# Comparison Results for Quasilinear Elliptic Equations via Picone-Type Identity 

Tadié<br>Matematisk Institute, Universitetsparken 5<br>2100, Copenhagen, Denmark<br>E-mail: tad@math.ku.dk


#### Abstract

We find some comparison results between solutions of some quasilinear problems in regular bounded domains in $\mathbb{R}^{n}$, using a Picone-type multidimensional identity. Here we will not be investigating how to use the identity for super-sub-solutions methods purpose but to use it as to check how/if the concerned solutions "co-habit" or not in the concerned domains.


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## 1 Introduction

Let $p$ and $Q$ be two differential operators. To extend the comparison theorem of C. Sturm for solutions $u$ and $v$ of the Sturm-Liouville equations

$$
-\left(p_{1}(x) u^{\prime}\right)^{\prime}+p_{0}(x) u=0 ; \quad p_{1}>0
$$

and

$$
-\left(P_{1}(x) v^{\prime}\right)^{\prime}+P_{0}(x) v=0 ; \quad P_{1}>0
$$

Mauro Picone ([5]) used the fact that if $u, v, p u^{\prime}$ and $Q v^{\prime}$ are differentiable with $v \neq 0$, then

$$
\begin{align*}
& \frac{d}{d x}\left\{\frac{u}{v}\left[v p u^{\prime}-u Q v^{\prime}\right]\right\}=u\left(p u^{\prime}\right)^{\prime}-\frac{u^{2}}{v}\left(Q v^{\prime}\right)^{\prime}  \tag{P}\\
& +(p-Q)\left(u^{\prime}\right)^{2}+Q\left(u^{\prime}-\frac{u}{v} v^{\prime}\right)^{2}
\end{align*}
$$

This equation bears his name since. Many extensions and generalizations of that identity had been made (e.g., $[2,3]$ and references therein). One of the interests of such identities is that integrating them over regular bounded domains provides
crucial information about the functions $u$ and $v$ compared with each other in the required domain. This work is focused on the multidimensional type identity [3], namely, if $G$ is a bounded domain in $\mathbb{R}^{n} \quad(n \geq 2)$ with a regular boundary (e.g., $\left.\partial G \in C^{l}, l \geq 1\right)$, we define for $\alpha>0$ and $f, F \in C(\bar{G} \times \mathbb{R} ; \mathbb{R})$ and $\mathbb{R}_{+}:=[0, \infty)$ the operators

$$
\left.\begin{array}{l}
P u:=P_{f} u=\nabla \cdot\{a \Phi(\nabla u)\}+c \phi(u)+f(x, u),  \tag{1}\\
Q v:=Q_{F} v=\nabla \cdot\{A \Phi(\nabla v)\}+C \phi(v)+F(x, v), \\
\text { where } \quad a, A \in C^{1}\left(\bar{G} ; \mathbb{R}_{+}\right), \quad c, C \in C(\bar{G} ; \mathbb{R}) ; \\
\phi(t)=|t|^{\alpha-1} t \quad \text { and } \quad \Phi(\xi)=|\xi|^{\alpha-1} \xi \text { for } t \in \mathbb{R}, \xi \in \mathbb{R}^{n} .
\end{array}\right\}
$$

Solutions will be supposed to be in

$$
\begin{equation*}
\mathcal{D}_{P}(G):=\left\{u \in C^{1}(\bar{G} ; \mathbb{R}) \mid a \Phi(\nabla u) \in C^{1}(G ; \mathbb{R}) \bigcap C(\bar{G} ; \mathbb{R})\right\} \tag{2}
\end{equation*}
$$

and respectively in $\mathcal{D}_{Q}(G)$ which is defined similarly. As in [3], we note that $s \phi^{\prime}(s)=$ $\alpha \phi(s) ; \phi(s) \neq 0$ if $s \neq 0 ; \phi(s) \phi(t)=\phi(s t) ; \phi(s) \Phi(\xi)=\Phi(s \xi)$. So, similar to Theorem 1.1 of [3], we have the following result:

