Libraries and Procedures

COE 205

Computer Organization and Assembly Language
Dr. Aiman El-Maleh

College of Computer Sciences and Engineering King Fahd University of Petroleum and Minerals

[Adapted from slides of Dr. Kip Irvine: Assembly Language for Intel-Based Computers]

Presentation Outline

- Link Library Overview
- ❖ The Book's Link Library
- Runtime Stack and Stack Operations
- Defining and Using Procedures
- Program Design Using Procedures

Link Library Overview

- ❖ A link library is a file containing procedures that have been assembled into machine code
 - ♦ Can be constructed from one or more object (.OBJ) files
- Textbook provides link libraries to simplify Input/Output
 - ♦ Irvine32.lib is for programs written in 32-bit protected mode
 - ♦ Irvine16.lib is for programs written in 16-bit real-address mode
- You can also construct your own link library
 - ♦ Start with one or more assembler source files (extension .ASM)
 - ♦ Assemble each source file into an object file (extension .OBJ)
 - ♦ Create an empty link library file (extension .LIB)
 - ♦ Add the OBJ files to the library file using the Microsoft LIB utility

Procedure Prototypes & Include File

- ❖ Before calling an external procedure in a library ...
 - ♦ You should make the external procedure visible to your program.
- ❖ To make an external procedure visible, use a prototype
- Examples of Procedure Prototypes

```
ClrScr PROTO ; Clear the screen
WriteChar PROTO ; Write a character
WriteInt PROTO ; Write a signed integer
ReadString PROTO ; Read a string
```

- ❖ The procedure prototypes are placed in an include file
 - ♦ The Irvine32.inc include file (extension .INC) contains the prototypes of the procedures that are defined in Irvine32.lib
 - ♦ The INCLUDE directive copies the content of the include file.

Calling a Library Procedure

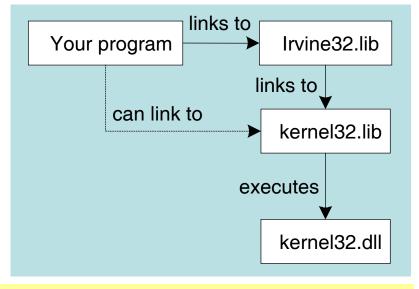
- ❖ To call a library procedure, use the CALL instruction
- Some procedures require input arguments
 - ♦ We can pass arguments in registers
- The following example displays "1A8C" on the console

```
Include Irvine32.inc
...

INCLUDE Irvine32.inc
.code
mov eax, 1A8Ch; eax = argument
call WriteHex; Display eax in hex
call Crlf; Display end of line
```

Linking to a Library

- Your program links to Irvine32.lib
- The link32.exe executable file is the 32-bit linker.
 - The linker program combines a program's object file with one or more object files and link libraries
- ❖ To link myprog.obj to Irvine32.lib & kernel32.lib type ...
 link32 myprog.obj Irvine32.lib kernel32.lib
- If a procedure you are calling is not in the link library, the linker issues an error message
- Kernel32.dll is called a dynamic link library, part of MS-Windows. It contains procedures that perform character-base I/O



Next...

- Link Library Overview
- The Book's Link Library
- Runtime Stack and Stack Operations
- Defining and Using Procedures
- Program Design Using Procedures

The Book's Link Library

- The book's link library Irvine32.lib consists of ...
 - ♦ Input procedures: ReadInt, ReadChar, ReadString, ...
 - ♦ Output procedures: Clrscr, WriteInt, WriteHex, WriteString, ...
 - ♦ Dumping registers and memory: DumpRegs and DumpMem
 - → Random number generation: Randomize, Random32, ...
 - ♦ Cursor control procedures: GetMaxXY and Gotoxy
 - → Miscellaneous procedures: SetTextColor, Delay, ...

Console Window

- → Text-only window created by MS-Windows (cmd.exe program)
- ♦ The Irvine32.lib writes output to the console (standard output)
- → The Irvine32.lib reads input from the keyboard (standard input)

Output Procedures

Procedure	Description
Clrscr	Clears screen, locates cursor at upper left corner.
Crlf	Writes end of line sequence (CR,LF) to standard output.
WriteChar	Writes character in register AL to standard output.
WriteString	Writes a null-terminated string to standard output. String address should be passed in register EDX.
WriteHex	Writes EAX in hexadecimal format to standard output.
WriteInt	Writes EAX in signed decimal format to standard output.
WriteDec	Writes EAX in unsigned decimal format to standard output.
WriteBin	Writes EAX in binary format to standard output.

