

Remote Ultrasonic Detector
Using
He-Ne Laser
and
Confocal Fabry-Perot Interferometer

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Physics Department
Oct. 24, 2004

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Why to build this sensor?

sensor

Remote
detection

specimen

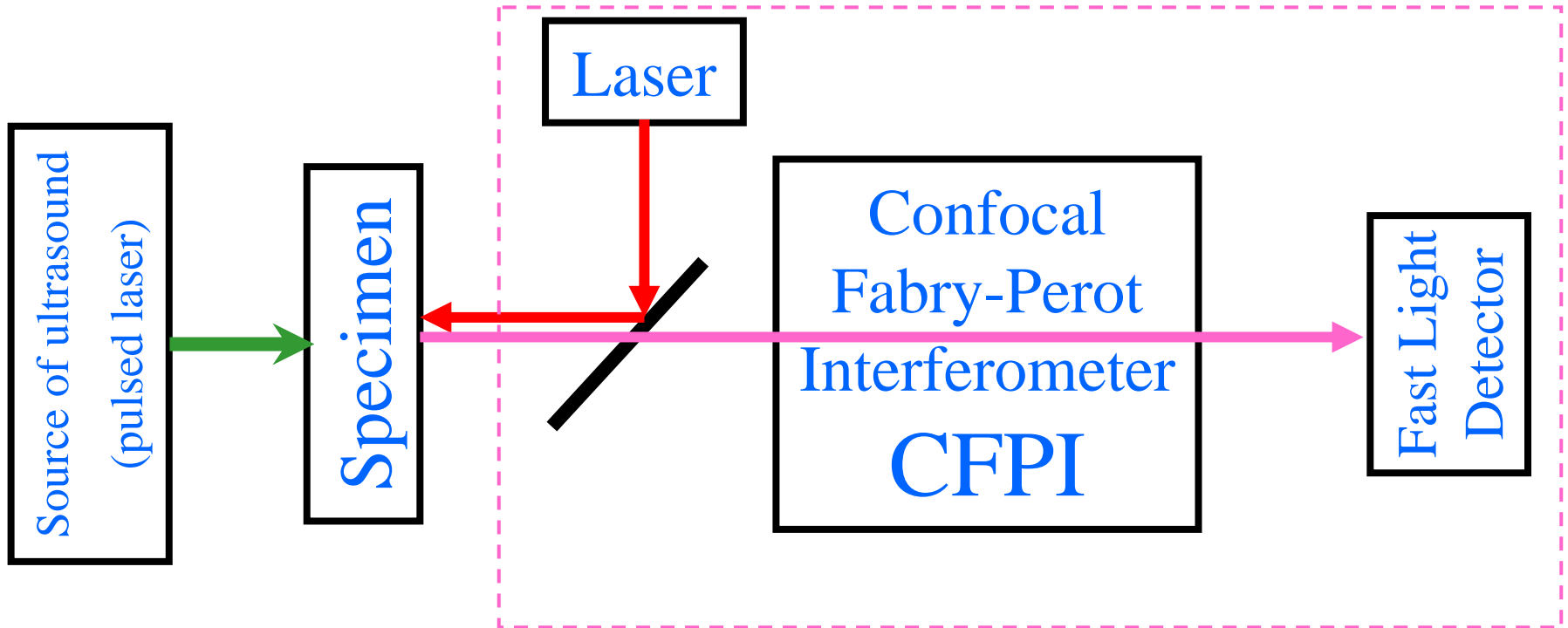
Fast inspection

Hot

Hazardous

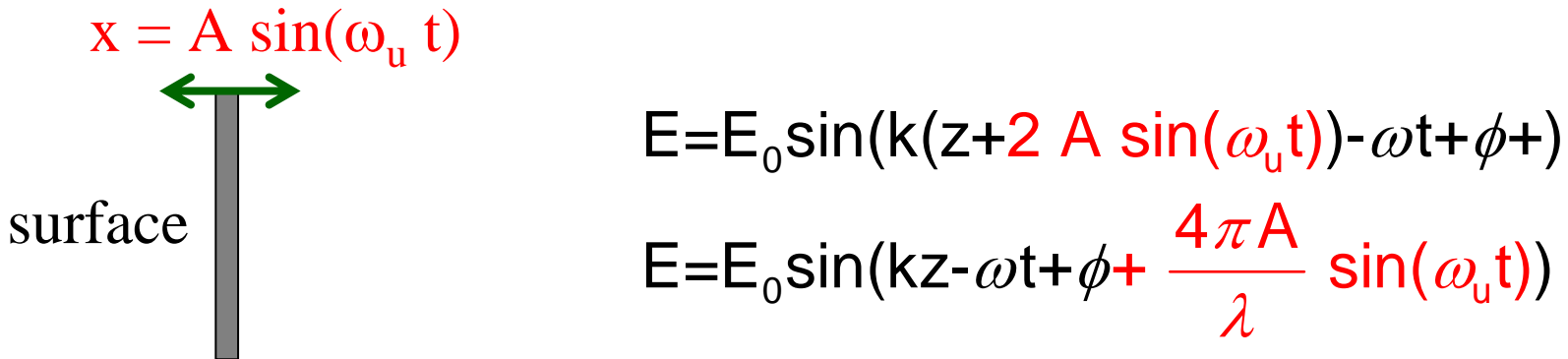
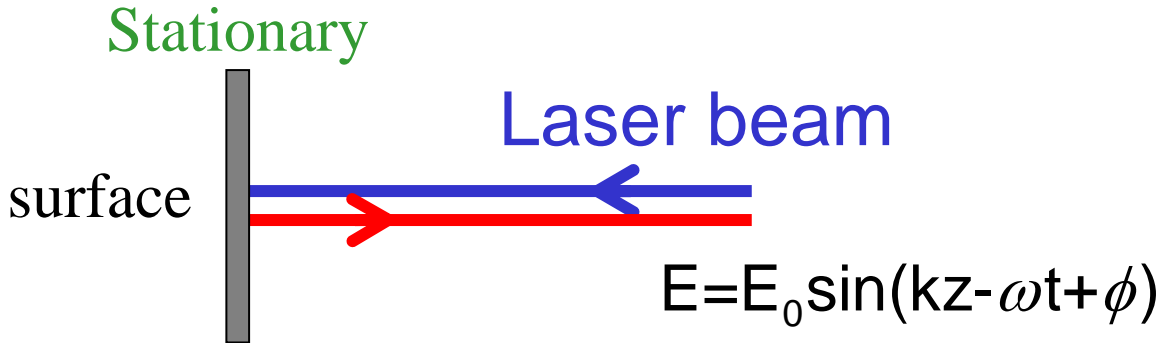
Fragile

Main Components?

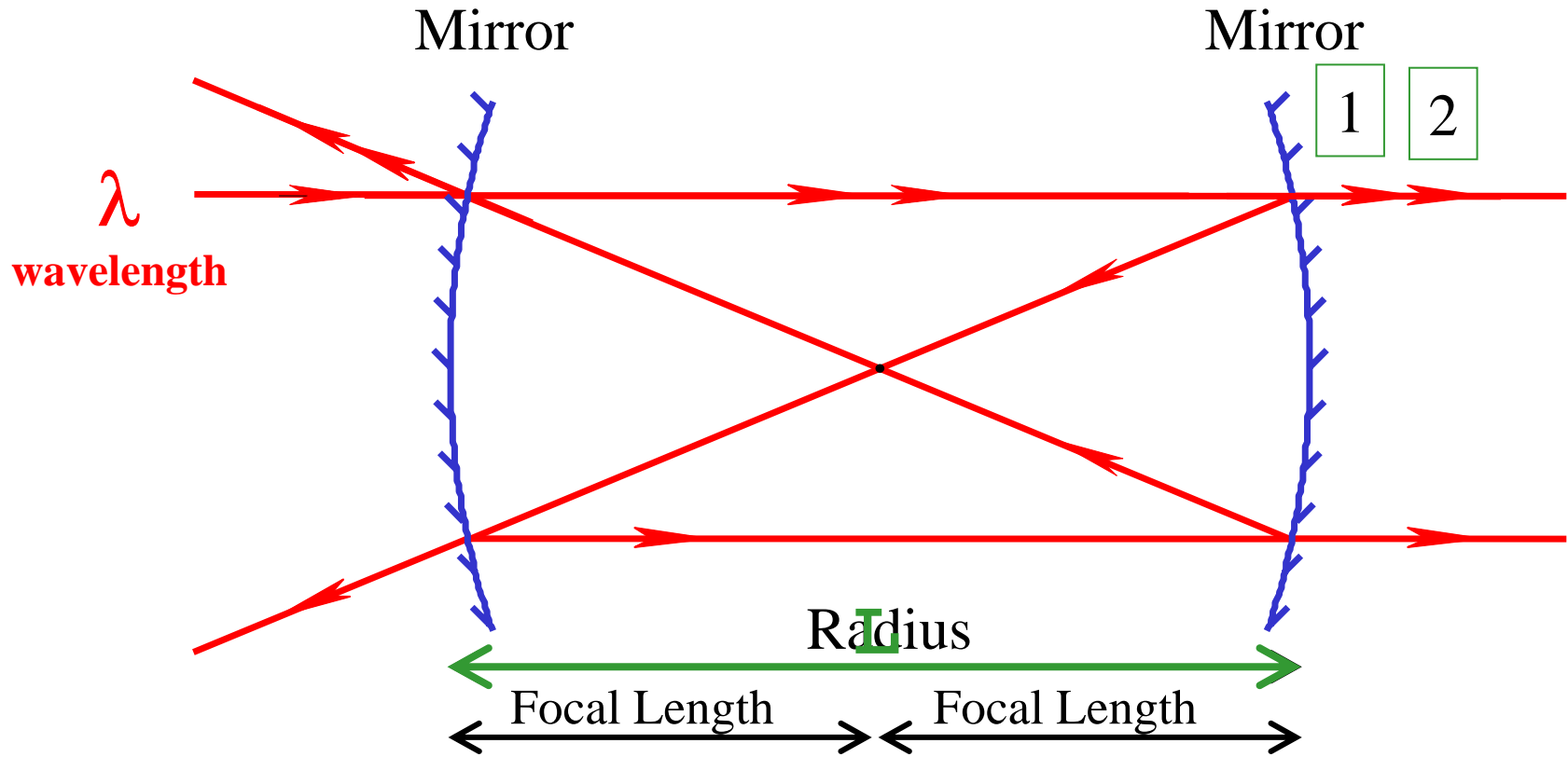


Measure motion of surfaces by analyzing the phase of the reflected light

Light modulation by moving surfaces

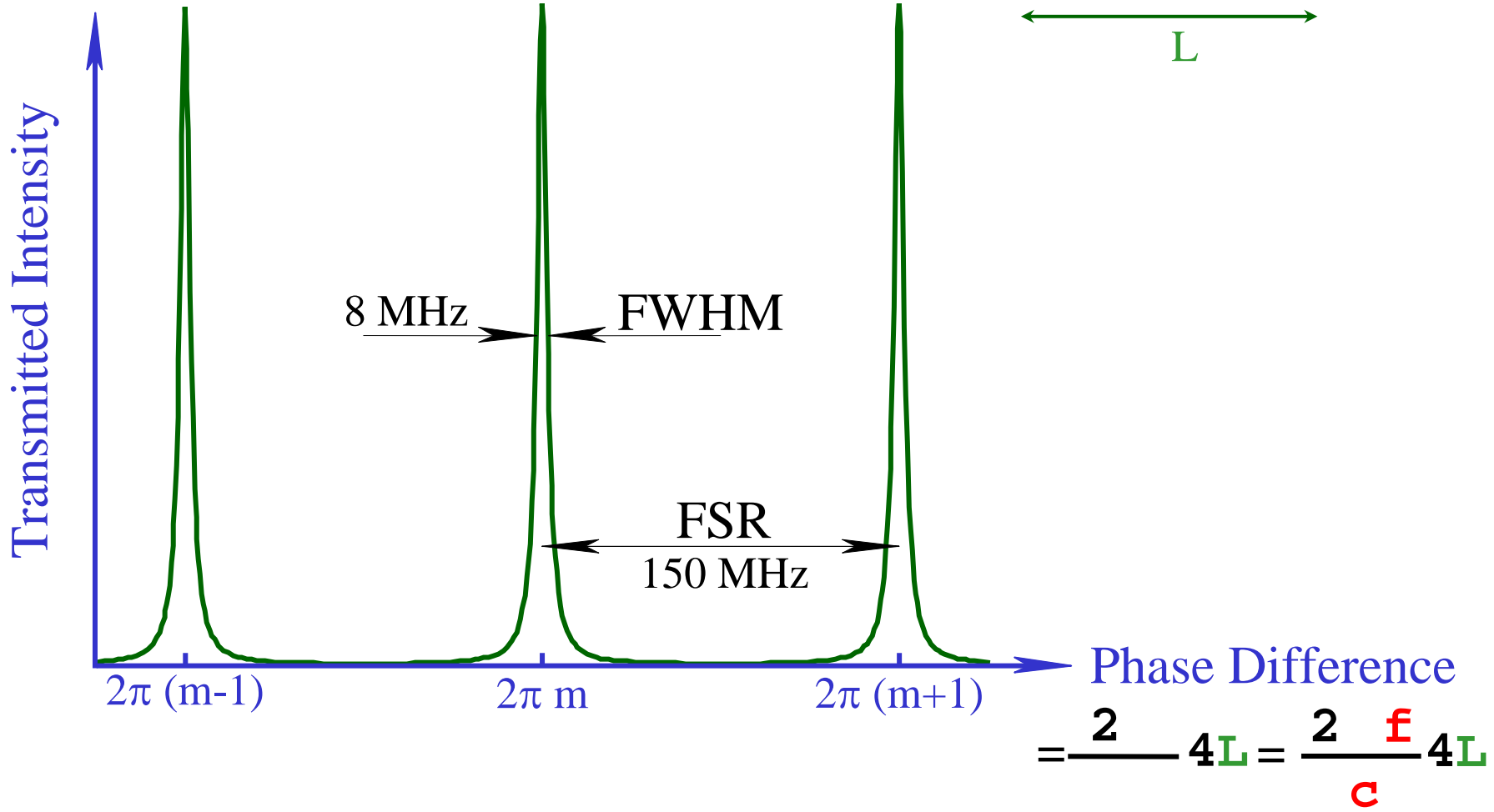
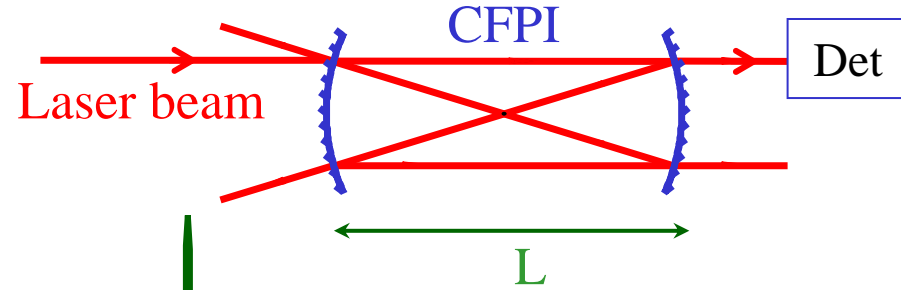


What is Confocal Fabry-Perot Interferometer?

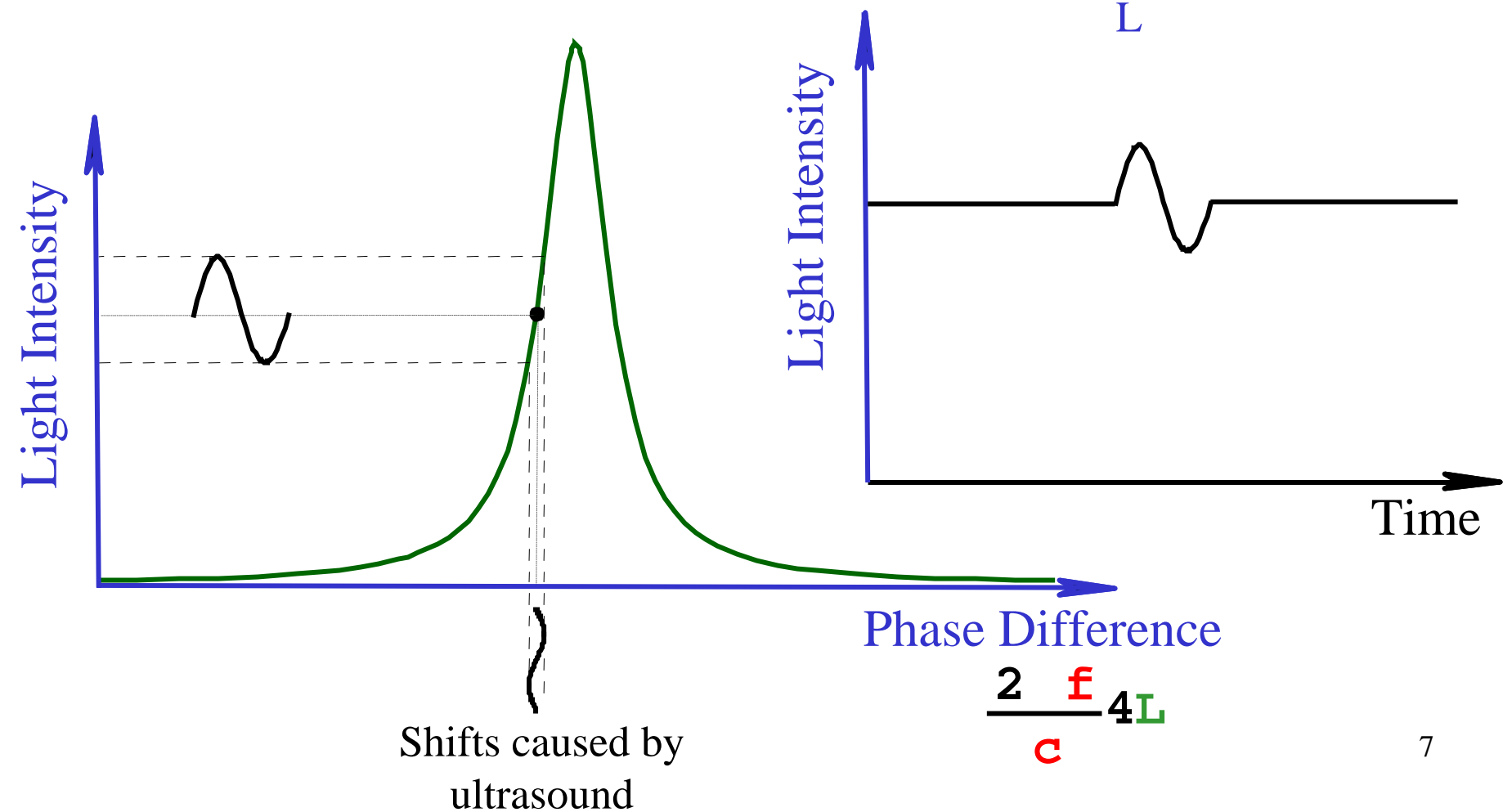
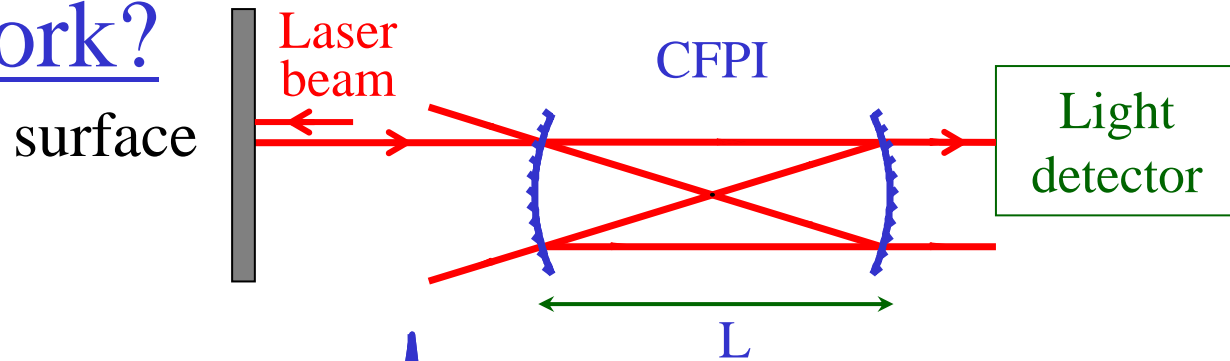


