

**KING FAHD UNIVERSITY OF PETROLEUM & MINERALS
DEPARTMENT OF ELECTRICAL ENGINEERING**

EE 380

CONTROL ENGINEERING

MAJOR EXAM I

TIME: 5:15 p.m.

November 8, 2009

NAME :	
I.D. # :	
SEC # :	

QUESTION #	SCORE	MAXIMUM
1.		20
2.		30
3.		25
4		25
TOTAL		100

Instructor: Dr. J. M. BAKHASHWAIN

1. Find the value of a for the following system

$$\dot{x} = \begin{pmatrix} a & a \\ a & a \end{pmatrix} x + \begin{pmatrix} 0 \\ 1 \end{pmatrix} u(t)$$

$$y = \begin{pmatrix} 1 & 0 \end{pmatrix} x$$

If $y(t) = 0.5(1 - e^{-t} + te^{-t})$ for an input $u(t) = e^{-t}$. Assume zero initial conditions

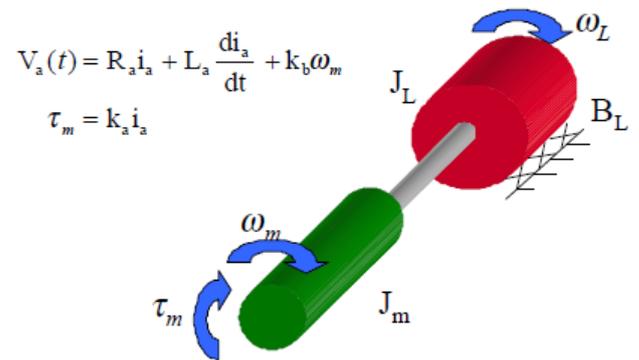
2. Draw the block diagram for armature controlled dc motor. Show that the transfer function is given

by
$$\frac{\omega_m(s)}{V_a(s)} = \frac{a}{s^2 + bs + c}$$

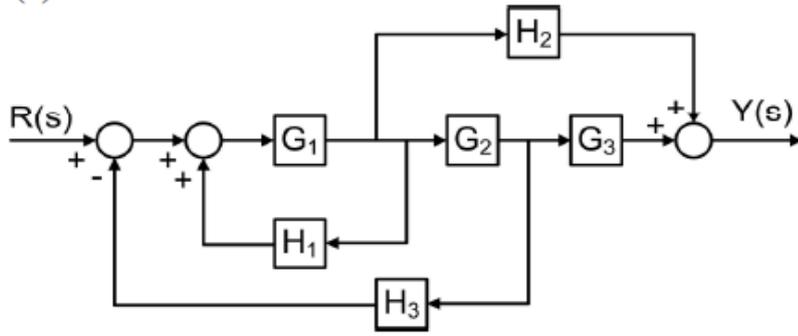
(i) Find a, b, and c

(ii) Find the state space representation when the

state vector $x = (i_a \quad \omega_m \quad \theta_m)^T$



3. Simplify the block diagram shown and obtain the closed-loop transfer function $\frac{Y(s)}{R(s)}$.



4. Using Mason's gain formula, find the transfer function for the shown signal flow graph

