in user space; Efficient
- Drawbacks

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- Entire process will block if a thread makes a blocking system call
- Unable to run multiple threads in parallel on multiprocessors
- Example: Green threads library for Solaris



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Multithroading Models One to One

- Maps each user thread to a kernel thread
- Provides more concurrency than the many-to-one model (i.e., the kernel allows another thread to run when a thread makes a blocking system call)
- Allows multiple threads to run in parallel on multiprocessors
- Drawback
 - creating a user thread requires creating the corresponding kernel thread which can burden the overall system performance. Therefore, most implementations of this model restrict the number of threads supported by this system



- multiplex many user-level threads to a smaller or equal number of kernel threads
- The number of kernel threads may be specific to either a particular application or a particular machine
- An application may be allocated more threads on a multiprocessor than a uniprocessor machine
- Tow-level model: a popular variation of many-to-many which allows ULT to bound to KTL
- Example: Solaris 2 OS



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Pthreads

- Posix Threads (pthreads) is a standardized programming interface for UNIX systems,
 - the interface is specified by the IEEE 1003.1c standard (1995)
 - this standard specifies behavior of the thread library
 - implementations which adhere to this standard are referred to as POSIX threads, or Pthreads
- Pthreads is:

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- Widely used threads package
- defined as a set of C language programming types and procedure calls, implemented with a pthread.h header
- Conforms to the Posix standard
- Sample Calls: pthread_create(), pthread_exit(), pthread_join(), etc.
- Typical used in C/C++ applications
- Examples of OS implementing Pthreads: Solaris 2, Linux, Mac OS X, True64 Unix and shareware implementation for Windows



Win32 Threads Similar to pthreads in several ways Kernel-level library available on Windows systems #include < windows.h> void main(int argc, char *argv){ ThreadHandle = CreateThread(......, Summation,) if(ThreadHandle ! = NULL){ WaitForSingleObject(ThreadHandle, INFINITE); CloseHandle(ThreadHandle); printf("sum = %d", Sum); }



Java Threads

- Java language and its API provide a rich set of features for creating and managing threads
- As JVM is running on the top of host OS, Java thread API is typically implemented using a thread library available on the host system
 - Windows: Java Threads API uses Win32 API
 - Unix and Linux: Java Threads API uses Pthread
- Thread is a fundamental model of program execution in Java
 - All Java programs comprise of at least a single thread
- Java threads are managed by the JVM
- Two approaches to create threads in Java
 - Create a new class that extends Thread class and override the run() method
 - Define a class that implements Runnable interface (and define the run() method)
 - A thread is created by creating an instance of the Thread class and passing a Runnable object; then call the start() method to actually create the thread

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Threading Issues: fork and exec system calls

- Semantics of fork and exec system calls change in multithreaded program
- When a thread (associated with process A) calls fork, two things can happen:
 - The new process duplicates all threads associated with process A
 - The new process will be single-threaded
- Some Unix operating systems support these two versions of fork
- The exec system call is used after a fork system call and typically work as described in a single-thread program
 - It replaces the entire process (including all threads) with the program specified in the parameter to exec
 - It loads a binary file into memory
 - It destroys the memory image containing the exec system call .
 - It starts its execution

Threading Issues – Cancellation

- Thread cancellation is the task of terminating a thread before it is completed
 - For example: assume that multiple threads are searching a database. As soon as one thread returns the search result, we can terminate the remaining threads
- A thread to be cancelled is referred to as a target thread
- Thread cancellation can happen in two ways:
 - Asynchronous cancellation: One thread immediately terminates the target thread
 - Deferred cancellation: the target thread can periodically checks whether it should terminate; allows termination to happen in an orderly manner

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Threading Issues – Cancellation (cont.)	Threading Issues – Signal Handling

- Thread cancellation is not as easy as it appears
 - What about resources allocated to a canceled thread
 - A thread might be cancelled while in the middle of updating a shared variable
- Becomes especially troublesome with asynchronous cancellation
- An OS usually reclaim system resources from a cancelled thread. But often does not reclaim all resources. Why?
- Deferred cancellation provides safer cancellation
 - A thread check whether it should be canceled at points when it can be cancelled safely (cancellation points)
 - The Pthreads API provides cancellation points



Inreading Issues – Signal Handling

- A signal is used in Unix to notify a process that a particular event has occurred
 - illegal memory access, division be zero, terminating a process with Ctrl-C, time expire
- All signals follow the same pattern
 - A signal is generated by the occurrence of a particular event
 - A generated signal is delivered to a process
 - Once delivered, the signal must be dealt with
- A signal might occur synchronously and asynchronously

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Threading Issues – Signal Handling (cont.)

- Synchronous signals:
 - Generated by events internal to the running process
 - Synchronous signals are delivered to the same process that performed the operation causing the signal
 - Examples include illegal memory access, division be zero, etc
- Asynchronous signals:
 - Generated by events external to the running process
 - Examples include terminating a process by specific keystrokes (e.g., control c), time expire
 - Asynchronous signals are more complicated

Threading Issues – Signal Handling (cont.)

- Every signal, whether synchronous or asynchronous, is handled in two ways
 - A default signal handler
 - A user-defined signal handler
- By default, every signal has a default signal handler that is run by the kernel
- This default signal handler can be overwritten by the user-defined signal handler
- Single-threaded programs: straightforward, signals are always delivered to the process
- Multithreaded programs: more complicated

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Threading Issues – Signal Handling (cont.)

- When a signal is delivered to a multithreaded program, the following can happen:
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread
 - Deliver the signal to certain threads in the process
 - Deliver the signal to a specific thread
- Examples:
 - A terminating signal should be sent to all thread in the process
 - Solaris 2 implements the fourth option (i.e., creates a special thread within each process solely for signal handling)



Threading Issues – Thread Pools

- Creating threads can be time consuming
- Too many threads can bog down the system
- Thread pools help with this problem
- Threads are pre-allocated
- The number of threads available at a given time is fixed
- Some systems may adjust the thread pool size depending on usage

Threading Issues – Thread Specific Data

- Threads belonging to the same process share the process data; benefit multithreaded programs
- However, in some instances, each thread might need its own copy of data.
 - For example, a transaction processing multithreaded application might service each transaction in a separate thread
- Most thread libraries such as Win32, Pthreads, and Java provide support for thread-specific data

Threading Issues – Scheduler Activations

LWF

- Both many-to-many and two-level models require communication between the kernel and thread library
- Such coordination allows the appropriate number of kernel threads to be dynamically adjusted to ensure best performance
- Scheduler activation
 - The kernel provides an application with a set of virtual processors (LWPs)
 - The application can schedule user threads onto an available LWP
- Scheduler activations provide upcalls
 - a communication mechanism from the kernel to the thread library
 - Upcall handler must run on a virtual processor