Example: Displaying a String

Displaying a null-terminated string

Moving the cursor to the beginning of the next line

```
.data
str1 BYTE "Assembly language is easy!",0
.code
   mov edx, OFFSET str1
   call WriteString
   call Crlf
```

Adding the CR/LF control characters to the string definition

Example: Displaying an Integer

```
.code

mov eax, -1000
call WriteBin ; display binary
call Crlf
call WriteHex ; display hexadecimal
call Crlf
call WriteInt ; display signed decimal
call Crlf
call WriteDec ; display unsigned decimal
call Crlf
```

Sample output

```
1111 1111 1111 1111 1100 0001 1000

FFFFC18
-1000
4294966296
```

Input Procedures

Procedure	Description
ReadChar	Reads a char from keyboard and returns it in the AL register. The character is NOT echoed on the screen.
ReadHex	Reads a 32-bit hex integer and returns it in the EAX register. Reading stops when the user presses the [Enter] key. No error checking is performed.
ReadInt	Reads a 32-bit signed integer and returns it in EAX. Leading spaces are ignored. Optional + or – is allowed. Error checking is performed (error message) for invalid input.
ReadDec	Reads a 32-bit unsigned integer and returns it in EAX.
ReadString	Reads a string of characters from keyboard. Additional null-character is inserted at the end of the string. EDX = address of array where input characters are stored. ECX = maximum characters to be read + 1 (for null byte) Return EAX = count of non-null characters read.

Example: Reading a String

Before calling ReadString ...

EDX should have the address of the string.

ECX specifies the maximum number of input chars + 1 (null byte).

```
.data
inputstring BYTE 21 DUP(0); extra 1 for null byte
actualsize DWORD 0

.code
   mov edx, OFFSET inputstring
   mov ecx, SIZEOF inputstring
   call ReadString
   mov actualsize, eax
```

Actual number of characters read is returned in EAX A null byte is automatically appended at the end of the string

Dumping Registers and Memory

DumpRegs

- ♦ Writes EAX, EBX, ECX, and EDX on first line in hexadecimal
- ♦ Writes ESI, EDI, EBP, and ESP on second line in hexadecimal
- ♦ Writes EIP, EFLAGS, CF, SF, ZF, and OF on third line

DumpMem

- ♦ Writes a range of memory to standard output in hexadecimal
- ♦ ECX = number of elements to write
- \Rightarrow EBX = element size (1, 2, or 4)

Example: Dumping a Word Array

```
.data
array WORD 2 DUP (0, 10, 1234, 3CFFh)

.code

mov esi, OFFSET array
mov ecx, LENGTHOF array
mov ebx, TYPE array
call DumpMem
```

Console Output

```
Dump of offset 00405000
-----
0000 000A 04D2 3CFF 0000 000A 04D2 3CFF
```

Random Number Generation

Randomize

- ♦ Seeds the random number generator with the current time
- ♦ The seed value is used by Random32 and RandomRange

❖ Random32

- → Generates an unsigned pseudo-random 32-bit integer
- ♦ Returns value in EAX = random (0 to FFFFFFFh)

RandomRange

- \diamond Generates an unsigned pseudo-random integer from 0 to n-1
- \diamond Call argument: EAX = n
- \Rightarrow Return value in EAX = random (0 to n-1)

Example on Random Numbers

Generate and display 5 random numbers from 0 to 999

```
mov ecx, 5 ; loop counter

L1: mov eax, 1000 ; range = 0 to 999
call RandomRange ; eax = random integer
call WriteDec ; display it
call Crlf ; one number per line
loop L1
```

Console Output

```
194
702
167
257
607
```

Additional Library Procedures

Procedure	Description
WaitMsg	Displays "Press [Enter] to Continue" and waits for user.
SetTextColor	Sets the color for all subsequent text output. Bits 0 – 3 of EAX = foreground color. Bits 4 – 7 of EAX = background color.
Delay	Delay program for a given number of milliseconds. EAX = number of milliseconds.
GetMseconds	Return in EAX the milliseconds elapsed since midnight.
Gotoxy	Locates cursor at a specific row and column on the console. DH = row number DL = column number
GetMaxXY	Return the number of columns and rows in console window buffer Return value DH = current number of rows Return value DL = current number of columns