$$\text{phase difference} = \frac{2}{4} R$$

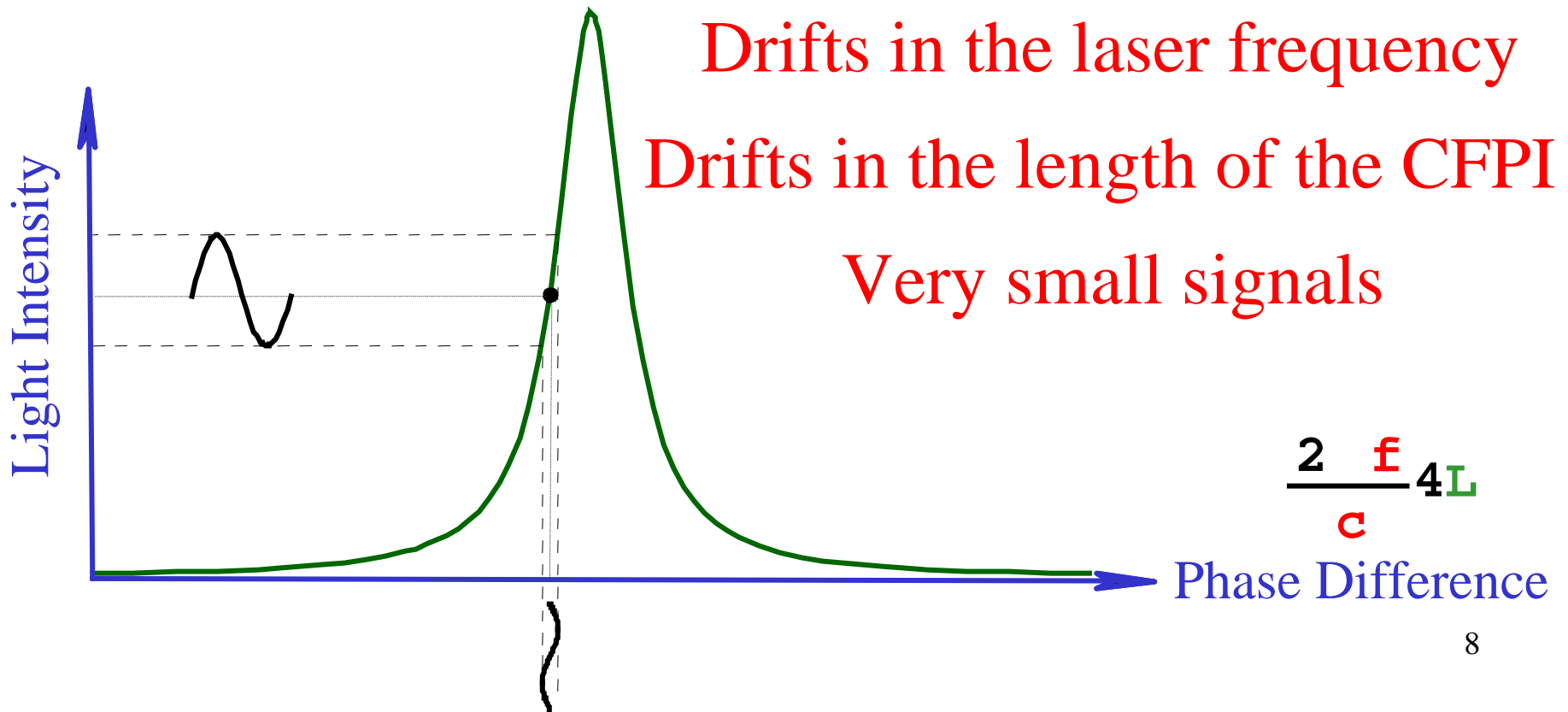
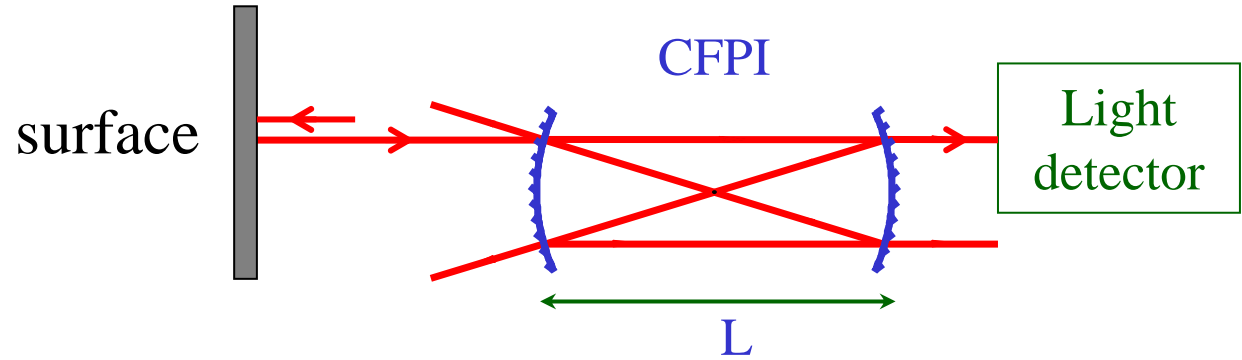
Transmission of CFPI



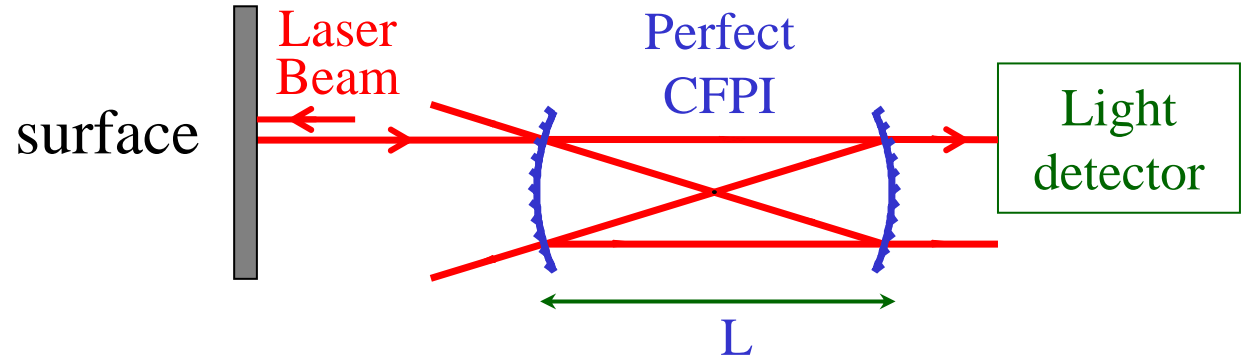
How does it work?



Practical Considerations

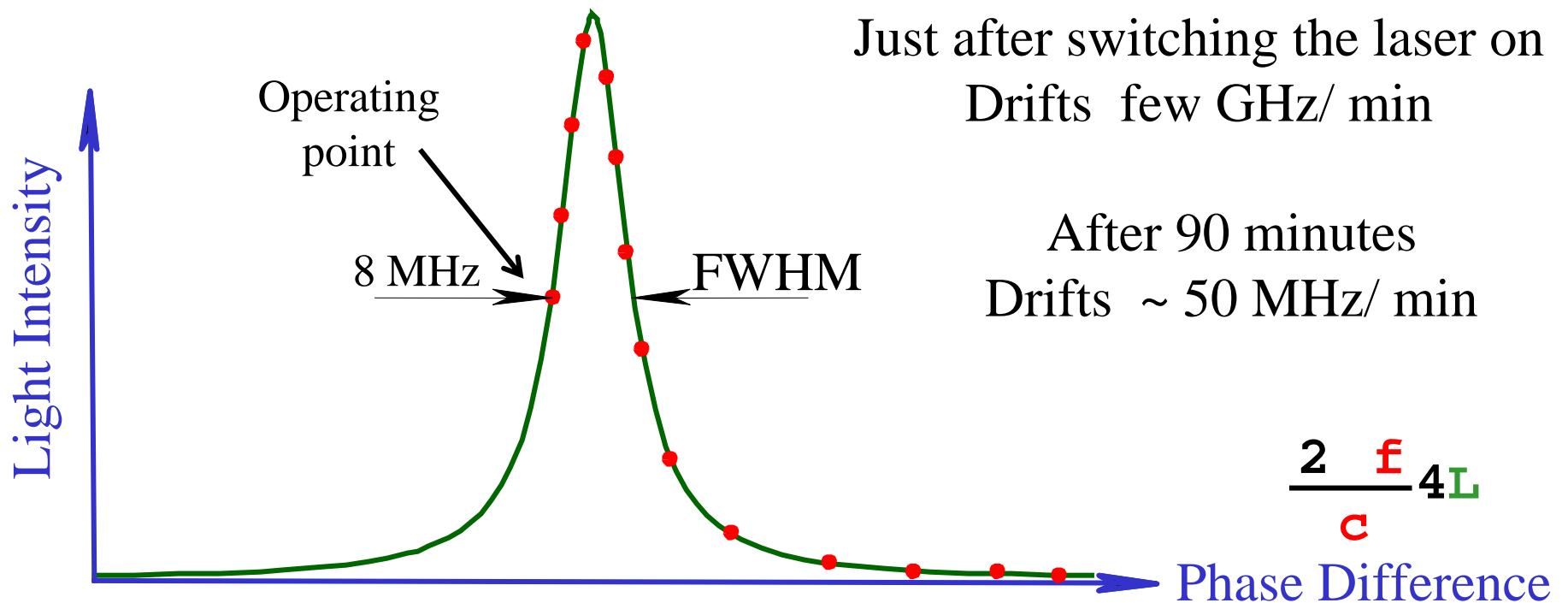


Drifts in the laser frequency

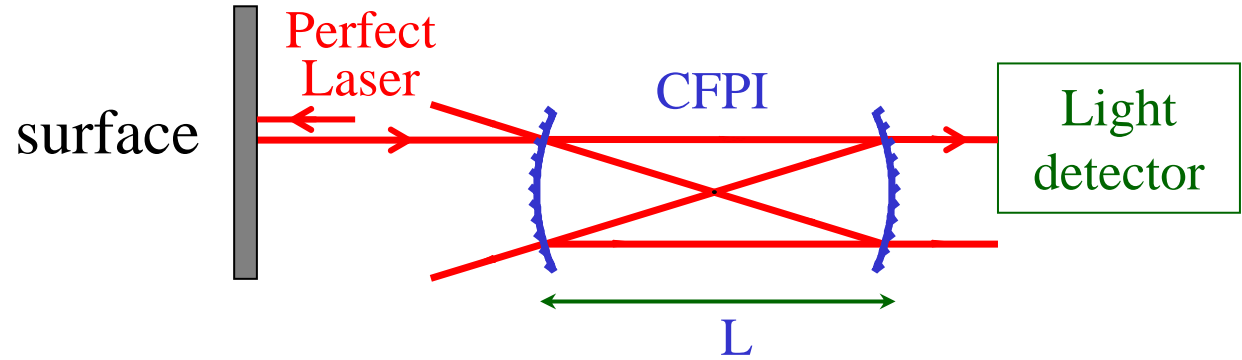


Just after switching the laser on
Drifts few GHz/ min

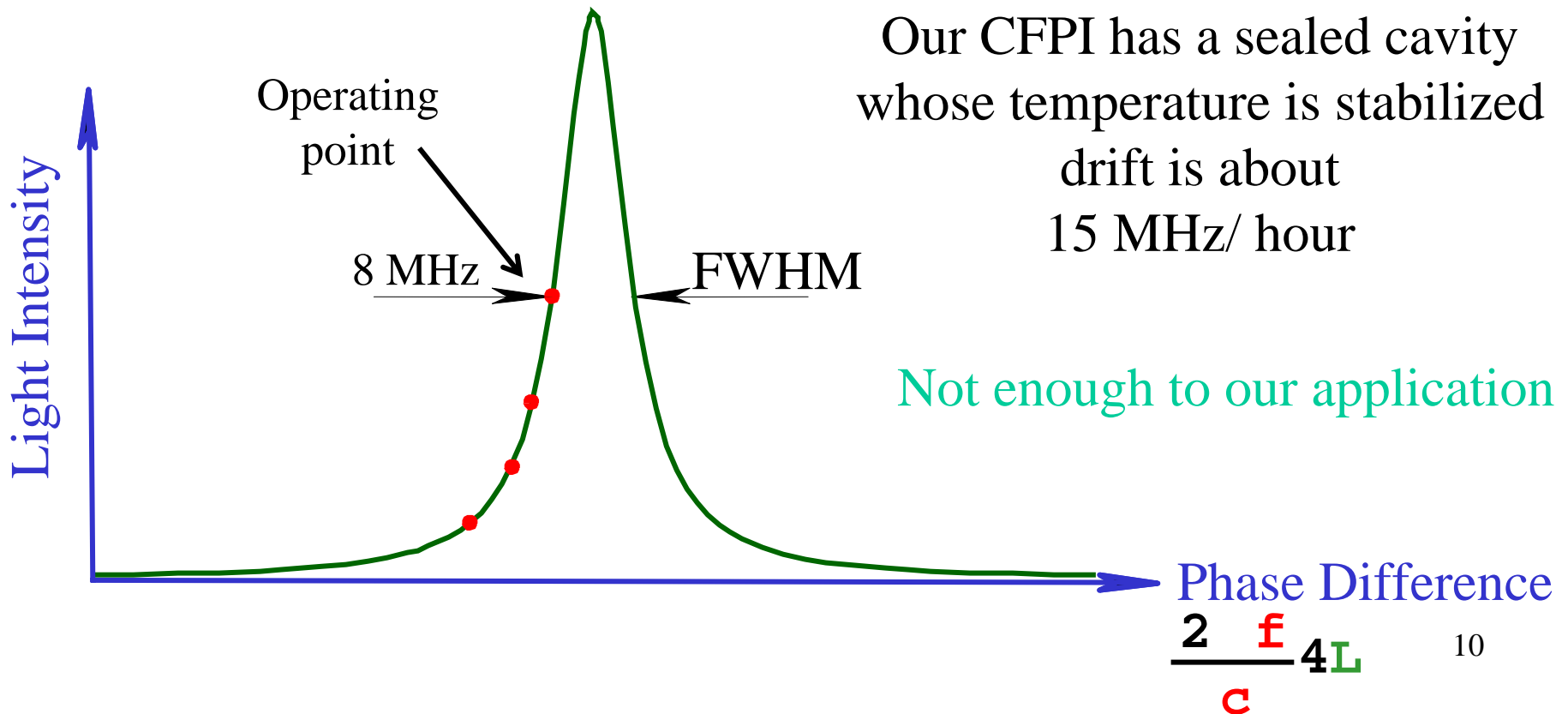
After 90 minutes
Drifts ~ 50 MHz/ min



Drifts in the Length of CFPI

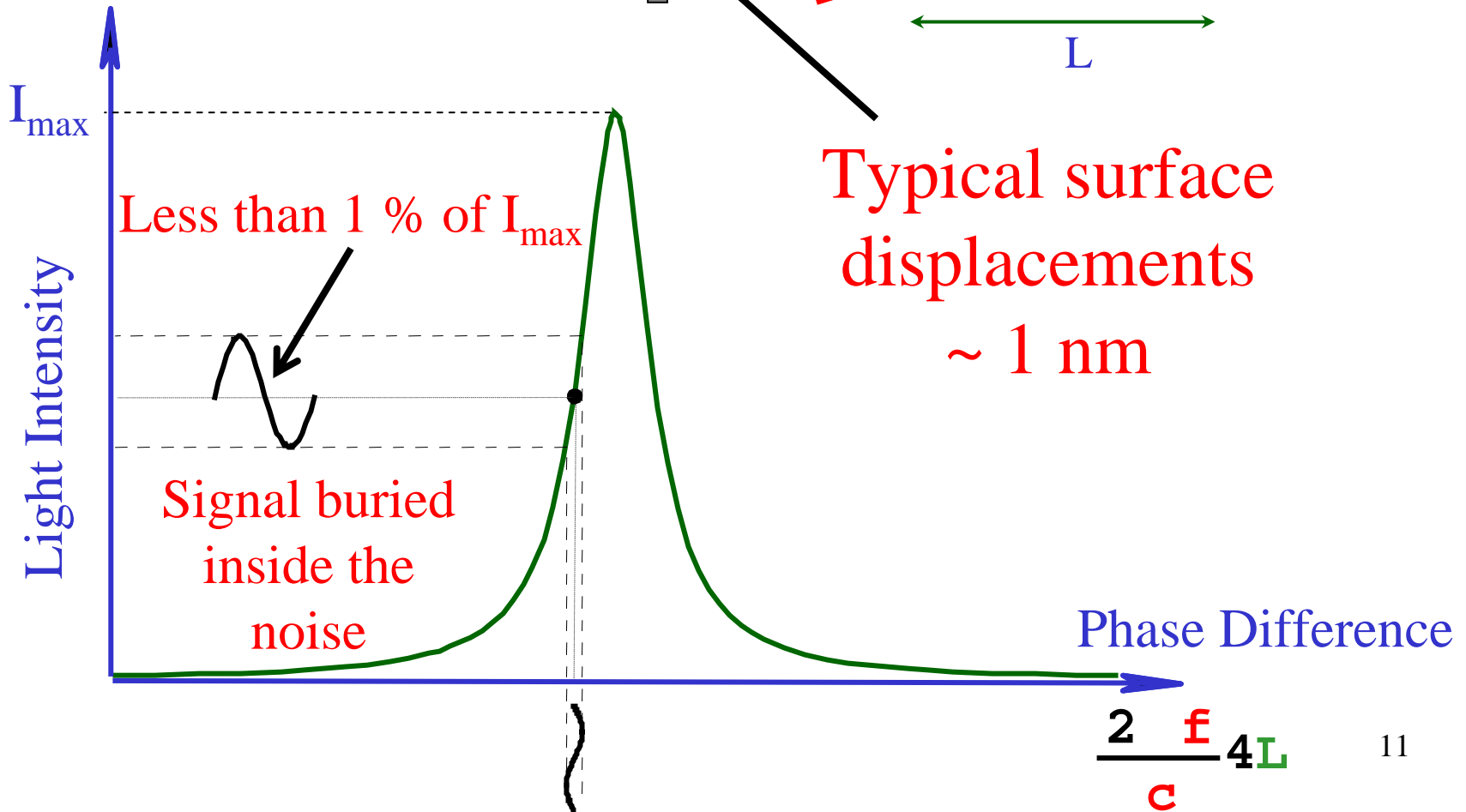
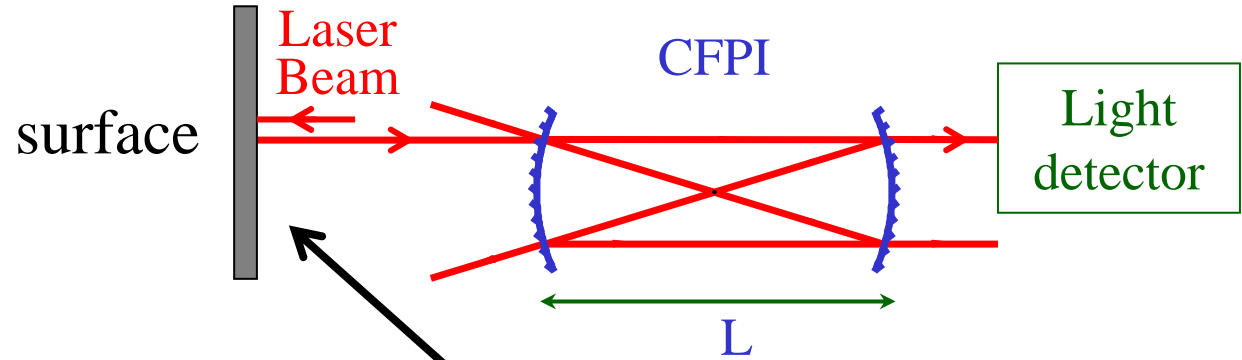


Our CFPI has a sealed cavity whose temperature is stabilized drift is about 15 MHz/ hour



