

Major 2 - 011

Q13 \rightarrow Q18

Q13

$$I = 6.0 \text{ kg} \cdot \text{m}^2$$

$$\alpha = 2.0 \text{ rad/s}^2$$

$$\Sigma \tau = I \alpha$$

$$\Sigma \tau = (6.0)(2) = 12 \text{ kg} \cdot \text{m} \cdot \text{N} \cdot \text{m}$$

$$t=0 \rightarrow t=5$$

$$W = \int (\Sigma \tau) d\theta$$

$\Sigma \tau$ is constant

$$W = (\Sigma \tau) \Delta \theta$$

$$W = I \alpha \Delta \theta$$

$$\Delta \theta = ?$$

$\alpha \checkmark$, $\omega_0 = 0$ (start from rest)

$$\& t = 5.0 \text{ s}$$

find $\Delta \theta \checkmark$ ok

$$\Delta \theta = \omega_0 t + \frac{1}{2} \alpha t^2$$

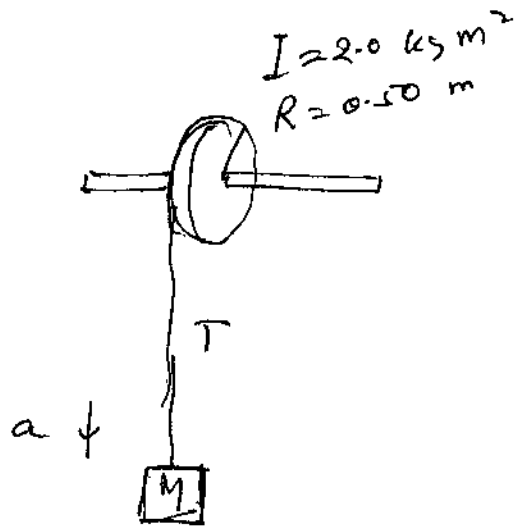
$$\Delta \theta = 0 + \frac{1}{2} \alpha t^2$$

$$\Rightarrow W = (I \alpha) \left(\frac{1}{2} \alpha t^2 \right)$$

$$= (12) \left(\frac{1}{2} (2) (5)^2 \right)$$

$$\boxed{W = 300 \text{ J}}$$

(14)



\Rightarrow

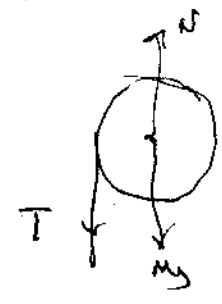
$$\sum \vec{F} = m\vec{a}$$



$$Mg - \textcircled{T} = M\textcircled{a}$$

a & T are both unknowns.

~~part~~ flywheel



$$\sum \tau = I\alpha$$

$$TR = I\left(\frac{a}{R}\right)$$

$$T = \left(\frac{Ia}{R^2}\right) \quad \textcircled{2}$$

$$Mg - \frac{Ia}{R^2} = Ma$$

$$Mg = a\left(M + \frac{I}{R^2}\right)$$

$$a = \frac{Mg}{M \left(1 + \frac{I}{MR^2} \right)}$$

$$a = \frac{9}{1 + \frac{I}{MR^2}} = \frac{9.8}{1 + \frac{2}{(10)(0.50)^2}}$$

$$a = 5.4 \text{ m/s}^2$$

(15)

$$\omega_0 = 0, \Delta\theta = 8 \text{ rev}, t = 17 \text{ s}$$

~~$\alpha = ?$~~

$\omega = ?$

$$\Delta\theta = \frac{1}{2}(\omega + \omega_0)t$$

$$\Delta\theta = 8 \text{ rev} = 8 \text{ rev} \times \left(\frac{2\pi \text{ rad}}{1 \text{ rev}} \right)$$
$$= 8(2\pi) \text{ rad}$$

$$16\pi = \frac{1}{2}(\omega + 0)17$$

$$\omega = \frac{(2)(16)\pi}{17} \approx 5.9 \text{ rad/s}$$

(16)

$$K = K_T + K_R = \frac{1}{2}mv^2 + \frac{1}{2}I_{\text{com}}\omega^2$$

$$= \frac{1}{2} \left(\frac{m}{32} \right) (5.0)^2 + \frac{1}{2} \left(\frac{1}{2} m R^2 \right) \frac{v^2}{R^2}$$

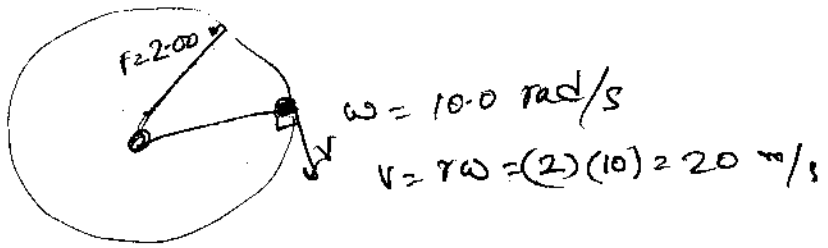
$$= \frac{1}{2}mv^2 + \frac{1}{2} \left(\frac{1}{2}mv^2 \right)$$

$$= \frac{3}{4}mv^2$$

$$= \frac{3}{4}(32)(5.0)^2$$

$$\boxed{W = 600 \text{ J}}$$

Q17

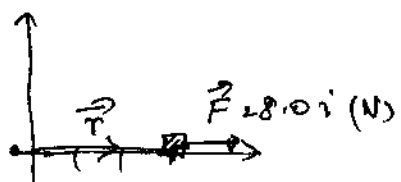


$$\vec{L} = \vec{r} \wedge \vec{p} = r m v \sin \theta$$

$$L = r m v = (2)(10)(20) \quad \theta = 90$$

$$L = 400 \frac{\text{kg} \cdot \text{m}^2}{\text{s}}$$

Q18



$$\vec{L} = \vec{r} \wedge \vec{F} = \text{zero}$$