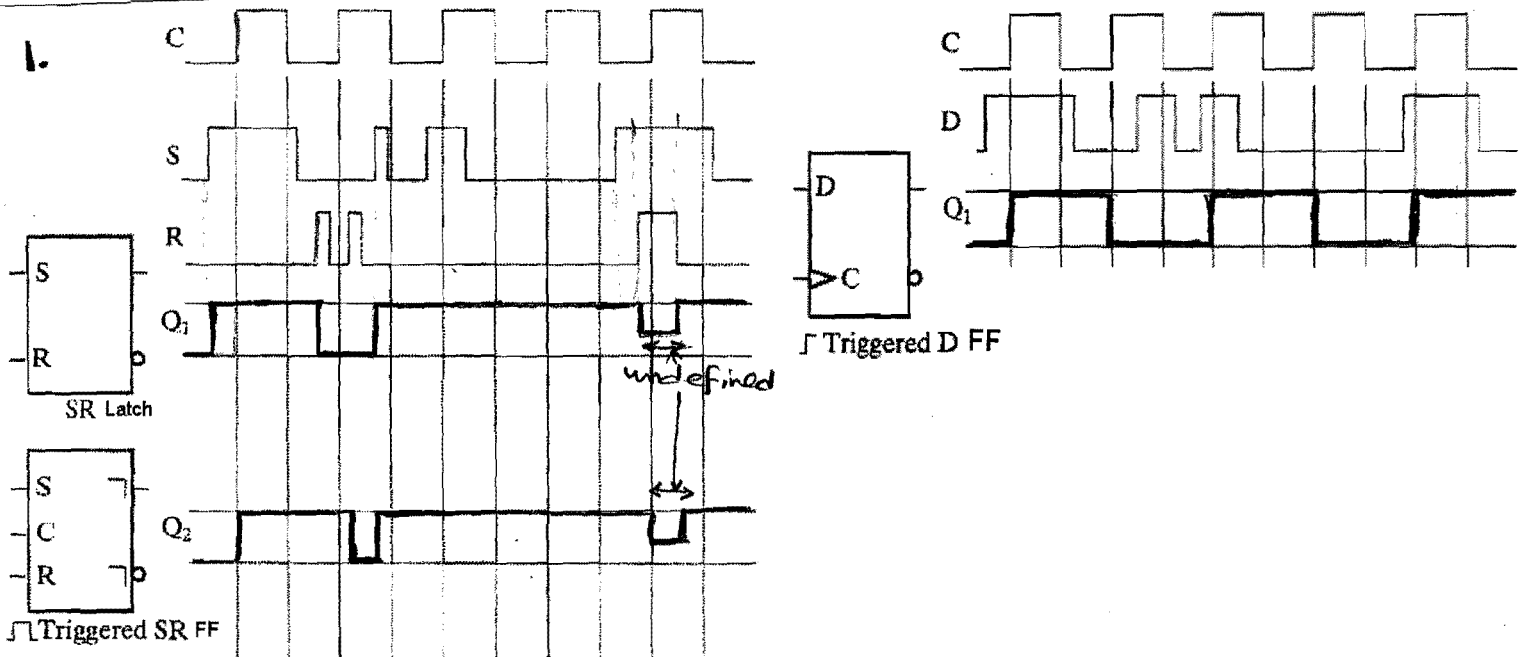


# COE 202.03 Homework #7 Solutions

H7-1

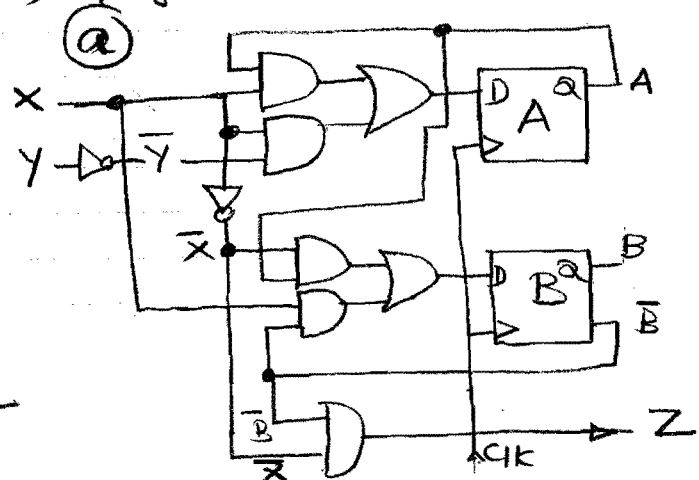


2.  $S_6$  in the textbook, page 299:

$$D_A = XA + X\bar{Y}$$

$$D_B = X\bar{B} + \bar{X}A$$

$$Z = \bar{X}\bar{B}$$



b. 1-D state table  
I/Ps

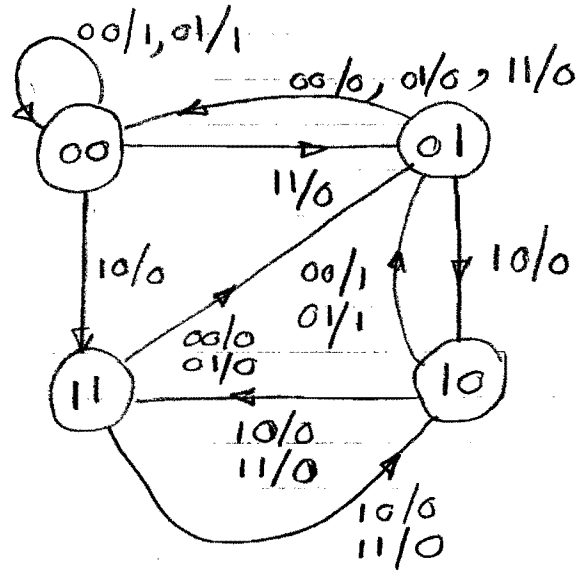
A	B	X	Y	$XA$	$X\bar{Y}$	$D_A$	$X\bar{B}$	$\bar{X}A$	$D_B$	$Z = \bar{X}\bar{B}$
0	0	0	0	0	1	0	1	0	0	1
0	0	0	1	0	0	0	1	0	0	1
0	0	1	0	0	1	0	1	0	0	0
0	0	1	1	0	0	0	1	0	0	0
0	1	0	0	0	1	0	0	0	0	0
0	1	0	1	0	0	0	0	0	0	0
0	1	1	0	0	1	0	0	0	0	0
0	1	1	1	0	0	0	0	0	0	0
1	0	0	0	1	1	1	0	1	1	0
1	0	0	1	1	0	1	0	1	1	0
1	0	1	0	1	1	1	0	1	1	0
1	0	1	1	1	0	1	0	1	1	0
1	1	0	0	1	1	1	0	0	0	0
1	1	0	1	1	0	1	0	0	0	0
1	1	1	0	1	1	1	0	0	0	0
1	1	1	1	1	0	1	0	0	0	0

2 contd, b.

2-D state table

Present state A(t) B(t)	Next state A(t+1) B(t+1)				output Z = $\overline{X}B$			
	xy=00	xy=01	xy=10	xy=11	00	01	10	11
0 0	00	00	11	01	1	1	0	0
0 1	00	00	10	00	0	0	0	0
1 0	01	01	11	11	1	1	0	0
1 1	01	01	10	10	0	0	0	0

c.

