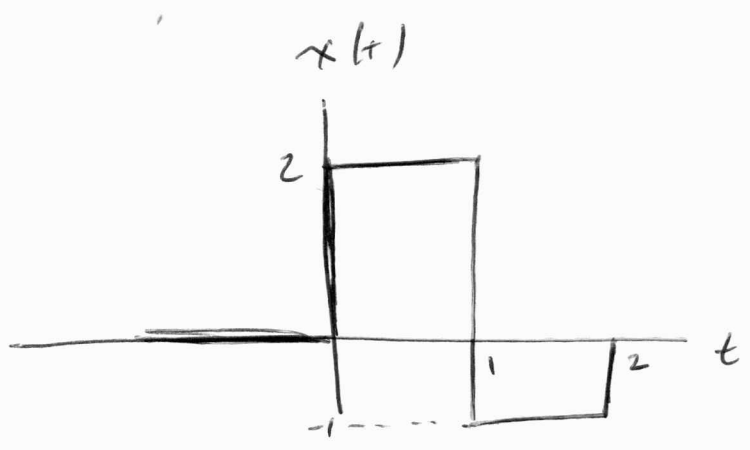
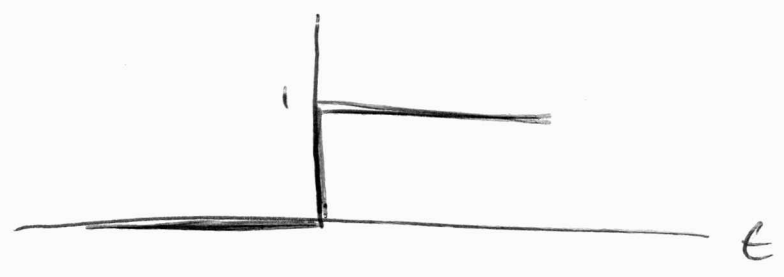


3.2

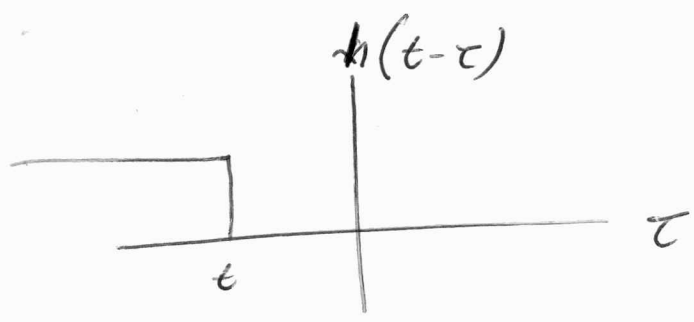
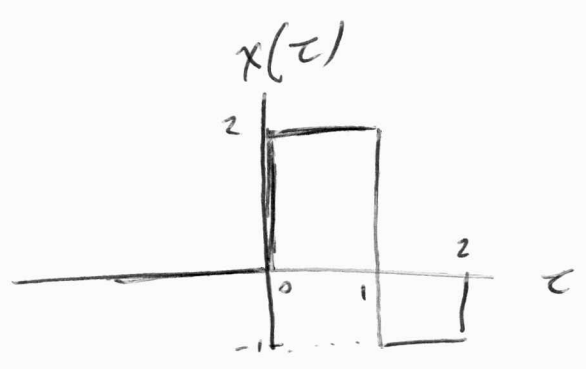
$$h(t) = u(t)$$



$$y(t) = \int_{-\infty}^{\infty} h(\tau) \cdot x(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) \cdot h(t-\tau) d\tau$$

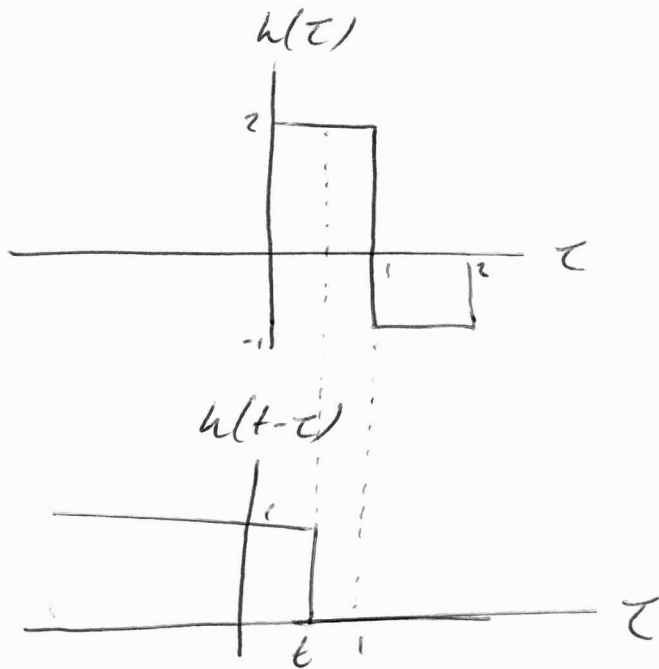
← will do this.



