



Signal-to-noise-ratio Enhancement

FX Processing Codes

% A program for linear prediction of harmonic models, 1D example.

```
dt = 4./1000.; nt = 290;
```

```
t = 0:dt:(nt-1)*dt;
```

```
f = 10;
```

```
lf = 20;
```

```
D_in = cos(2*pi*f*t)' + 0.2*randn(nt,1);
```

```
D_pred = zeros(nt,1);
```

```
C = convmtx(D_in,lf);
```

```
d = zeros(nt+lf-1,1); d(1:nt-1) = D_in(2:nt);
```

```
mu = .001;
```

```
f = inv(C'*C+mu*eye(lf))* C'*d;
```

```
aux = conv(f,D_in);
```

```
D_pred(2:nt,1) = aux(1:nt-1);
```

```
E = D_in - D_pred;
```

Prediction of harmonic models using AR filters

Program used to obtain Figures (5.1) and (5.2)

% First we prepare a synthetic

% Prepare a noise signal

% Compute the pef

% Forward prediction

% Prediction error



Signal-to-noise-ratio Enhancement

Canales method for SNR enhancement

% FX.m - needs function ar.m to compute the predicted at a given frequency

```
clear; clf
```

```
dt = 4./1000;
```

% Make a synthetic t-x model

```
w = ricker(20.,dt);
```

```
nw=max(size(w));
```

```
nx = 32; nt = 128;
```

```
DATA = zeros(nx,nt);
```

```
for i=1:nx
```

```
for j=1:nw
```

```
DATA(i,20+j+i) = w(j);
```

```
end
```

```
end
```

```
NOISE = 0.2 * randn(nx,nt);
```

% Add noise to data

```
DATA = DATA + NOISE;
```

```
p = 20
```

%

Length of the pef

```
DATA_FX = fft(DATA,[],2);
```

% Go to f-x

```
for i=1:nt;
```

% Do

prediction at each freq

```
aux_in = DATA_FX(:,i);
```

```
aux_out = ar(aux_in,p);
```

```
DATA_FX(:,i) = aux_out;
```

```
end
```

```
DATA = real(ifft(DATA_FX,[],2));
```

% Back to t-x

```
subplot(211);wigg(DATA');
```

```
title('Input, \sigma_n=0.2')
```

```
subplot(212);wigg(DATA');
```

```
title('Output after FX filtering, p=20')
```



Signal-to-noise-ratio Enhancement

Linear prediction using AR filters

```
function [D_pred] = ar(D_in,lf);  
% 1D prediction function used by Canales' method.  
%  
% D_in: Data in f-x (one column at freq. f)  
% lf: length of the pef (AR)  
% D_pred: predicted data (clean data)  
%  
n = max(size(D_in));  
D_pred = zeros(n,1);  
C = convmtx(D_in,lf);  
d = zeros(n+lf-1,1);  
(desired output)  
d(1:n-1) =D_in(2:n);  
mu = .001;  
f = inv(C'*C+mu*eye(lf))* C'*d;           % Filter (AR)  
aux = conv(f,D_in);                          % apply filter  
to data  
D_pred(2:n,1) = aux(1:n-1);                  % Prediction  
return
```



Signal-to-noise-ratio Enhancement

ARMA filtering

```
function [s,w,g] = eigen_filtering(y,p,mu);  
% Given a 1D noisy sequence y, the order p of  
% the ARMA(p,p) model and the regularization parameter mu  
% this function computes the clean signal s, an estimate of  
% the noise sequence w, and the prediction error filter g.  
  
N = length(y);  
Y = convmtx(y,p+1);  
R = Y'*Y/N;  
[g,Pw] = eigs(R,1,'SM');  
  
g0 = g(1);  
g = g/g0;  
e = Y*g;  
G = convmtx(g,N);  
D = eye(N)*mu;  
w = inv(G'*G+D)*G'*e;  
s = y-w;  
return
```

% data convolution matrix
% data correlation matrix
% compute 1 eigenvalue (the SMallest)
% and the associated eigenvector

% non-white sequence e
% convolution matrix of the filter
% regularization term
% estimate of the noise
% estimate of the clean signal



Signal-to-noise-ratio Enhancement

Practicing – **Assignments (Chapter 5)**

1. Using the routines and creating your own synthetic data, as shown in previous slides, reproduce figures of Chapter 5. Try to use a real time series to re-run the algorithms.