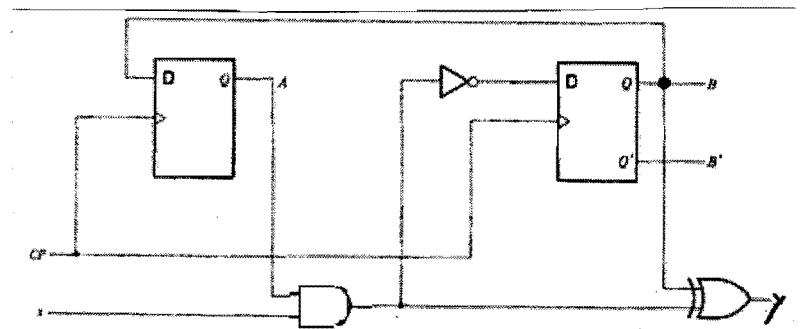


3.

$D_A = B$

$D_B = \overline{AX}$

$Y = AX \oplus B$



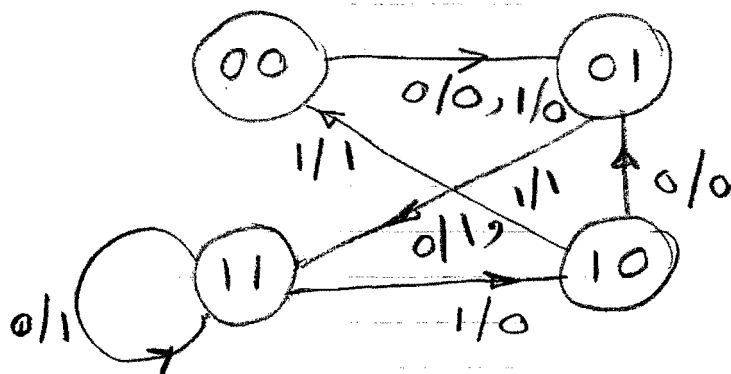
a. 1-D State Table

I/Ps			O/Ps			
A	B	X	$D_A$	$D_B$	AX	$Y = AX \oplus B$
0	0	0	0	1	0	0
0	0	1	0	1	0	0
0	1	0	1	1	0	1
0	1	1	1	1	0	1
1	0	0	0	1	0	0
1	0	1	0	0	1	1
1	1	0	1	1	0	1
1	1	1	1	0	1	0

b. 2-D state table

Present state $A(t) B(t)$		Next state $A(t+1) B(t+1)$		o/p $Y$	
		$X=0$	$X=1$	$X=0$	$X=1$
0	0	01	01	0	0
0	1	11	11	1	1
1	0	01	00	0	1
1	1	11	10	1	0

c. state Diagram



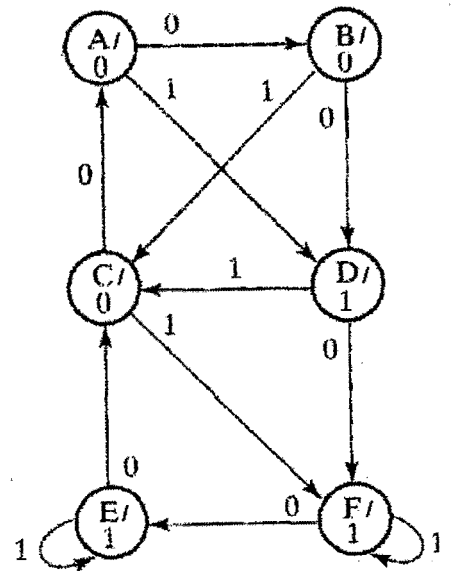
4.

a. Moore (External o/p tied to state)  
- does not depend on I/p

b. 6 states, 3 FFs, 1 external I/p  
 $01 = o/p$

c. - 2-D Table

Present state	Next state		o/p
	$I/p=0$	$I/p=1$	
A	B	D	0
B	D	C	0
C	A	F	0
D	F	C	1
E	C	E	1
F	E	F	1