for  $t < 0$

$$y(t) = 0$$

for  $0 \leq t < 1$

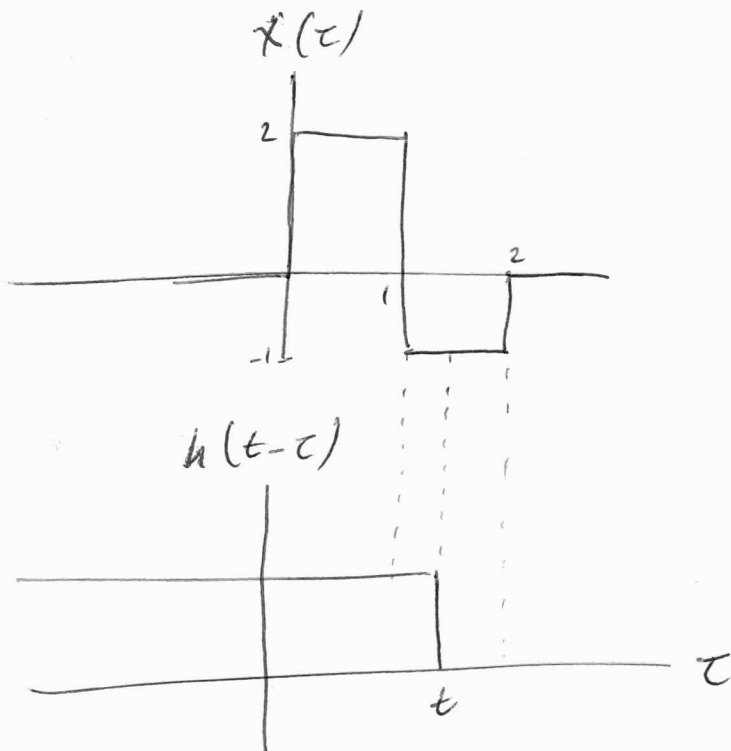


$$y(t) = \int_0^t (1)(2) d\tau = 2\tau \Big|_0^t = 2t - 0 = 2t$$

~~for  $t > 1$~~

for  $1 \leq t < 2$

---

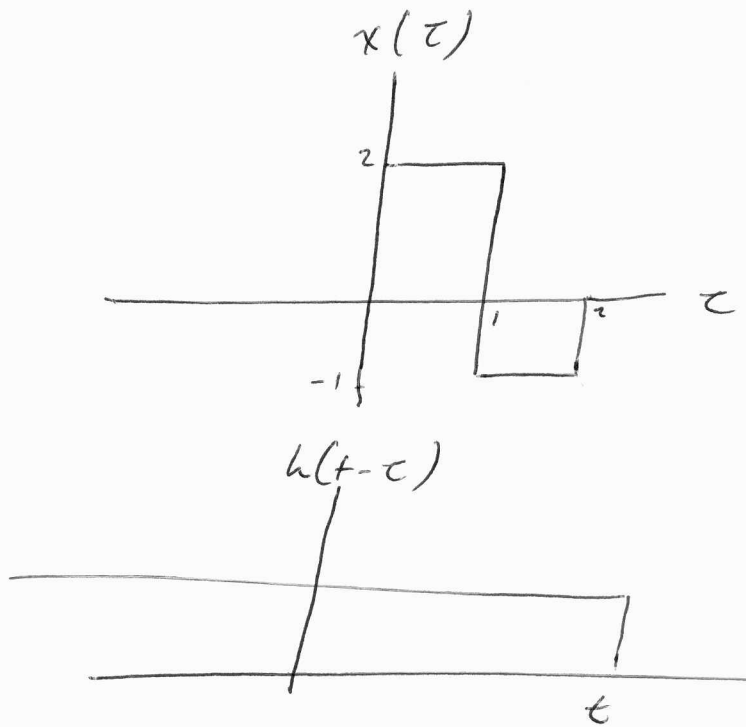


$$y(t) = \int_0^1 (1)(2) d\tau + \int_1^t (1)(-1) d\tau$$

$$= 2\tau \Big|_0^1 + (-\tau) \Big|_1^t$$

$$= 2 + (-t) + 1 = 3 - t$$

For  $t \geq 2$