Example on TextColor

Display a null-terminated string with yellow characters on a blue background

```
.data
str1 BYTE "Color output is easy!",0
.code
mov eax, yellow + (blue * 16)
call SetTextColor
call Clrscr
mov edx, OFFSET str1
call WriteString
call Crlf

The colors defined in Imin 20 incorrer
```

The colors defined in Irvine32.inc are:

black, white, brown, yellow, blue, green, cyan, red, magenta, gray, lightBlue, lightGreen, lightCyan, lightRed, lightMagenta, and lightGray.

Measuring Program Execution Time

```
.data
  time
        BYTE "Execution time in milliseconds: ",0
  start DWORD ?
                     : start execution time
.code
main PROC
  call GetMseconds ; EAX = milliseconds since midnight
  mov start, eax
                     ; save starting execution time
  call WaitMsg ; Press [Enter] to continue ...
                     : 2000 milliseconds
  mov eax, 2000
  call delay
                     ; pause for 2 seconds
  lea edx, time
  call WriteString
                                                        _ | _ | ×
                          Command Prompt
  call GetMseconds
                          C:\COE205>exectime
                           ress [Enter] to continue...
  sub eax, start
                          Execution time in milliseconds: 3145
  call WriteDec
                          C:\C0E2Ø5>
  exit
main ENDP
END main
```

Next...

- Link Library Overview
- The Book's Link Library
- Runtime Stack and Stack Operations
- Defining and Using Procedures
- Program Design Using Procedures

What is a Stack?

- Stack is a Last-In-First-Out (LIFO) data structure
 - ♦ Analogous to a stack of plates in a cafeteria
 - ♦ Plate on Top of Stack is directly accessible
- Two basic stack operations
 - → Push: inserts a new element on top of the stack
 - → Pop: deletes top element from the stack
- View the stack as a linear array of elements
 - ♦ Insertion and deletion is restricted to one end of array
- Stack has a maximum capacity
 - ♦ When stack is full, no element can be pushed
 - ♦ When stack is empty, no element can be popped

Runtime Stack

- Runtime stack: array of consecutive memory locations
- Managed by the processor using two registers
 - ♦ Stack Segment register SS
 - Not modified in protected mode, SS points to segment descriptor
 - ♦ Stack Pointer register ESP
 - For 16-bit real-address mode programs, SP register is used
- ESP register points to the top of stack
 - ♦ Always points to last data item placed on the stack
- Only words and doublewords can be pushed and popped
 - ♦ But not single bytes
- Stack grows downward toward lower memory addresses

Runtime Stack Allocation

- .STACK directive specifies a runtime stack
 - ♦ Operating system allocates memory for the stack
 - → Runtime stack is initially empty

ESP = 0012FFC4

- ♦ The stack size can change dynamically at runtime
- Stack pointer ESP
 - ♦ ESP is initialized by the operating system
 - → Typical initial value of ESP = 0012FFC4h
- The stack grows downwards
 - → The memory below ESP is free
 - ♦ ESP is decremented to allocate stack memory

high address
?
?
?
?
?
?
? ? ?
?
?
low address

Stack Instructions

- Two basic stack instructions:
 - ♦ push source
 - ♦ pop destination
- Source can be a word (16 bits) or doubleword (32 bits)

 - ♦ Segment register: CS, DS, SS, ES, FS, GS
 - Memory operand, memory-to-stack transfer is allowed
 - ♦ Immediate value
- Destination can be also a word or doubleword
 - ♦ General-purpose register
 - ♦ Segment register, except that pop CS is NOT allowed
 - ♦ Memory, stack-to-memory transfer is allowed

Push Instruction

- Push source32 (r/m32 or imm32)
 - → ESP is first decremented by 4
 - ESP = ESP 4 (stack grows by 4 bytes)
 - ♦ 32-bit source is then copied onto the stack at the new ESP
 - [ESP] = source32
- Push source16 (r/m16)
 - ♦ ESP is first decremented by 2
 - ESP = ESP 2 (stack grows by 2 bytes)
 - ♦ 16-bit source is then copied on top of stack at the new ESP
 - [ESP] = source16
- Operating system puts a limit on the stack capacity
 - ♦ Push can cause a Stack Overflow (stack cannot grow)

