

King Fahd University of Petroleum & Minerals Computer Engineering Dept

COE 540 – Computer Networks
Term 151
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Lecture Contents

1. The channel allocation problem
2. Multiple access protocols
3. Ethernet
4. Wireless LANs
5. Broadband Wireless
6. Bluetooth, RFID
7. Data link layer switching

These slides are based on the Tanenbaum's
textbook and original author slide

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Medium Access Control (MAC)

- Data link layer typically divided into
 - Logical link control (LLC), and
 - Medium access control (MAC)
- MAC determined how to access the medium and transmit the information
 - Point-to-point link – MAC is simple
 - Shared media - ?
- The central theme of the chapter is how to allocate a single broadcast channel among competing users.

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The Channel Allocation Problem – Static Allocation

- Traffic:
 - Bursty – data (variable/random intensity)
 - Non-bursty – constant arrival rate (bits, frames, etc.)
- FDM – an example of static allocation scheme
 - System bandwidth B Hz is divided equally between N users – each user has B/N Hz
 - Excellent for non-bursty traffic but VERY poor for highly bursty traffic.
 - Hard capacity limit – if more than N users want to access the channel → blocked
- Same arguments apply for time division multiplexing (TDM) as well

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The Channel Allocation Problem – Static Allocation (2)

- Assume total capacity = C b/s, frames arrive with λ frames/sec and have average length of $1/\mu$ bits, then the mean time delay T is given by

$$T = \frac{1}{\mu C - \lambda}$$

- The above formula is valid for an M/M/1 queue setting
- Now, divide the total capacity in to N sub-channels (FDM or TDM) and let the frame arrivals per sub-channel to be λ/N . The mean time delay now, T_N , is given by

$$T_N = \frac{1}{\mu(C/N) - \lambda/N} = \frac{N}{\mu C - \lambda} = N T$$

- It is clear than T_N is N times the original T – This is referred to by the scaling effect for M/M/1 queues; refer to queueing slides.
- Conclusion – Static allocation is very bad for bursty traffic
 - No need to reserve the channel for the entire duration of the bursty traffic session

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Background – Probability and Statistics – (1)

- Bernoulli Distribution**
 - Experiment with two outcomes: 0 and 1
 - Prob of success = p \rightarrow prob of failure = 1-p
- Binomial Distribution**
 - If $I \in \{0,1\}$ represents the outcome of a Bernoulli experiment, then $K = I_1 + I_2 + \dots + I_N$ is the sum of N Bernoulli experiments
 - $K \in \{0, 1, \dots, N\}$ is a discrete RV, where the prob mass function is given by

$$\text{Prob}[K = k] = \binom{N}{k} p^k (1-p)^{N-k} \quad k = 0, 1, \dots, N$$
 - Mean of K is given by $E[K] = Np$
- Geometric Distribution**
 - If $I \in \{0,1\}$ represents the outcome of a Bernoulli experiment, then define K as the number of experiment till a success occurs
 - $K \in \{1, 2, \dots, \infty\}$ is a discrete RV, where the prob mass function is given by

$$\text{Prob}[K = k] = p(1-p)^{k-1} \quad k = 1, 2, \dots, \infty$$
 - Mean of K is given by $E[K] = 1/p$

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Background – Probability and Statistics – (2)

- Poisson Distribution

- Limiting case of Binomial distribution where $N \rightarrow \infty$ and $p \rightarrow 0$ such that $\lambda = Np$ remains constant
- λ is the average number of events per time unit
- The number of events K occurring in a time unit is a discrete RV; $K \in \{0, 1, \dots, \infty\}$
- The prob mass function is given by

$$\text{Prob}[K = k] = \frac{\lambda^k}{k!} e^{-\lambda} \quad k = 0, 1, \dots, \infty$$

- Note that if we define K as the number of events in an interval of length T , then K has the following prob mass function

$$\text{Prob}[K = k] = \frac{(\lambda T)^k}{k!} e^{-\lambda T} \quad k = 0, 1, \dots, \infty$$

Note that the mean in this case is $E[K] = \lambda T$

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Background – Probability and Statistics – (3)

- Exponential Distribution

- Let τ denote the inter-event time for the Poisson process - τ is a continuous RV; $\tau \in (0, \infty)$
- The prob density function for τ is given by

$$f_{\tau}(t) = \lambda e^{-\lambda t} \quad t, \lambda > 0$$

- The mean for τ is $E[\tau] = 1/\lambda$ time units
- The Poisson distribution and Exponential distribution are two faces for one coin!

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Dynamic Channel Allocation - Assumptions

- Independent traffic – N independent sources (e.g. computers, telephones, users)
 - Average number of arrivals during Δt is equal to $\lambda \Delta t$.
 - Once a frame is generated, the source is blocked till the frame has been successfully transmitted
 - Poisson model – mathematically tractable.
- Single channel – only a single channel is available for all communications
- Observable collisions
- Continuous or slotted time
- Carrier sense versus no carrier sense

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Multiple Access Protocols – Pure ALOHA

- Two versions
 - Pure ALOHA
 - Slotted ALOHA
- Pure ALOHA – users transmit whenever they have data to be sent
- Assumptions:
 - Group of N terminals send frames to a central computer
 - Correctly received frames are acknowledged on the downlink channel
 - Frames not acknowledged (i.e. were not received or not correctly received) are scheduled for retransmission
 - Two or more frame overlapping in time are said to be collided
- ALOHA is a contention system

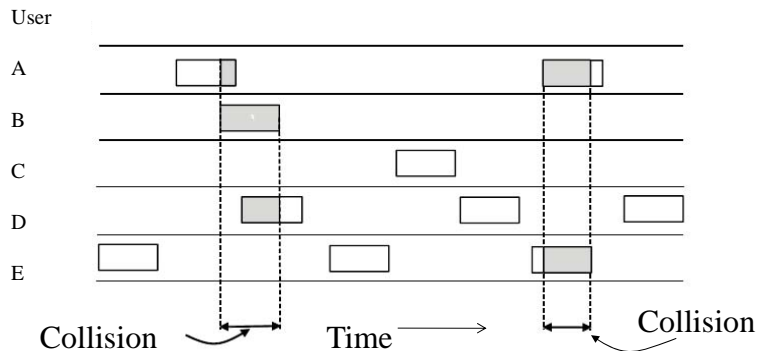
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Multiple Access Protocols – Pure ALOHA (2)