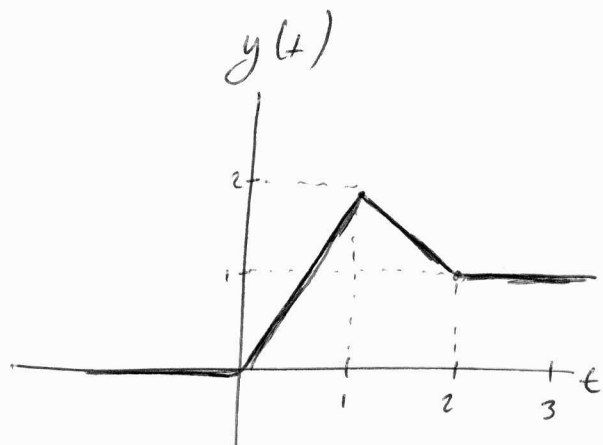


$$y(t) = \int_0^1 (1)(2) d\tau + \int_1^2 (1)(-1) d\tau$$

$$= 2 - 1 = 1$$

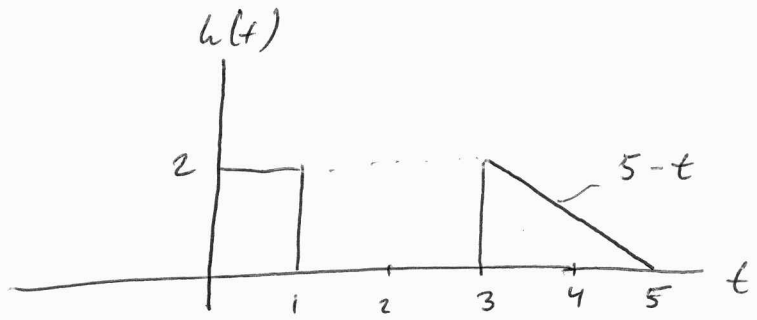
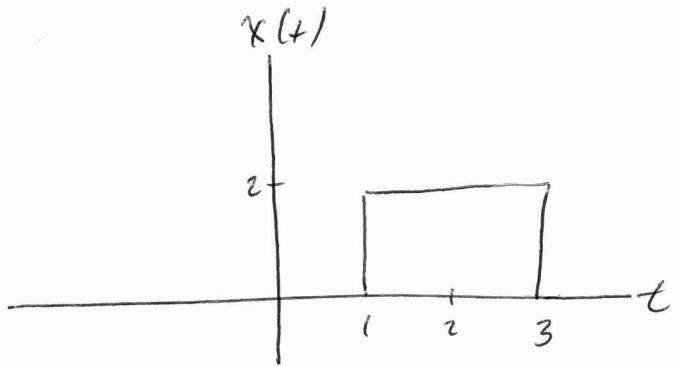
So,

$$y(t) = \begin{cases} 0 & t < 0 \\ 2t & 0 \leq t < 1 \\ 3-t & 1 \leq t < 2 \\ 1 & 2 \leq t \end{cases}$$

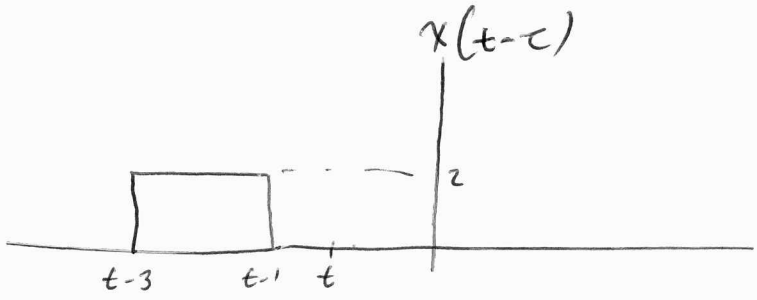
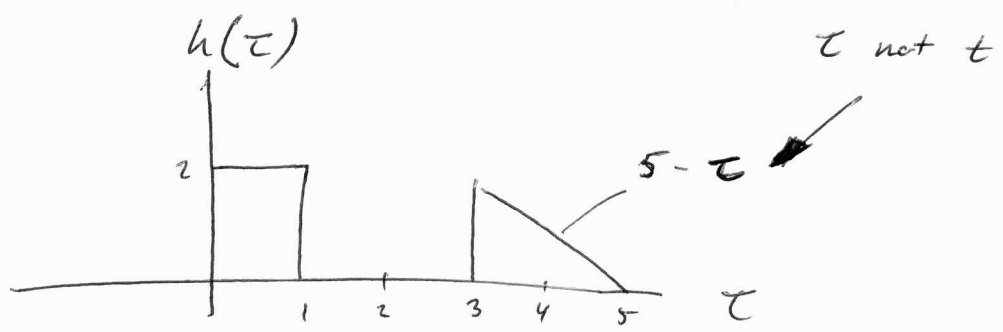