Lemma 1.1 If $u \in \mathcal{D}_{P}(G), v \in \mathcal{D}_{Q}(G)$ with $v \neq 0$ in $G$, then from

$$
\begin{aligned}
& \nabla \cdot\left\{\frac{u}{\phi(v)}[\phi(v) a \Phi(\nabla u)]\right\}=a|\nabla u|^{\alpha+1}+u P u-c|u|^{\alpha+1}-u f(x, u) \quad \text { and } \\
& \nabla \cdot\left\{u \phi(u) \frac{A \Phi(\nabla v)}{\phi(v)}\right\}=(\alpha+1) A \phi(u / v) \nabla u \cdot \Phi(\nabla v) \\
& -\alpha A\left|\frac{u}{v} \nabla v\right|^{\alpha+1}+\frac{u}{\phi(v)} \phi(u) Q v-C|u|^{\alpha+1}-\frac{u}{\phi(v)} \phi(u) F(x, v),
\end{aligned}
$$

we get

$$
\begin{align*}
& \nabla \cdot\left\{\frac{u}{\phi(v)}[\phi(v) a \Phi(\nabla u)-\phi(u) A \Phi(\nabla v)]\right\} \\
& =(a-A)|\nabla u|^{\alpha+1}+(C-c)|u|^{\alpha+1} \\
& +A\left\{|\nabla u|^{\alpha+1}-(\alpha+1)\left|\frac{u}{v} \nabla v\right|^{\alpha-1} \nabla u \cdot\left(\frac{u}{v} \nabla v\right)+\alpha\left|\frac{u}{v} \nabla v\right|^{\alpha+1}\right\}  \tag{3}\\
& +\frac{u}{\phi(v)}\{[\phi(v) P u-\phi(u) Q v]+[\phi(u) F(x, v)-\phi(v) f(x, u)]\} .
\end{align*}
$$

## Remarks 1.2

In the formulae (3) diverse values attributed to the coefficients $a, A, c, C$ and the functions $f$ and $F$ provide various identities.

1) a) For a general operator $K u:=\nabla \cdot\{a \Phi(\nabla u)\}+g(x, u)$, results related to $P$ can apply after defining $f(x, u)=g(x, u)-c \phi(u)$.
b) Let $a$ be a function as that in (1). For the operator

$$
E_{\lambda} u:=\nabla \cdot\{a(x) \Phi(\nabla u)\}+\lambda \phi(u),
$$

the corresponding "first eigenvalue" in the domain $G$ if it exists will be defined for $\nu:=\alpha+1$ as the number

$$
\lambda_{1}:=\lambda_{1}(a ; G)=\inf \left\{\frac{\int_{G} a(x)|\nabla v|^{\nu} d x}{\int_{G}|v|^{\nu} d x} ; \quad v \in W_{0}^{1, \nu}(G) \backslash\{0\}\right\} .
$$

Let $G$ be a bounded and regular domain and $a$ be bounded and bounded away from 0 . Then $\lambda_{1}$ exists and the solution $u_{1}$, say, of

$$
\nabla \cdot\{a \Phi(\nabla u)\}+\lambda_{1} \phi(u)=0 \quad \text { in } G ;\left.\quad u\right|_{\partial G}=0, \quad\left(E_{\lambda_{1}}(G)\right)
$$

is unique modulo a constant multiplier and belongs to $C^{1+\theta}(\bar{G})$ for some $\theta \in(0,1)$ $[1,4,6]$. The solution $u_{1}$ is called the eigenfunction corresponding to $\lambda_{1}$ and can be chosen positive.
2) a) For any $\mu>0$,

$$
\Psi(\mu u):=\nabla \cdot\{a(x) \Phi(\nabla \mu u)\}+c \phi(\mu u)=\mu^{\alpha} \Psi(u)
$$

and we will say that a function $f(x, \cdot)$ is $\alpha$-homogeneous if

$$
f(x, \mu t)=\mu^{\alpha} f(x, t) \quad \forall \mu>0
$$

b) We will denote $P_{0} u$ and $Q_{0} v$ for the operators in (1) where $f(x, u) \equiv 0$ and $F(x, v) \equiv 0$ respectively.
3) We have the following result from [3, Lemma 2.1]:

Given $\alpha>0$,

$$
\begin{equation*}
\forall \xi, \eta \in \mathbb{R}^{n} \quad|\xi|^{\alpha+1}+\alpha|\eta|^{\alpha+1}-(\alpha+1)|\eta|^{\alpha-1} \xi \cdot \eta \geq 0 \tag{4a}
\end{equation*}
$$

and the equality holds if and only if $\xi=\eta$.