Examples on the Push Instruction

Suppose we execute:

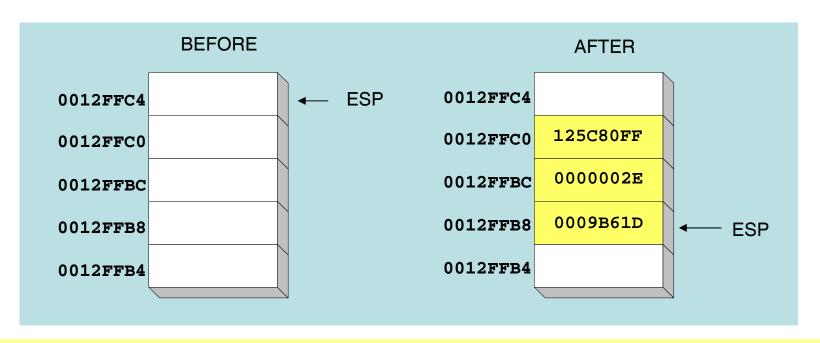
→ PUSH EAX ; EAX = 125C80FFh

→ PUSH EBX ; EBX = 2Eh

→ PUSH ECX ; ECX = 9B61Dh

The stack grows downwards

The area below ESP is free



Pop Instruction

- ❖ Pop dest32 (r/m32)
 - ♦ 32-bit doubleword at ESP is first copied into dest32
 - dest32 = [ESP]
 - ♦ ESP is then incremented by 4
 - ESP = ESP + 4 (stack shrinks by 4 bytes)
- Pop dest16 (r/m16)
 - ♦ 16-bit word at ESP is first copied into dest16
 - dest16 = [ESP]
 - ♦ ESP is then incremented by 2
 - ESP = ESP + 2 (stack shrinks by 2 bytes)
- Popping from an empty stack causes a stack underflow

Examples on the Pop Instruction

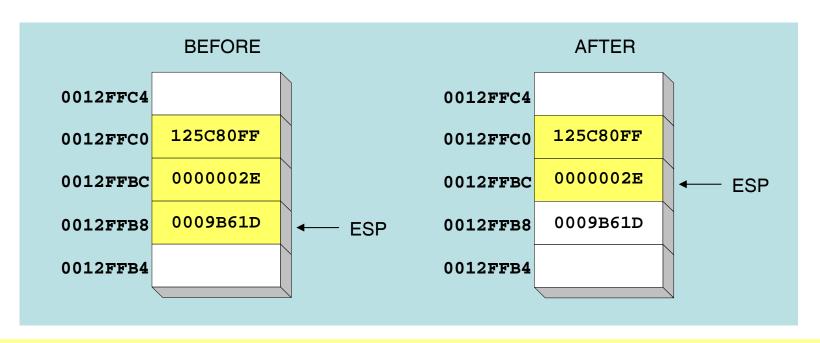
Suppose we execute:

 \Rightarrow POP SI ; SI = B61Dh

 \Rightarrow POP DI ; DI = 0009h

The stack shrinks upwards

The area at & above ESP is allocated



Uses of the Runtime Stack

Runtime Stack can be utilized for

- → Temporary storage of data and registers
- ♦ Transfer of program control in procedures and interrupts
- ♦ Parameter passing during a procedure call
- ♦ Allocating local variables used inside procedures

Stack can be used as temporary storage of data

```
push var1 ; var1 is pushed
push var2 ; var2 is pushed
pop var1 ; var1 = var2 on stack
pop var2 ; var2 = var1 on stack
```

Temporary Storage of Registers

Stack is often used to free a set of registers

```
push EBX   ; save EBX
push ECX   ; save ECX
. . .
; EBX and ECX can now be modified
. . .
pop ECX   ; restore ECX first, then
pop EBX   ; restore EBX
```

Example on moving DX:AX into EBX

Example: Nested Loop

When writing a nested loop, push the outer loop counter ECX before entering the inner loop, and restore ECX after exiting the inner loop and before repeating the outer loop

```
mov ecx, 100 ; set outer loop count
L1:...; begin the outer loop
push ecx ; save outer loop count

mov ecx, 20 ; set inner loop count
L2:...; begin the inner loop
...; inner loop
loop L2 ; repeat the inner loop

outer loop
pop ecx ; restore outer loop count
loop L1 ; repeat the outer loop
```

