

Coherent Light and Vibrating Films

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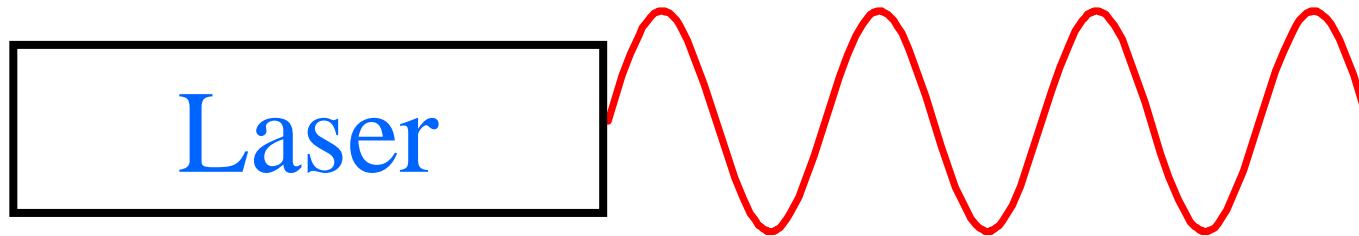


University College London

Department of Medical Physics and Bioengineering
Lasers and Endoscopy Group - Dr. Paul Beard



Coherent Light?



Continuous Wave

Narrow Band

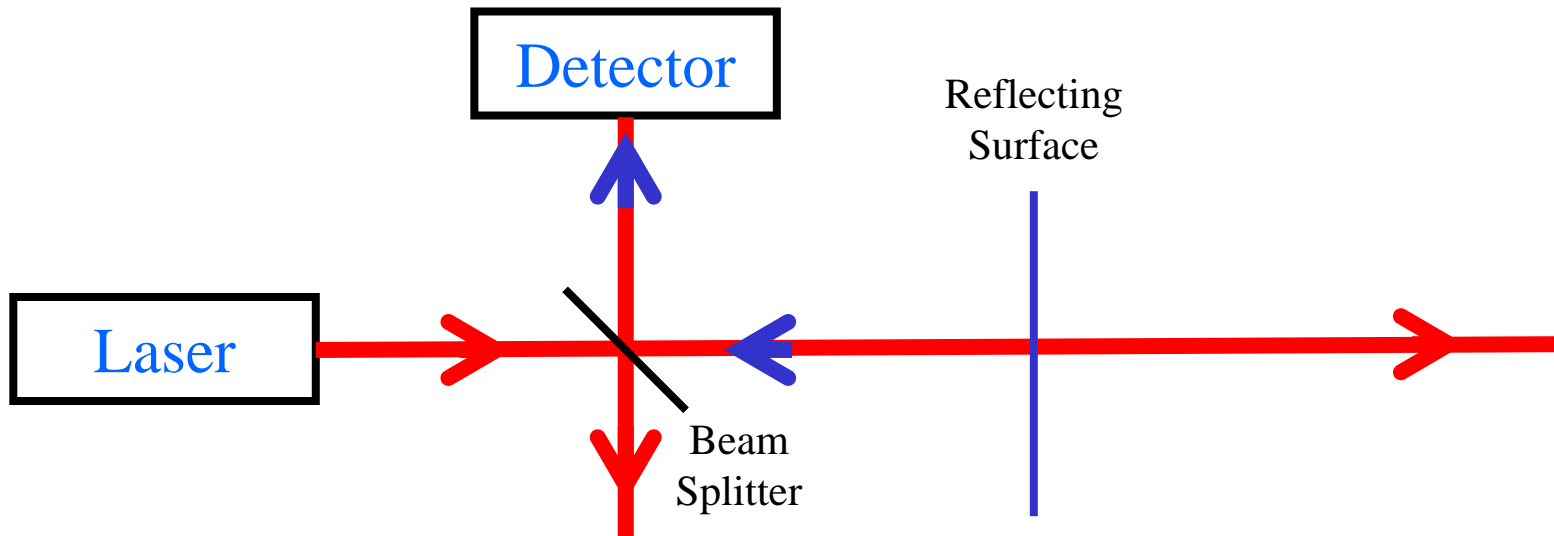
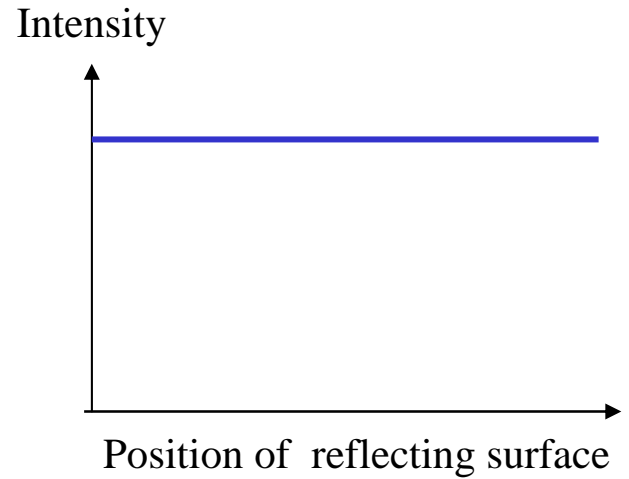
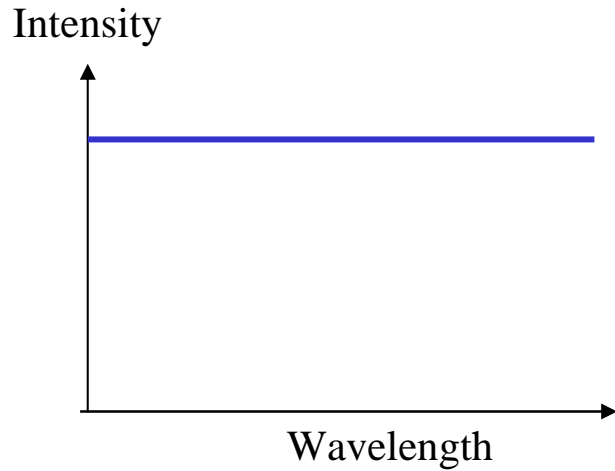
What is special about light?