## Some identities:

4) If $a=A, c=C, P u=Q v=0$ in $G$, then (3) becomes

$$
\begin{align*}
& \nabla \cdot\left\{\frac{u}{\phi(v)} a[\phi(v) \Phi(\nabla u)-\phi(u) \Phi(\nabla v)]\right\} \\
& =Z(u, v)+u \phi(u)\left[\frac{F(x, v)}{\phi(v)}-\frac{f(x, u)}{\phi(u)}\right]  \tag{4b}\\
& =a\left\{|\nabla u|^{\alpha+1}-(\alpha+1)\left|\frac{u}{v} \nabla v\right|^{\alpha-1} \nabla u \cdot\left(\frac{u}{v} \nabla v\right)+\alpha\left|\frac{u}{v} \nabla v\right|^{\alpha+1}\right\} \\
& +u \phi(u)\left[\frac{F(x, v)}{\phi(v)}-\frac{f(x, u)}{\phi(u)}\right]
\end{align*}
$$

where $Z_{a}(u, v)$ or $Z(u, v)$ (if there is no confusion) is defined by

$$
Z(u, v):=a\left\{|\nabla u|^{\alpha+1}+\alpha\left|\frac{u}{v} \nabla v\right|^{\alpha+1}-(\alpha+1)\left|\frac{u}{v} \nabla v\right|^{\alpha-1} \nabla u \cdot\left(\frac{u}{v} \nabla v\right)\right\} .
$$

If we interchange the functions $u$ and $v$ in (4b) assuming that none of them takes zero value inside $G$ then as in (4b) we have

$$
\begin{align*}
& \nabla \cdot\left\{\frac{v}{\phi(u)} a[\phi(u) \Phi(\nabla v)-\phi(v) \Phi(\nabla u)]\right\} \\
& =a\left\{|\nabla v|^{\alpha+1}-(\alpha+1)\left|\frac{v}{u} \nabla u\right|^{\alpha-1} \nabla v \cdot\left(\frac{v}{u} \nabla u\right)+\alpha\left|\frac{v}{u} \nabla u\right|^{\alpha+1}\right\}  \tag{4c}\\
& +v \phi(v)\left[\frac{F(x, u)}{\phi(u)}-\frac{f(x, v)}{\phi(v)}\right] \\
& =Z(v, u)+v \phi(v)\left[\frac{F(x, u)}{\phi(u)}-\frac{f(x, v)}{\phi(v)}\right] .
\end{align*}
$$

5) For the functions $u$ and $v$ above, if $\Omega \subset G$ has a nonempty interior and $f(x, t) \equiv$ $F(x, t)$, then after integrating (4b) over $\Omega$ we get

$$
\begin{align*}
& \int_{\partial \Omega} a u\left\{|\nabla u|^{\alpha-1} \frac{\partial u}{\partial \nu_{\Omega}}-|\nabla v|^{\alpha-1} \frac{\partial v}{\partial \nu_{\Omega}}\right\} d s \\
= & \int_{\Omega}\left[Z(u, v)+|u|^{\alpha+1}\{\chi(x, v)-\chi(x, u)\}\right] d x,  \tag{4d}\\
& \text { and from }(4 \mathrm{c}) \\
& \int_{\partial \Omega} a v\left\{|\nabla v|^{\alpha-1} \frac{\partial v}{\partial \nu_{\Omega}}-|\nabla u|^{\alpha-1} \frac{\partial u}{\partial \nu_{\Omega}}\right\} d s \\
= & \int_{\Omega}\left[Z(v, u)+|v|^{\alpha+1}\{\chi(x, u)-\chi(x, v)\}\right] d x, \tag{4e}
\end{align*}
$$

where $\nu_{\Omega}$ denotes the outward normal unit vector to $\partial \Omega$ and

$$
\begin{equation*}
\chi(x, t):=f(x, t) / \phi(t) . \tag{5}
\end{equation*}
$$

In the sequel $G$ and any subset of its are assumed to be of the class $C^{l}, l \geq 1$.