Push/Pop All Registers

pushad

- ♦ Pushes all the 32-bit general-purpose registers
- ♦ EAX, ECX, EDX, EBX, ESP, EBP, ESI, and EDI in this order.
- ♦ Initial ESP value (before pushad) is pushed
- \Rightarrow ESP = ESP 32

pusha

- ♦ Same as pushad but pushes all 16-bit registers AX through DI
- \Rightarrow ESP = ESP 16

popad

- ♦ Pops into registers EDI through EAX in reverse order of pushad
- ♦ ESP is not read from stack. It is computed as: ESP = ESP + 32

popa

♦ Same as popad but pops into 16-bit registers. ESP = ESP + 16

Stack Instructions on Flags

- Special Stack instructions for pushing and popping flags
 - ♦ pushfd
 - Push the 32-bit EFLAGS
 - ♦ popfd
 - Pop the 32-bit EFLAGS
- No operands are required
- Useful for saving and restoring the flags
- For 16-bit programs use pushf and popf
 - ♦ Push and Pop the 16-bit FLAG register

Next...

- Link Library Overview
- ❖ The Book's Link Library
- Runtime Stack and Stack Operations
- Defining and Using Procedures
- Program Design Using Procedures

Procedures

- ❖ A procedure is a logically self-contained unit of code
 - ♦ Called sometimes a function, subprogram, or subroutine
 - ♦ Receives a list of parameters, also called arguments
 - ♦ Performs computation and returns results
 - ♦ Plays an important role in modular program development
- * Example of a procedure (called function) in C language

```
int sumof (int x,int y,int z) {
Result type int temp;
    temp = x + y + z;
    return temp;
}
Return function result
```

The above function sumof can be called as follows:

```
sum = sumof( num1, num2, num3 ); Actual parameter list
```

Defining a Procedure in Assembly

- Assembler provides two directives to define procedures
 - PROC to define name of procedure and mark its beginning
 - → ENDP to mark end of procedure
- ❖ A typical procedure definition is

procedure_name should match in PROC and ENDP

Documenting Procedures

- Suggested Documentation for Each Procedure:
 - ♦ Does: Describe the task accomplished by the procedure
 - ♦ Receives: Describe the input parameters
 - Returns: Describe the values returned by the procedure
 - Requires: List of requirements called preconditions

Preconditions

- ♦ Must be satisfied before the procedure is called
- If a procedure is called without its preconditions satisfied, it will probably not produce the expected output

Example of a Procedure Definition

- The sumof procedure receives three integer parameters
 - ♦ Assumed to be in EAX, EBX, and ECX
 - ♦ Computes and returns result in register EAX

The ret instruction returns control to the caller

The Call Instruction

- ❖ To invoke a procedure, the call instruction is used
- The call instruction has the following format

```
call procedure_name
```

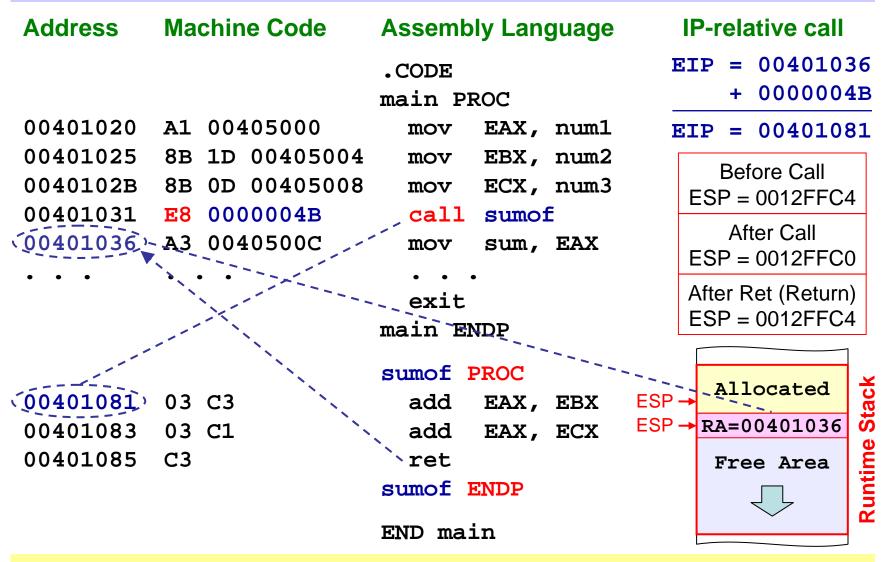
- Example on calling the procedure sumof
 - ♦ Caller passes actual parameters in EAX, EBX, and ECX
 - ♦ Before calling procedure sumof