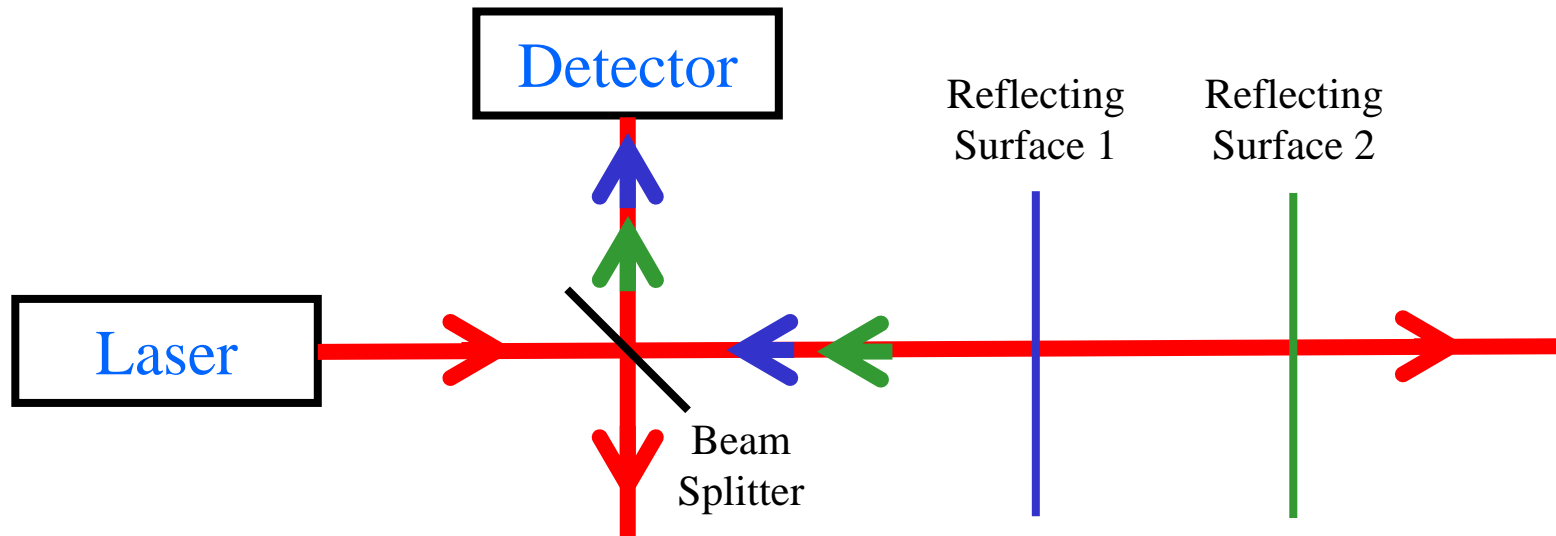
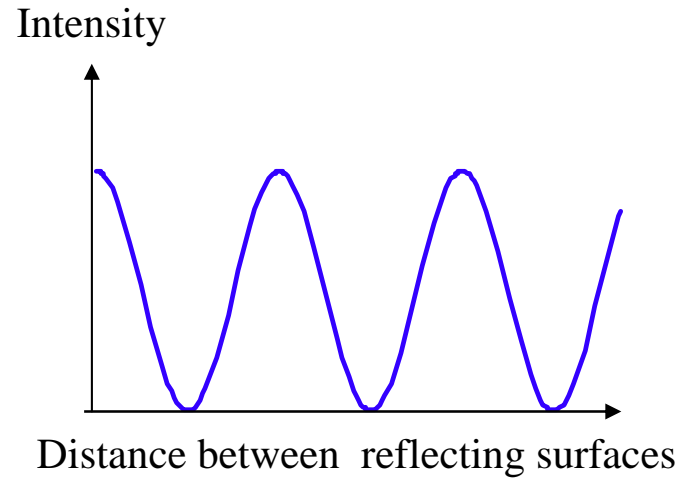
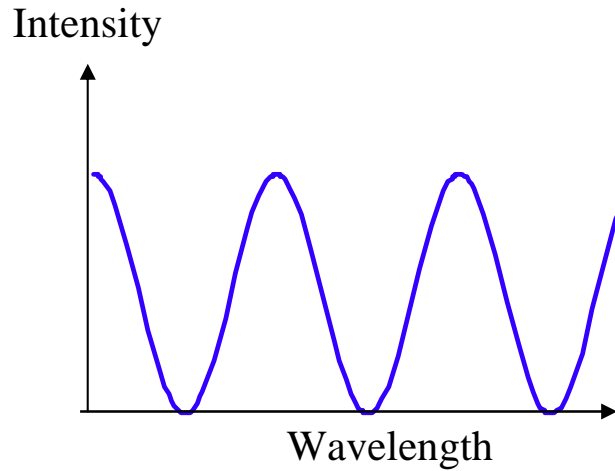
$\lambda \sim 0.5 \mu\text{m}$