3.4

a

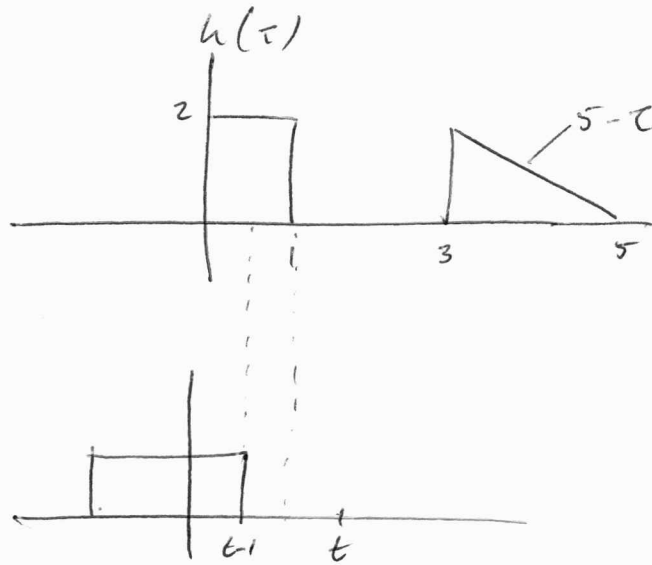


for  $t < 1$



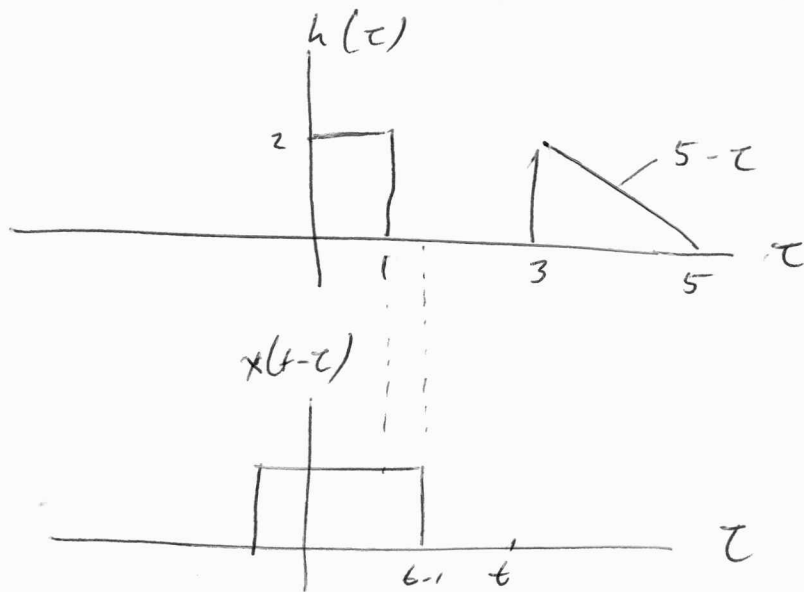
$y(t) = 0$

for  $1 \leq t < 2 \Rightarrow$  (i.e.,  $0 \leq (t-1) < 1$ )



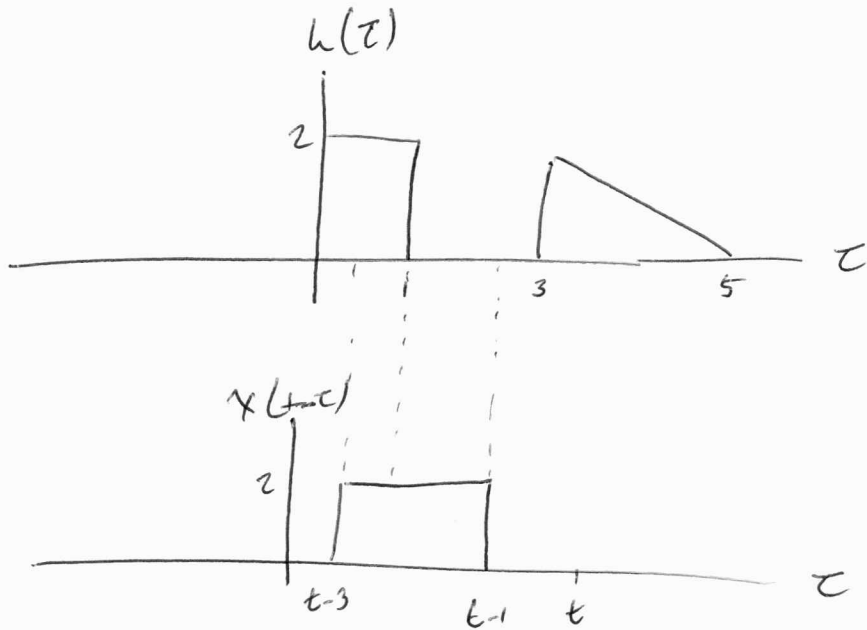
$$y(t) = \int_0^{t-1} (2)(2) d\tau = 4\tau \Big|_0^{t-1} = 4t-4$$

for  $2 \leq t < 3 \Rightarrow$  (i.e.,  $1 < (t-1) < 2$ )