## 2 Main results

When the perturbations are homogeneous only for $\alpha=1$, obviously the possibility that a solution of the problem coincides with a multiple of that of a half-linear equation cannot hold.

Theorem A Let $f \in C(\bar{G} \times \mathbb{R} ; \mathbb{R})$ and let $u, v \in \mathcal{D}_{P}(G)$ be two solutions of

$$
P w:=\nabla \cdot\{a \Phi(\nabla w)\}+c \phi(w)+f(x, w)=0 \text { in } G ;\left.\quad w\right|_{\partial G}=0
$$

such that each of them remains nonzero inside $G$ and they have the same sign.

1) If $t \mapsto f(x, t) / \phi(t):=\chi(x, t)$ is monotone in $\mathbb{R}$ uniformly for $x \in G$, then the two solutions have at least one common point.
If $\Omega$ is a subset of $G$ and $\chi(x, t)$ is increasing in $t>0$, then if $v \geq u$ in $\Omega$,

$$
\begin{equation*}
\int_{\partial \Omega} a u\left\{|\nabla u|^{\alpha-1} \frac{\partial u}{\partial \nu_{\Omega}}-|\nabla v|^{\alpha-1} \frac{\partial v}{\partial \nu_{\Omega}}\right\} d s \geq 0 \tag{a1}
\end{equation*}
$$

and if, in addition, $u=v$ on $\partial \Omega$, then

$$
\begin{align*}
0 & \geq \int_{\Omega}\left\{Z(v, u)+|v|^{\alpha+1}[\chi(x, u)-\chi(x, v)]\right\} d x \\
& =-\int_{\Omega}\left\{Z(u, v)+|u|^{\alpha+1}[\chi(x, v)-\chi(x, u)]\right\} d x \tag{a2}
\end{align*}
$$

2) If $\chi(x, t)$ is decreasing in $t$ and nonnegative for any $x \in \Omega$, then the two solutions coincide.

In the sequel, $\Omega \subset \mathbb{R}^{n}$ is a bounded domain with $\partial \Omega \in C^{1} ; a \in C^{1}\left(\bar{\Omega} ; \mathbb{R}_{+}\right)$and $K \in C\left(\bar{\Omega} \times \mathbb{R}_{+} ; \mathbb{R}_{+}\right)$.

Theorem B Consider in $\Omega$ the problems

$$
\left\{\begin{array}{l}
E u:=\nabla \cdot\left\{a(x)|\nabla u|^{\alpha-1} \nabla u\right\}+K(x, u)=0  \tag{E}\\
\left.u\right|_{\partial \Omega}=0 ; \quad u \in \mathcal{D}_{E}(\Omega)
\end{array}\right.
$$

If there are $\beta \in C\left(\bar{\Omega} ; \mathbb{R}_{+}\right)$and $W \in C^{1}\left(\bar{\Omega} ; \mathbb{R}_{+}\right)$such that a.e. in $\Omega$

$$
\begin{align*}
& \left.W\right|_{\partial \Omega}=0, \quad K(x, W)-\beta(x) \phi(W) \geq 0 \quad \text { and } \\
& \int_{\Omega}\left\{a|\nabla W|^{\alpha+1}-c|W|^{\alpha+1}\right\} d x \leq 0 \tag{Ea}
\end{align*}
$$

then any solution $u \in \mathcal{D}_{E}(\Omega)$ of ( $E$ ) has a zero inside $\Omega$ unless there is $\lambda \in \mathbb{R}$ such that $u=\lambda W$ and

$$
\int_{\Omega} W\left\{\lambda^{\alpha} K(x, W)-K(x, \lambda W)\right\} d x=0
$$

Theorem C Suppose that $a \in C^{1}(\bar{\Omega} ;(0, \infty))$ and let $\lambda_{1}:=\lambda_{1}(a, \Omega)$ as in Remarks 1.2. If $K$ is $\alpha$-homogeneous only for $\alpha=1$, then 1) if

$$
\begin{equation*}
K(x, t)-\lambda_{1} \phi(t) \geq 0 \quad \text { in } \Omega \times \mathbb{R}_{+} \tag{Eb}
\end{equation*}
$$

(E) has no solution which is strictly positive in $\Omega$;
2) assume that $K(x, t):=\mu \phi(t)+h(x, t) \quad$ where $h(x, t) \leq 0$ and $\mu>0$; then if $\lambda_{1} \geq \mu$, ( $E$ ) has no solution which is strictly positive in $\Omega$.