- PURE ALOHA = Start of transmission for frames can be at *any* point in time
- Example below – 5 terminals transmitting frames whenever the frames are ready to be sent
 - Observe the two collision events



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Multiple Access Protocols – Slotted ALOHA (3)

- Slotted ALOHA = Start of transmission for frames can be only at slot border
- Time axis is divided into equal slot periods equal to the frame time
 - Frames arriving in one slot can be transmitted at the beginning of the next slot

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Throughput of Pure/Slotted ALOHA (4)

- Throughput – fraction of transmitted frames that are correctly received per frame time.
- Assume new frames generation follow Poisson distribution – average of N frames per frame time
 - Note the channel can handle at most 1 frame per frame time
 - For reasonable throughput we expect $0 < N < 1$.
- Further assume that old and new frames generated follow Poisson distribution – average of G frames per frame time
 - Clearly $G \geq N$
- Throughput, S , is the fraction of G that do NOT collide

$$S = G \text{ Prob [no transmissions from the rest of the population in the vulnerable period]}$$

$$= G P_0$$

where G – frames per frame time represent the average load injected into the system

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Throughput of Pure/Slotted ALOHA (5)

- Vulnerable period for pure ALOHA is of length equal to TWO frame time
- Vulnerable period for Slotted ALOHA is of length equal to ONE frame time
- Prob of k frames generated during a given frame time in which G frames are expected is given by the Poisson distribution:

$$P_k = \frac{G^k e^{-G}}{k!}$$

- Therefore, P_0 is equal to

$$P_0 = \frac{(2G)^0 e^{-(2G)}}{0!} = e^{-2G} \leftarrow \text{Pure ALOHA}$$

$$= \frac{(1G)^0 e^{-(1G)}}{0!} = e^{-G} \leftarrow \text{Slotted ALOHA}$$

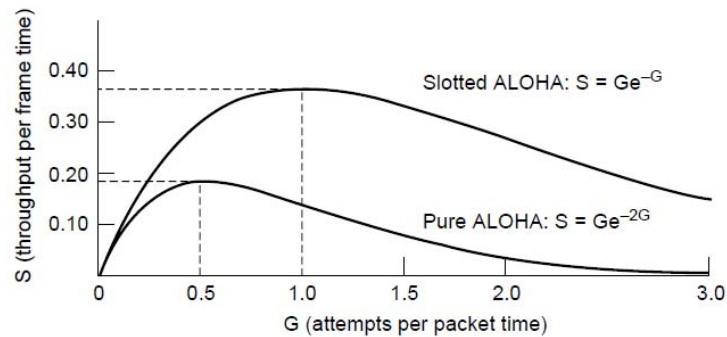
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Throughput of Pure/Slotted ALOHA (6)

- Throughput versus offered traffic



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Throughput of Pure/Slotted ALOHA (7)

- Throughput peak at G^*
 - $G^* = 0.5$ attempt per packet time for pure ALOHA
 - $G^* = 1.0$ attempt per packet time for slotted ALOHA
- For $G > G^* \rightarrow$ collisions increase exponentially \rightarrow throughput approaches zero
- Proof (Slotted ALOHA case)

Probability of success = $P_0 = e^{-G}$

Prob of failure = $1 - P_0 = 1 - e^{-G}$

Consider the random variable (RV) k defined as the number of transmission for packet until it is success $\rightarrow k$ is a geometric RV – refer to discrete RVs material

$$P_k = e^{-G}(1 - e^{-G})^{k-1} \quad \text{for } k = 1, 2, \dots$$

The expected number of transmission can be computed as

$$E = \sum_{k=1}^{\infty} kP_k = \sum_{k=1}^{\infty} ke^{-G}(1 - e^{-G})^{k-1} = e^G$$

Exponential increase with load

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Slotted ALOHA with Finite Number of Terminals

- N terminals – each performs a Bernoulli experiment at every slot
 - Transmits with prob p – does not transmit with prob $1-p$
 - Number of transmission attempts in a slot $K \rightarrow$ Binomial distribution with average Np
 - The prob mass function is given by

$$\text{Prob}[K = k] = \binom{N}{k} p^k (1-p)^{N-k} \quad k = 0, 1, \dots, N$$

- Prob of successful transmission is the probability of only one terminal transmitting in a time slot

$$P_s = Np(1-p)^{N-1}$$

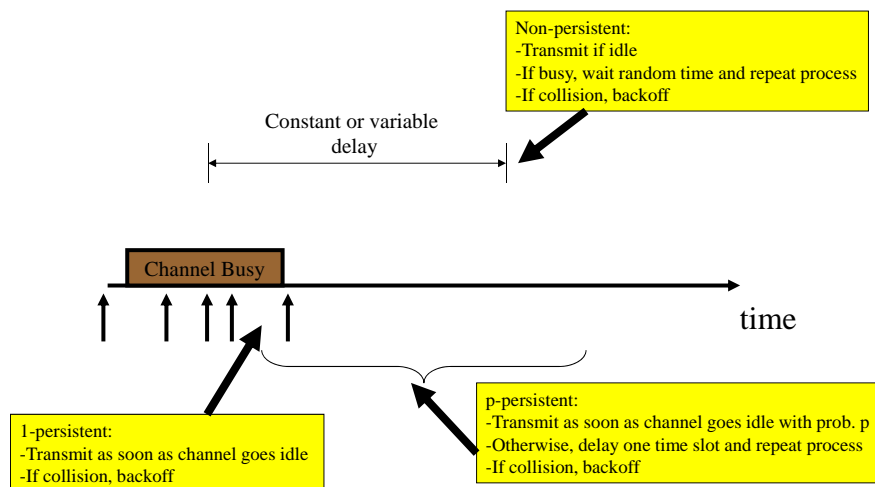
- As with Slotted ALOHA with infinite number of terminal, P_s is the throughput while Np represents the load
- Note that P_s can be maximized if we set $p=1/N$ – more on this later!

