Jan. 26, 2011

COMPUTER ENGINEERING DEPARTMENT

COE 205

COMPUTER ORGANIZATION & ASSEMBLY PROGRAMMING

Final Exam

First Semester (101)

Time: 7:30 -10:00 AM

Student Name : \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Student ID. : \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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| --- | --- | --- |
| **Question** | **Max Points** | **Score** |
| **Q1** | **16** |  |
| **Q2** | **8** |  |
| **Q3** | **22** |  |
| **Q4** | **40** |  |
| **Q5** | **14** |  |
| **Total** | **100** |  |

Dr. Aiman El-Maleh

# **[16 Points]**

# **(Q1)** Fill the blank in each of the following:

## Three main differences between interrupts and procedures include: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## The three main types of processor interrupts are: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## Hardware interrupts initiated at the NMI pin are \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ while those initiated at the INTR pin are \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

##  The interrupt flag controls \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## Segment-not-present error is an example of \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ interrupt.

## Interrupts initiated due to execution of a break point in debugging mode belong to interrupts of the following type \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## In protected mode, the address of the interrupt service routine of interrupt 15h is obatined from offset \_\_\_\_\_\_\_\_\_\_\_\_\_\_ within \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## In protected mode, when an interrupt occurs, the following actions are taken by the CPU:

## \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## To send control back to the interrupted program, the interrupt service routine should end up with the instruction \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

## If the trap flag is set, the CPU automatically generates \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_.

# **[8 Points]**

# **(Q2)** Given the CPU-Memory interface circuit shown below, complete the given timing diagram assuming the following given control sequnce as shown below:

**T4 BXout, MARin, Read, Zin**

**T5 Zout, BXin, WMFC**

**T6 MDRout, AXin**

Note that the control unit is assumed to be rising-edge triggered.



# **[22 Points]**

# **(Q3)** It is required to design an 8-bit CPU the has four 8-bit registers, namely R0, R1, R2, and R3. Assume that the data bus and address bus are 8-bits. The CPU has 8-bit instructions with the following foramt:

|  |  |  |
| --- | --- | --- |
| 4 bits | 2 bits | 2 bits |
| OPCODE | Rdst | Rsrc |

# The CPU has the following set of instructions:

|  |  |  |
| --- | --- | --- |
| **Instruction** | **Register Transfer** | **Effect on Flags** |
| MOV Rdst, Rsrc | Rdst 🡨 Rsrc | **N** |
| XCHG Rdst, Rsrc | Rdst 🡨 Rsrc; Rsrc 🡨 Rdst | **N** |
| ADD Rdst, Rsrc | Rdst 🡨 Rdst + Rsrc | **Y** |
| SUB Rdst, Rsrc | Rdst 🡨 Rdst – Rsrc | **Y** |
| INC Rdst | Rdst 🡨 Rdst + 1 | **Y** |
| DEC Rdst | Rdst 🡨 Rdst – 1 | **Y** |
| SHL Rdst, Rsrc | Rdst 🡨 shift left Rdst by Rsrc | **Y** |
| SHR Rdst, Rsrc | Rdst 🡨 shift right Rdst by Rsrc | **Y** |
| AND Rdst, Rsrc | Rdst 🡨 Rdst AND Rsrc | **Y** |
| OR Rdst, Rsrc | Rdst 🡨 Rdst OR Rsrc | **Y** |
| MUL Rdst, Rsrc | Rdst 🡨 Rdst \* Rsrc | **Y** |
| PUSH Rdst  | Rdst is saved on stack | **N** |
| POP Rdst | Rdst is poped from stack | **N** |
| JMP Rsrc | IP 🡨 Rsrc | **N** |
| JE Rsrc | If (ZF) IP 🡨 Rsrc | **N** |
| JNE Rsrc | If (!ZF) IP 🡨 Rsrc | **N** |

## Design a **single-bus** **data path** for this CPU. Clearly illustrate all design details and all the required control signals. Assume that you can only use the following combinational logic blocks in addition to basic gates like AND, OR, NOR, INV, XOR, MUX and Tri-state Buffers:

## An 8-bit **Adder** that has the inputs A[7:0], B[7:0] and Cin, and produces the Sum in C[7:0] and Cout.

## An 8-bit **Multiplier** that has the inputs A[7:0], B[7:0], and produces the Product in C[7:0] and Cout. Cout=1 means that the result does not fit in 8-bits.