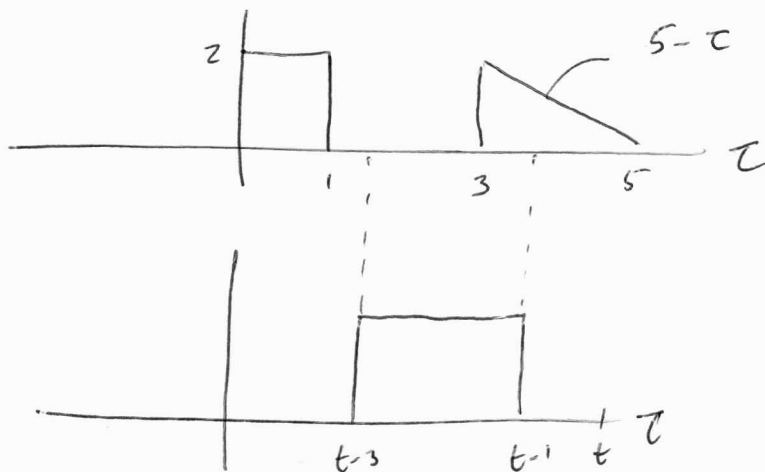
$$y(t) = \int_0^1 (2)(2) d\tau = 4$$

for  $3 \leq t < 4 \Rightarrow$  (i.e.,  $2 < (t-1) < 3$ )



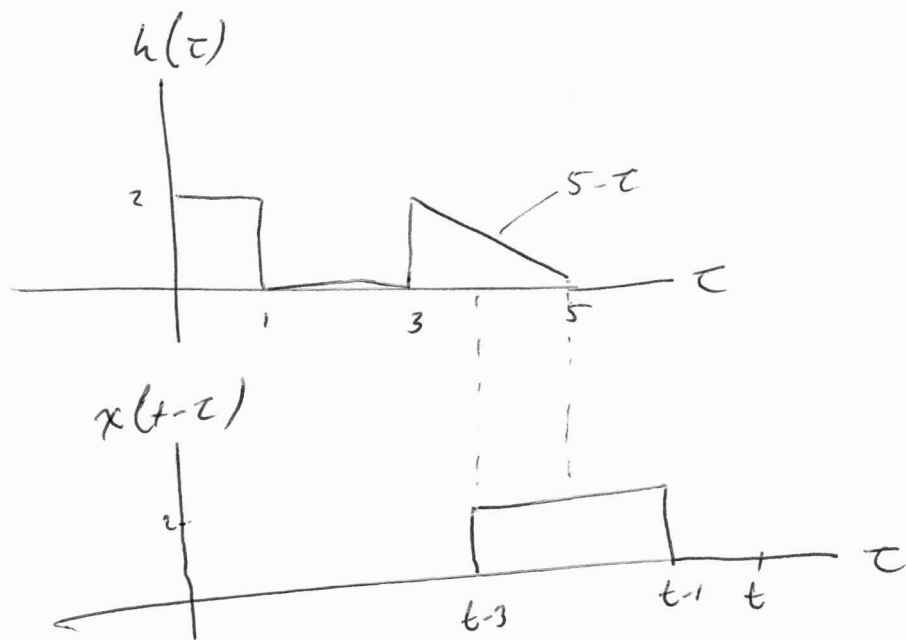
$$y(t) = \int_{t-3}^{t-1} (2)(2) d\tau = 4\tau \Big|_{t-3}^{t-1} = 4 - 4(t-3) = -4t + 16$$

for  $4 \leq t < 6 \Rightarrow$  (i.e.,  $3 \leq (t-1) < 5$ )



$$y(t) = \int_3^{t-1} (2)(5-\tau) d\tau = \int_3^{t-1} 10 - 2\tau d\tau = 10\tau - \frac{2\tau^2}{2} \Big|_3^{t-1} = 10(t-1) - \frac{2(t-1)^2}{2} - 30 + 9$$

For  $6 \leq t < 8 \Rightarrow$  (i.e.,  $5 \leq (t-1) < 7$ )



$$\begin{aligned} y(t) &= \int_{t-3}^5 (2)(5-\tau) d\tau = \int_{t-3}^5 (10-2\tau) d\tau \\ &= 10\tau - \tau^2 \Big|_{t-3}^5 = 50 - 25 - 10(t-3) + (t-3)^2 \end{aligned}$$