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Carrier Sense Multiple Access Protocols



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Throughput of CSMA Protocols

- Unslotted Nonpersistent CSMA $S = \frac{Ge^{-aG}}{G(1+2a) + e^{-aG}}$
- Slotted Nonpersistent CSMA $S = \frac{aGe^{-aG}}{1 - e^{-aG} + a}$
- Unslotted 1-Persistent CSMA $S = \frac{G[1+G+aG(1+G+aG/2)]e^{-G(1+2a)}}{G(1+2a) - (1 - e^{-aG}) + (1+aG)e^{-G(1+a)}}$
- Slotted 1-Persistent CSMA $S = \frac{G[1+a - e^{-aG}]e^{-G(1+a)}}{(1+a)(1 - e^{-aG}) + ae^{-G(1+a)}}$

$a = T_{prop}T_p$
 T_{prop} = propagation delay
 T_p = packet/frame transmission time

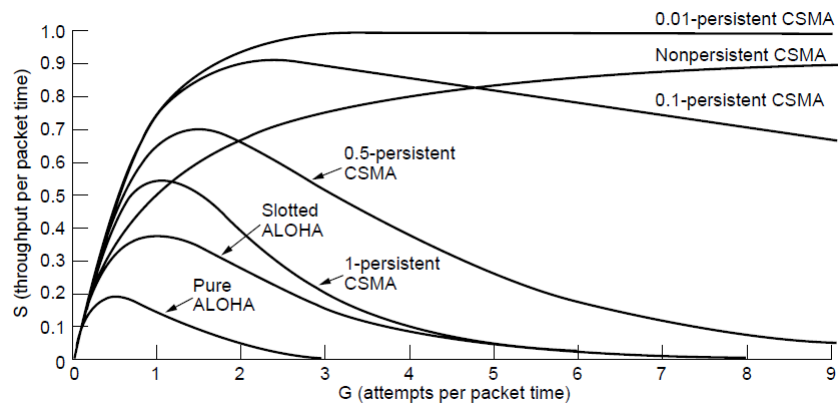
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Throughput of CSMA Protocols – cont'd

- Comparison of the channel utilization versus load for various random access protocols



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CSMA with Collision Detection

- Persistent and nonpersistent CSMA protocols are an improvement over ALOHA protocols. Why?
- An added improvement is CSMA with collision detection – CSMA/CD; the basis for the classical Ethernet LAN
- CSMA/CD model:
 - At t_0 a station has finished transmission
 - Stations may attempt to transmit during the contention period
 - If collision
 - Abort transmission
 - Wait for a random time
 - Retry

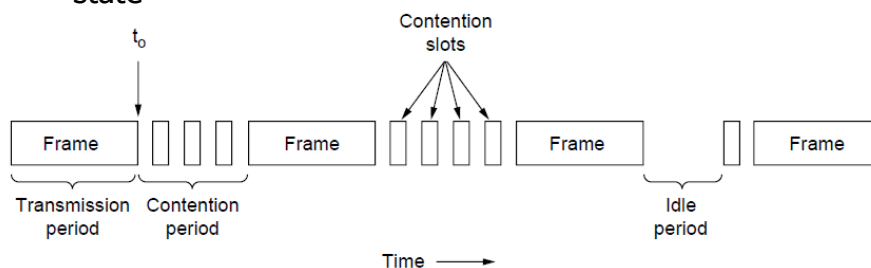
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CSMA with Collision Detection (2)

- CSMA/CD can be in contention, transmission, or idle state



- If two stations begin transmitting at t_0 – How long does it take them to detect the collision?
- A station cannot be sure that it has seized the channel until it has transmitted for 2τ without detecting a collision
 - τ is the signal propagation time for the full cable length

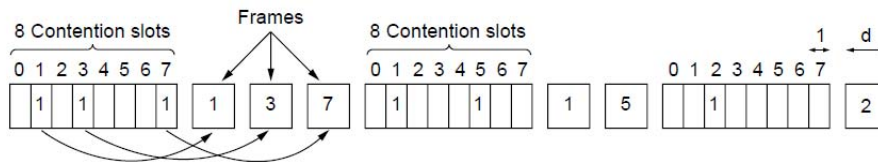
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Collision-Free Protocols – Bit-Map Protocol

- For N stations we have N contention slots
 - There is not real contention here – ith slot is dedicated for ith station.
 - If station i has data to send, then it transmits a bit 1 in its contention slot
- When the N contention slots are complete, all stations (assuming all are listening) have a map of traffic to be sent from all stations
- Refer to the figure.



- Example for $N = 8$; stations 1, 3, and 7 have traffic to send for the first round
- A form of reservation protocol
- Length of contention slot = 1 unit, length of data frame = d units

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Bit-Map Protocol (2)

- Mean access delay – low load case:
 - Low numbered stations (such as 0 or 1) – $N/2 + N = 1.5 N$
 - High numbered stations (such as $N-1$ and N) – $N/2$
 - Average = $1.5 N + 0.5 N = N$ for all terminals
- Mean access delay – high load case
 - Queueing time + $(N-1)d + N$
- Channel efficiency
 - Low load – $d/(d + N)$
 - High load – $Nd/(Nd + N) = d/(d + 1)$

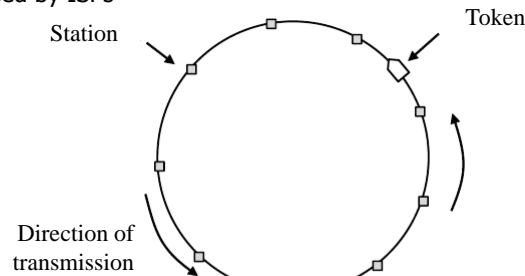
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Token Passing

- Token = permission to send
- Topology determines the order of transmission/permissions
- Frames transmitted in the direction of the token
- Source of destination of frame must remove frame transmission from ring
- Performance –
- IEEE802.5
- Fiber Distributed Data Interface (FDDI)
- Resilient Packet Ring (RPR) – IEEE802.17 ~ 2000's metropolitan area rings used by ISPs



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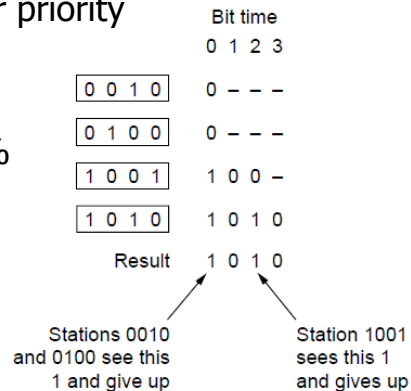
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Binary Count Down

- Basic bit-map and token rings suffer from overhead of 1 bit per station
 - Does not scale well
- Transmit addresses in binary form
- Higher address have higher priority
- Channel efficiency $d/(d+\log_2 N)$
 - May be as high as 100%

The binary countdown protocol.
A dash indicates silence.