## An 8-bit **Shifter** that has the inputs A[7:0] for specifiying the input to be shifted, B[2:0] to specify the amount of shift to be performed and one select line SS to determine the required operation as follows: SS=0 to shift left, and SS=1 to shift right. The resulting operand is produced on the output C[7:0]. The last bit shifted is produced on the output signal LS.

# Assumat that R3 is the stack pointer. Assume that the CPU has a flags register consisting of 2 flags: Carry Flag (CF) and Zero Flag (ZF). Assume that flags are affected as indicated in the table above. Note that the Carry Flag for SUB and DEC instructions should represent a borrow.

**[40 Points]**

# **(Q4)** Assume that a CPU has **16 instructions** with an opcode of 4 bits, seven **16-bit** general purpose registers namely AX, BX, CX, DX, SI, DI and SP, a **16-bit data bus**, and a **16-bit address bus**. Assume that all the instructions are 16-bit. The CPU has an **Arithmetic and Logic Unit (ALU)** with inputs A and B and output C, that can perform any of the following functions shown below based on the three selection lines AS2, AS1, and AS0:

|  |  |
| --- | --- |
| AS2 AS1 AS0 | Operation |
| 000 | C=A+B |
| 001 | C=A-B |
| 010 | C=A+1 |
| 011 | C=A-1 |
| 100 | C=B |
| 101 | C=A+2 |
| 110 | C=A-2 |
| 111 | C=NOT A |

# The CPU has also a **Shift Unit** that can perform shifting as shown below based on the two selection lines SS1 and SS0:

|  |  |
| --- | --- |
| SS1 SS0 | Operation |
| 00 | No shift |
| 01 | W=Shift logic right(X) by M bits |
| 10 | W=Shift logic left(X) by M bits |
| 11 | W=Shift arithmetic right(X) by M bits |

# Assume that the IR, PC, MAR, and MDR registers are also **16-bit regiters**. Also assume that the instructions for this processor follow the syntax and semantics and addressing modes of the 8086 processor. Also assume that registers play the same role as assumed in the 8086 processor.

# Assume that the data path of this processor is implemented using a **three-bus architecture** as shown in the next page.

## Write the minimum number of control steps required for fetching an instruction from memory.

AX

BX

CX

DX

IR

PC

MAR

MDR

ALU

A

B

C

A Bus

B Bus

C Bus

**Data Path Design**

SI

DI

SP

TMP

SHIFTER

M

X

W

## Write the minimum number of control steps required for the execution of each of the following instructions:

### XCHG AX, BX

### ADD I, -10

###

### INC Array[BX]

### POP AX

### LOOPNE Next

### CALL MTest

###

### JZ Next

### SAR AX, BX

###

## Based on the fetch and execution control sequence of the eight instructions given in this question, show the logic equation required for generating the signals **PCin** and **End.**

**[14 Points]**

#  **(Q5)** Using the CPU described in the previous question and the given data path, it is required to implement the control unit for this CPU using both hardwired and microprogrammed approaches. Assume that the number of signals that have to be generated by the control unit to control the data path and the memory interface circuit for this CPU is **30** signals.

## Assume that the maximum number of control steps required for the fetch and execution of any of the 16 instructions is **8 control steps**. Show the block diagram of the **hardwired control unit** organization for this CPU indicating all the necessary components and signals. Assume that the flags needed for the execution of the instructions are the zero and carry flags. Clearly indicate the size of the various components.

## Assume that the control unit for this CPU is to be implemented using a microprogrammed approach and that the number of different control words to be stored in the control store for all the microroutines is **50 CWs**. Also, assume that the microprogrammed control unit design should support unconditional branch (UBR), branch on zero (BRZ), branch on not zero (BRNZ), branch on carry (BRC) and branch on no carry (BRNC).

## Show the format and size of the control word using **horizontal control store**. What is the **size of the control store** needed?

## Show the block diagram of the **microprogrammed control unit** organization for this CPU indicating all the necessary components and signals. Clearly indicate the size of the various components.