1-D Table

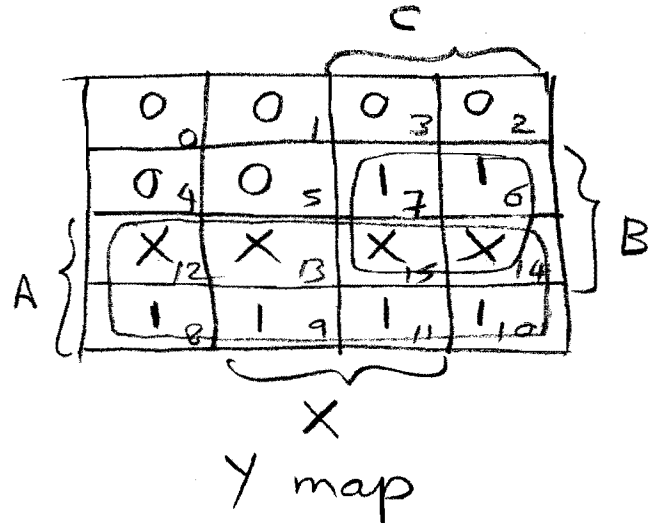
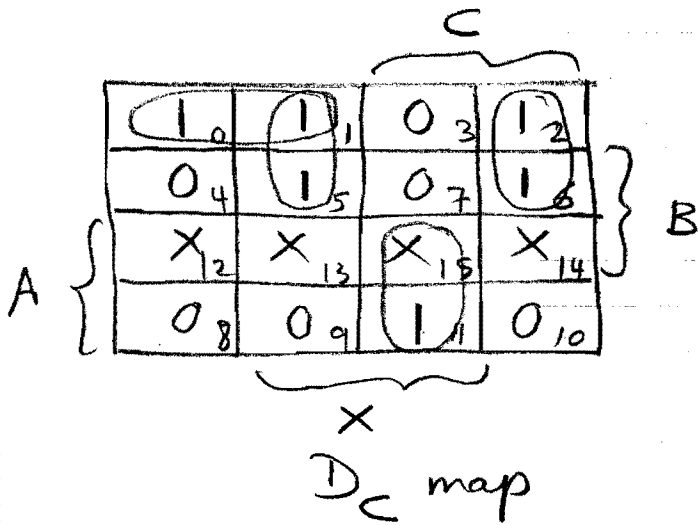
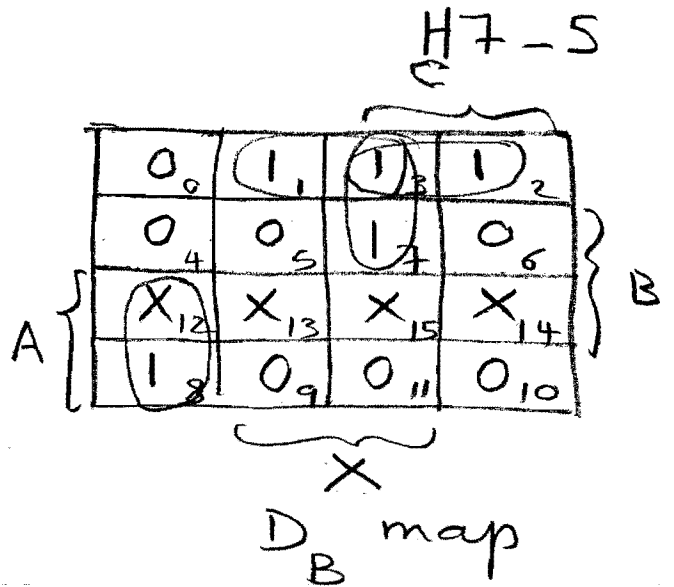
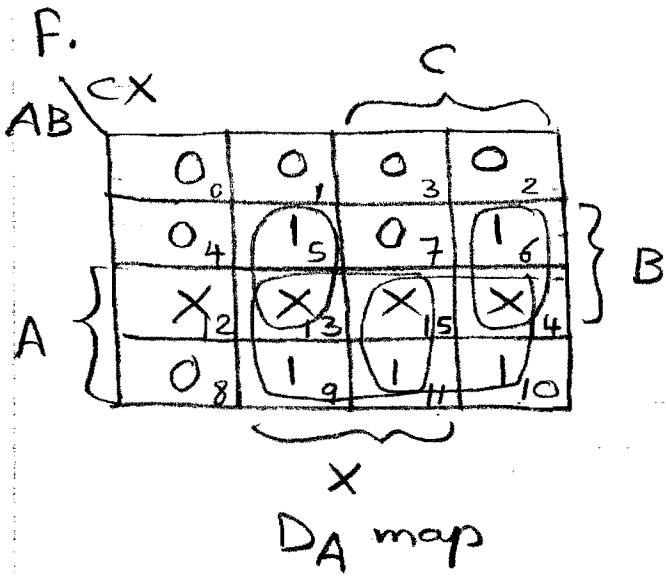
H7-4