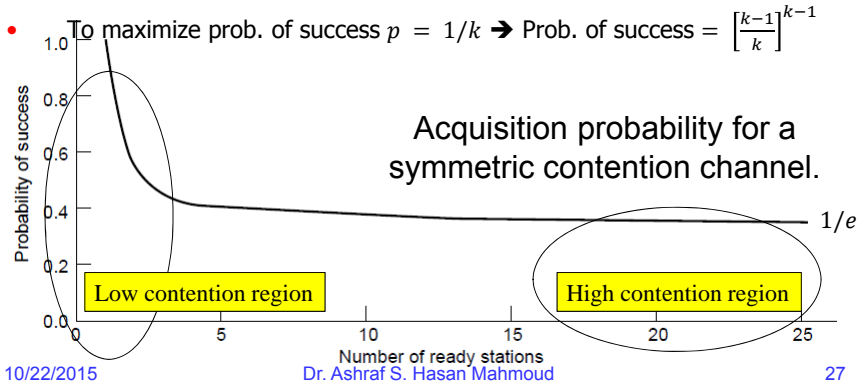


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Limited-Contention Protocols

- Combination of contention and collision-free protocols
- Station attempts to acquire channel with prob. p – may be different for different terminals
 - Prob. $(1 - p)$ to defer transmission
- Prob. of success – Binomial distribution = $kp(1 - p)^{k-1}$
- To maximize prob. of success $p = 1/k \rightarrow$ Prob. of success = $\left[\frac{k-1}{k}\right]^{k-1}$

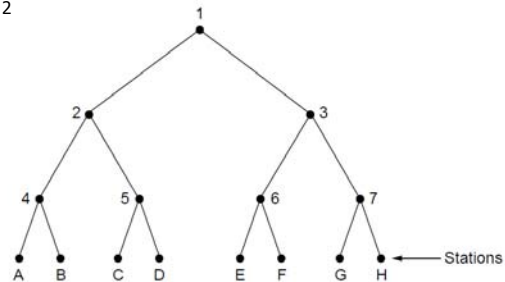


Adaptive Tree Walk

- Stations are represented by the leaves of the binary tree.
- Rules:
 - Slot 0 (first contention slot following a successful frame transmission) – all terminals are permitted to attempt
 - If collision, during slot 1, only stations falling under node 2 are permitted to compete
 - If one of them acquires the channel, then subsequent slot (slot 2) is reserved for stations under node 3
 - If collision (i.e. 2 or more stations under node 2 want to Tx), only stations under node 4 are allowed to compete for slot 2
 - Etc.

- Enhancements – when load is heavy no need to dedicate slot 0 for node 1

- Same can be argued for nodes 2 and 3 since many terminals want to transmit!
- Where to start the search?



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Adaptive Tree Walk – cont'd

- Assume q terminals on average want to send – distributed uniformly in the tree
- Level i of binary tree has 2^{-i} fraction of terminals
→ number of terminals with traffic under node i is equal to $2^{-i}q$
- For optimality, we should start the search at the level where the expected number of contending stations is equal to 1 → $i = \log_2(q)$

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Wireless LAN Protocols

- IEEE802.11 versus WiFi
- For wireless – no collision detection; Limited radio range
- Transmitter has no means of finding out the status at the receiver → Hidden and exposed terminal problems
- Solution – Medium Access with Collision Avoidance (MACA) - RTS and CTS
- Collisions are still possible

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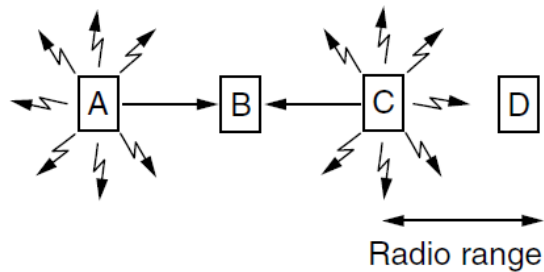
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Wireless LANs (2) – Hidden terminals

Hidden terminals are senders that cannot sense each other but nonetheless collide at intended receiver

- Want to prevent; loss of efficiency
- A and C are hidden terminals when sending to B

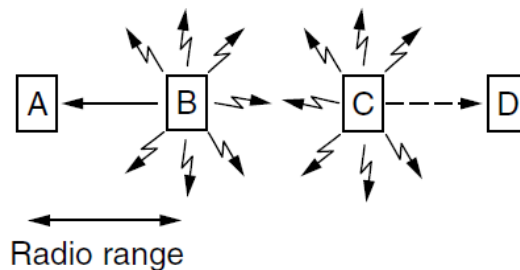


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Wireless LANs (3) – Exposed terminals

Exposed terminals are senders who can sense each other but still transmit safely (to different receivers)

- Desirably concurrency; improves performance
- B → A and C → D are exposed terminals

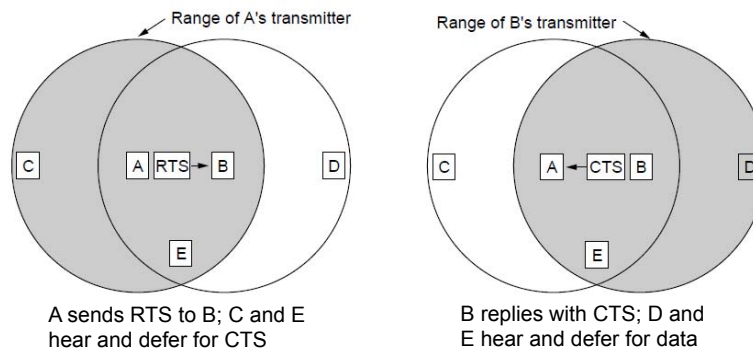


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Wireless LANs (4) – MACA

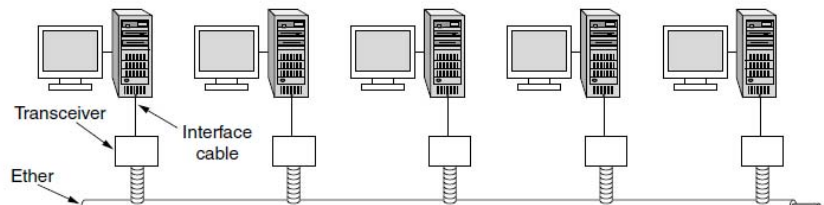
MACA protocol grants access for A to send to B:

- A sends RTS to B [left]; B replies with CTS [right]
- A can send with exposed but no hidden terminals



Ethernet

- De facto LAN standard
- Classical versus switched Ethernet
- Relation to IEEE802.3
- Classical Ethernet physical layer
 - 1978 – 10 Mb/s Ethernet (DIX standard)
 - Coaxial cable (thick versus thin) – BNC connectors
 - Repeaters connecting multiple segments – max 2.5 km with 4 repeaters at most



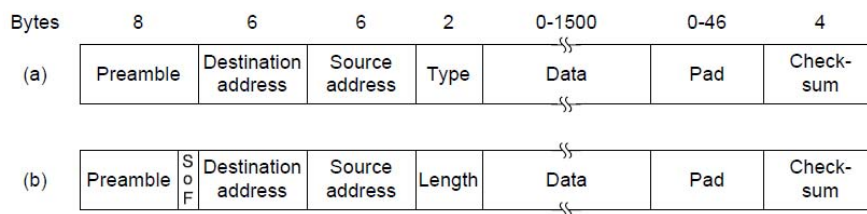
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Classic Ethernet – MAC Sublayer

- Preamble – 8 bytes; each byte 10101010 with the exception of the last byte in which the last 2 bits are set to 11
 - Last byte is called SOF for IEEE802.3
- Manchester encoding – 10 MHz
- Type/Length fields
 - Max frame length – 1500 bytes of data
 - Min frame length – 64 bytes (with padding if needed)
- 32-bit CRC - checksum



Frame formats. (a) Ethernet (DIX). (b) IEEE 802.3.

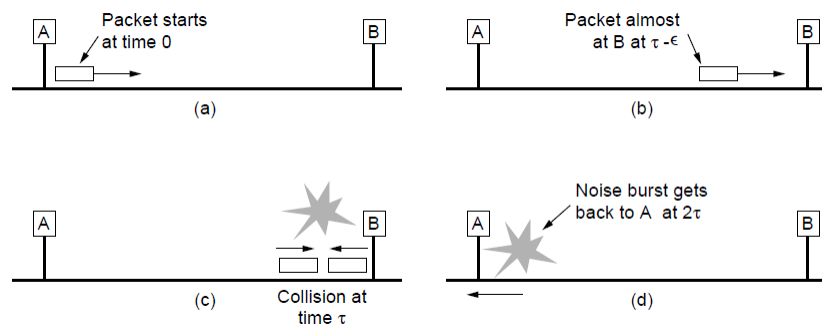
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Classic Ethernet – MAC Sublayer (2)

- Ethernet slot time = $2xT_{prop}$
- Min frame length is longer than the slot time



Collision detection can take as long as 2τ .

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Classic Ethernet - CSMA/CD with Binary Exponential Backoff

- After the i th collision, a random number between 0 and $2^i - 1$ is chosen where $k = \min(i, 10)$
- Up to 16 consecutive collisions – what happens afterwards?
- No ack provided

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Classic Ethernet Performance

- Assumptions
 - Constant and heavy load – k stations are always ready to transmit
 - Constant retransmission probability in each slot
- If each station transmits during a contention slot with probability p , then the probability of success is
$$A = kp(1 - p)^{k-1}$$
- Remember that A is maximized when $p = 1/k$, with $A \rightarrow 1/e$ as $k \rightarrow \infty$
- The probability that the contention interval has exactly j slots in it is $A(1 - A)^{j-1} \rightarrow$ mean number of slots per contention interval is

$$\sum_{j=1}^{\infty} jA(1 - A)^{j-1} = \frac{1}{A}$$

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Classic Ethernet Performance – cont'd

F – frame length
 B – link rate
 L – cable length
 c – signal propagation speed
 e – contention slots per frame

- Then the mean of contention interval, w , is $2\tau/A$
- Let P be mean frame time → Efficiency is calculated as

$$\text{Channel Efficiency} = \frac{P}{P + 2\tau/A}$$

- Under optimum conditions, efficiency may be written as

$$\text{Channel Efficiency} = \frac{1}{1 + 2BLE/(cF)}$$

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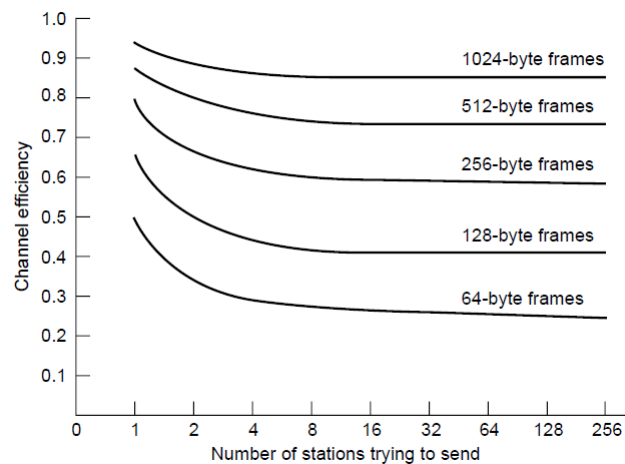
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Classic - Ethernet Performance – cont'd

- Efficiency of Ethernet at 10 Mb/s with 512-bit time slot

- → $2\tau = 51.2 \mu\text{sec}$



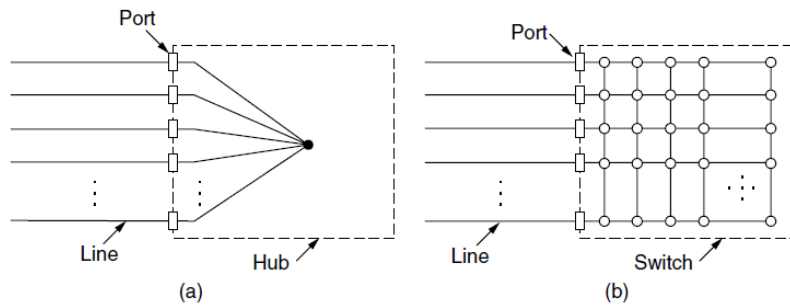
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Switched Ethernet