For  $8 \leq t$

$$y(t) = 0$$

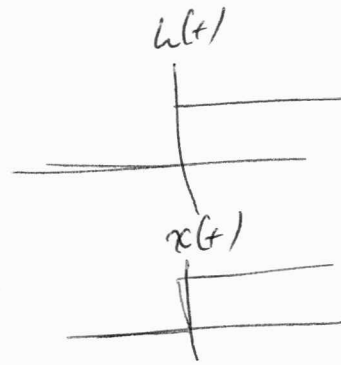


3.8 a

i)

$$h(t) = u(t)$$

$$x(t) = u(t)$$



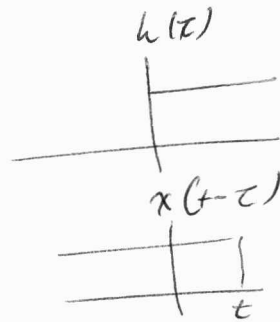
for  $t < 0$

$$y(t) = 0$$

for  $t > 0$

$$y(t) = \int_0^t 1 \, d\tau$$

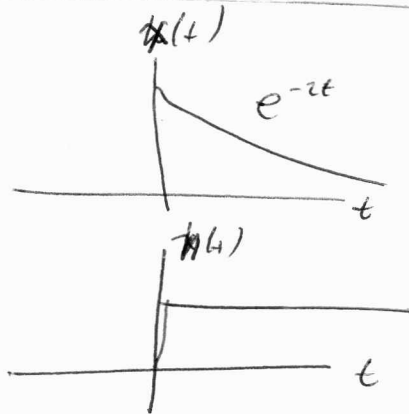
$$= \tau \Big|_0^t = t$$



ii)

$$h(t) = u(t)$$

$$x(t) = e^{-2t} u(t)$$



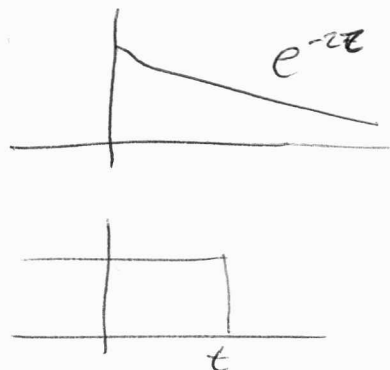
for  $t < 0$

$$y(t) = 0$$

for  $t > 0$

$$y(t) = \int_0^t e^{-2\tau} \, d\tau = -\frac{1}{2} e^{-2\tau} \Big|_0^t$$

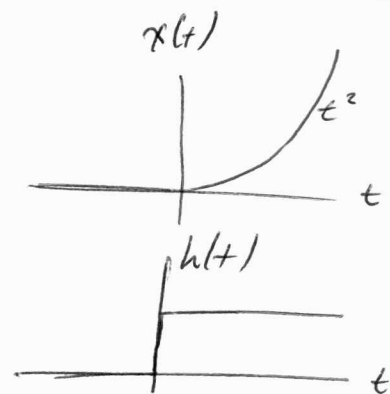
$$= -\frac{1}{2} e^{-2t} + \frac{1}{2}$$



iii)

$$h(t) = u(t)$$

$$x(t) = t^2 u(t)$$



for  $t < 0$

---

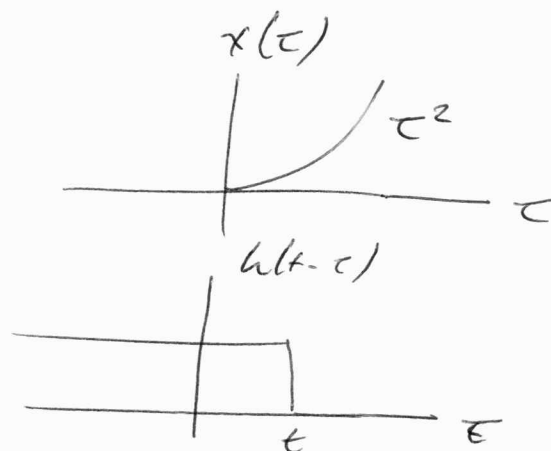

$$y(t) = 0$$

for  $t > 0$

---


$$y(t) = \int_0^t \tau^2 d\tau$$

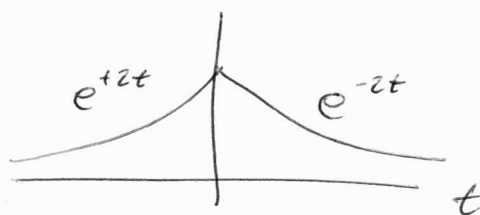
$$= \frac{\tau^3}{3} \Big|_0^t = \frac{t^3}{3}$$