Present state	I/P	Next state	O/P
A	0	B	0
A	1	D	0
B	0	D	0
B	1	C	0
C	0	A	0
C	1	E	0
D	0	F	1
D	1	F	1
E	0	F	1
E	1	F	1
F	0	F	1
F	1	F	1

e. A = 000 B = 001 C = 010  
 D = 011 E = 100 F = 101

We need 3 FFS  $\rightarrow 2^3 = 8$  states, we use  
 6 out of these 8 states giving

Index	Present state			I/P X	Next state			O/P Y
	A <sub>t</sub>	B <sub>t</sub>	C <sub>t</sub>		A <sub>t+1</sub>	B <sub>t+1</sub>	C <sub>t+1</sub>	
0	0	0	0	0	0	0	0	0
1	0	0	0	1	0	0	0	0
2	0	0	1	0	0	1	0	0
3	0	0	1	1	0	1	0	0
4	0	1	0	0	0	0	0	0
5	0	1	0	1	0	0	0	0
6	0	1	1	0	1	0	1	0
7	0	1	1	1	1	0	1	0
8	1	0	0	0	0	0	0	1
9	1	0	0	1	0	0	0	1
10	1	0	1	0	1	0	0	1
11	1	0	1	1	1	0	0	1
12	1	1	0	0	X	X	X	X
13	1	1	0	1	X	X	X	X
14	1	1	1	0	X	X	X	X
15	1	1	1	1	X	X	X	X



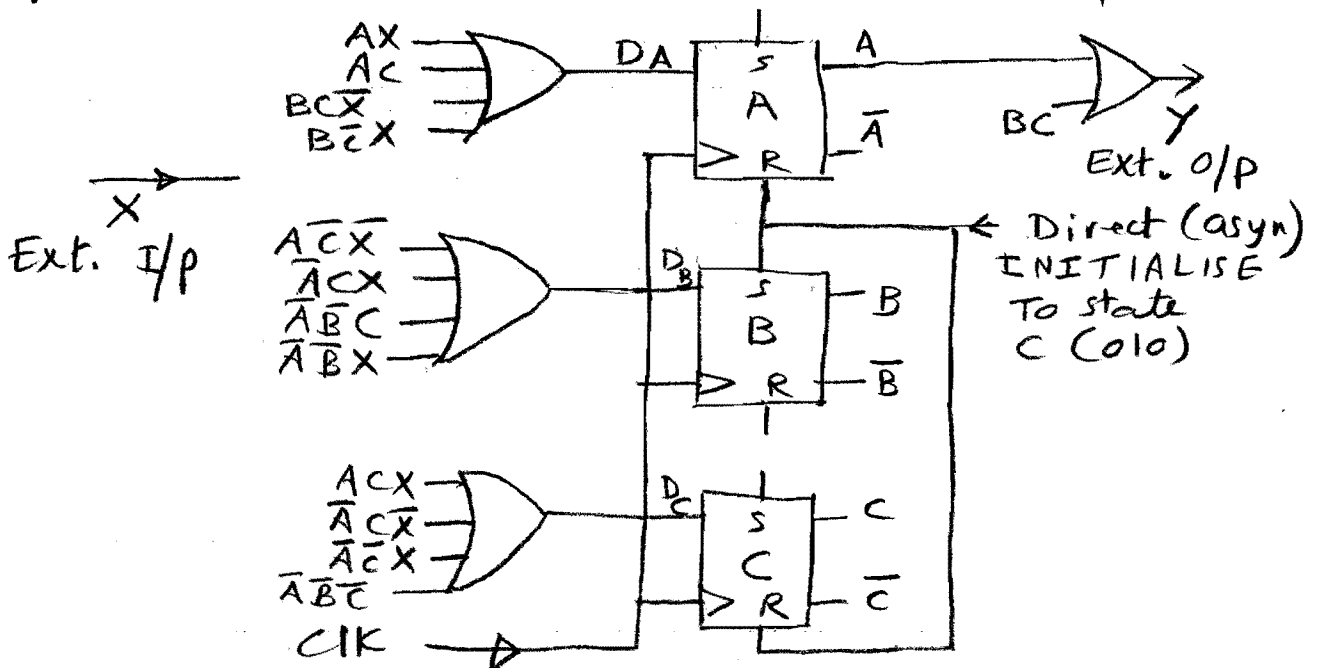
$$D_A = AX + AC + BC\bar{X} + B\bar{C}X$$