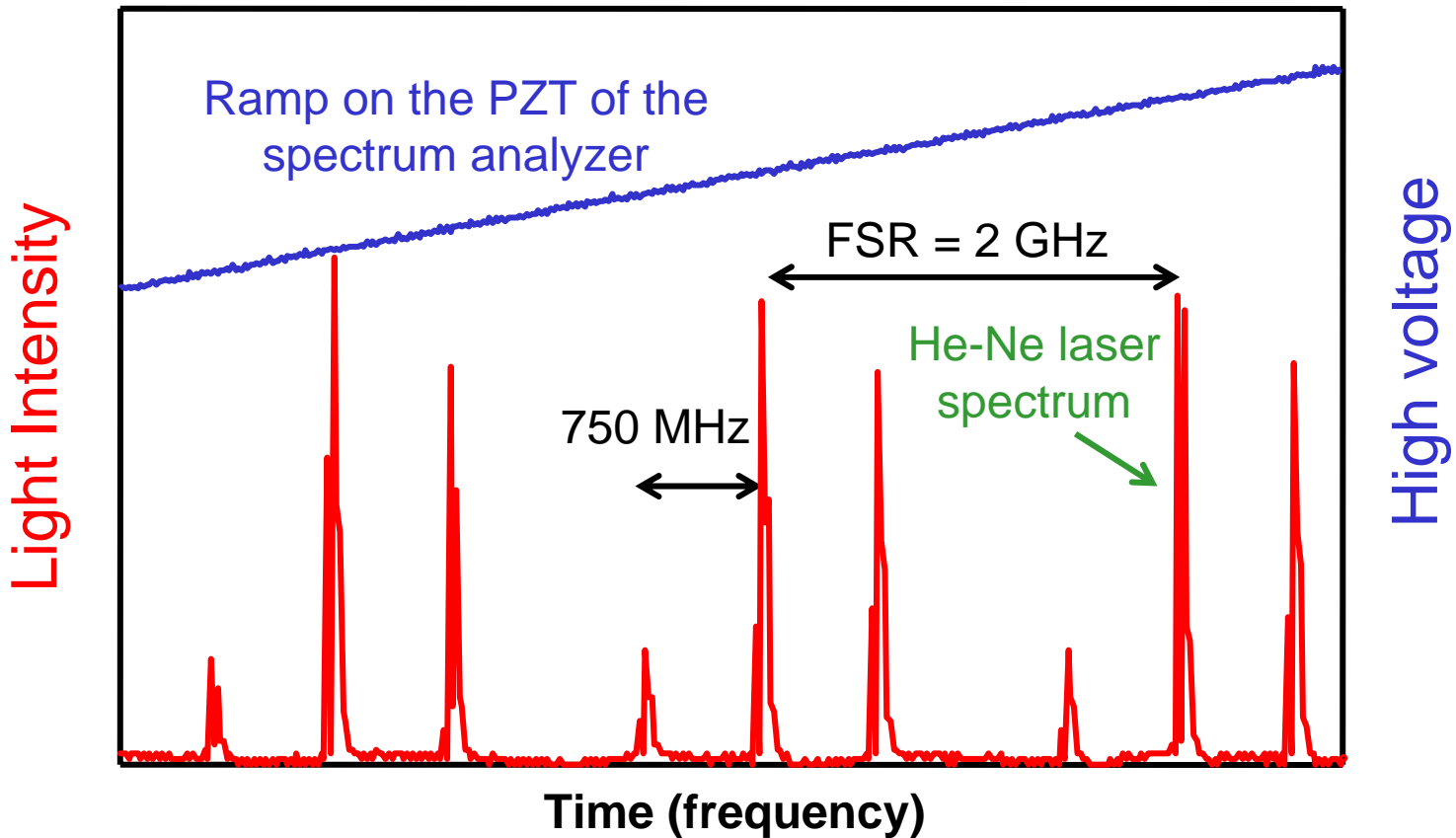
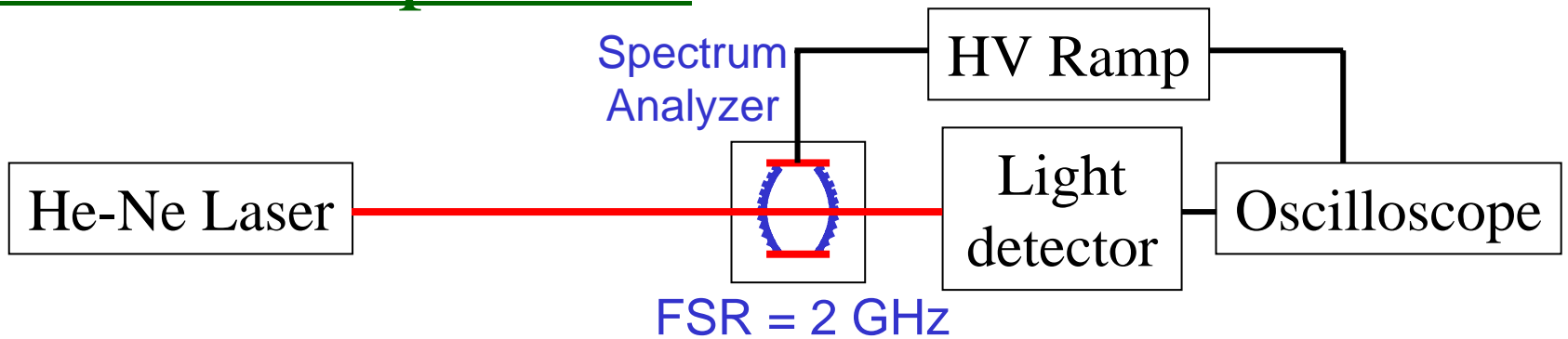
Not enough to our application

Very small signal

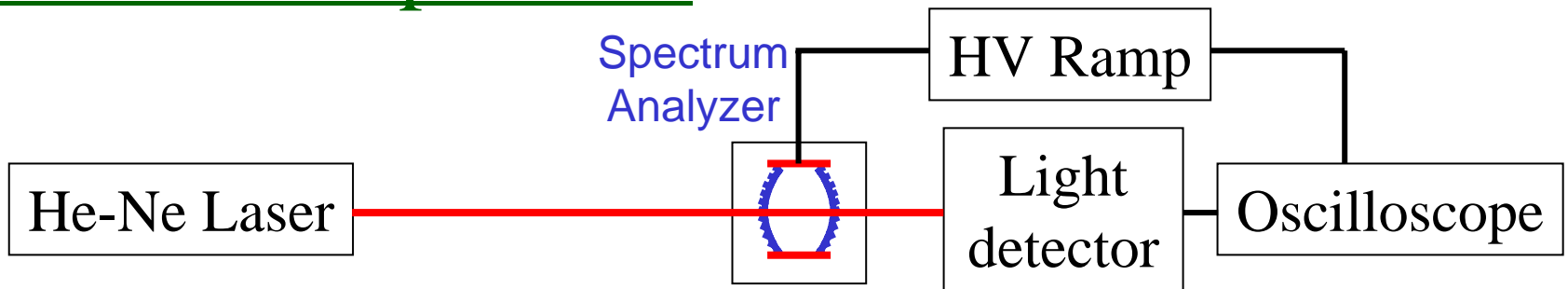


Typical surface displacements
 $\sim 1 \text{ nm}$

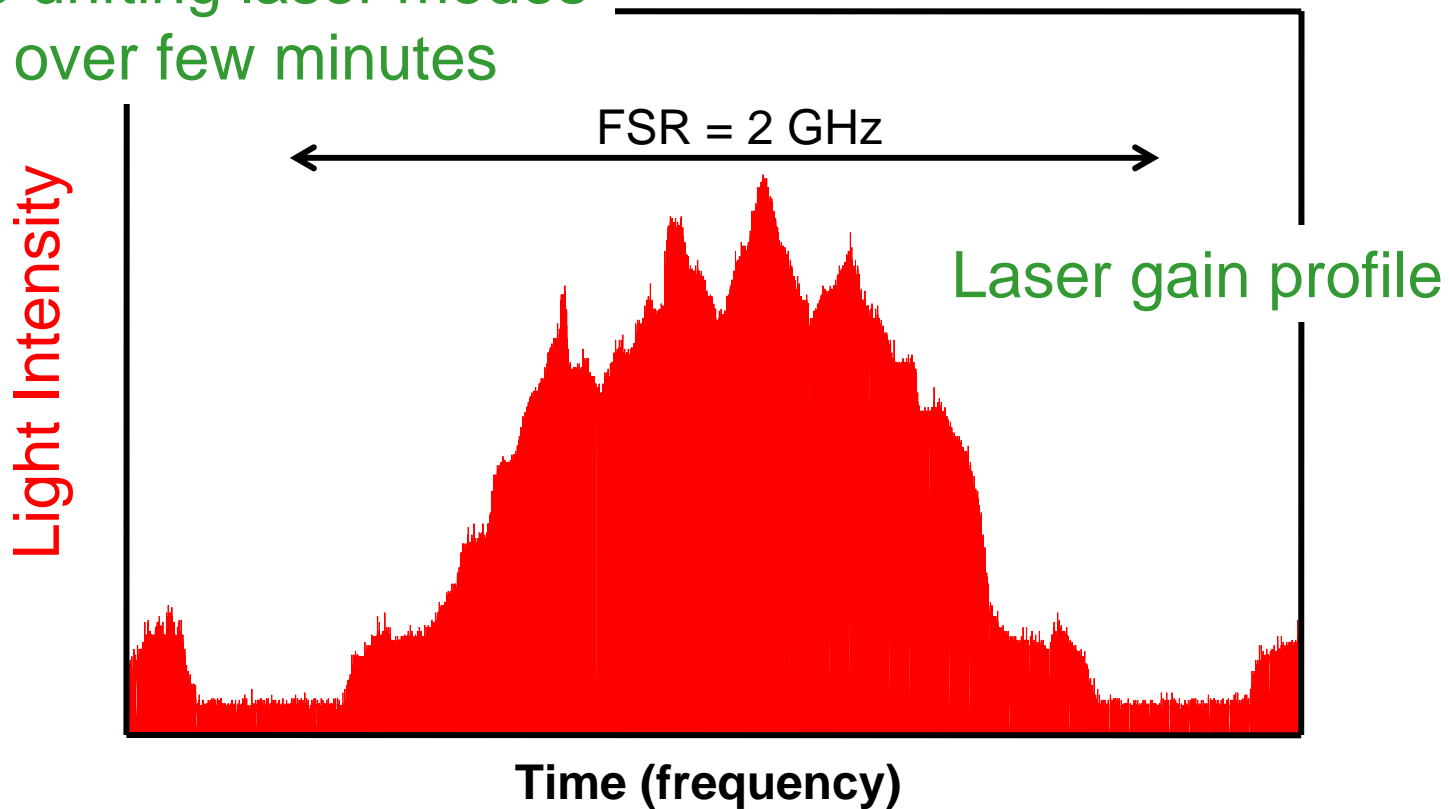
He-Ne laser spectrum



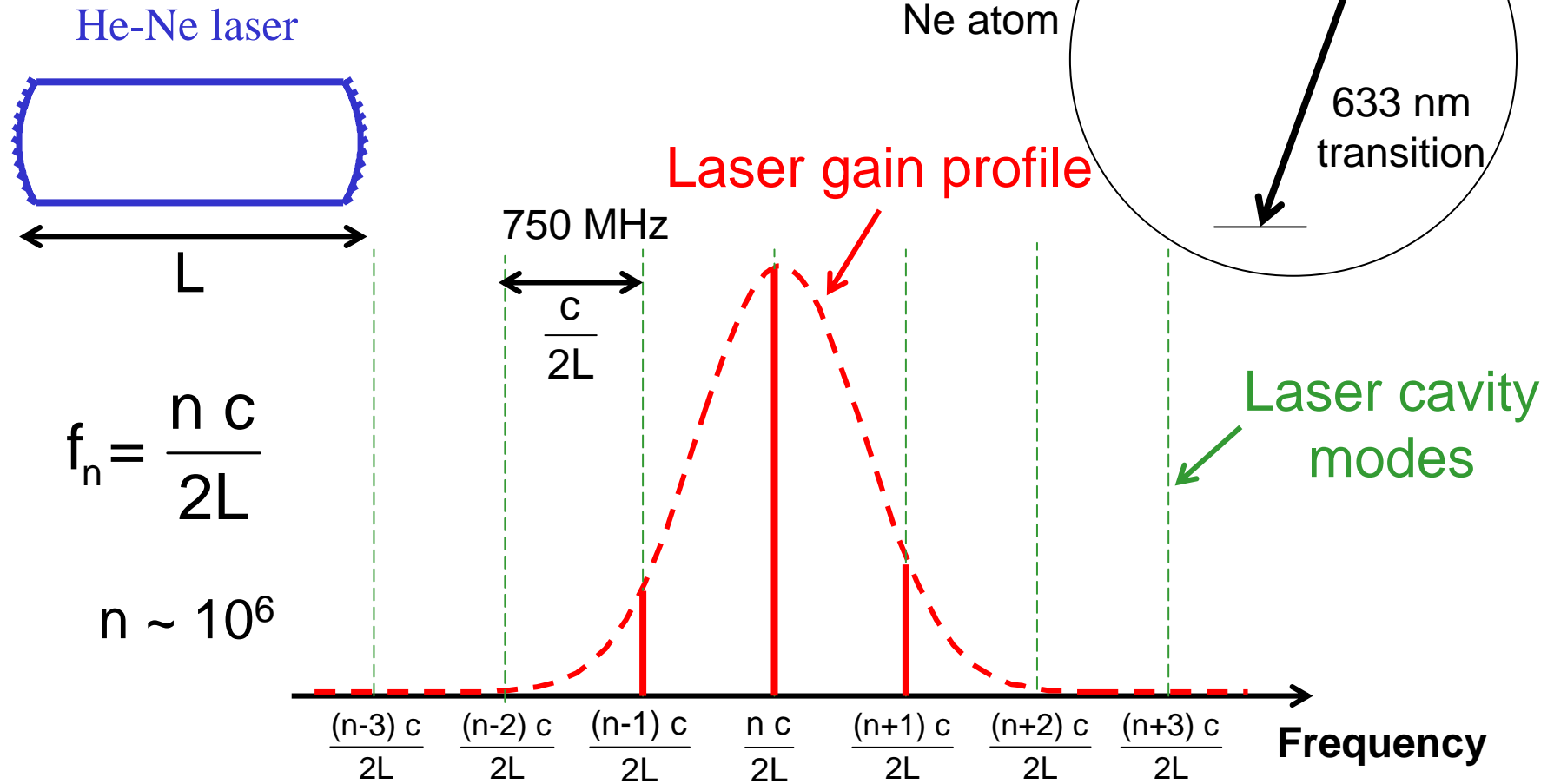
He-Ne laser spectrum



Accumulated traces of the drifting laser modes over few minutes



Why does the frequency drift?



Changes in the laser cavity length
cause frequency drifts

Changes in temperature and pressure

Estimate of temperature change

What ΔT that causes $\Delta f = 1$ MHz?

$$f_n = \frac{n c}{2L}$$

$$\frac{\Delta f_n}{f_n} = - \frac{\Delta L}{L} = \alpha \Delta T$$

For glass tube,
coefficient of linear expansion
 $9 \times 10^{-6} / \text{K}$

$$\Delta T \approx 0.25 \text{ mK}$$

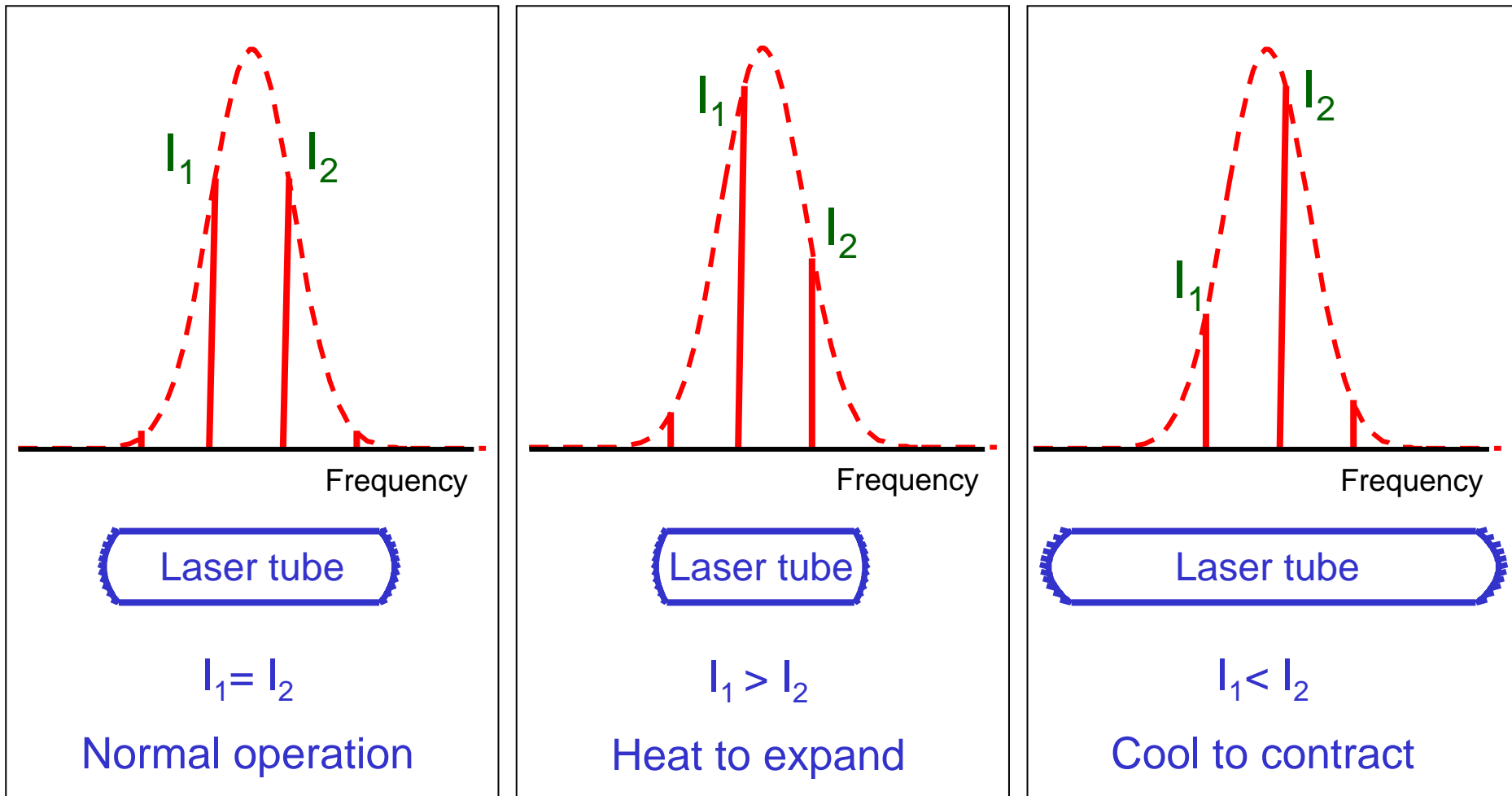
$$\Delta L \approx 1 \text{ nm} \quad \text{For a laser tube of 30 cm length}$$

Control the temperature of the laser tube
to better than 0.25 mK

Fortunately, there are many ways to do this!