iii)

$$h(t) = u(t)$$

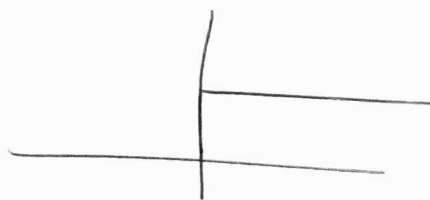
$$x(t) = \begin{cases} e^{-2t} & t \geq 0 \\ e^{2t} & t < 0 \end{cases}$$



for  $t < 0$

---

$$y(t) = \int_{-\infty}^t e^{2\tau} d\tau = \frac{1}{2} e^{2\tau} \Big|_{-\infty}^t = \frac{1}{2} e^{2t} - 0$$

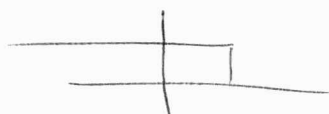
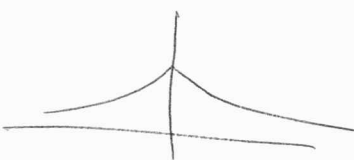


for  $t > 0$

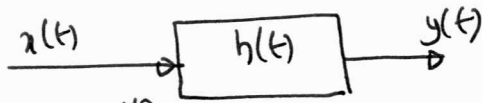
---

$$y(t) = \int_{-\infty}^0 e^{2\tau} d\tau + \int_0^t e^{-2\tau} d\tau$$

$$= \frac{1}{2} e^{2\tau} \Big|_{-\infty}^0 + \frac{1}{2} e^{-2\tau} \Big|_0^t = \frac{1}{2} - \frac{1}{2} e^{-2t} + \frac{1}{2} = 1 - \frac{1}{2} e^{-2t}$$



Problem 3.15:



$$y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$$

For each of the following cases, find  $h(t)$ :

a)  $y(t) = x(t-5)$   
 $= \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$

This is true only if  $h(t) = \delta(t-5)$

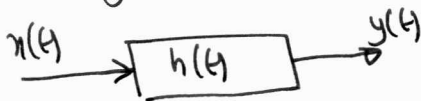
b)  $y(t) = \int_{-\infty}^t x(\tau-s) d\tau$   
 $= \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$

This is true only if  $h(t) = u(t-5)$

c)  $y(t) = \int_{-\infty}^t \left[ \int_{-\infty}^s x(\tau-s) d\tau \right] d\tau$   
 $= \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$

This is true only if  $h(t) = t u(t-5)$

Problem 3.20:



$$y(t) = \omega(t) x(t)$$

a)  $a_1 x_1(t) \rightarrow a_1 y_1(t) = a_1 \omega(t) x_1(t)$

$a_2 x_2(t) \rightarrow a_2 y_2(t) = a_2 \omega(t) x_2(t)$

$a_1 x_1(t) + a_2 x_2(t) \rightarrow \omega(t) [a_1 x_1(t) + a_2 x_2(t)]$   
 $= a_1 \omega(t) x_1(t) + a_2 \omega(t) x_2(t)$   
 $= a_1 y_1(t) + a_2 y_2(t)$  }  $\therefore$  The system is linear

b)  $x(t) \rightarrow y(t) = \omega(t) x(t)$

$y_d(t) = \omega(t) x(t-t_0)$

$x(t-t_0) \rightarrow y_d(t) = \omega(t) x(t-t_0)$

$y(t-t_0) = \omega(t-t_0) x(t-t_0)$

$\therefore y(t-t_0) \neq y_d(t)$   
 System is time-varying

c)  $y(t) = \omega(t) \delta(t)$   
 $= \omega(0) \delta(t) = \delta(t)$

$$\begin{aligned} \text{d) } y(t) &= \omega t \delta\left(t - \frac{\pi}{2}\right) \\ &= \omega\left(\frac{\pi}{2}\right) \delta\left(t - \frac{\pi}{2}\right) \\ &= 0 \times \delta\left(t - \frac{\pi}{2}\right) \\ &= 0 \end{aligned}$$

3.22.

$$\begin{aligned}
 y(t) &= \int_0^{\infty} e^{-\tau} x(t-\tau) d\tau \\
 &= \int_{-\infty}^{\infty} e^{-\tau} u(\tau) x(t-\tau) d\tau \\
 &= e^{-t} u(t) * x(t)
 \end{aligned}$$