$$D_B = A\bar{C}\bar{X} + \bar{A}CX + \bar{A}\bar{B}C + \bar{A}\bar{B}X$$

$$D_C = ACX + \bar{A}C\bar{X} + \bar{A}\bar{C}X + \bar{A}\bar{B}\bar{C}$$

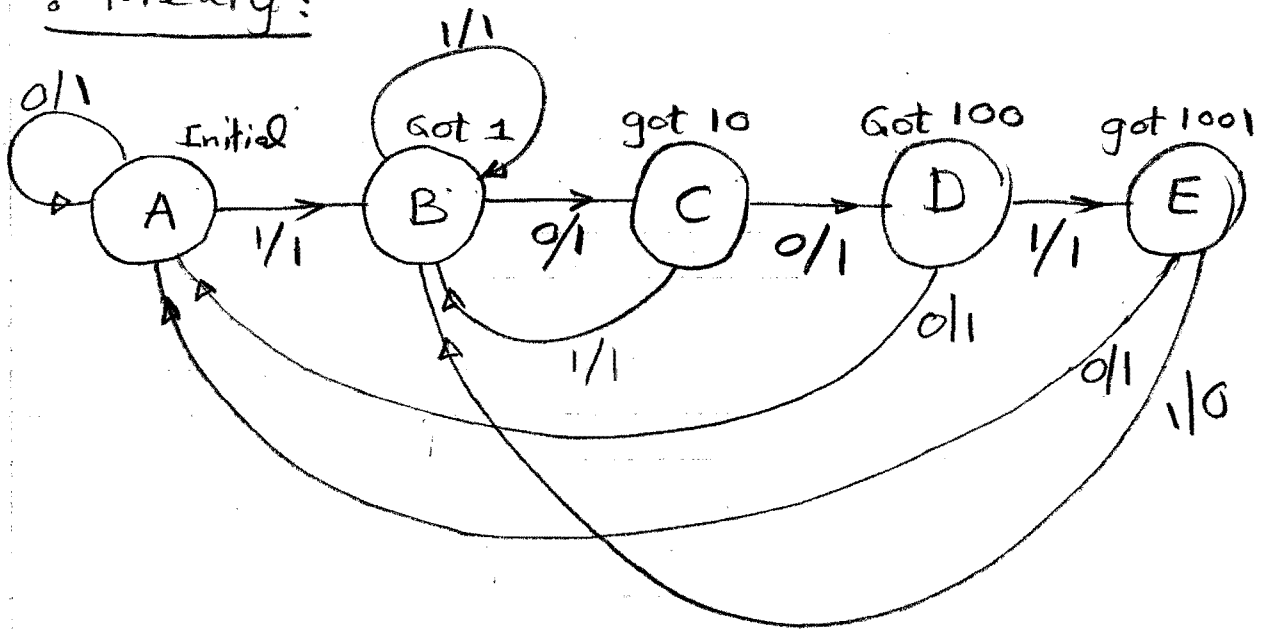
$$Y = A + BC$$

9.