call sumof will call the procedure sumof

How a Procedure Call / Return Works

- How does a procedure know where to return?
 - ♦ There can be multiple calls to same procedure in a program.
 - ♦ Procedure has to return differently for different calls
- It knows by saving the return address (RA) on the stack
 - ♦ This is the address of next instruction after call
- ❖ The call instruction does the following
 - ♦ Pushes the return address on the stack
 - → Jumps into the first instruction inside procedure
- The ret (return) instruction does the following
 - ♦ Pops return address from stack
 - → Jumps to return address: EIP = [ESP]; ESP = ESP + 4

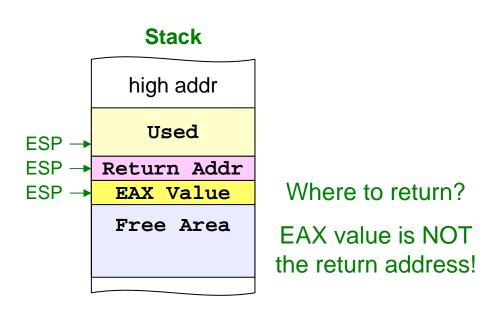
Details of CALL and Return



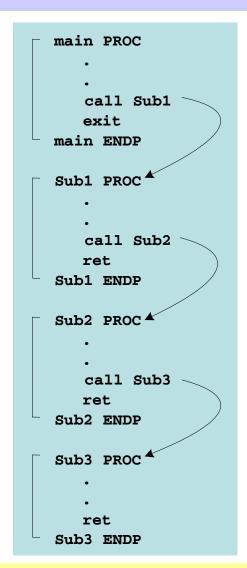
Don't Mess Up the Stack!

- Just before returning from a procedure
 - ♦ Make sure the stack pointer ESP is pointing at return address
- Example of a messed-up procedure
 - Pushes EAX on the stack before returning
 - ♦ Stack pointer ESP is NOT pointing at return address!

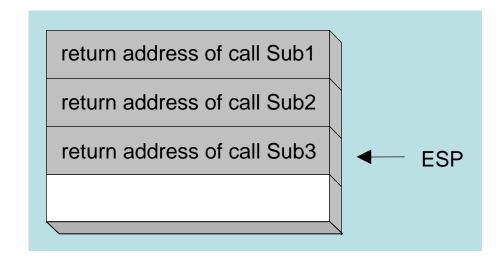
```
main PROC
    call messedup
    . . .
    exit
main ENDP
messedup PROC
    push EAX
    ret
messedup ENDP
```



Nested Procedure Calls



By the time Sub3 is called, the stack contains all three return addresses



Parameter Passing

- Parameter passing in assembly language is different
 - ♦ More complicated than that used in a high-level language
- In assembly language
 - ♦ Place all required parameters in an accessible storage area
 - ♦ Then call the procedure
- Two types of storage areas used
 - ♦ Registers: general-purpose registers are used (register method)
 - ♦ Memory: stack is used (stack method)
- Two common mechanisms of parameter passing
 - ♦ Pass-by-value: parameter value is passed
 - ♦ Pass-by-reference: address of parameter is passed

Passing Parameters in Registers

```
; ArraySum: Computes the sum of an array of integers
; Receives: ESI = pointer to an array of doublewords
       ECX = number of array elements
: Returns: EAX = sum
ArraySum PROC
   mov eax,0
              ; set the sum to zero
L1: add eax, [esi] ; add each integer to sum
   add esi, 4
              ; point to next integer
   loop L1
                        ; repeat for array size
   ret
ArraySum ENDP
```