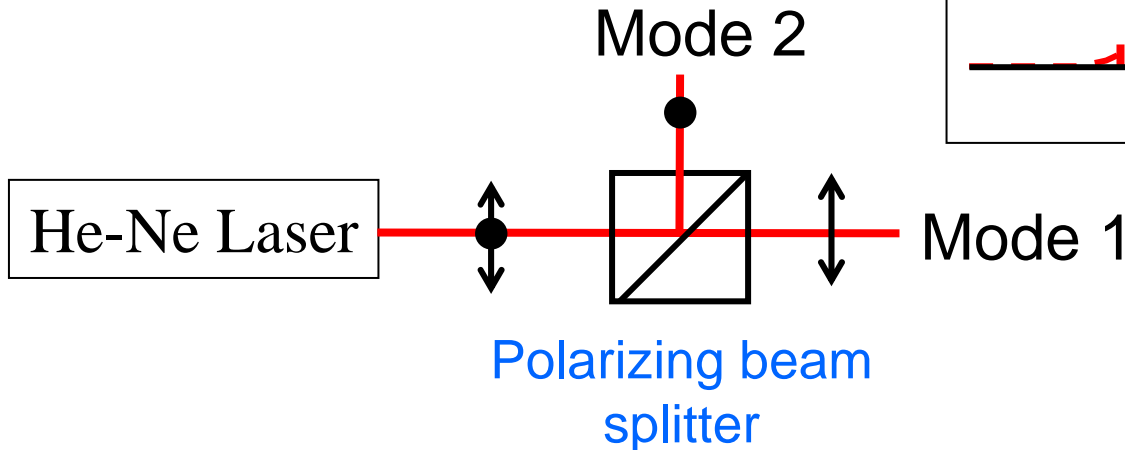
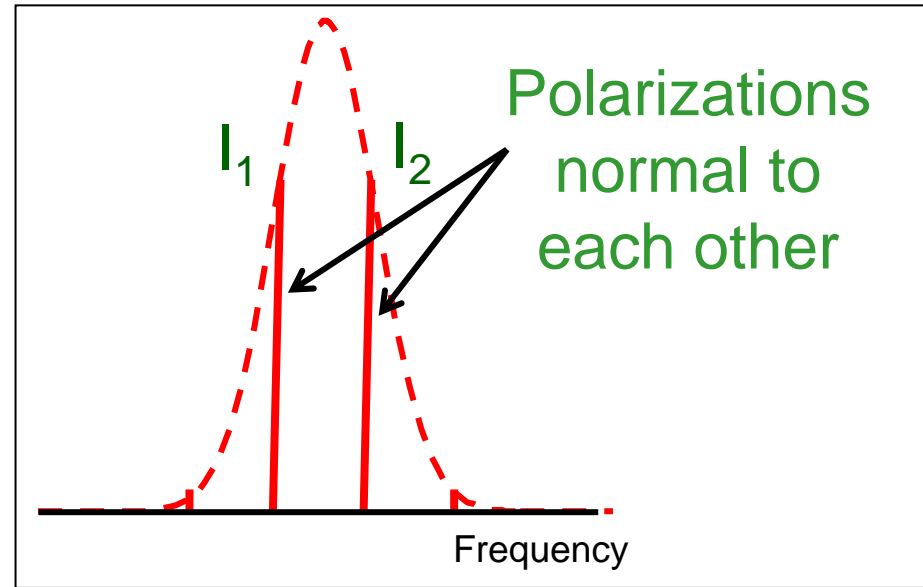
Stabilizing the laser

Compare the intensities of the two main modes



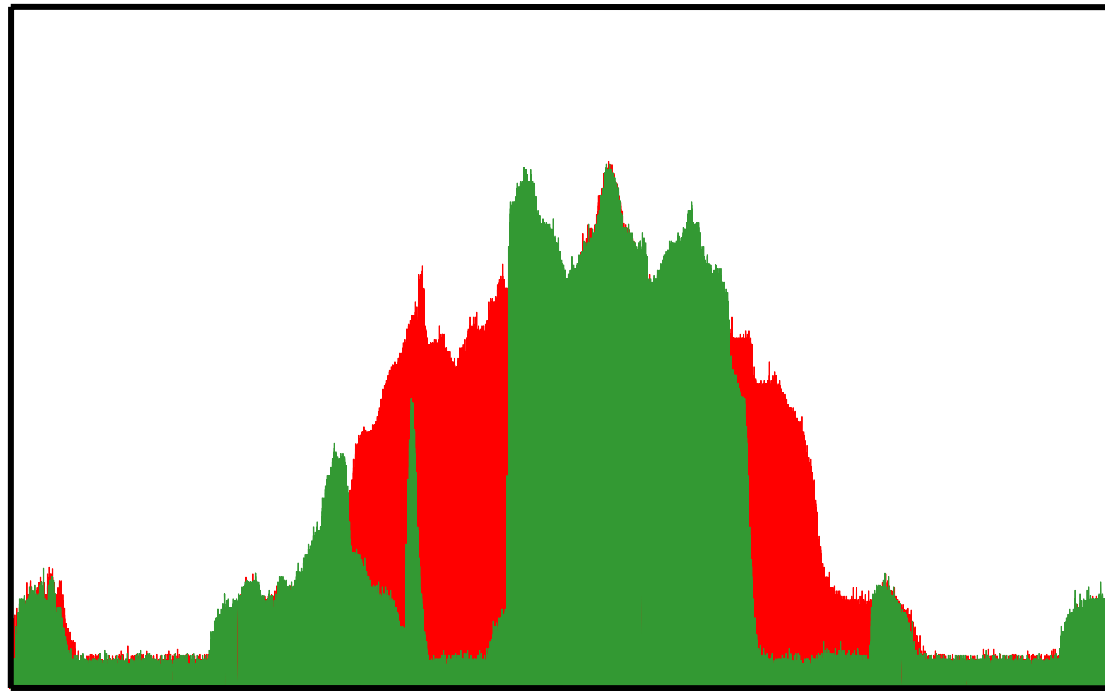
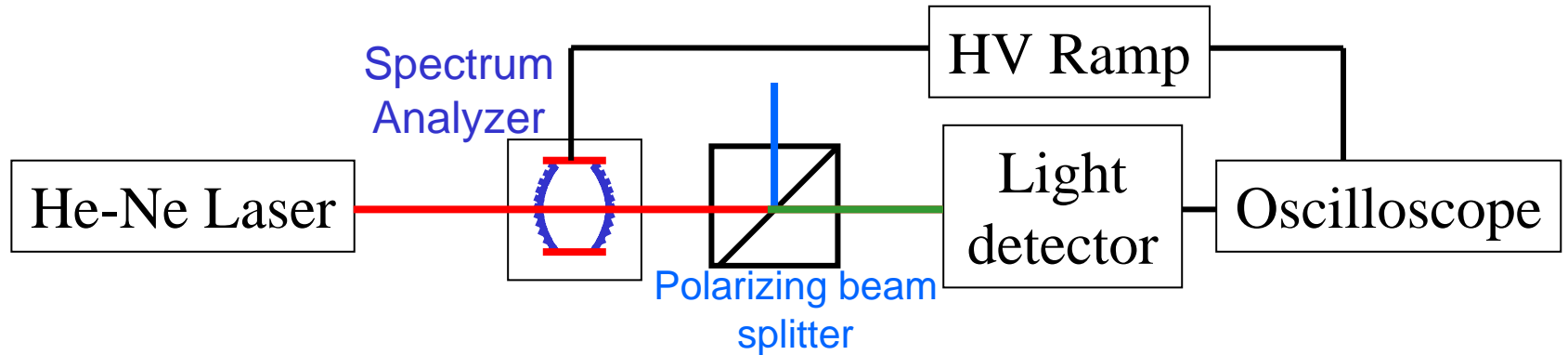
Stabilizing the laser

How to separate modes spatially?



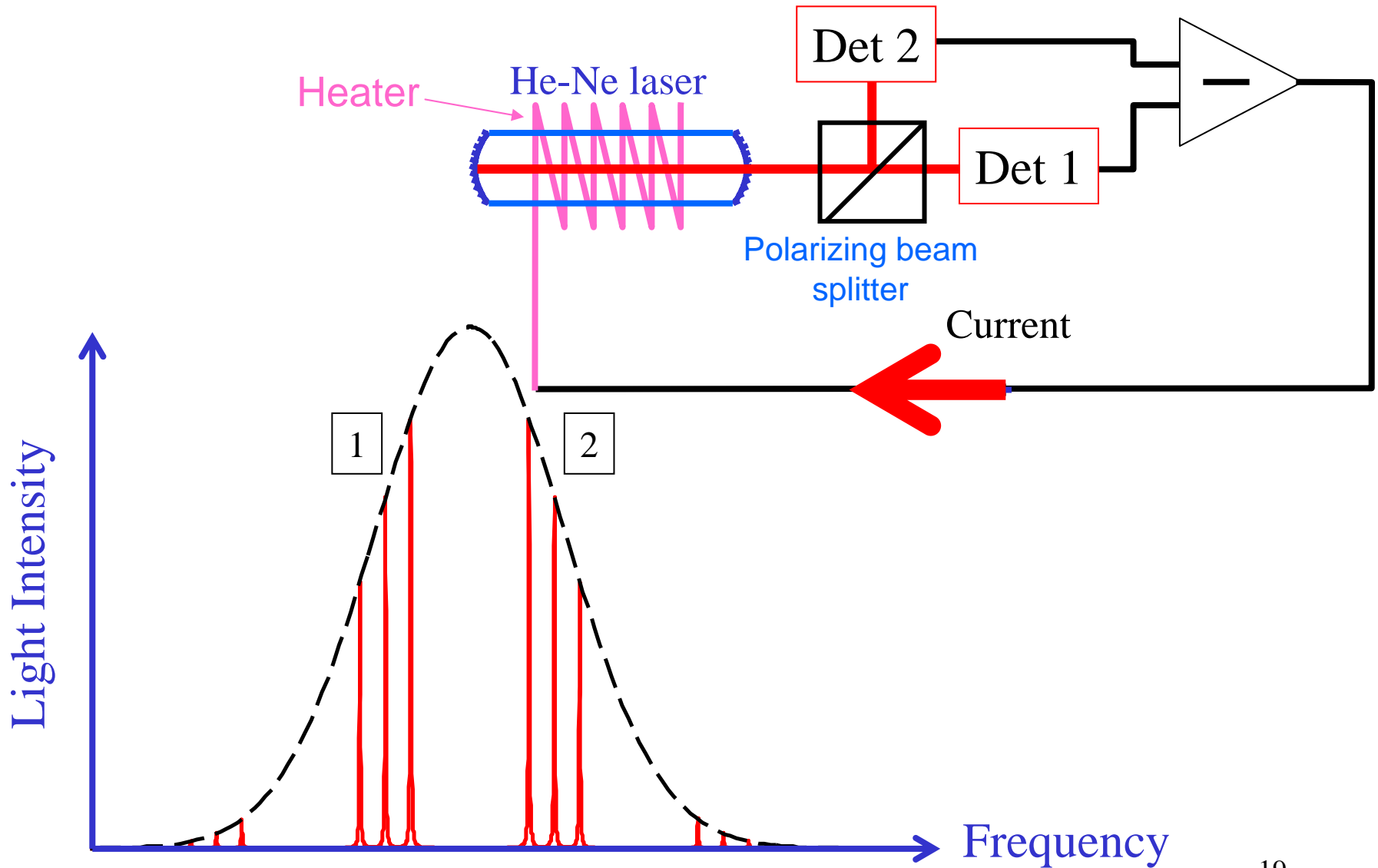
Stabilizing the laser

Polarization of laser modes

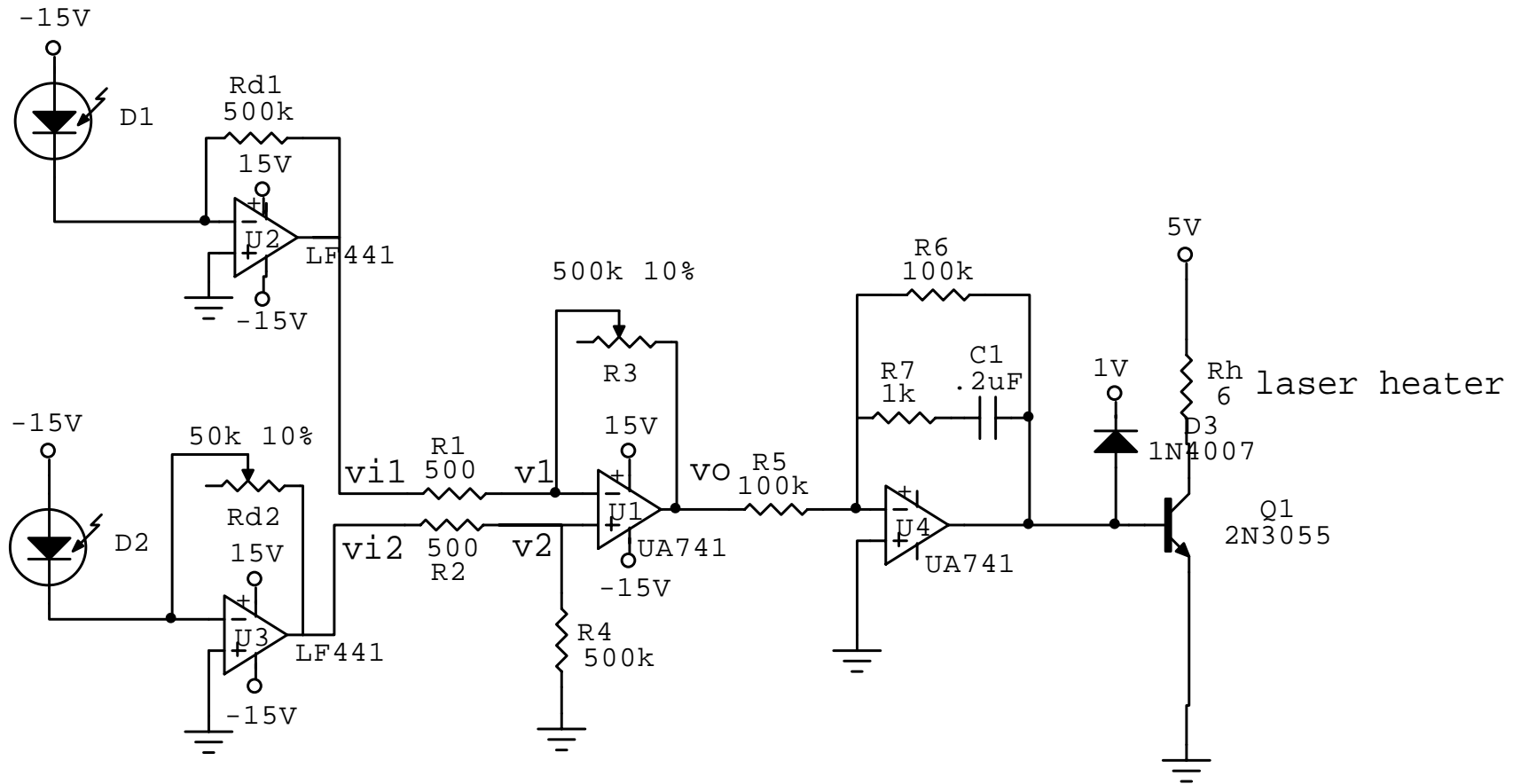


Frequency

Stabilizing the laser

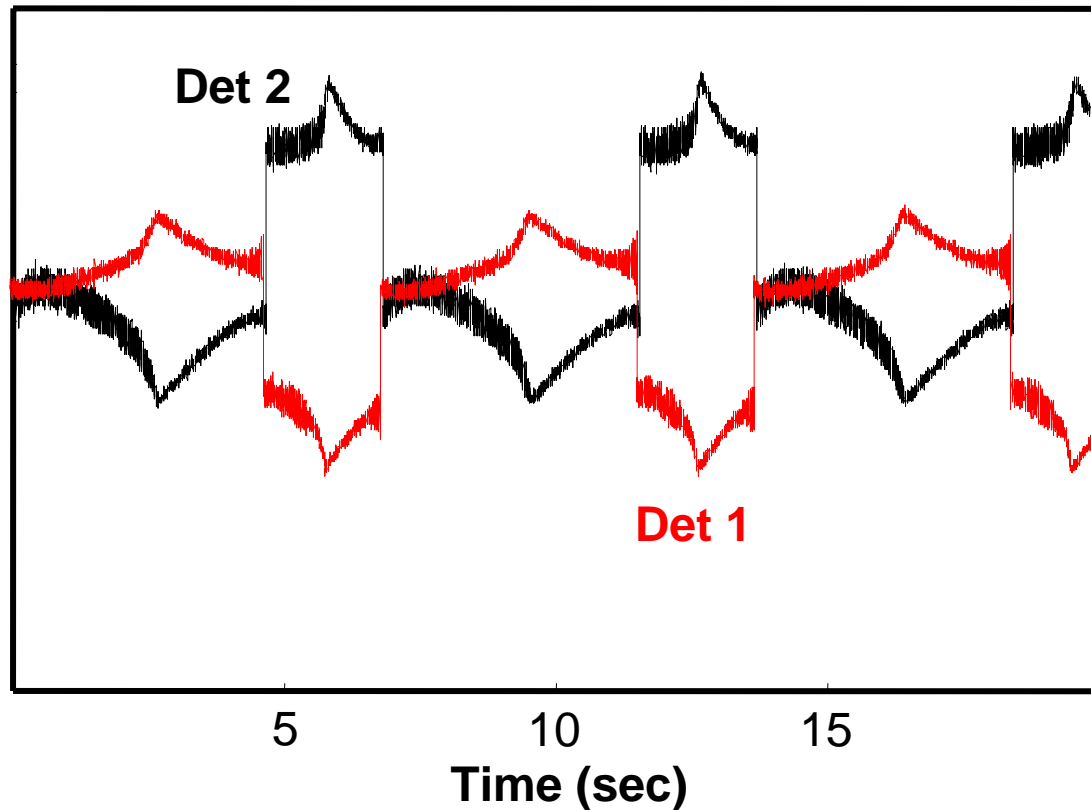
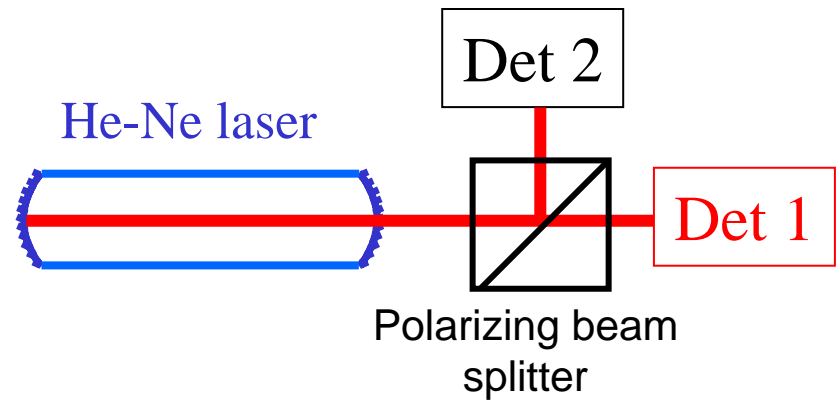


Laser stabilization Circuit



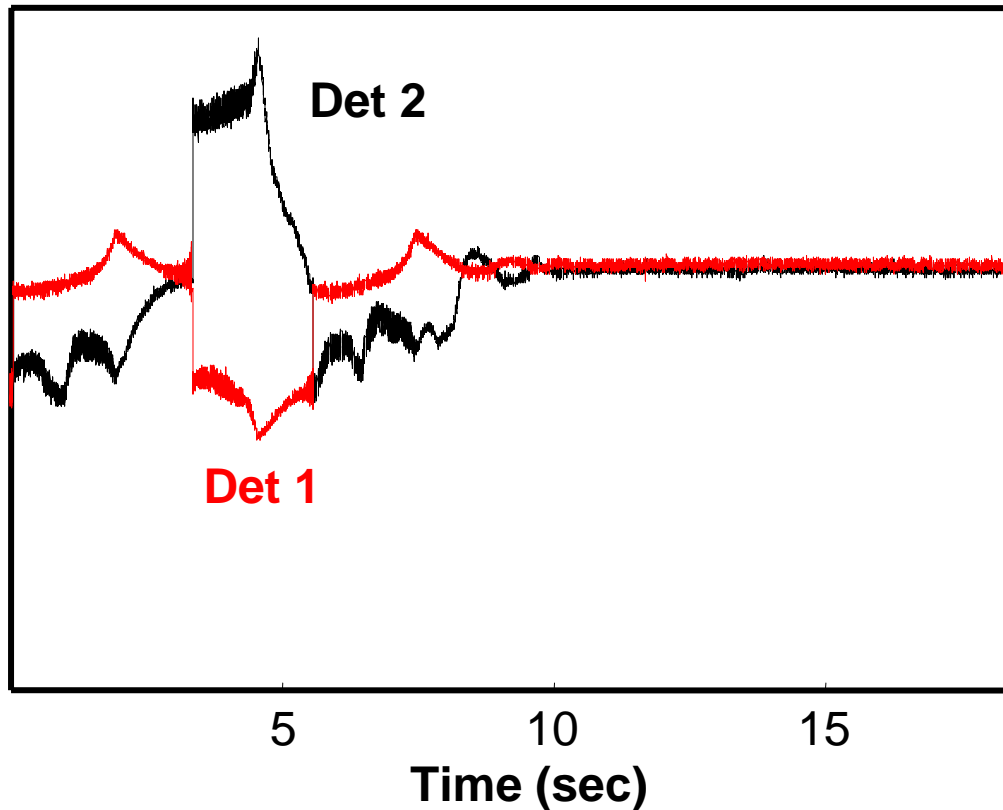
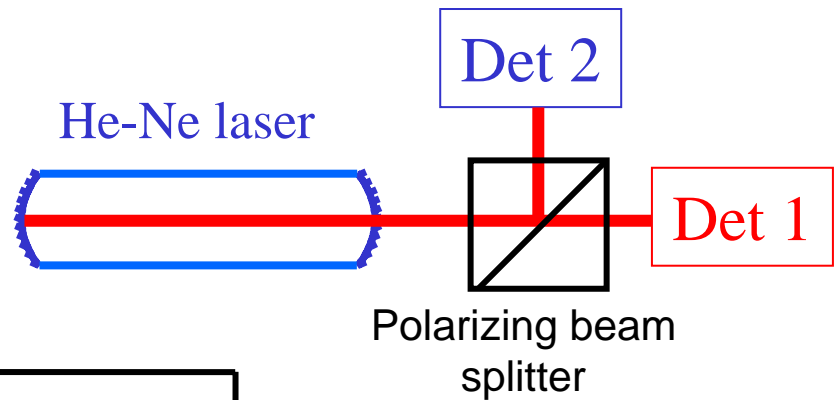
Stabilizing the laser