- For fast 100 Mb/s Ethernet
- High-speed backplane that connects all ports
- Proprietary algorithm



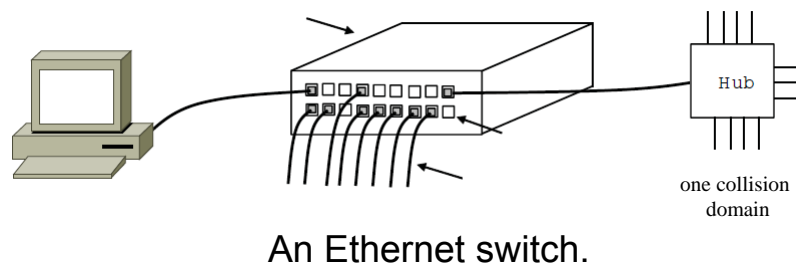
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Switched Ethernet (2)

- Collision domain
- Concentration ports
- Promiscuous mode – Security benefits



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Fast Ethernet

- IEEE802.3u (June 1995) – amendment to the existing IEEE802.3
- Identical frame format and procedural rules to 10 Mb/s Ethernet
- 100BaseTX
 - Uses 4B/5B encoding – 125 MHz signal to provide 100 Mb/s
 - Full duplex – can send 100 Mb/s on one twisted pair and receive at 100 Mb/s on another pair
- 100BaseFX – two strands of multimode fiber (one per direction)
- Supports switches and hubs

Name	Cable	Max. segment	Advantages
100Base-T4	Twisted pair	100 m	Uses category 3 UTP
100Base-TX	Twisted pair	100 m	Full duplex at 100 Mbps (Cat 5 UTP)
100Base-FX	Fiber optics	2000 m	Full duplex at 100 Mbps; long runs

Original fast Ethernet cabling

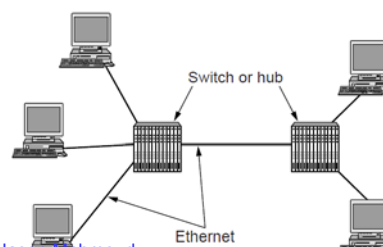
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Gigabit Ethernet

- All configurations use point-to-point links only between computers/switches
- Two modes supported – Full Duplex (when connecting to a switch) and Half Duplex
- Full duplex mode –
 - Lines are buffered
 - No CSMA/CD; max cable length determined by signal strength
 - Auto negotiation
- Half-duplex –
 - Connecting to a hub
 - CSMA/CD is used
 - How to deal with the min frame length of 64-Bytes issue?
 - **Carrier-extension** – padding of frame to extend to 512 bytes
 - **Frame bursting** – allow sending to send multiple frames in a single transmission – padding is used if the burst is less than 512 Bytes



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Gigabit Ethernet

- 8B/10B – 8-bit data encoded as 10-bit code words – balanced and have sufficient transitions
- NRZ – requires 25% extra bandwidth
- Jumbo frames – extends maximum frame length from 1500 Bytes to 9KBytes – proprietary feature

Name	Cable	Max. segment	Advantages
1000Base-SX	Fiber optics	550 m	Multimode fiber (50, 62.5 microns)
1000Base-LX	Fiber optics	5000 m	Single (10 μ) or multimode (50, 62.5 μ)
1000Base-CX	2 Pairs of STP	25 m	Shielded twisted pair
1000Base-T	4 Pairs of UTP	100 m	Standard category 5 UTP

Gigabit Ethernet cabling

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10 Gigabit Ethernet

- Full duplex mode only
- CSMA/CD is not part of the design
- Fiber options: 64B/66B code
- 10GBase-CX4: 4 pairs of twinaxial copper wiring – each pair 8B/10B coding provides 3.125 Gsymbol/sec
- 10GBase-T: 800 Msymbols/sec (16 different voltage levels) – LDPC coding

Name	Cable	Max. segment	Advantages
10GBase-SR	Fiber optics	Up to 300 m	Multimode fiber (0.85 μ)
10GBase-LR	Fiber optics	10 km	Single-mode fiber (1.3 μ)
10GBase-ER	Fiber optics	40 km	Single-mode fiber (1.5 μ)
10GBase-CX4	4 Pairs of twinax	15 m	Twinaxial copper
10GBase-T	4 Pairs of UTP	100 m	Category 6a UTP

10 Gigabit Ethernet cabling

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40 GbE and 100 GbE

- IEEE 802.3ba-2010 and IEEE802.3bg 2011
- 40GbE is original designed for server applications – while 100GbE is meant for Internet backbone

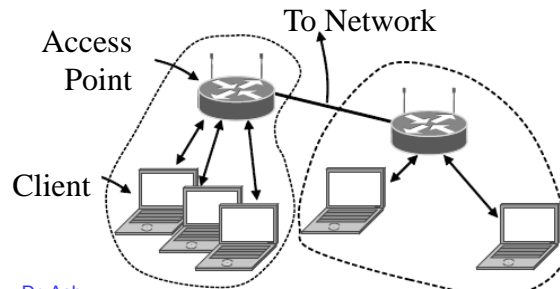
Physical layer	40 Gigabit Ethernet	100 Gigabit Ethernet
Backplane	40GBASE-KR4	100GBASE-KP4
Improved Backplane		100GBASE-KR4
7 m over twinax copper cable	40GBASE-CR4	100GBASE-CR10
30 m over " Cat.8 " twisted pair	40GBASE-T	
100 m over OM3 MMF	40GBASE-SR4	100GBASE-SR10
125 m over OM4 MMF ^[16]		
2 km over SMF, serial	40GBASE-FR	
10 km over SMF	40GBASE-LR4	100GBASE-LR4
40 km over SMF		100GBASE-ER4

1 TbE

- Terabit Ethernet – planning phase; expected by 2015
- 100 Terabit Ethernet – expected by 2020
- Work on 400 Gb/s Ethernet started by IEEE802.3 in March 2013 – results to be reported in 2017