The solution $u_{1}$ corresponding to $\lambda_{1}$ can be taken to satisfy $\left|u_{1}\right|_{C(\bar{\Omega})} \leq 1$ and replace $W$ in $(E a)$. Thus the inequality in $(E b)$ to hold in $\Omega \times[0,1]$ will be sufficient. An application of these results is

Theorem D Assume that $K$ is $\alpha$-homogeneous only for $\alpha=1$. Then the problem

$$
\left\{\begin{array}{l}
E u:=\nabla \cdot\left\{a(x)|\nabla u|^{\alpha-1} \nabla u\right\}+K(x, u)=0, \quad u>0 \quad \text { in } \quad \Omega ; \\
\left.u\right|_{\partial \Omega}=0 ; \quad u \in \mathcal{D}_{E}(\Omega)
\end{array}\right.
$$

has at most one solution satisfying for some $\beta \in C\left(\bar{\Omega} ; \mathbb{R}_{+}\right)$

$$
K(x, u)-\beta(x) \phi(u) \geq 0 \quad \text { in } \quad \Omega .
$$

In particular, for any $\beta \in C\left(\bar{\Omega} ; \mathbb{R}_{+}\right)$and $f \in C\left(\bar{\Omega} \times \mathbb{R}_{+} ; \mathbb{R}_{+}\right)$

$$
\begin{aligned}
& \nabla \cdot\left\{a(x)|\nabla u|^{\alpha-1} \nabla u\right\}+\beta(x) \Phi(u)+f(x, u)=0, \quad u>0 \text { in } \Omega ; \\
& \left.u\right|_{\partial \Omega}=0 ; \quad u \in \mathcal{D}_{E}(\Omega)
\end{aligned}
$$

has at most one solution.

## 3 Some comparison results

Theorem 3.1 Assume that there are $u, v \in \mathcal{D}_{P}(G)$, respectively nontrivial solutions of

$$
P_{0} u:=\nabla \cdot\{a \Phi(\nabla u)\}+c \phi(u)=0 \quad \text { in } \quad G
$$

and

$$
P_{g} v:=\nabla \cdot\{a \Phi(\nabla v)\}+g(x, v)=0 \quad \text { in } \quad G,\left.\quad v\right|_{\partial G}=0
$$

for some $g \in C(\bar{G} \times \mathbb{R} ; \mathbb{R})$.
a) If

$$
\begin{equation*}
\int_{G} v(x)\{c \phi(v)-g(x, v)\} d x \geq 0 \tag{6}
\end{equation*}
$$

then $u$ has a zero inside $G$. If equality prevails in (6), then there is $k \in \mathbb{R}$ such that $u \equiv k v$ in $G$.
b) If

$$
\begin{align*}
& g(x, v)-c \phi(v) \geq 0 \quad \text { in } \quad G \quad \text { or } \\
& \int_{G} \frac{|u|^{\alpha+1}}{\phi(v)}[g(x, v)-c \phi(v)] d x \geq 0,
\end{align*}
$$

then $v$ has a zero inside $G$. If equality prevails in ( $6^{\prime}$ ), then there is $k \in \mathbb{R}$ such that $u \equiv k v$ in $G$.

Proof.
a) Assume that $u \neq 0$ in $G$.