Stabilizing circuit is
not engaged



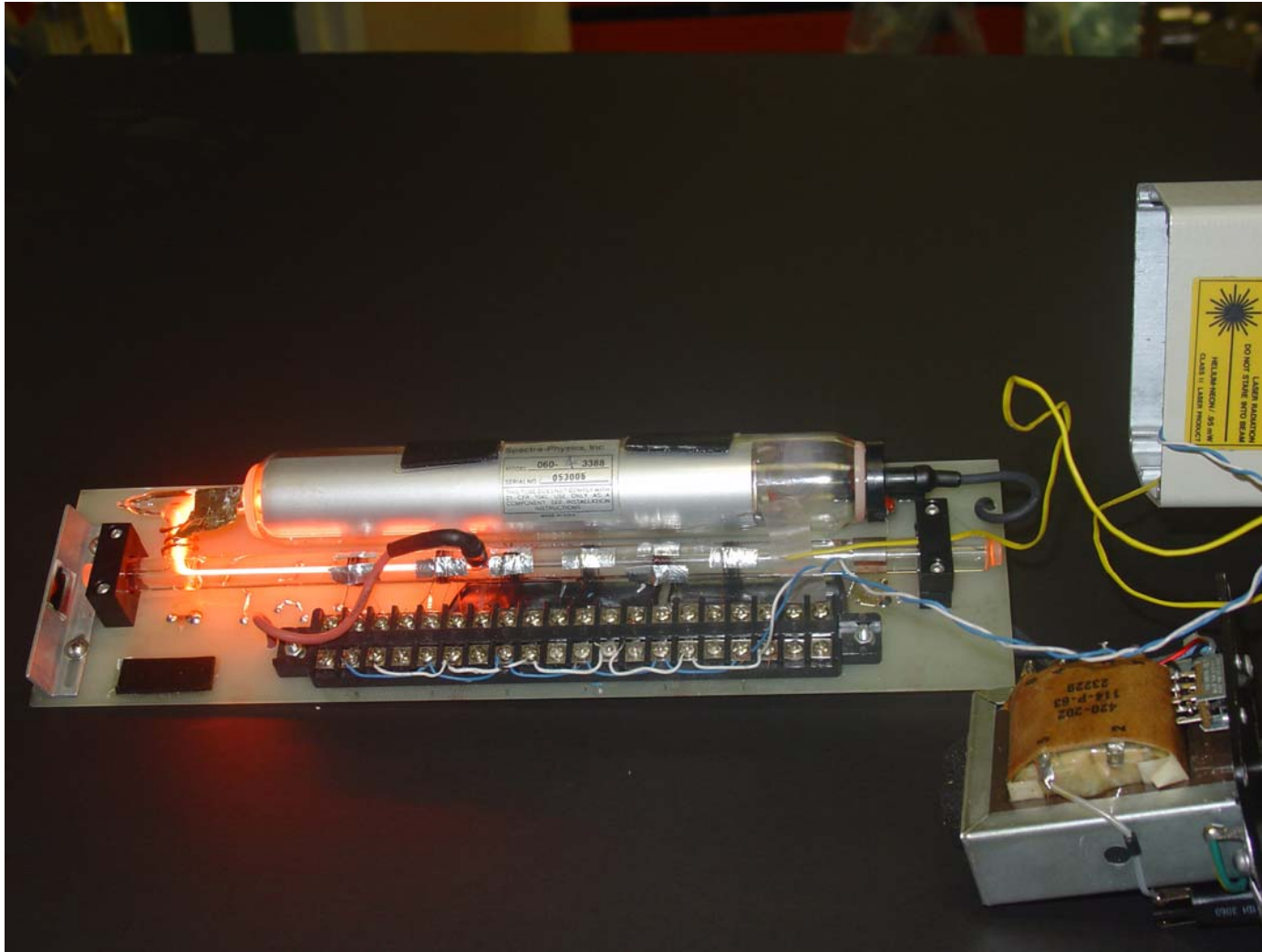
Stabilizing the laser

Stabilizing circuit is engaged



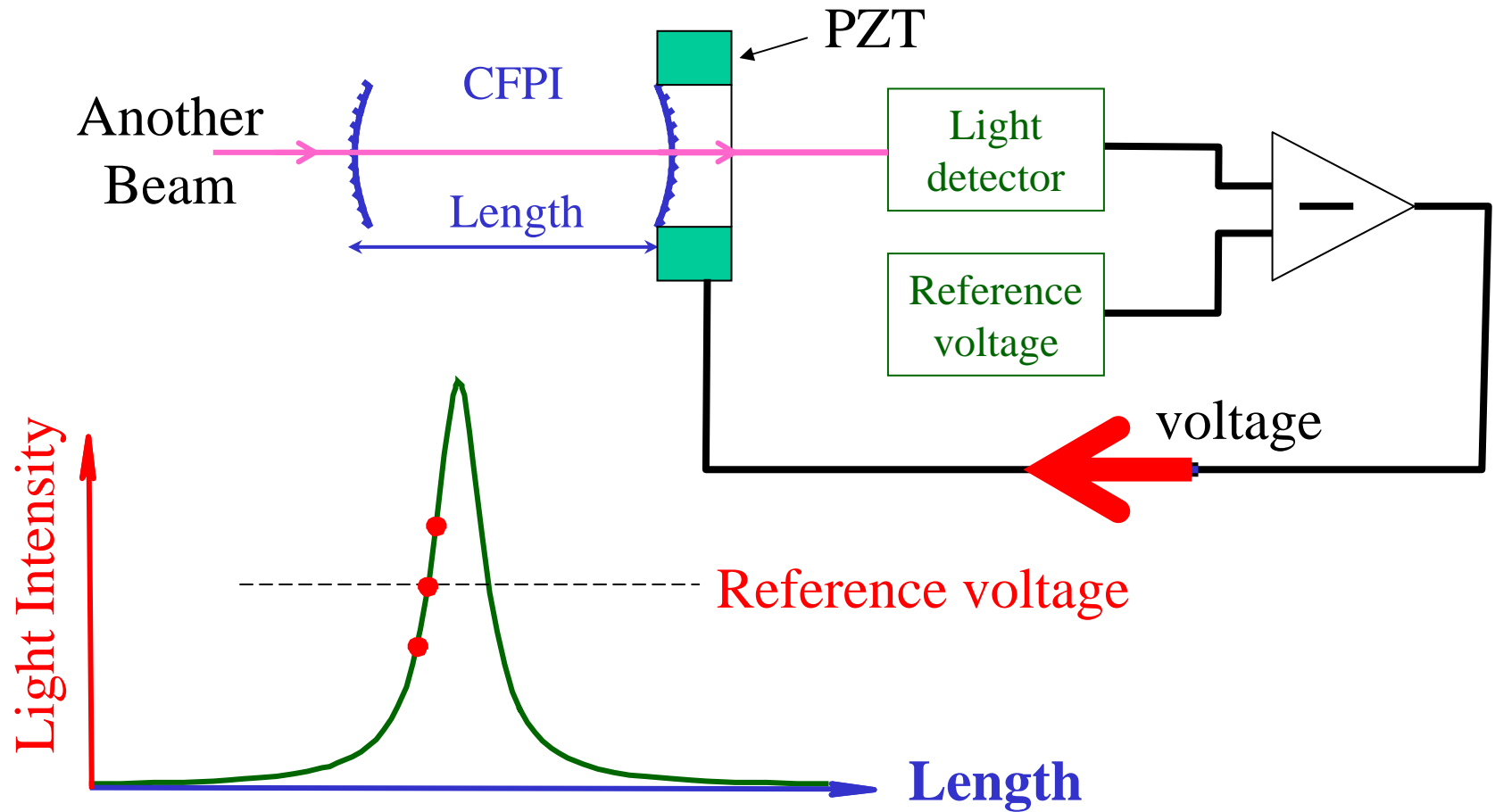
The He-Ne laser is stabilized to about 1 MHz

