#### Joint Probing and Scheduling in Wireless Communications Systems

Dr. Yahya S. Al-Harthi Electrical Engineering Department Nov. 11, 2008

This work has been conducted during my visit to the School of Mathematics, University of Bristol, UK.

#### Outline

- □ The concept of Multiuser Diversity.
- □ Literature Review
- □ System Model
- □ Algorithm 1
- □ Algorithm 2
- □ Conclusions

### Basic Concept of Multiuser Diversity

- In a large system, there is likely to be a user with a very good channel at any time.
- Long term total system throughput can be maximized Uplink [Knopp and Humblet "1995"], and Downlink [Tse "1997"].
- Scheduling schemes that exploit the time-varying channel conditions are "opportunist".



Two users

#### Multiuser Diversity (cont'd)

- The a mount of multiuser diversity gain depends crucially on the tail of the fading distribution.
- The heavier the tail, the more likely there is a user with very strong channel, and the larger the multiuser diversity gain.



#### Literature Review

- □ In [D. Zheng *et al* "2007"], an optimal stopping algorithm was used to obtain the optimal number of probing for opportunistic scheduling in ad-hoc networks.
- □ In [N. Chang *et al* "2007"], a study of the optimal strategy for joint probing and transmission in multiple channel was conducted. The goal is to decide which channel to probe and in which order.
- □ Similar study was conducted by [S. Guha *et al* "2006"]
- □ In [P. Chaporkar *et al* "2008"], optimal strategies were provided to optimize the joint probing and scheduling.
- □ In [A. Sabharwal *et al* "2007"], opportunistic band selection is considered and analysis of the optimal skipping rule was derived.

#### System Description

- □ Let  $\Gamma = \{\gamma_i : i = 1, 2, ..., K\}$  be i.i.d. rv's with  $F_{\Gamma}(\gamma)$  distribution function
- Scheduling based on the following yields optimal channel capacity (MUDiv):

$$\begin{cases} \gamma^{\star} = \max_{i=1,2,\dots,K} \gamma_i, \\ R^{\star} = \max_{i=1,2,\dots,K} \log_2(1+\gamma_i). \end{cases}$$

□ Unfortunately, the is a cost, which we call "*probing load*"

$$T(x) = (1-\beta x) \log_2(1+\gamma_x).$$
 number of probes

#### System Description (cont'd)

 $\Box \quad \text{Let } C_i = \log_2(1 + \gamma_i), \text{ then }$ 

$$M_k = \max_{i=1,2,\dots,k} C_i,$$

□ A paper by G. Song *et al* found an asymptotic result for the throughput using Extreme Value Theorem. They showed that the distribution of the throughput belongs to the domain of attraction of the Gumbel distribution.

 $\exists a_k, b_k : \frac{M_k - a_k}{b_k} \to Y, Y \sim \exp(-e^{-y})$  (Gumbel distribution), where

$$a_{k} = \log_{2} \left( 1 + F_{\Gamma}^{-1} \left( 1 - \frac{1}{k} \right) \right),$$
$$b_{k} = \log_{2} \left( \frac{1 + F_{\Gamma}^{-1} \left( 1 - \frac{1}{(k)(e)} \right)}{1 + F_{\Gamma}^{-1} \left( 1 - \frac{1}{k} \right)} \right).$$

EE Department Seminar

### System Description (cont'd)

□ Therefore,

1

$$\begin{split} M_k &= b_k Y + a_k \\ &= \log_2 \left( 1 + \frac{\bar{\gamma}}{1 + \bar{\gamma} \ln k} \right) Y + \log_2 \left( 1 + \bar{\gamma} \ln k \right). \end{split} \text{MUDiv gain}$$

#### □ and

If 
$$k \to \infty$$
,  $a_k \to \infty$ ,  $b_k \to 0$   
$$M_k \approx \log_2(1 + \bar{\gamma} \ln k).$$

### System Description (cont'd)

□ Therefore, the maximization become (average domain)

į

$$\max_{i=1,2,\dots,k} (1-\beta i) M_i,$$

or

$$\max_{i=1,2,\dots,k} e^{-\beta i} M_i.$$

 $\Box$  Given the number of users (*n*), the maximum average throughput is:

$$\bar{T}^{\star}(n) = (1 - \beta n) \log_2(1 + \bar{\gamma} \ln n).$$

 $\Box$  d*T*/d*n* = 0 to find *n* that maximizes the above equation.