Applied to $u$ and $v,(4 \mathrm{c})$ where $f(x, v):=g(x, v)-c \phi(v)$ and $F(x, u) \equiv 0$ reads

$$
\begin{align*}
& \nabla \cdot\left\{\frac{v}{\phi(u)} a[\phi(u) \Phi(\nabla v)-\phi(v) \Phi(\nabla u)]\right\}  \tag{6a}\\
& =Z(v, u)+v\{c \phi(v)-g(x, v)\}
\end{align*}
$$

The integration of (6a) over $G$ and using (4a) leads to

$$
\begin{equation*}
0=\int_{G} Z(v, u)+\int_{G} v(x)\{c \phi(v)-g(x, v)\} d x \tag{7}
\end{equation*}
$$

Thus if (6) holds, $v \neq 0$ cannot hold throughout $G$ as otherwise (7) would not hold. From (7), if equality holds in (6), then by (4a) $\nabla u=(u / v) \nabla v$ whence $v \nabla u-u \nabla v:=v^{2} \nabla(u / v)=0$ and the conclusion follows.
b) If we suppose that $v \neq 0$ in $G$, then from (4b) we have

$$
\begin{align*}
& \nabla \cdot\left\{\frac{u}{\phi(v)} a[\phi(v) \Phi(\nabla u)-\phi(u) \Phi(\nabla v)]\right\} \\
& =Z(u, v)+\frac{|u|^{\alpha+1}}{\phi(v)}\{g(x, v)-c \phi(v)\} \tag{6b}
\end{align*}
$$

and the proof is completed as in the a)-case.
Theorem 3.2 Let $\Omega$ be a regular bounded domain in $\mathbb{R}^{n}$ as $G$ in (1) and $\Omega_{1}$ be a domain containing $\Omega$. Let $a, A \in C^{1}\left(\bar{\Omega}_{1} ; \mathbb{R}_{+}\right)$and $c, C \in C\left(\bar{\Omega}_{1} ; \mathbb{R}\right)$ with $a \equiv c \equiv 0$ in $\Omega$. Assume that there is $u \in C^{1}(\bar{\Omega})$ such that $\left.u\right|_{\partial \Omega}=0$ and

$$
\begin{equation*}
\int_{\Omega}\left\{A|\nabla u|^{\alpha+1}-C|u|^{\alpha+1}\right\} d x \leq 0 \tag{8}
\end{equation*}
$$

Then any solution $v \in \mathcal{D}_{Q}(\Omega)$ of

$$
\left\{\begin{array}{l}
Q v:=Q_{f} v=\nabla \cdot\{A \Phi(\nabla v)\}+C \phi(v)+f(x, v)=0 \quad \text { in } \Omega  \tag{9}\\
\text { satisfying } \quad \phi(v) f(x, v) \geq 0 \text { in } \Omega \\
\text { or } \quad \int_{\Omega}\left\{Z(v, u)+|u|^{\alpha+1} \frac{f(x, v)}{\phi(v)}\right\} d x \geq 0
\end{array}\right.
$$

must vanish somewhere in $\Omega$ unless there is $k \in \mathbb{R}$ such that $u=k v$ and either $f$ is $\alpha$-homogeneous or $\int_{\Omega} v\left\{k^{\alpha} f(x, v)-f(x, k v)\right\} d x=0$.

Note that the (heavy) introduction of $\Omega_{1}$ can be avoided by defining the operator $P$ as $P v \equiv f(x, v)$.
Proof. Assume that such $v$ is nonzero throughout $\Omega$. With the operator $P:=P_{f}$ as in (1), in $\Omega, \quad P u=f(x, u)$ and (3) reads

$$
\begin{equation*}
\nabla \cdot\{\phi(u / v) A \Phi(\nabla v)\}=A|\nabla u|^{\alpha+1}-C|u|^{\alpha+1}-Z(u, v)-u \phi(u / v) f(x, v) . \tag{9a}
\end{equation*}
$$