Stabilizing the laser

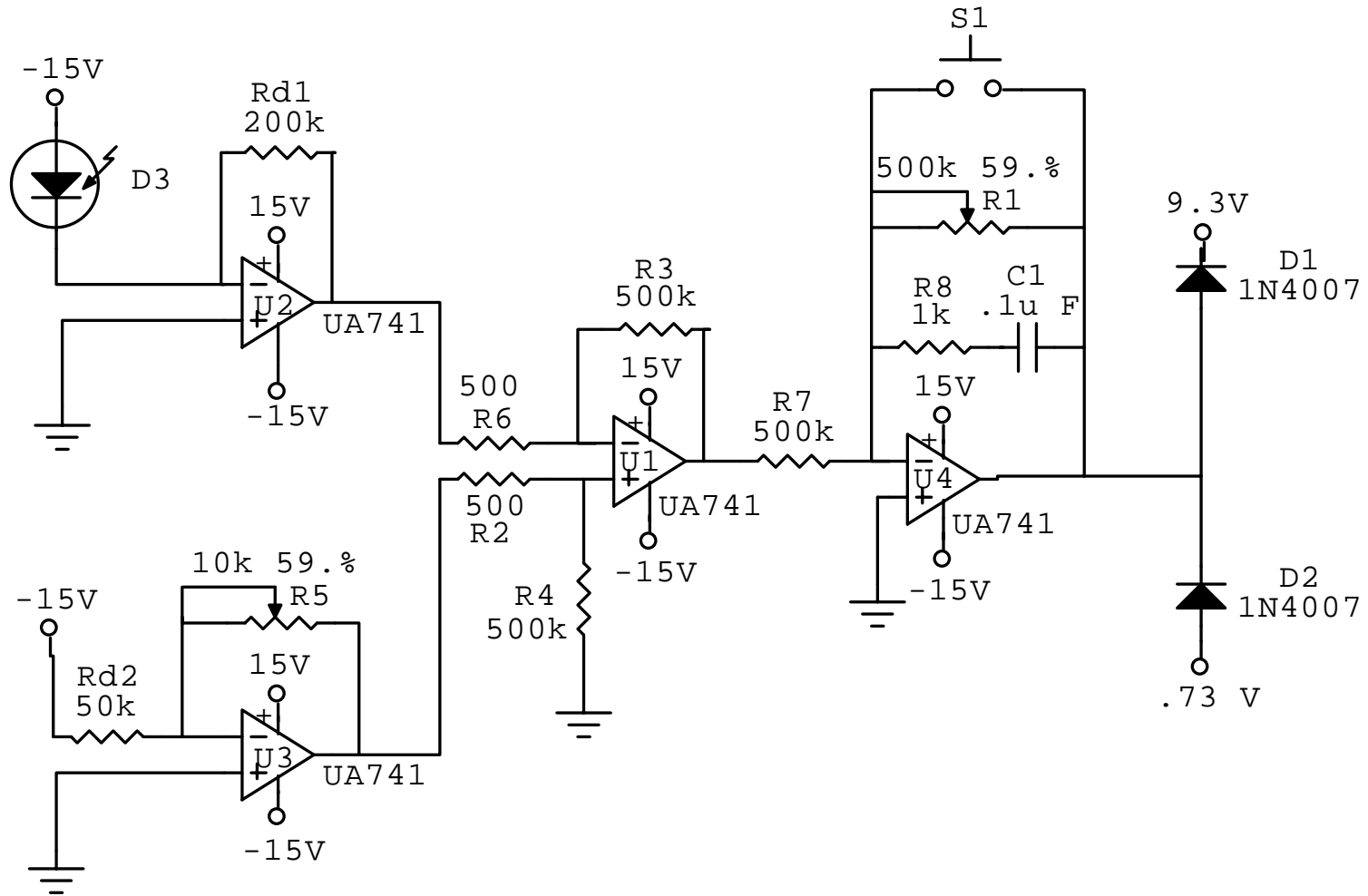


Locking CFPI to laser

Compare transmission to a reference voltage

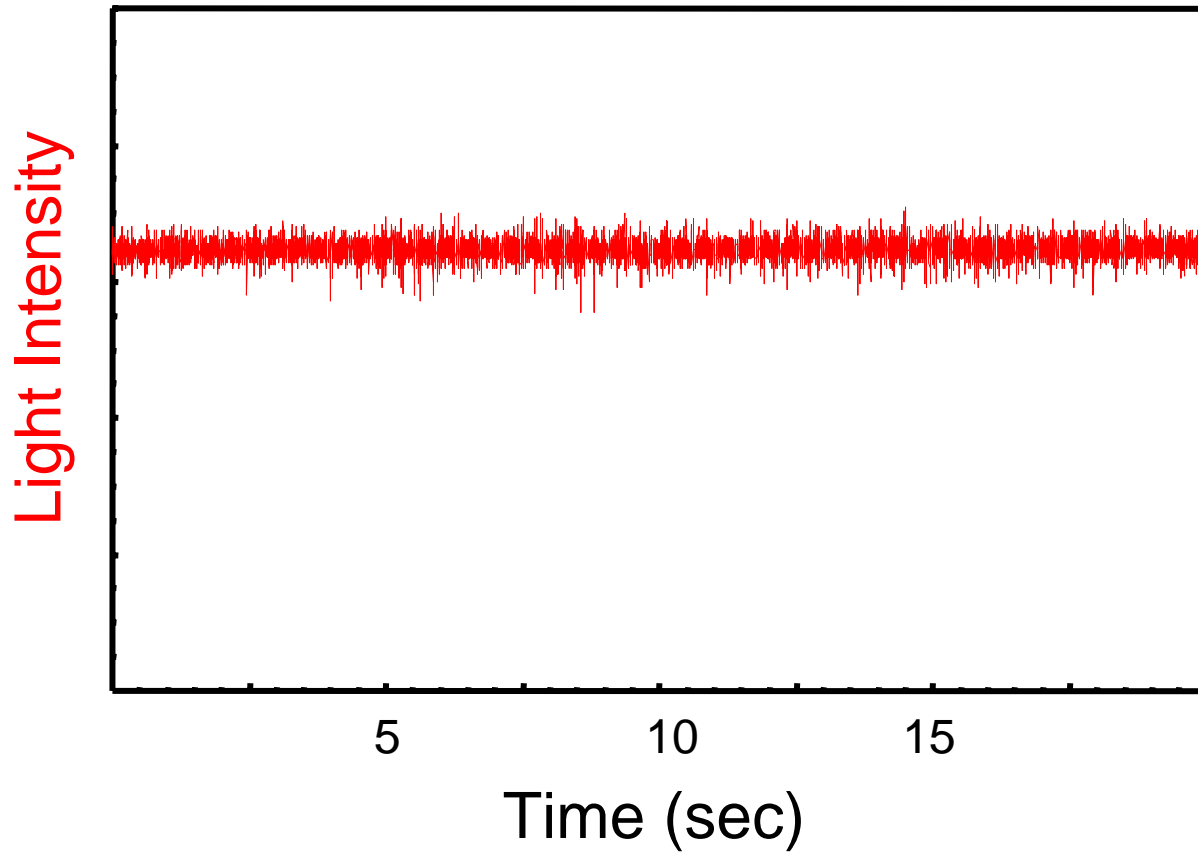


Locking CFPI to laser circuit

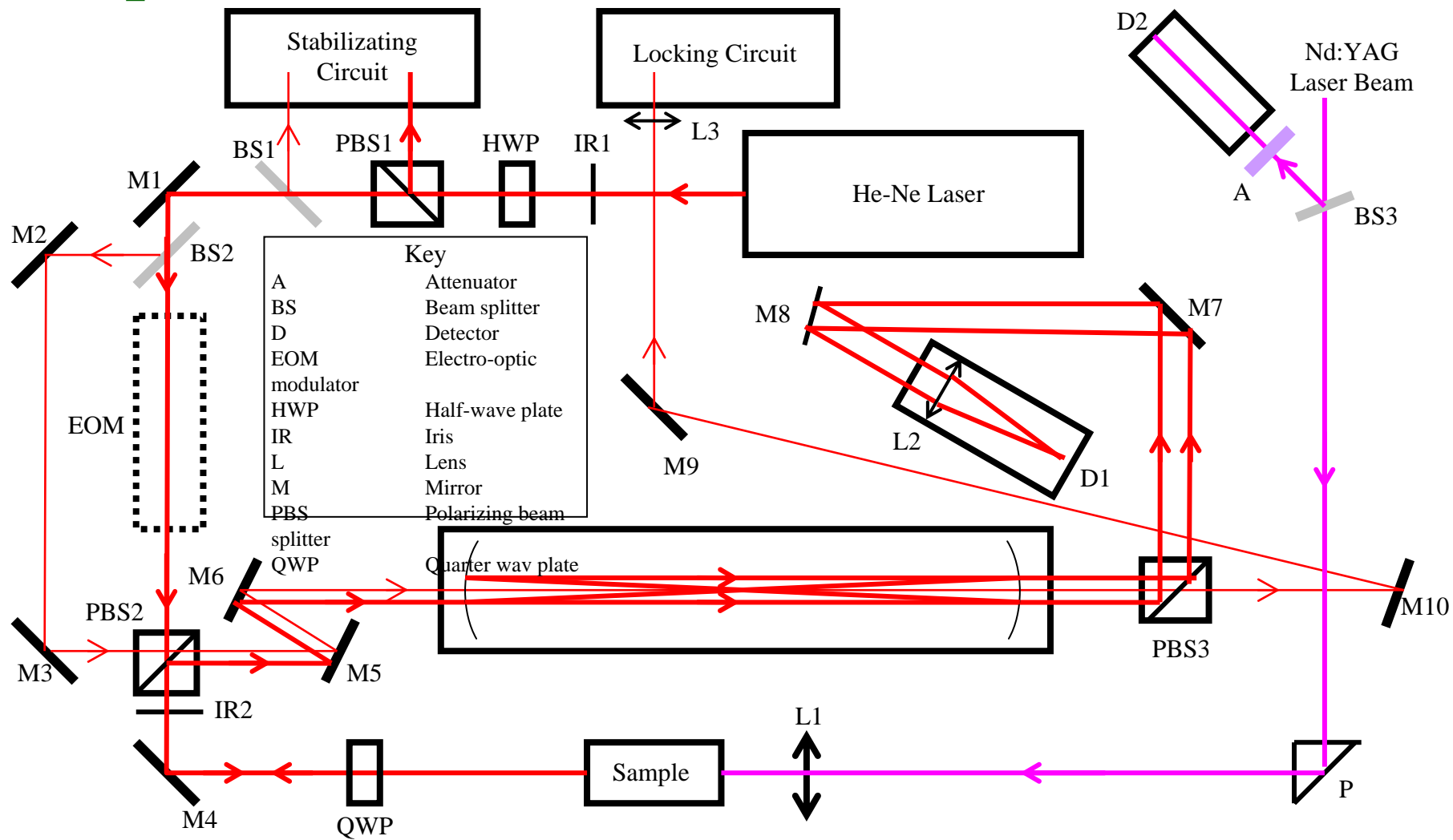


Locking CFPI to laser

Transmission of CFPI when it is locked to the laser



Setup



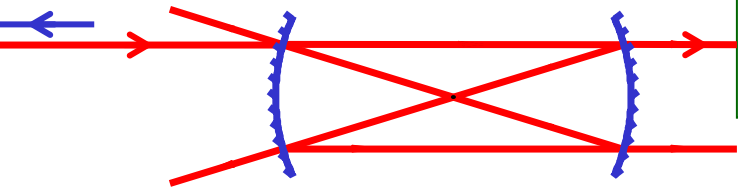
Response

$$x = A \sin(2\pi f_u t)$$

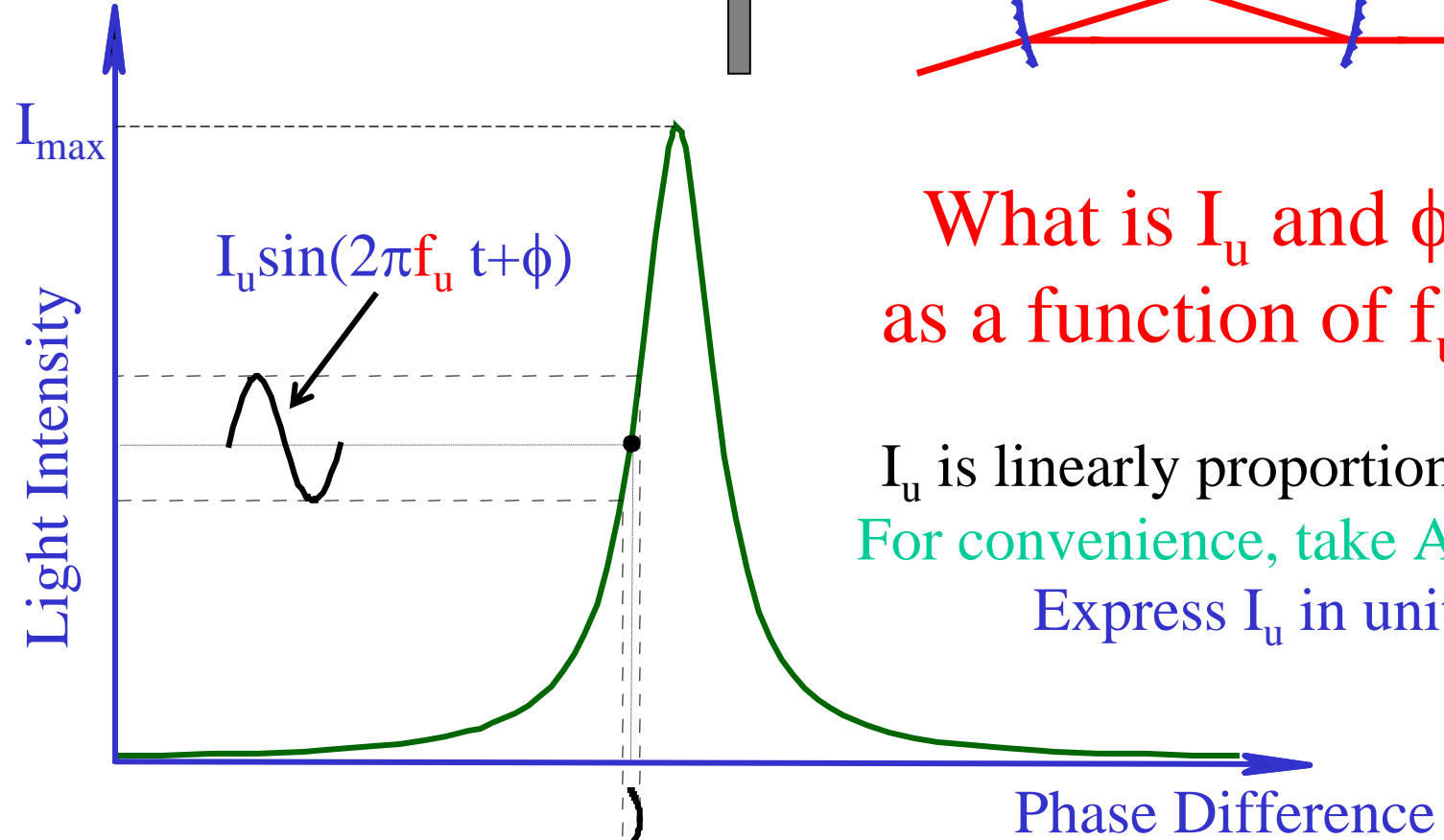
1 nm
surface



CFPI



Light detector



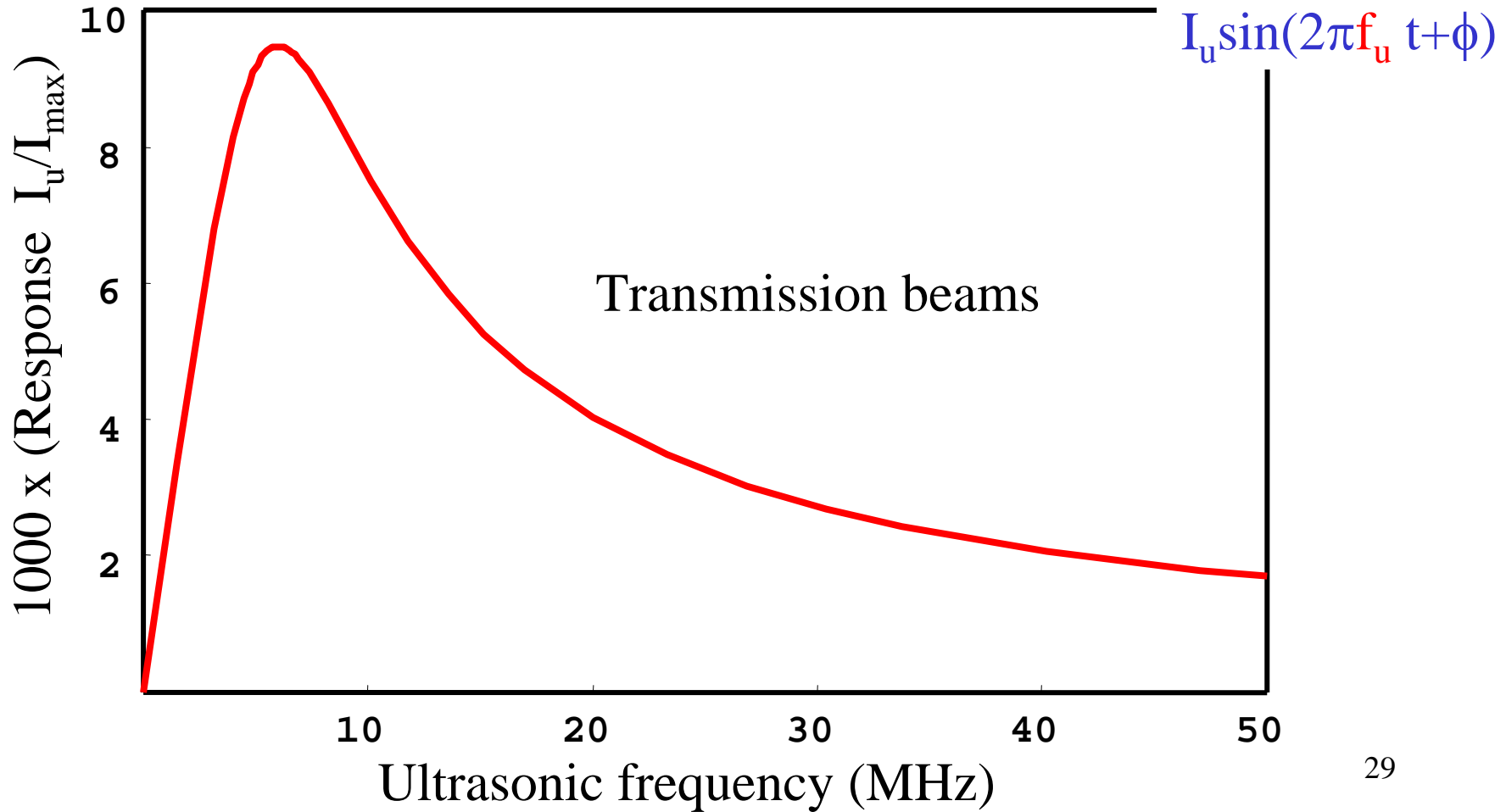
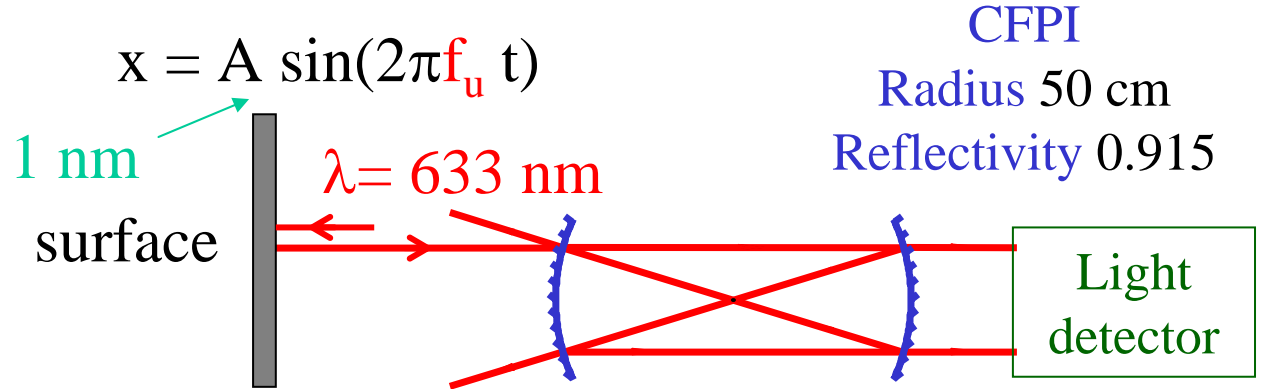
What is I_u and ϕ as a function of f_u ?

I_u is linearly proportional to A
 For convenience, take $A = 1 \text{ nm}$
 Express I_u in units of I_{\max}

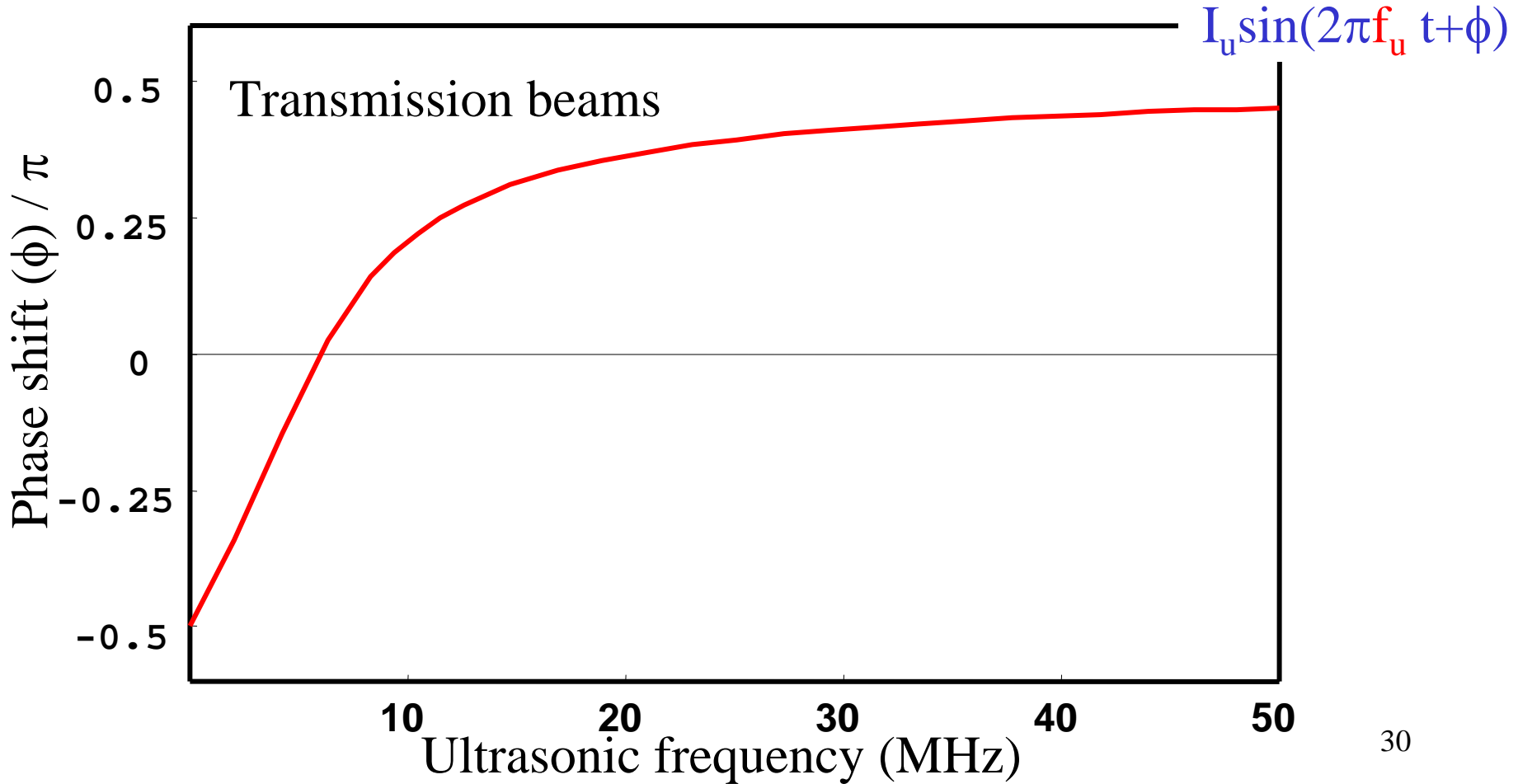
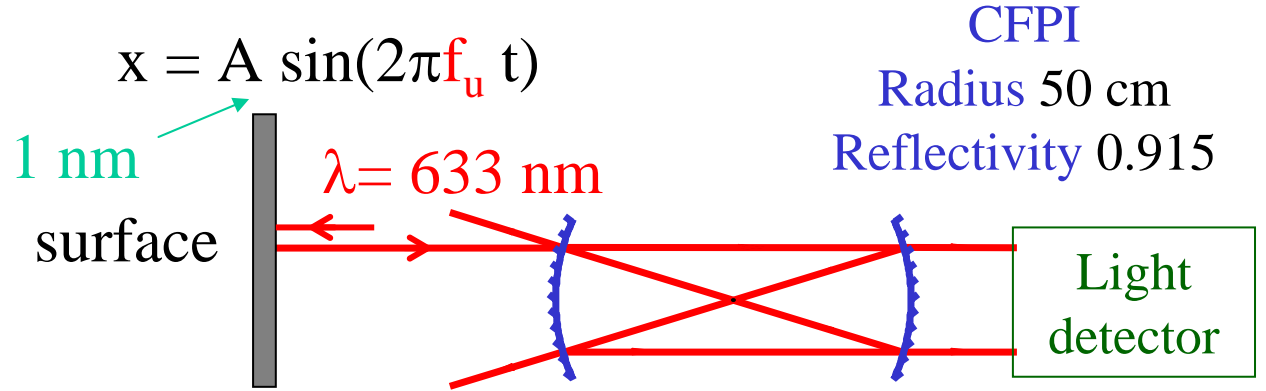
$$\frac{2 f 4L}{c}$$

Shifts caused by ultrasound

Response



Response



Calibration

$$x=A \sin(\omega_u t)$$

Specimen

Laser

EOM

$$V=V_0 \sin(\omega_m t)$$

CFPI

Fast Light
Detector

Ultrasound
modulation

$$E=E_0 \sin(kz-\omega t+ \frac{4\pi}{\lambda} A \sin(\omega_u t))$$

EOM
modulation

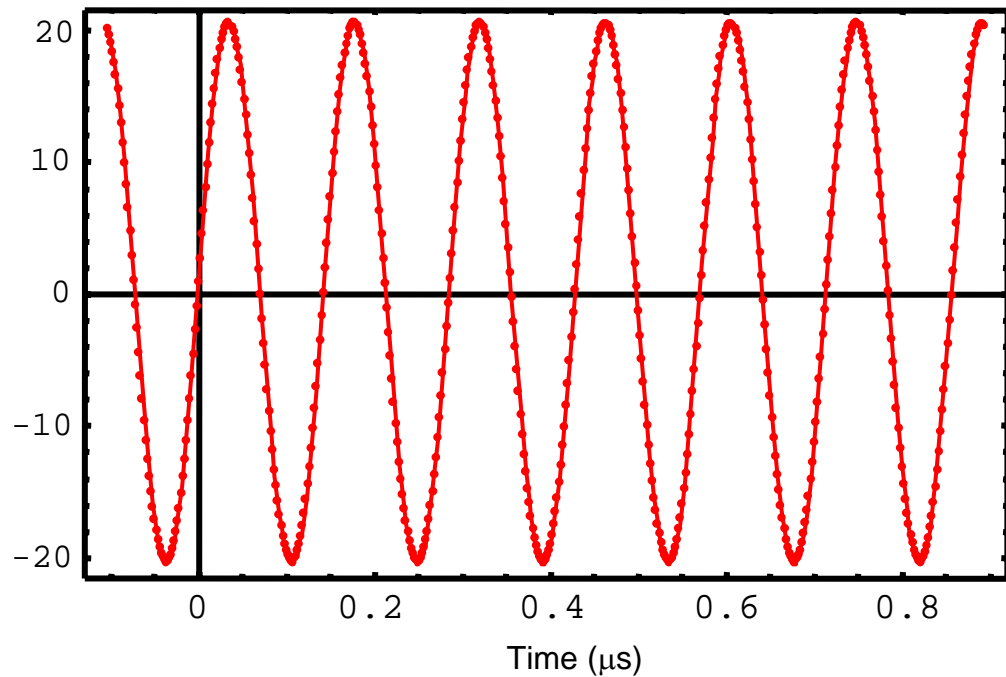
$$E=E_0 \sin(kx-\omega t+ \frac{\pi}{2} \frac{V_0}{V_\pi} \sin(\omega_m t))$$

$$A = \frac{\lambda}{8} \frac{V_0}{V_\pi}$$

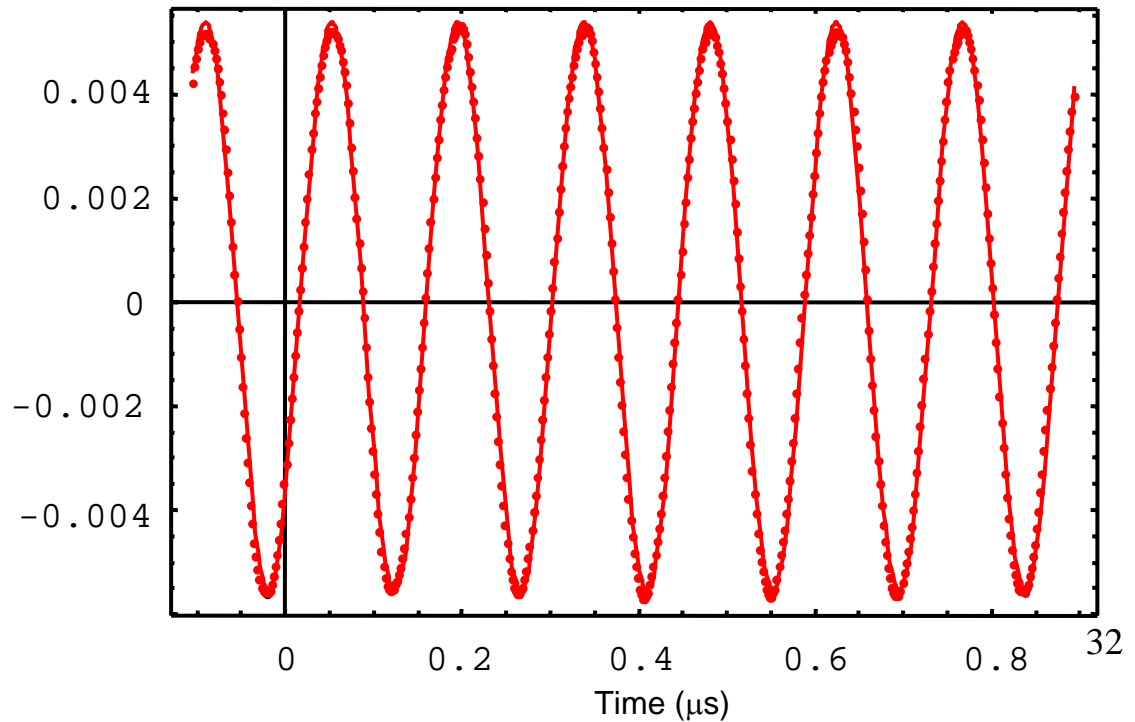
Half-wave voltage for
our EOM $V_\pi=230 \text{ V}$