Wireless LANs - Architecture

- Infrastructure mode and Ad-hoc mode
- Distribution system

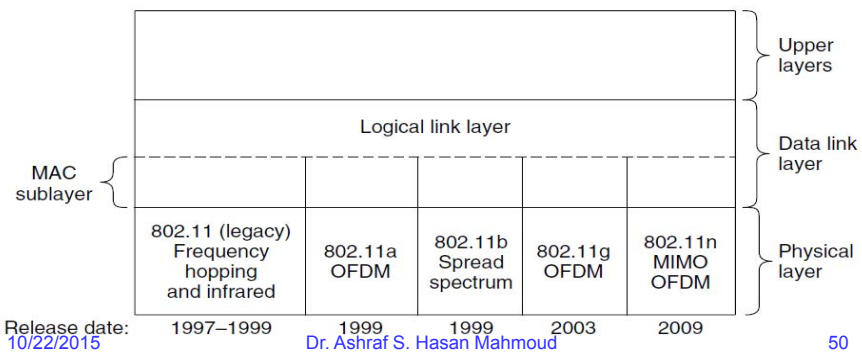


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Wireless LANs - Protocol Stack

- IEEE802.11 (legacy) – 2.4 GHz FH & Infrared provided 1-2 Mb/s – not any more
- IEEE 802.11b – 2.4 GHz Spread Spectrum (CCK) – up to 11 Mb/s – 1999
- IEEE802.11a – 5 GHz – OFDM – 54 Mb/s - 1999
- IEEE802.11g – 2.4 GHz – OFDM – 54 Mb/s - 2003



Release date:
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Wireless LANs – Protocol Stack

- IEEE802.11n – 2.4 & 5 GHz – MIMO/OFDM – up to 600 Mb/s – 2009
 - Uses 20 and 40 MHz channels
 - Using MIMO (up to 4 by 4) – up to 4 spatial streams are supported – 600 Mb/s is achievable if 4 streams are used
 - Modulation and Coding Scheme Index – 32 possible indices - Different signal/modulation constellation and coding rates are used – defining on the quality of channel
 - Lowest is BPSK – 1 bit per symbol – Highest – 64 QAM 6 bits per symbol
 - Lowest $R_c = 1/2$; Highest $R_c = 5/6$;
 - Can work with previous versions - Mixed mode

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Wireless LANs – Protocol Stack

- IEEE802.11ac – 2.4 & 5 GHz – MIMO/OFDM – up to 6.77 Gb/s – Approved Jan 2014
 - Uses 20, 40, 80, and 160 MHz channels
 - Using MIMO (up to 8 by 8) – up to 8 spatial streams are supported – Single stream up to 866.7 Mb/s on a 160 MHz – 6.77 Gb/s is achievable if 8 streams are used
 - Modulation and Coding Scheme Index – Lowest is BPSK – 1 bit per symbol – Highest – 256 QAM 8 bits per symbol
 - Lowest $R_c = 1/2$; Highest $R_c = 5/6$;
 - Can work with previous versions - Mixed mode

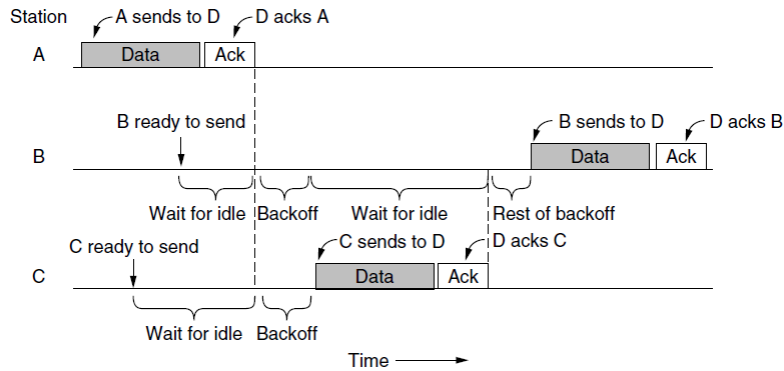
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802.11 MAC (1)

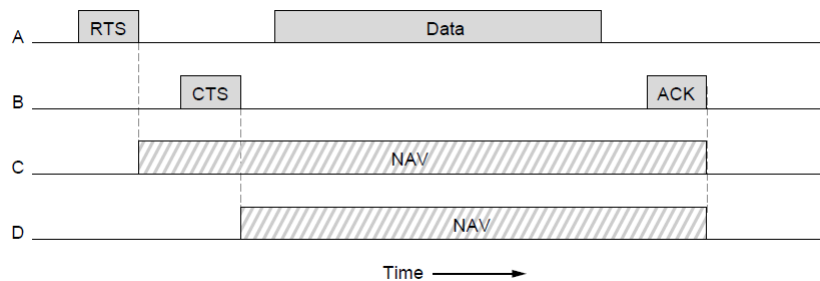
- CSMA/CA inserts backoff slots to avoid collisions
- MAC uses ACKs/retransmissions for wireless errors



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802.11 MAC (2)

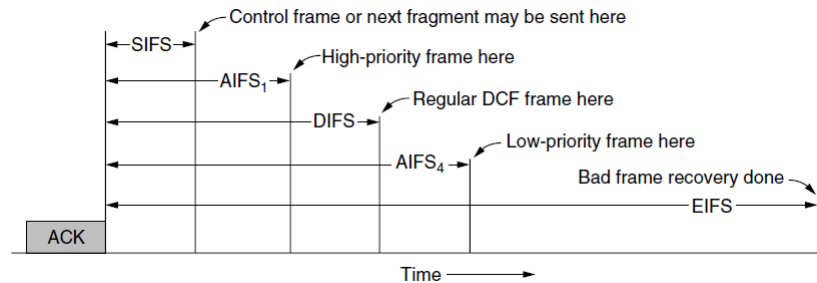
Virtual channel sensing with the NAV and optional RTS/CTS (often not used) avoids hidden terminals



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802.11 MAC (3)

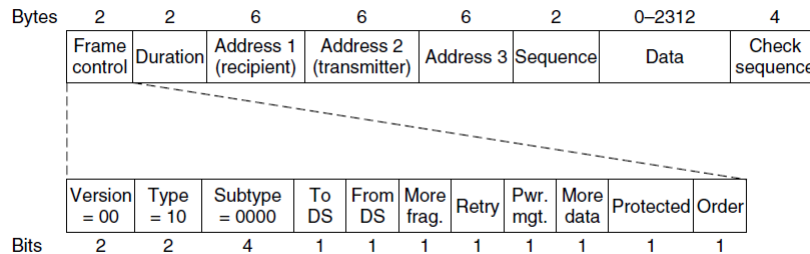
- Different backoff slot times add quality of service
 - Short intervals give preferred access, e.g., control, VoIP
- MAC has other mechanisms too, e.g., power save



