Computer Aided Circuit Analysis and State Variable Analysis

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- One way of solving complicated circuits containing inductors, capacitors is through computer aided circuit analysis.
- \circ The order of the circuit n is equivalent to the number of non-trivial inductors and capacitors.
- O The variable of interest (voltage or current) can be represented by single n^{th} order differential equation or n first order equations.
- o Computer aided circuit analysis involves two Major steps:
 - o Convert the circuit to matrix state equation. (a. systematic, b. non-systematic)
 - o Numerically solve the matrix state equation.

1.a Convert the circuit to matrix state equation (non-systematic).

- \circ The conversion can be done in a non-systematic way to come up with n first order equations.
 - O Usually to find $\frac{dv_C}{dt}$, we apply KCL at a relevant node.
 - O Usually to find $\frac{di_L}{dt}$, we apply KVL in the relevant loop.
- o For a circuit of the 2 order the matrix state equation may have the following form. If no source exists the second term in the right-hand is zero

$$\frac{\mathrm{d}}{\mathrm{dt}} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} w(t)$$

It's better you check the equations after writing them by multiplication property of the matrices. A common mistake is to miss-place the elements of the matrix

1.b Convert the circuit to matrix state equation (systematic).

- o A systematic procedure is needed to be programmed on a computer.
- O You need to know some Graph Theory concepts (Graph, node, edges, connected graph, spanning tree, branch, non-branch, loop, fundamental loop, cut set, fundamental cut set).

Important terms in GRAPH Theory

GRAPH: is a collection of junction points called **NODES**, and line segments connecting the nodes called **BRANCHES**

TREE: a connected sub-graph, connecting all nodes of the graph but containing no loops. Branches of a tree are called **TREE-Branches**. Other Branches are called **NON-TREE-BRANCHES**.

Spanning Tree: a tree chosen to write circuit equations.

Cut set: a minimum set of branches that, when cut, will divide a graph into two separate parts.

Fundamental cut set: a cut set containing only a single tree branch.

Fundamental loop: a loop that results when a link is put into the tree.

Formal Procedure for Obtaining State Equations

- **STEP1:** Pick a spanning tree such that voltage sources and capacitors correspond to branches, whereas current sources and inductors correspond to non-branch edges. Furthermore, if possible, an element whose voltage controls a dependent source should correspond to a branch, and one whose current controls a dependent source should correspond to a non-branch edge. More than one such tree may exist, or none at all.
- **STEP2:** Arbitrarily assign a voltage to each branch capacitor and a current to each non-branch inductor, these are the state variables. If possible, express the voltage across each element corresponding to a branch and the current through each element corresponding to a non-branch edge in terms of voltage sources, current sources, and state variables. If it is not possible, assign a new voltage variable to a resistor corresponding to a branch and new current variable to a resistor corresponding to a non-branch edge.
- **STEP3:** Apply *KVL* to the fundamental loop determined by each non-branch inductor.
- **STEP4:** Apply *KCL* to the node or super-node corresponding to the fundamental cut-set determined by each branch capacitor.
- **STEP5:** Apply *KVL* to the fundamental loop determined by each resistor with a new current variable assigned in STEP2.
- **STEP6:** Apply *KCL* to the node or super-node corresponding to the fundamental cut-set determined by each resistor with a new voltage variable assigned in STEP2.
- **STEP7:** Solve the simultaneous equations obtained from STEP5 and STEP6 for the new variables in terms of the voltage sources, current sources, and state variables.
- STEP8: Substitute the expressions obtained in STEP7 into the equations determined in STEP3 and STEP4.
 - 2. Numerically solve the matrix state equation.
 - Utilizing Euler's Method: $x([k+1]\Delta t) = x(k\Delta t)[1+A\Delta t]$
 - o The matrix state equation can be solved numerically:
 - o For a two circuit of the second order and a single source, the solution is given by

$$x_{I}([k+1]\Delta t) = x_{I}(k\Delta t) + [a_{II}x_{I}(k\Delta t) + a_{I2}x_{2}(k\Delta t) + b_{I}w(k\Delta t)] \Delta t.$$

$$x_{2}([k+1]\Delta t) = x_{2}(k\Delta t) + [a_{2I}x_{I}(k\Delta t) + a_{22}x_{2}(k\Delta t) + b_{2}w(k\Delta t)] \Delta t.$$

- o where: $(a_{11}, a_{12}, a_{21}, a_{22})$ are the component of the matrix.
- \circ $k = 0, 1, 2, 3, \dots, b1$ and b_2 are component of B matrix (given source w(t))
- \circ The initial conditions for x_1 and x_2 should be given /can be calculated.
- o The previous equation can be easily extended to higher order circuits and more sources.