Calibration

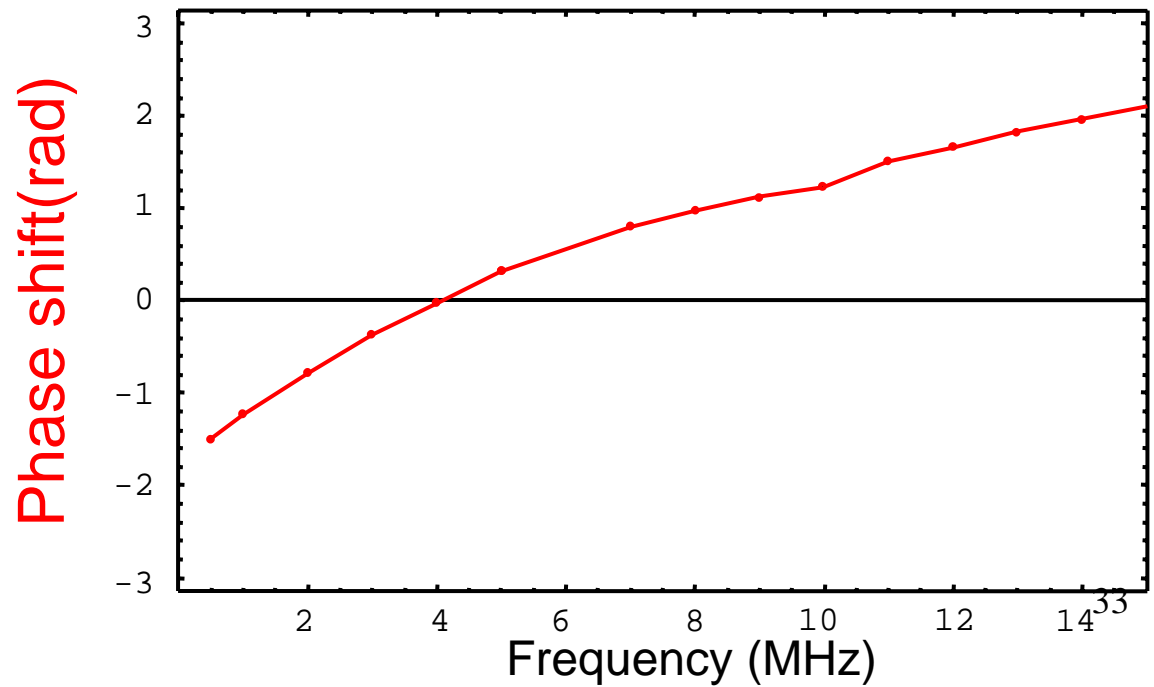
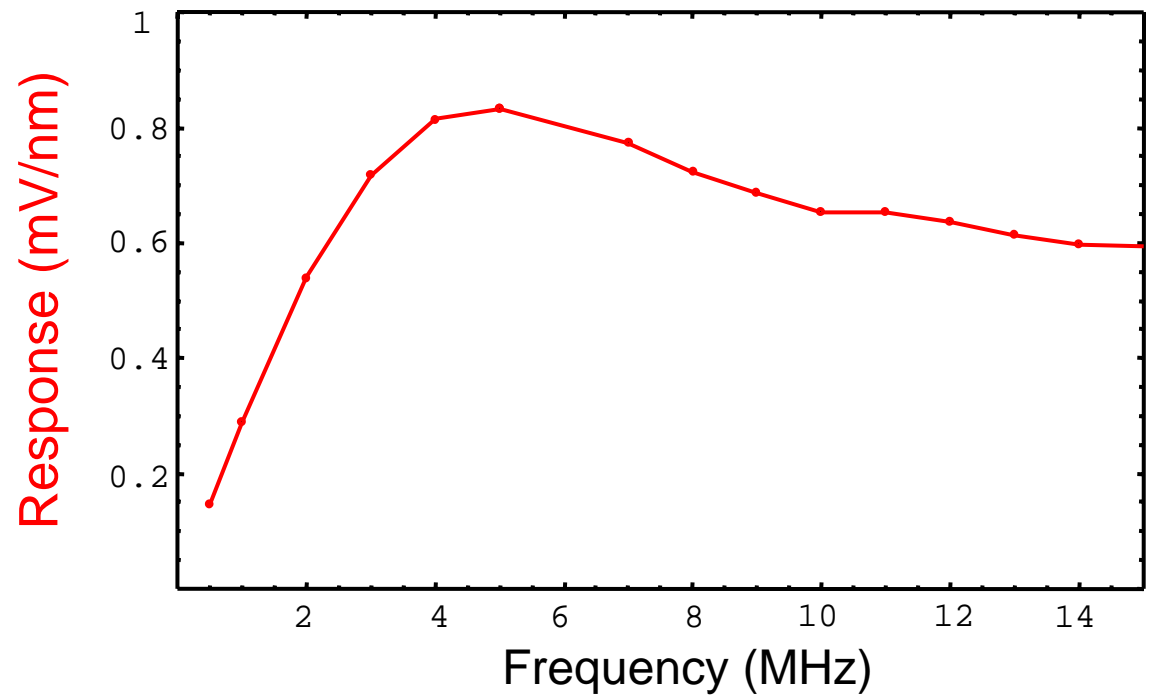
Signal fed to
the EOM



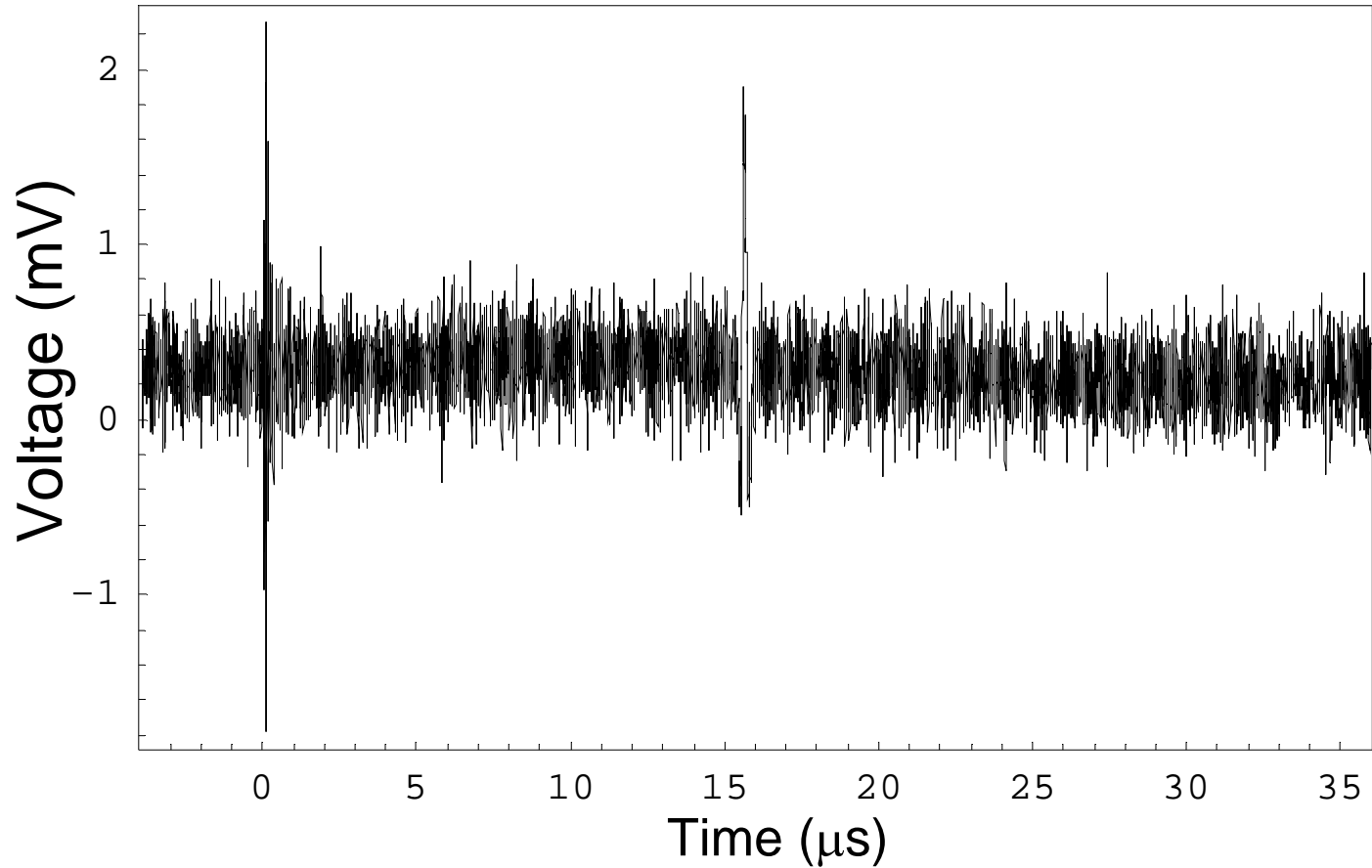
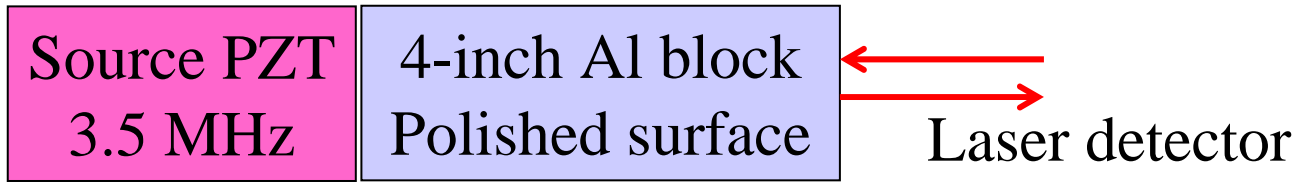
Signal
detected by
our detector



Calibration

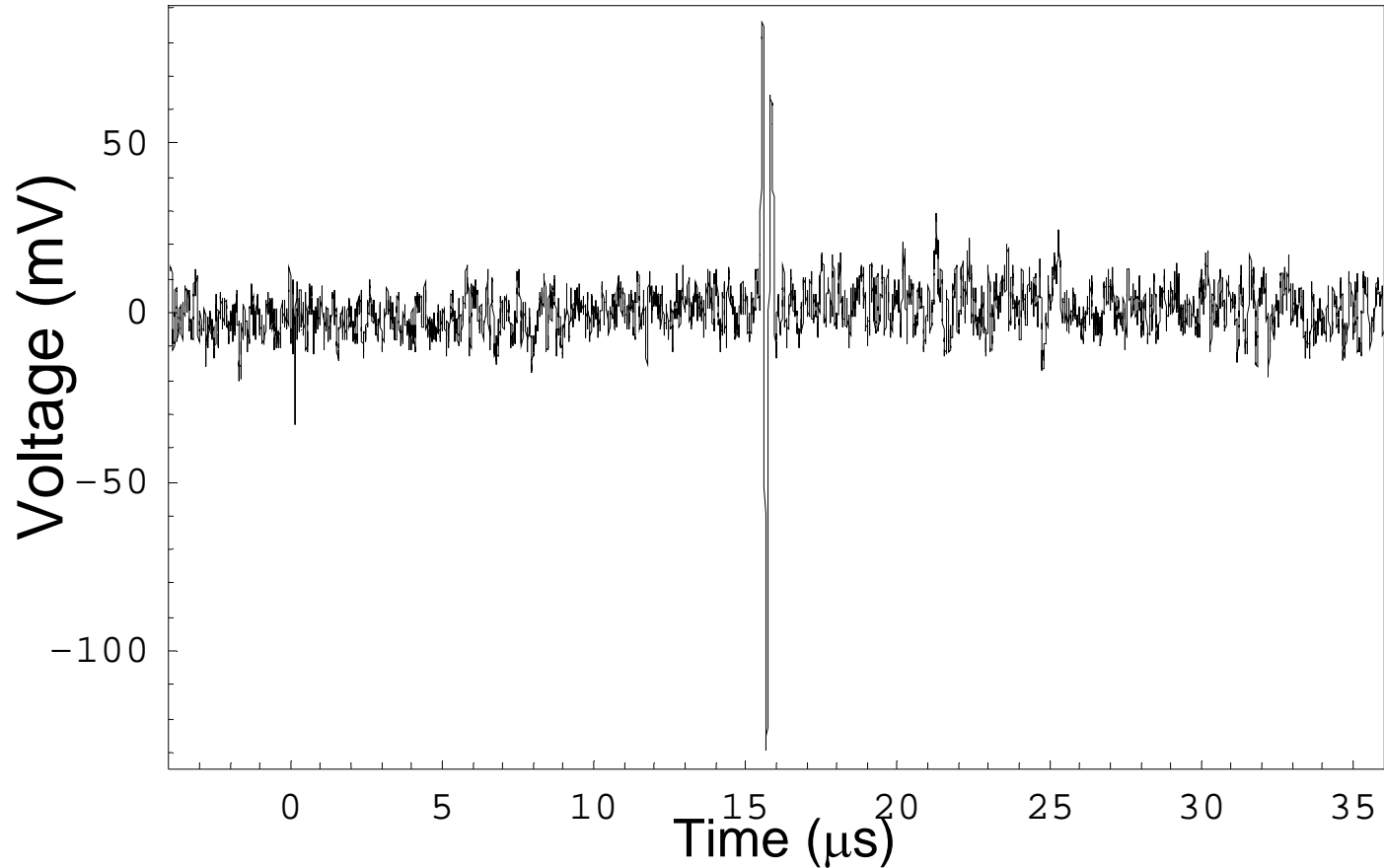
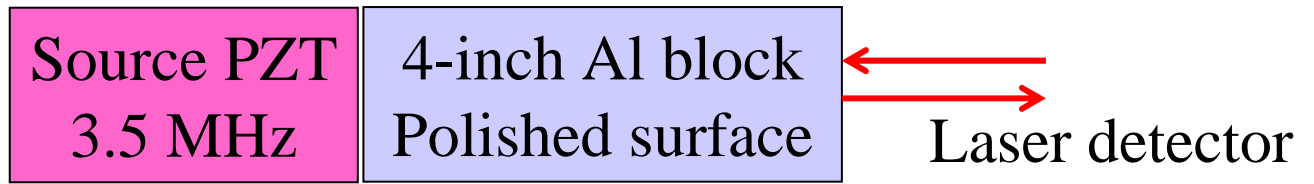


Testing



Averaged over 128 traces

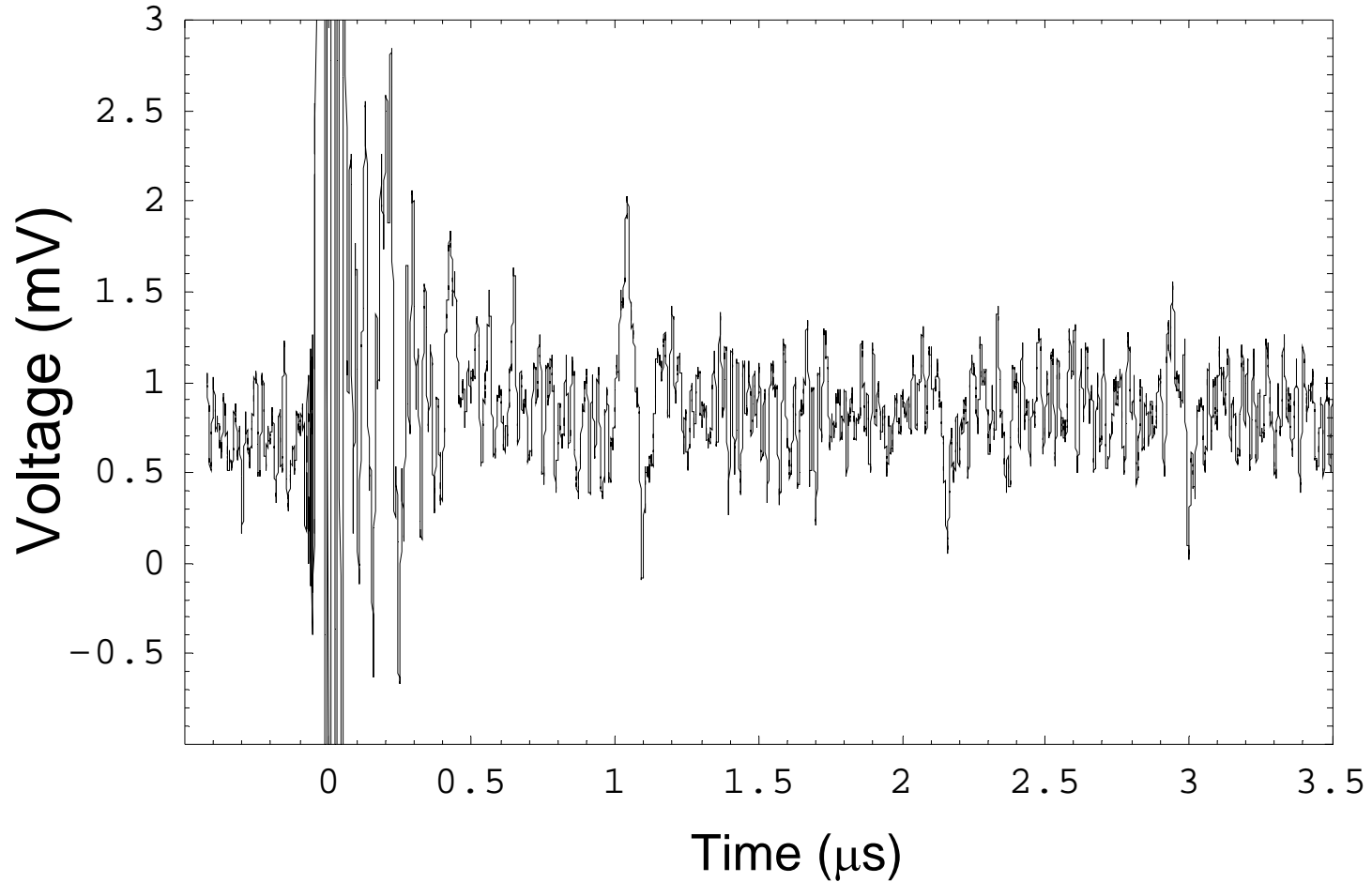
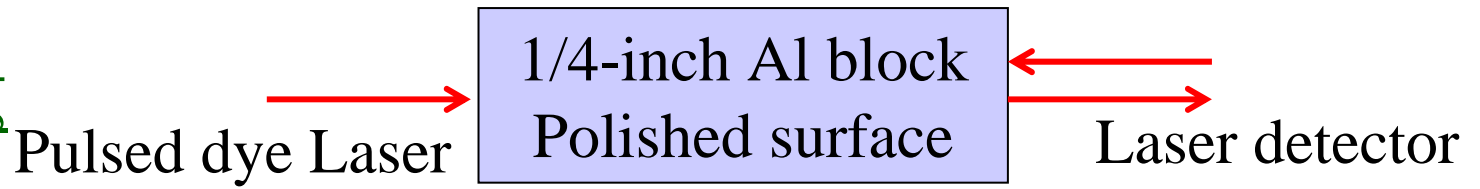
Testing