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802.11 Frames

- Frames vary depending on their type (Frame control)
- Data frames have 3 addresses to pass via APs



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Broadband Wireless

- Section not covered this offering

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Bluetooth

- Section not covered this offering

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RFID

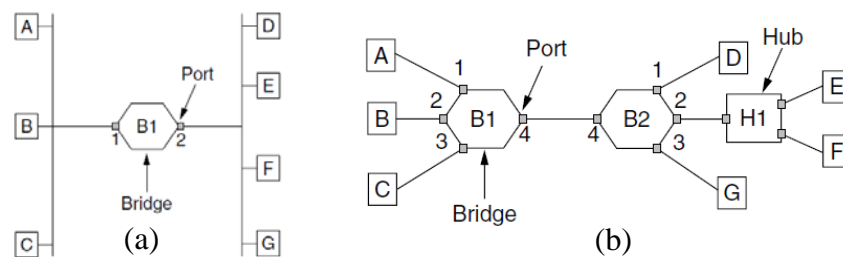
- Section not covered this offering

Data Link Switching – The Use of Bridges

- Interconnect (extend) different LANs within an organization
- Bridges can join two geographically distant LANs
- Bridges can be used to split one large LAN segment into smaller ones
- Bridges should be transparent – no hardware or software changes required to the existing LANs
 - Backward learning algorithm
 - Spanning tree algorithm

Data Link Switching - The Use of Bridges - cont'd

- Ethernet switch – if LAN technology is Ethernet
- Bridge is used to connection two multi-drop lines in (a)
- In (b) two bridges B1 and B2 are used to replace two hubs to increase performance – H1 still there
- Link 4-4 may be a long-distance fiber optic link or a short-hual TP
- Bridge operates in promiscuous mode – accepts all received frames
 - Bridging function – must decide whether to forward the Tx-n to the other LAN or not



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Learning Bridges - Backward Learning

- Initially uses a flooding algorithm to forward all transmission
- As it learns the topology (Hash table building) – it will forward a transmission to the concerned LAN segment only
- To handle dynamic topologies – hash table time stamps for entries are used
 - Old items are purged
 - Entries are updated
- The routing procedure for the incoming frame depends on the port (the source port) it arrives on and the address to which it is destined
- Cut-through switching – forwarding of frame starts before entire frame is received

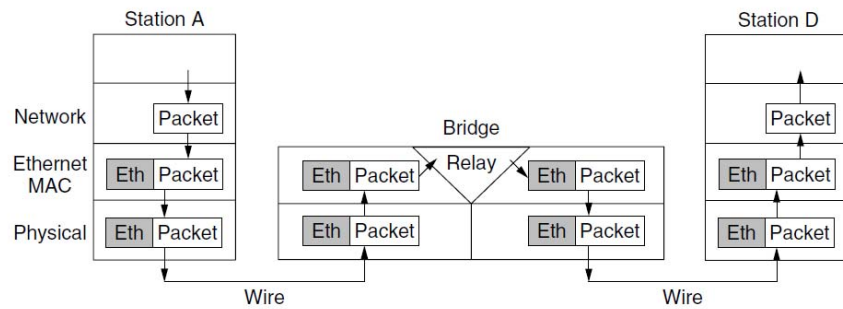
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Bridges - Protocol Stacks

- Protocol stacks



Protocol processing at a bridge.

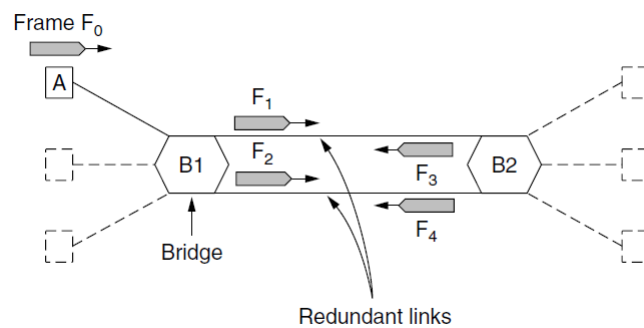
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Spanning Tree Bridges

- X



Bridges with two parallel links

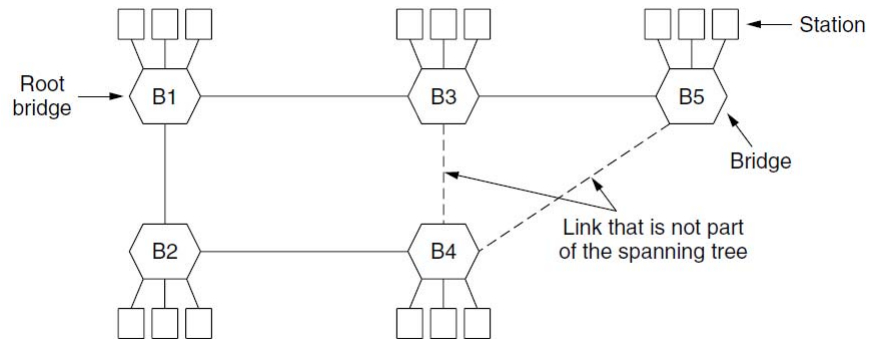
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Spanning Tree Bridges - cont'd

- X



A spanning tree connecting five bridges. The dotted lines are links that are not part of the spanning tree.

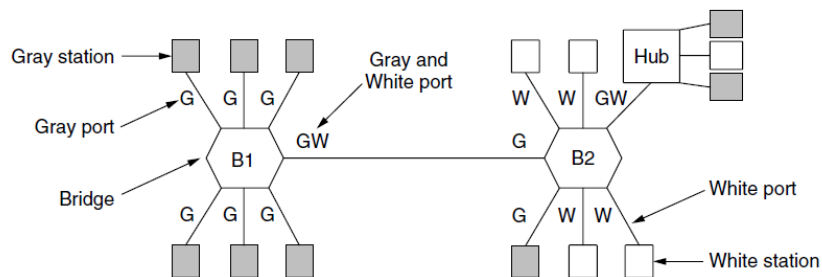
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Virtual LANs

- X



Two VLANs, gray and white, on a bridged LAN.

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