ESI: Reference parameter = array address

ECX: Value parameter = count of array elements

Preserving Registers

- Need to preserve the registers across a procedure call
 - ♦ Stack can be used to preserve register values
- Which registers should be saved?
 - ♦ Those registers that are modified by the called procedure
 - But still used by the calling procedure
 - ♦ We can save all registers using pusha if we need most of them
 - However, better to save only needed registers when they are few
- Who should preserve the registers?
 - ♦ Calling procedure: saves and frees registers that it uses
 - Registers are saved before procedure call and restored after return
 - ♦ Called procedure: preferred method for modular code
 - Register preservation is done in one place only (inside procedure)

Example on Preserving Registers

```
; ArraySum: Computes the sum of an array of integers
; Receives: ESI = pointer to an array of doublewords
      ECX = number of array elements
; Returns: EAX = sum
ArraySum PROC
   push esi
                 ; save esi, it is modified
                    ; save ecx, it is modified
   push ecx
                     ; set the sum to zero
   mov eax, 0
L1: add eax, [esi]; add each integer to sum
   add esi, 4
                         ; point to next integer
                         ; repeat for array size
   loop L1
                         ; restore registers
   pop ecx
   pop esi
                         ; in reverse order
   ret
                         No need to save EAX. Why?
ArraySum ENDP
```

USES Operator

- The USES operator simplifies the writing of a procedure
 - ♦ Registers are frequently modified by procedures
 - ♦ Just list the registers that should be preserved after USES.
 - ♦ Assembler will generate the push and pop instructions

```
ArraySum PROC
                                        push esi
ArraySum PROC USES esi ecx
                                        push ecx
        eax,0
   mov
                                        mov eax,0
L1: add eax, [esi]
                                    L1: add eax, [esi]
   add esi, 4
                                        add esi, 4
   loop L1
                                        loop L1
   ret
                                        pop
                                             ecx
ArraySum ENDP
                                             esi
                                        pop
                                        ret
                                    ArraySum ENDP
```

Next...

- Link Library Overview
- ❖ The Book's Link Library
- Runtime Stack and Stack Operations
- Defining and Using Procedures
- Program Design Using Procedures

Program Design using Procedures

Program Design involves the Following:

- ♦ Break large tasks into smaller ones
- ♦ Use a hierarchical structure based on procedure calls
- → Test individual procedures separately

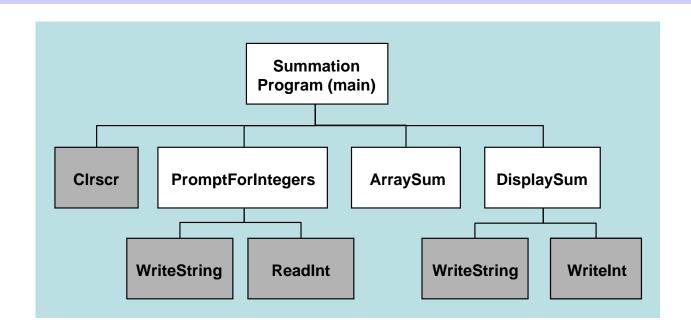
Integer Summation Program:

Write a program that prompts the user for multiple 32-bit integers, stores them in an array, calculates the array sum, and displays the sum on the screen.

Main steps:

- 1. Prompt user for multiple integers
- 2. Calculate the sum of the array
- 3. Display the sum

Structure Chart



Structure Chart

Above diagram is called a structure chart

Describes program structure, division into procedure, and call sequence Link library procedures are shown in grey

Integer Summation Program - 1 of 4

```
INCLUDE Irvine32.inc
ArraySize EQU 5
.DATA
  prompt1 BYTE "Enter a signed integer: ",0
  prompt2 BYTE "The sum of the integers is: ",0
  array DWORD ArraySize DUP(?)
CODE
main PROC
  call Clrscr
                         : clear the screen
  mov esi, OFFSET array
  mov ecx, ArraySize
  call PromptForIntegers ; store input integers in array
  call ArraySum
                   ; calculate the sum of array
  call DisplaySum ; display the sum
  exit
main ENDP
```