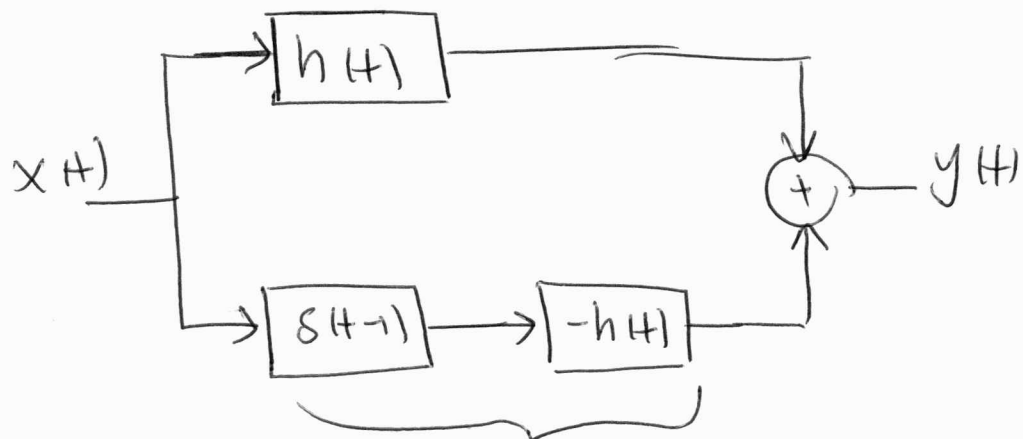
(a)  $h(t) = e^{-t} u(t) * \delta(t)$   
 $= e^{-t} u(t)$

(b) Causal, since  $h(t) = 0 \quad t < 0$

(c)  $x(t) = u(t+1)$

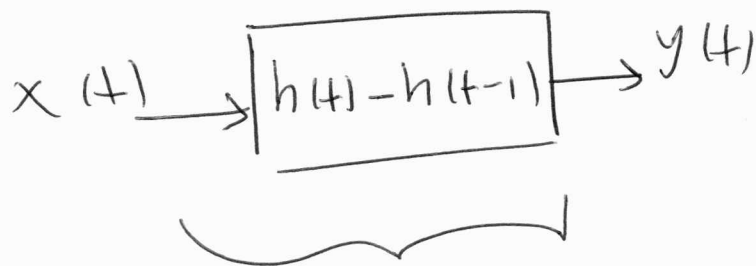
$$\begin{aligned}
 y(t) &= h(t) * x(t) \\
 &= e^{-t} u(t) * u(t+1) \\
 &= \int_{-\infty}^{\infty} e^{-\tau} u(\tau) \cdot \underbrace{u(t+1-\tau)}_{=1} d\tau \\
 &\qquad\qquad\qquad \begin{array}{l} t+1-\tau \geq 0 \\ \Rightarrow \tau \leq t+1 \end{array} \\
 &= \int_0^{t+1} e^{-\tau} (1) d\tau = 1 - e^{-(t+1)}
 \end{aligned}$$

(d)



$$\delta(t-1) * (-h(t))$$

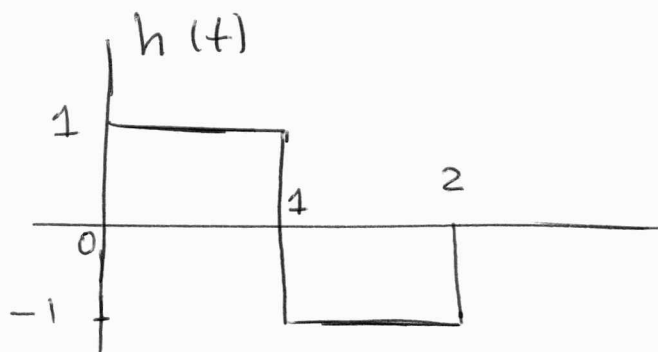
$$= -h(t-1)$$



$$\begin{aligned} h_{\text{total}}(t) &= h(t) - h(t-1) \\ &= e^{-t} u(t) - e^{-(t-1)} u(t-1) \end{aligned}$$

3.25

$$h(t) = u(t) - 2u(t-1) + u(t-2)$$



(a) Since  $h(t) = 0$   $t < 0 \Rightarrow$  Causal

(b) Stable (BIBO)  $\Rightarrow \int_{-\infty}^{\infty} |h(t)| dt < \infty$

$$\begin{aligned} \int_{-\infty}^{\infty} |h(t)| dt &= \int_0^1 |1| dt + \int_1^2 |-1| dt \\ &= 1 + 1 = 2 < \infty \end{aligned}$$

$\Rightarrow$  stable (BIBO).

$$\begin{aligned} (c) \quad y(t) &= x(t) * h(t) \\ &= [\delta(t-1) - 2\delta(t-2)] * h(t) \\ &= \delta(t-1) * h(t) - 2\delta(t-2) * h(t) \\ &= h(t-1) - 2h(t-2) \end{aligned}$$