#### Algorithm 1

- Given **K** users in the system. Find  $x = n^*$
- □ Probe the users and stop if one of the following occurs:
  - *x* users have been probed, or
  - a user is found such that

$$T_p(i) - \bar{T}^{\star}(n) \ge 0,$$

where,

$$T_p(i) = (1 - \beta i) \log_2(1 + \max_{j=1,2,\dots,i} \gamma_j).$$

#### Numerical Example (Algorithm 1)



Figure 1: Average throughput for different value is  $\beta$  ( $\bar{\gamma} = 20$ dB).

Figure 2: Average number of probes (probes users) for different value is  $\beta$  ( $\bar{\gamma} = 20$ dB).

#### Numerical Example (Algorithm 1)



Figure 3: Average throughput for different value is  $\bar{\gamma}$  ( $\beta = 0.01$ ).

Figure 4: Average number of probes (probes users) for different value is  $\bar{\gamma}$  ( $\beta = 0.01$ ).

## Stopping Rule Problem

- □ The Theory of optimal stopping rule is concerned with the problem of choosing a time to take a given action based on sequentially observed rv's in order to maximize an expected payoff or to minimize an expected cost.
- **Definition:** Stopping rule problems are defined by two objects,
  - a sequence of rv's,  $X_1, X_2, \ldots$ , whose joint distribution is assumed know, and
  - a sequence of real-valued reward functions,

 $y_o, y_1(x_1), y_2(x_1, x_2), y_3(x_1, x_2, x_3), \dots, y_{\infty}(x_1, x_2, \dots)$ 

□ **The 1-stage look-ahead rule.** For stopping rule problems, the 1-sla is described by the stopping time,

$$N^* = \min\{n \ge 0 : Y_n \ge x^*\}.$$

### Algorithm 2

**Problem statement:** 

$$\max_{i=1,2,...,k} (1-\beta i) M_i, \quad \text{or} \quad \max_{i=1,2,...,k} e^{-\beta i} M_i.$$

□ We consider the second maximization and find the 1-sla threshold,

$$e^{-\beta k}M_k \ge E[e^{-\beta(k+1)}(M_k \vee C_{k+1})]$$
$$M_k \ge e^{-\beta}E[M_k \vee C_{k+1}].$$

□ The optimal threshold is,

$$x^* = e^{-\beta} E[x^* \vee C_1].$$

□ Stop if,

$$\log_2(1 + \max_{j=1,2,\dots,i} \gamma_j) \ge x^*.$$

#### Iterative Computation of the threshold

- □ Assume  $C_1, C_2, ..., C_n$  *i.i.d* rv's with  $\overline{C} = \mu$  and distribution function  $F_C(x)$
- $\square \quad \text{Initially, set } v_1 = \mu$
- □ Iteratively calculate:

$$v_{l+1} = e^{-\beta} E[v_l \vee C_1]$$

where

$$E[v_l \vee C_1] = \int_0^{v_l} v_l f_C(y) dy + \int_{v_l}^{+\infty} y f_C(y) dy$$
  
=  $v_l + \int_{v_l}^{+\infty} (1 - F_C(y)) dy.$ 

#### Numerical Example

$\frac{Parameters}{beta=0.01,}$ mean channel gain = 7dB, K=100 users	Algorithm 1	Algorithm 2	Optimal
Throughput (bps/Hz)	3.5177	3.7354	3.8561
Probes (users)	14	11.1170	

<u>Parameters</u> beta=0.1, mean channel gain = 7dB, <i>K</i> =100 users	Algorithm 1	Algorithm 2	Optimal
Throughput (bps/Hz)	2.2124	2.5805	2.6885
Probes (users)	4	2.8690	

### **Open Questions**

- □ What is the optimal stopping rule of the first maximization?
- □ What about 2-sla or 3-sla?
- Does this scheme stabilizes the queues? The stability region?

# Thanks