Extra amplifier gain = 50 V/V

Averaged over 128 traces

Testing

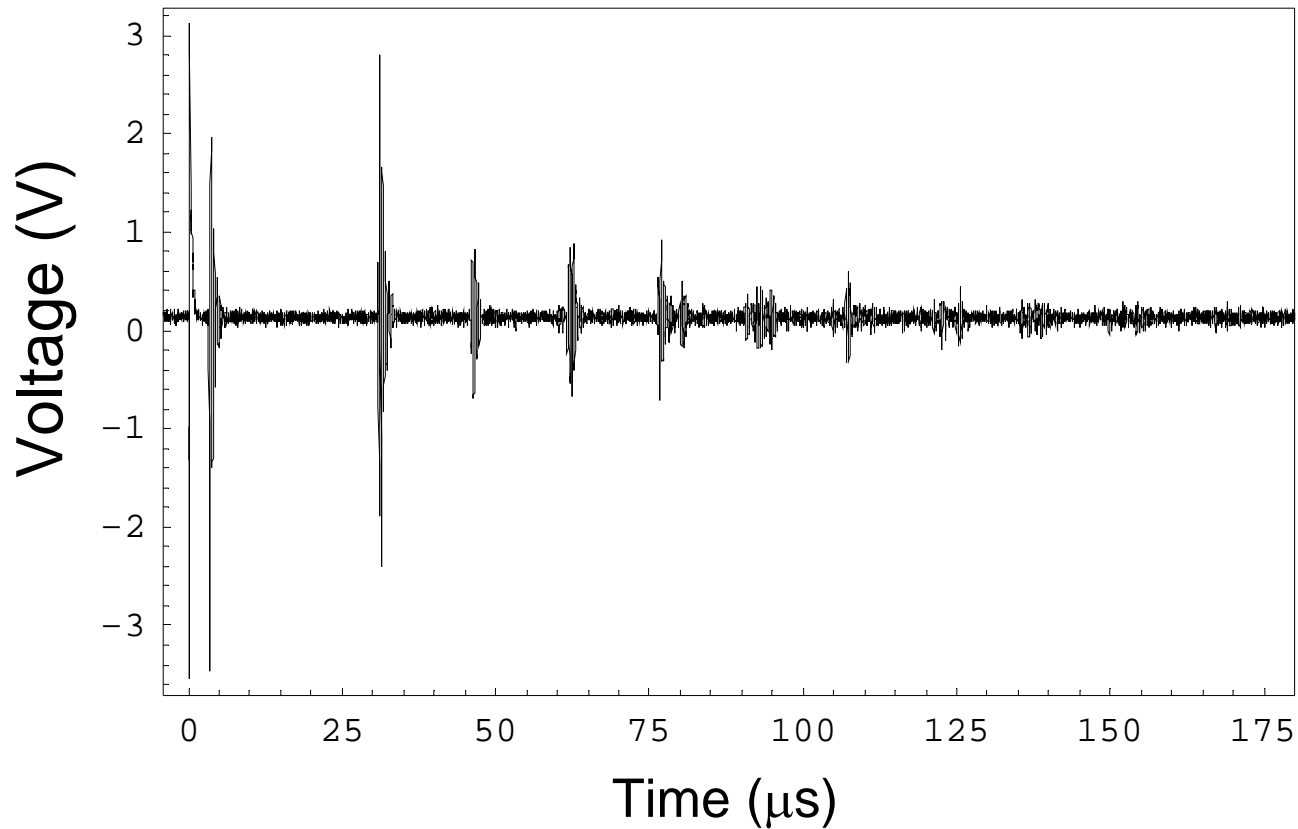


Averaged over 128 traces

Comparison with PZT transducer

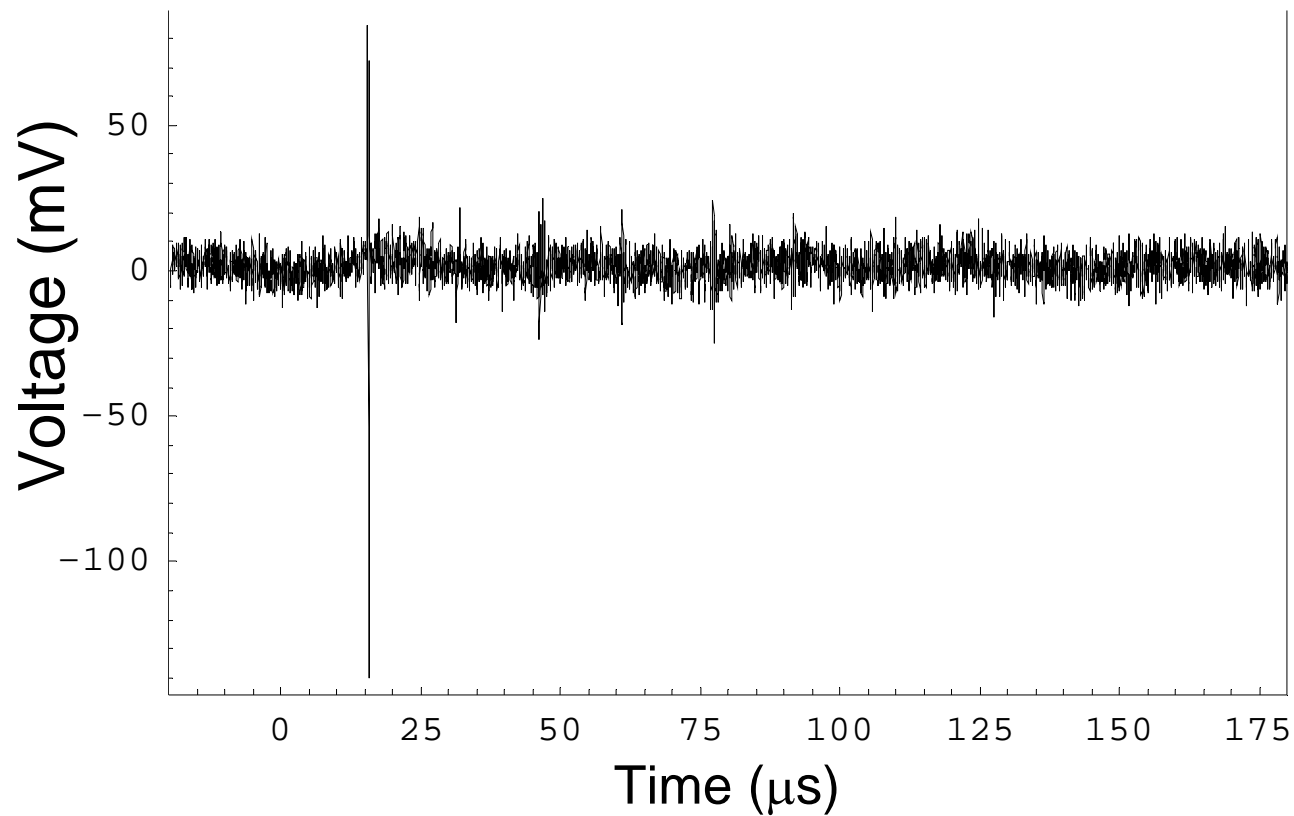
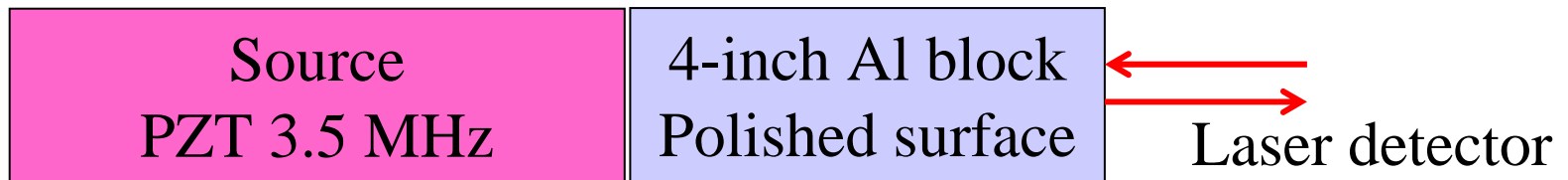
Source and receiver
PZT 3.5 MHz

4-inch Al block
Polished surface



One trace

Comparison with PZT transducer



Averaged over 128 traces

Comparison with PZT transducer

PZT transducer ~ 40 more sensitive than our laser detector

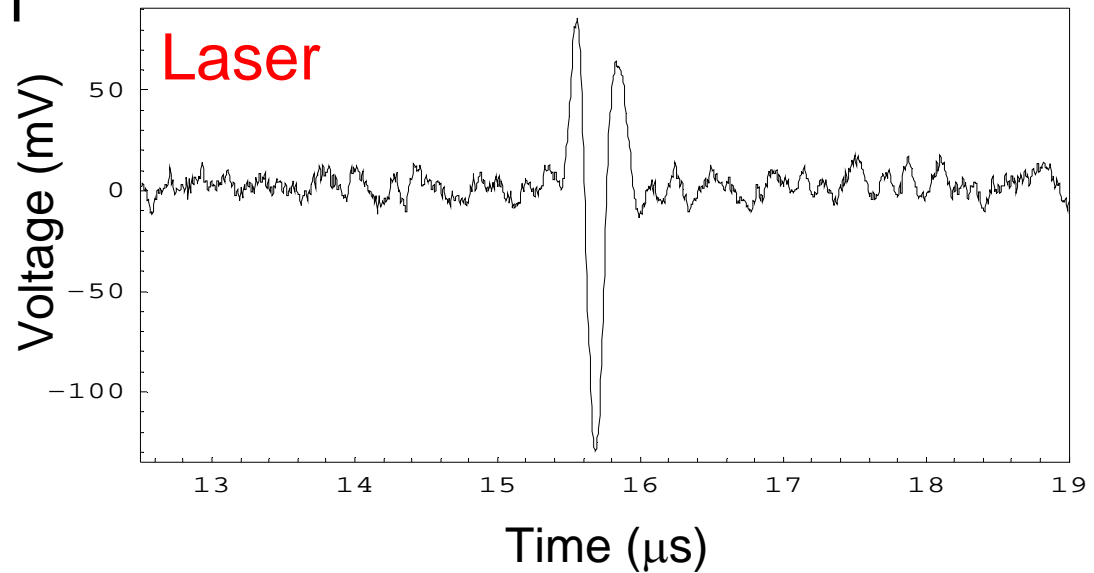
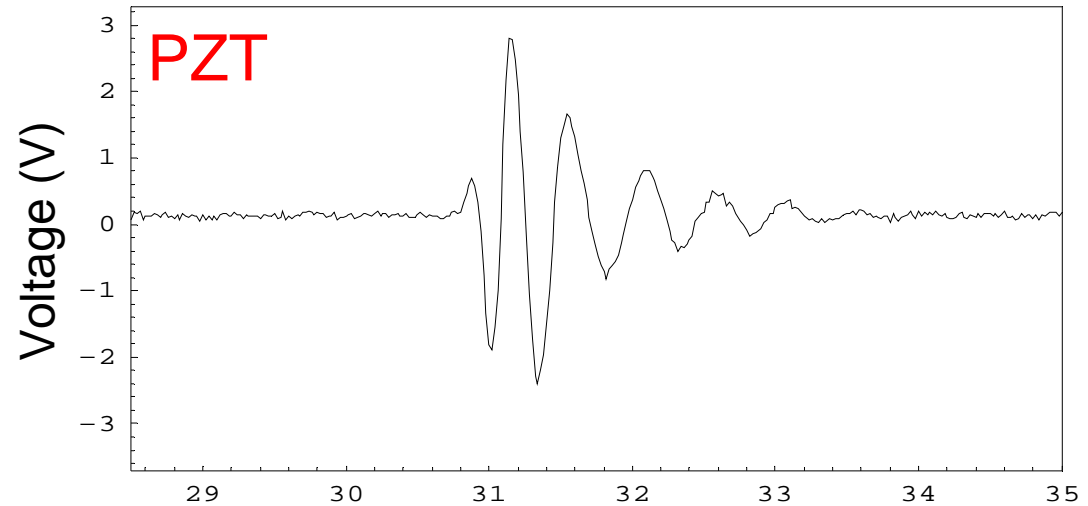
laser detector sensitivity $\propto \sqrt{\text{laser power}}$

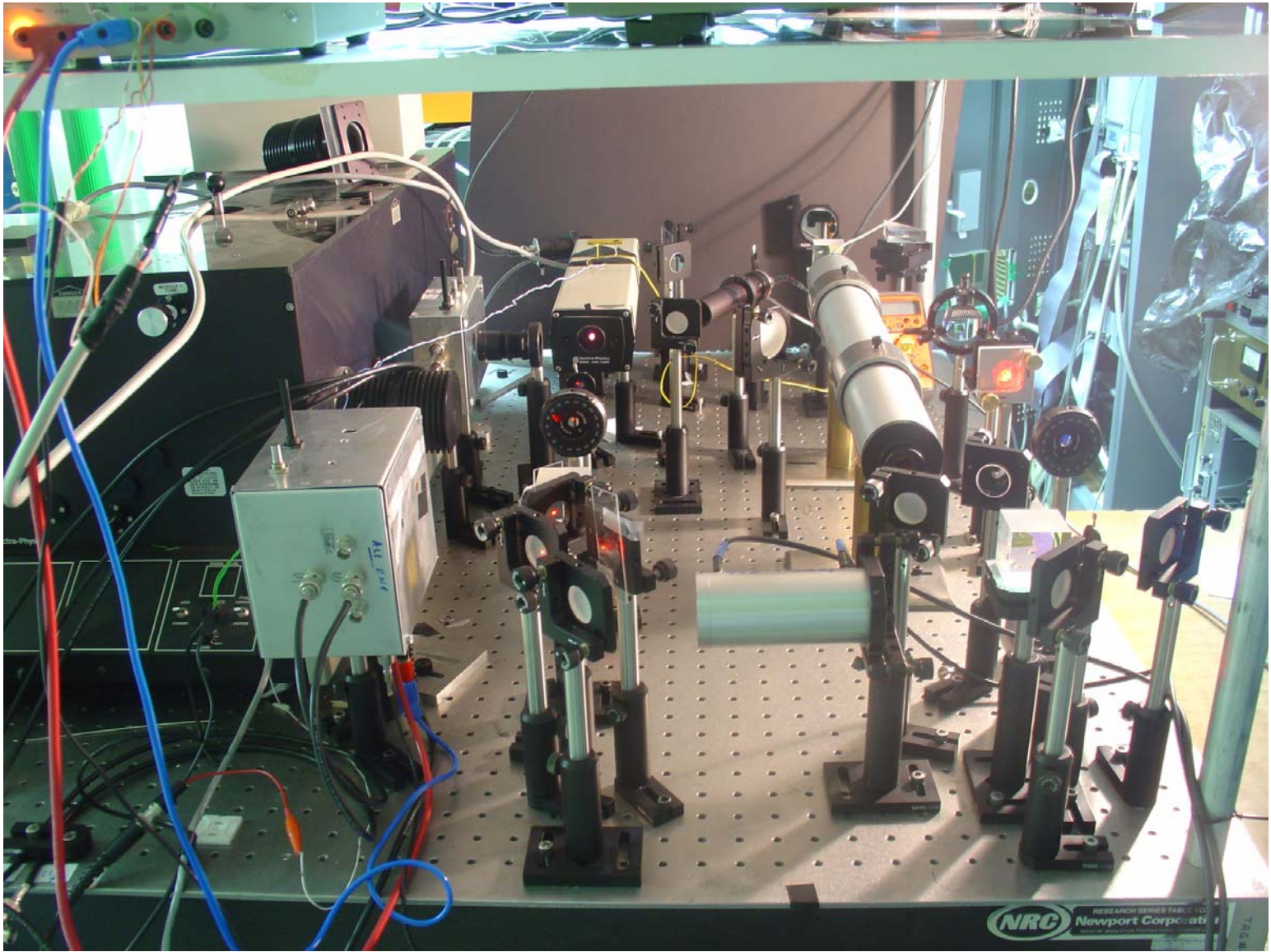
Only 30 μW of the laser power is used in our case

Comparable sensitivities of that of PZT transducers should be attained if we can channel 50 mW of the laser power through our detector

Comparison with PZT transducer

The laser detector provides much better temporal resolution than the PZT transducer





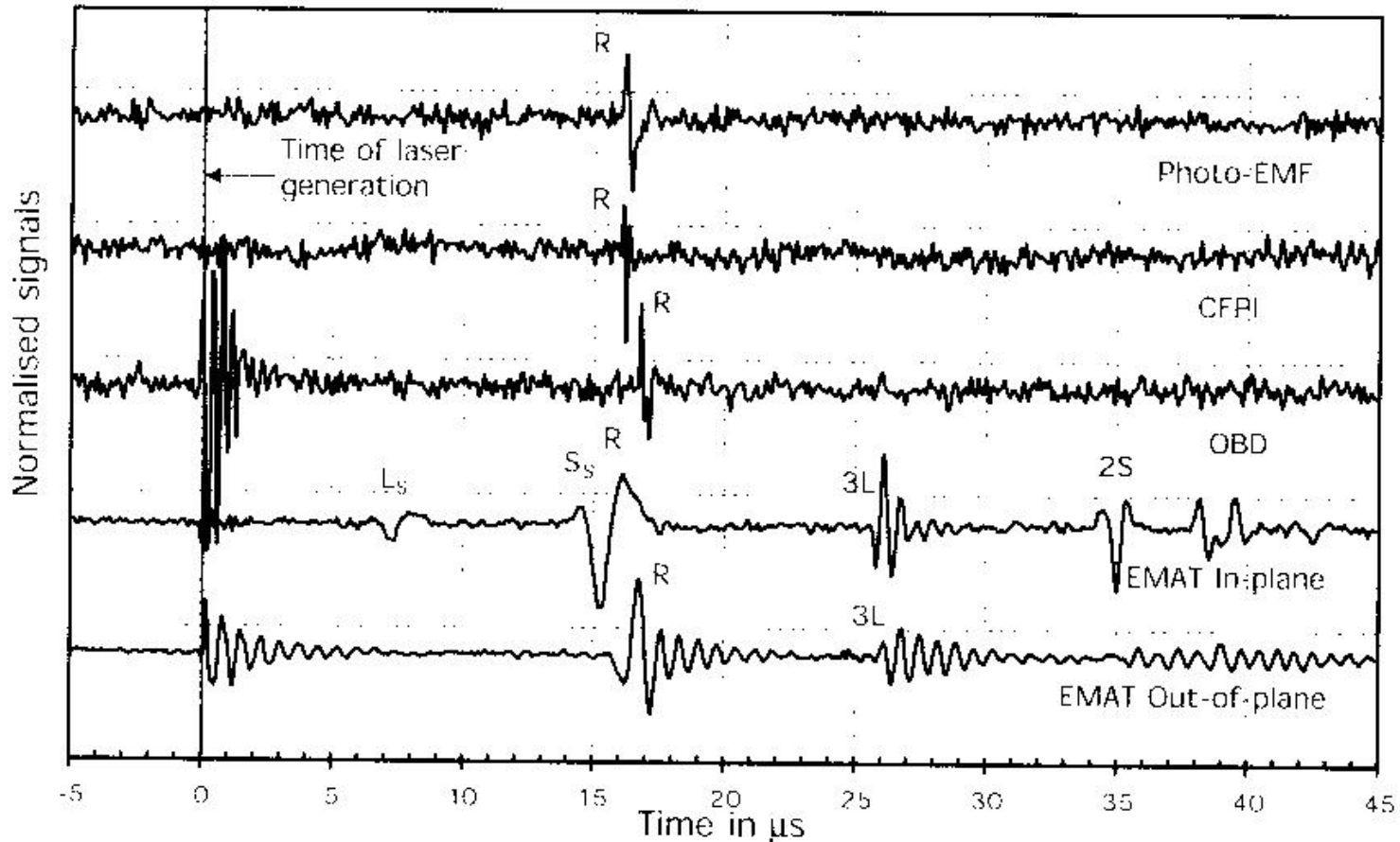
Thank You For Your Listening

- Applied Research Grant 2002 program
- Center for Applied Physical Sciences
- Physics Department

- Team

- Abdulaziz aljalal
- Mohammed Aslam Khan
- Rizq Alrehan

Comparison with other noncontact transducers



Ref. A. S. Murfin, R. A. J. Soden, D. Hatrick and R. J. Dewhurst, *Meas. Sci. Technol.*, 11, 1208 (2000).