Integrating this over $\Omega$ we get

$$
\begin{equation*}
\int_{\Omega}\left\{A|\nabla u|^{\alpha+1}-C|u|^{\alpha+1}\right\} d x=\int_{\Omega}\left\{Z(u, v)+u \phi\left(\frac{u}{v}\right) f(x, v)\right\} d x \tag{10}
\end{equation*}
$$

and the conclusion follows.
If $u=k v$, we have equality in (8) and (10) is reduced to

$$
k \phi(k) \int_{\Omega} v\left\{k^{\alpha} f(x, v)-f(x, k v)\right\} d x=0
$$

## 4 Proofs of Theorems

### 4.1 Proof of Theorem A

The statement (a1) follows from (4d). Adding (4d) and (4e), we get

$$
\begin{aligned}
& \int_{\partial \Omega} a(u-v)\{\Phi(u)-\Phi(v)\} \cdot \nu_{\Omega} d s \\
& =\int_{\Omega}\left\{Z(u, v)+Z(v, u)+\left[|u|^{\alpha+1}-|v|^{\alpha+1}\right](\chi(x, v)-\chi(x, u))\right\} d x
\end{aligned}
$$

leading to (a2). For the two solutions, (4b) and (4c) lead (after an integration over $G$ ) to

$$
\begin{align*}
0 & \leq \int_{G} Z(u, v) d x=-\int_{G} u \phi(u)\left\{\frac{f(x, v)}{\phi(v)}-\frac{f(x, u)}{\phi(u)}\right\} d x  \tag{A1}\\
& =-\int_{G}|u|^{\alpha+1}\{\chi(x, v)-\chi(x, u)\} d x
\end{align*}
$$

and

$$
\begin{align*}
0 & \leq \int_{G} Z(v, u) d x=-\int_{G} v \phi(v)\left\{\frac{f(x, u)}{\phi(u)}-\frac{f(x, v)}{\phi(v)}\right\} d x  \tag{A2}\\
& =\int_{G}|v|^{\alpha+1}\{\chi(x, v)-\chi(x, u)\} d x
\end{align*}
$$

Assume that $\chi(x, t)$ is increasing. If we suppose that $v>u$ in $G$, then (A1) provides a contradiction and if we suppose that $u>v$, (A2) would lead to a contradiction. Assume that $\chi(x, t)$ is decreasing and define

$$
G_{+}\left(G_{-}\right):=\{x \in G \mid X(x):=\chi(x, v)-\chi(x, u)>(<) 0\} .
$$

Then (without loss of generality) $0<v \leq u$ in $G_{+}$and $v>u \geq 0$ in $G_{-}$whence

$$
\begin{align*}
& \int_{G_{+}}|v|^{\alpha+1} X(x) d x \leq \int_{G_{+}}|u|^{\alpha+1} X(x) d x \text { and }  \tag{A3}\\
& \int_{G_{-}}|v|^{\alpha+1} X(x) d x \leq \int_{G_{-}}|u|^{\alpha+1} X(x) d x
\end{align*}
$$

This implies from (A1) and (A2) that

$$
0 \leq \int_{G}|v|^{\alpha+1} X(x) d x \leq \int_{G}|u|^{\alpha+1} X(x) d x \leq 0,
$$

whence $\int_{G} Z(u, v) d x=0$, leading to $v \equiv u$ in $G$ by (4a).
If $f$ is nonnegative and decreasing in $t, \chi$ is decreasing in $t$ and the same conclusion is reached.

### 4.2 Proof of Theorem B and Theorem C

B) This is an application of Theorem 3.2.

We just need to take $f(x, z):=K(x, z)-\beta \Phi(z)$.
C) 1) Follows easily from Theorem B when we take for $W$ the eigenfunction $u_{1}$ corresponding to $\lambda_{1}$ and $\beta=\lambda_{1}$.
2) This follows from Theorem 3.1, where $c=\lambda_{1}$ and $g(x, t):=K(x, t)$.

### 4.3 Proof of Theorem D

To prove this it is enough to notice that if we suppose to have two such solutions, with one of them playing the role of $W$, the conclusion follows from Theorem B. When $K$ is $\alpha$-homogeneous only for $\alpha=1$, the last part of the conclusion of Theorem B can apply only for that value of $\alpha$.