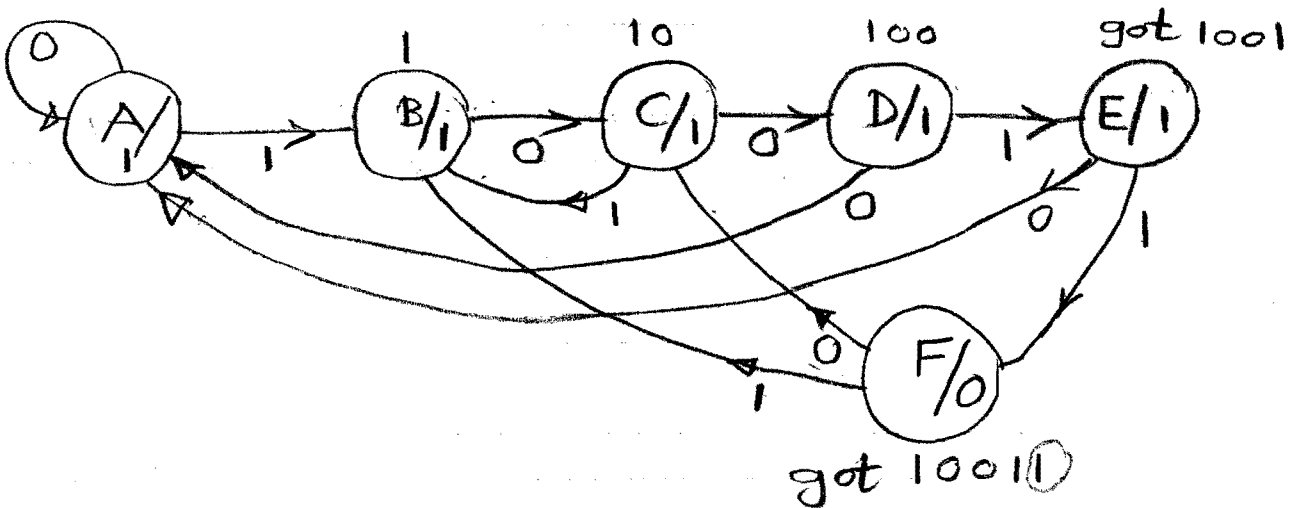
5.  $\frac{I}{P}$  sequence to be detected is 10011

• Mealy:



# of states = 5  
 # of FFs = 3  
 # of state variables = 3

• Moore



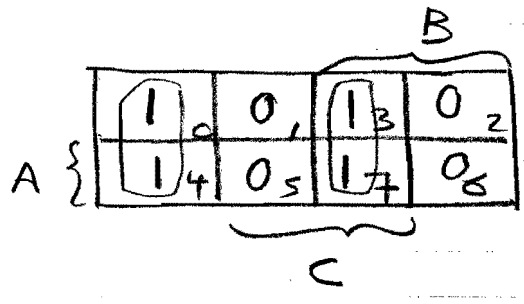
# of states = 6  
 # of FFs = 3  
 # of state variables = 3

6.

a.

Index	Present state			Next state		
	$A_t$	$B_t$	$C_t$	$A_{t+1}$ ( $D_A$ )	$B_{t+1}$ ( $D_B$ )	$C_{t+1}$ ( $D_C$ )
7	1	1	0	1	0	0
6	1	1	0	1	0	0
5	1	0	1	0	0	1
4	1	0	0	0	1	0
3	0	1	1	0	0	1
2	0	1	0	0	0	1
1	0	0	1	0	0	1
0	0	0	0	1	1	1

b.



$D_B$  map

$$D_B = BC + \bar{B}\bar{C}$$