Integer Summation Program - 2 of 4

```
; PromptForIntegers: Read input integers from the user
; Receives: ESI = pointer to the array
       ECX = array size
; Returns: Fills the array with the user input
PromptForIntegers PROC USES ecx edx esi
  mov edx, OFFSET prompt1
L1:
  call WriteString
                           ; display prompt1
  call ReadInt
                           ; read integer into EAX
  call Crlf
                           ; go to next output line
  mov [esi], eax
                           ; store integer in array
  add esi, 4
                           ; advance array pointer
  loop L1
  ret
PromptForIntegers ENDP
```

Integer Summation Program - 3 of 4

```
; ArraySum: Calculates the sum of an array of integers
; Receives: ESI = pointer to the array,
     ECX = array size
; Returns: EAX = sum of the array elements
ArraySum PROC USES esi ecx
 mov eax,0; set the sum to zero
L1:
 add eax, [esi] ; add each integer to sum
 add esi, 4 ; point to next integer
 loop L1
                      ; repeat for array size
                       ; sum is in EAX
 ret
ArraySum ENDP
```

Integer Summation Program - 4 of 4

```
; DisplaySum: Displays the sum on the screen
; Receives: EAX = the sum
; Returns: nothing
DisplaySum PROC
  mov edx, OFFSET prompt2
  call WriteString
                                ; display prompt2
  call WriteInt
                                ; display sum in EAX
  call Crlf
  ret
DisplaySum ENDP
END main
```

Sample Output

```
Enter a signed integer: 550

Enter a signed integer: -23

Enter a signed integer: -96

Enter a signed integer: 20

Enter a signed integer: 7

The sum of the integers is: +458
```

Parameter Passing Through Stack

- Parameters can be saved on the stack before a procedure is called.
- The called procedure can easily access the parameters using either the ESP or EBP registers without altering ESP register.

Example

```
Suppose you want to implement the following pseudo-code: i = 25; j = 4; Test(i, j, 1);
```

```
Then, the assembly language code fragment looks like: mov i, 25 mov j, 4 push 1 push j push i call Test
```

Parameter Passing Through Stack

```
Example: Accessing parameters on the
stack
Test PROC
                                      Lower Address
 mov AX, [ESP + 4] ;get i
 add AX, [ESP + 8]; add j
                                                        Return Address
                                                ESP
 sub AX, [ESP + 12]; subtract parm 3
                                              ESP+4
                                                           25 (i)
                    (1) from sum
                                              ESP+8
                                                            4 (i)
 ret
                                             ESP+12
Test ENDP
                                      Higher Address
```

Call & Return Instructions

Instruction	Operand	Note
CALL	label name	Push IP IP= IP + displacement relative to next instruction
CALL	r/m	Push IP IP = [r/m]
CALL	label name (FAR)	Push CS Push IP CS:IP=address of label name
CALL	m (FAR)	Push CS Push IP CS:IP= [m]
RET		Pop IP
RET	imm	Pop IP SP = SP + imm
RET	(FAR)	Pop IP Pop CS
RET	imm (FAR)	Pop IP Pop CS SP = SP + imm

Freeing Passed Parameters From Stack

Use RET N instruction to free parameters from stack

Local Variables

- Local variables are dynamic data whose values must be preserved over the lifetime of the procedure, but not beyond its termination.
- ❖ At the termination of the procedure, the current environment disappears and the previous environment must be restored.
- Space for local variables can be reserved by subtracting the required number of bytes from ESP.
- Offsets from ESP are used to address local variables.

Local Variables

Pseudo-code (Java-like)	Assembly Language
<pre>void Test(int i){ int k; k = i+9;</pre>	Test PROC push EBP mov EBP, ESP sub ESP, 4 push EAX mov DWORD PTR [EBP-4], 9 mov EAX, [EBP + 8] add [EBP-4], EAX
}	pop EAX mov ESP, EBP pop EBP ret 4 Test ENDP

Summary

- Procedure Named block of executable code
 - ♦ CALL: call a procedure, push return address on top of stack
 - ♦ RET: pop the return address and return from procedure
 - ♦ Preserve registers across procedure calls
- Runtime stack LIFO structure Grows downwards
 - → Holds return addresses, saved registers, etc.
 - → PUSH insert value on top of stack, decrement ESP
 - → POP remove top value of stack, increment ESP
- Use the Irvine32.lib library for standard I/O
 - ♦ Include Irvine32.inc to make procedure prototypes visible
 - ♦ You can learn more by studying Irvine32.asm code