### 4.4 Concluding remarks

Remark 4.1 Concerning the problems $(E)$, the hypothesis for the results in Theorem B through Theorem D is more or less $K(x, u)-\beta(x) \phi(u) \geq 0$ in $\Omega$; $\phi(t)=O\left(t^{\alpha}\right)$ for small $t>0$.
As the datum on $\partial \Omega$ is 0 , using the change $U(x):=u(x) /\left\{\max _{\bar{\Omega}} u(x)\right\}$ the results more likely hold for sublinear perturbations, (e.g., $\left.K(x, t)=O\left(t^{q}\right) ; q \in(0, \alpha]\right)$. But if we consider strictly positive solutions of the Neumann problem

$$
\left\{\begin{array}{l}
\nabla \cdot\left\{a(x)|\nabla v|^{\alpha-1} \nabla v\right\}+K(x, v)=0 \quad \text { in } \Omega ;  \tag{N}\\
\left.\nabla v\right|_{\partial \Omega}=0 ; \quad v \in \mathcal{D}_{E}(\Omega),
\end{array}\right.
$$

using this time the change $V(x):=v(x) /\left\{\min _{\bar{\Omega}} v(x)\right\}$ the results apply for superlinear perturbations $\left(K(x, t)=O\left(t^{p}\right) ; p>\alpha\right)$.

Remark 4.2 In [3], some oscillation theorems are established for half-linear problems. Following similar approaches (hopefully with the help of Theorem 3.1), similar results could be obtained for some cases with perturbations.

Remark 4.3 A Wirtinger-type inequality states that
For a regular domain $G$, if there is a solution $v \in \mathcal{D}_{P_{0}}(G)$ of the half-linear equation $P_{0} v=\nabla \cdot\left\{a(x)|\nabla v|^{\alpha-1} \nabla v\right\}+c(x) \phi(v)=0$ such that $v \neq 0$ in $G$, then $\int_{G}\left[a(x)|\nabla u|^{\alpha+1}-c(x)|u|^{\alpha+1}\right] d x \geq 0$ holds for any nontrivial function $u \in C^{1}(\bar{G} ; \mathbb{R})$ such that $\left.u\right|_{\partial G}=0$ where the equality holds if and only if $u$ is a constant multiple of $v$. (see [3])
For the perturbations cases, Theorem 3.2 provides some corresponding (alternative) version of the inequality, namely, for any domain $G$ as above and $f \in C\left(\bar{G} \times \mathbb{R} ; \mathbb{R}_{+}\right)$

Proposition 4.1 If $\int_{G} v\left\{k^{\alpha} f(x, v)-f(x, k v)\right\} d x \neq 0 \quad \forall k \notin\{0,1\} \quad$ where $v \in \mathcal{D}_{P}(G)$ is nonzero in $G$ and solves $\nabla \cdot\{A \Phi(\nabla v)\}+C \phi(v)+f(x, v)=0$ in $G$, then $\int_{G}\left\{A(x)|\nabla u|^{\alpha+1}-C(x)|u|^{\alpha+1}\right\} d x>0$ holds for any nontrivial $u \in C^{1}(\bar{G} ; \mathbb{R})$ such that $\left.u\right|_{\partial G}=0$.

Remark 4.4 For a nonhomogeneous perturbation $g(x, v)$, Theorem 3.1 implies that the respective solutions $u, v \in \mathcal{D}_{P}(G)$ of $\nabla \cdot\{a \Phi(\nabla u)\}+c \phi(u)=0$ in $G$ and $\nabla \cdot\{a \Phi(\nabla v)\}+g(x, v)=0$ in $G,\left.\quad v\right|_{\partial G}=0$ cannot be both nonzero inside $G$ if $g(x, v)-c \phi(v)$ is nonzero (whence keeps the same sign) in $G$.

Remark 4.5 The uniqueness result in Theorem A can be deduced from (a1) and (4d) or (4e).
In fact, if there are two solutions $u, v$, say, such that in some $D \Subset G v>u>0$ and
$u=v$ on $\partial D$, then by (4.e) and (a1) $0 \geq \int_{\partial D} a v\left\{|\nabla v|^{\alpha-1} \frac{\partial v}{\partial \nu_{D}}-|\nabla u|^{\alpha-1} \frac{\partial u}{\partial \nu_{D}}\right\} d s$ $=\int_{D}\left[Z(v, u)+|v|^{\alpha+1}\{\chi(x, u)-\chi(x, v)\}\right] d x$ and the last member is strictly positive if $\chi(x, t)$ is decreasing in $t$.

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