- Wavelength very short
 - help to detect small displacements fraction of λ
- Availability of coherent sources
- Availability of effective and fast detectors
- Light beam can be easily steered and shaped by mirrors and lenses and guided through fibers

Simple Setup



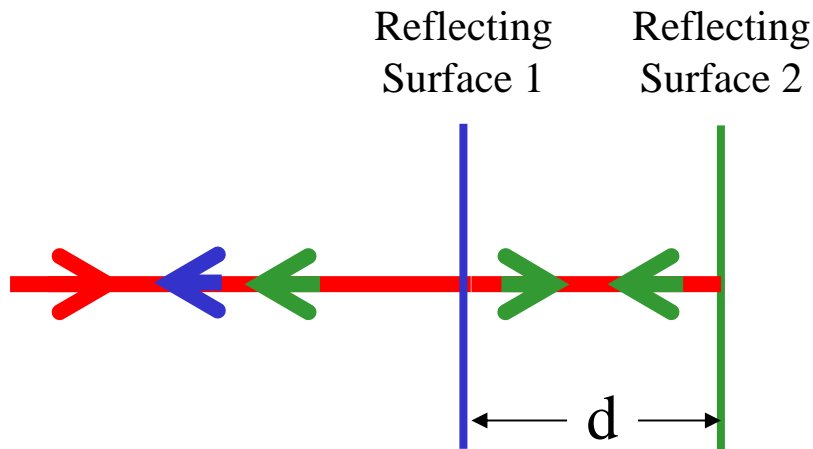
Improved Setup



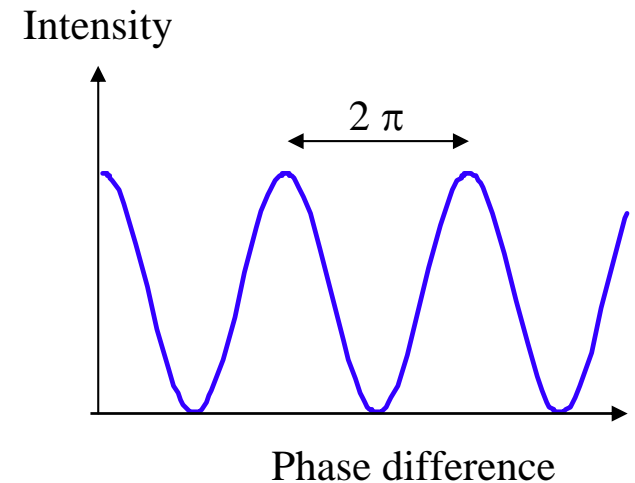
Why variation in intensity?

Wave interference

$$\text{Phase difference} = k(2d) = \frac{4\pi}{\lambda} d$$



Fabry-Perot
Interferometer



Applications of Fabry-Perót Interferometer?

- Analyze light sources

- Spectroscopy

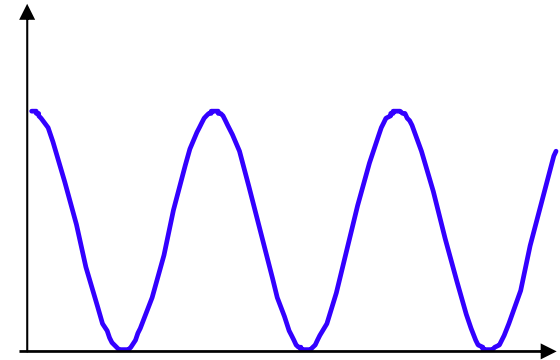
- Monitor distance variations

- Temperature

- Stress

✓ Ultrasonic waves

Intensity



Phase difference

$$Phase\ difference = \frac{4\pi}{\lambda} d$$

Reflecting
Surface 1

Reflecting
Surface 2

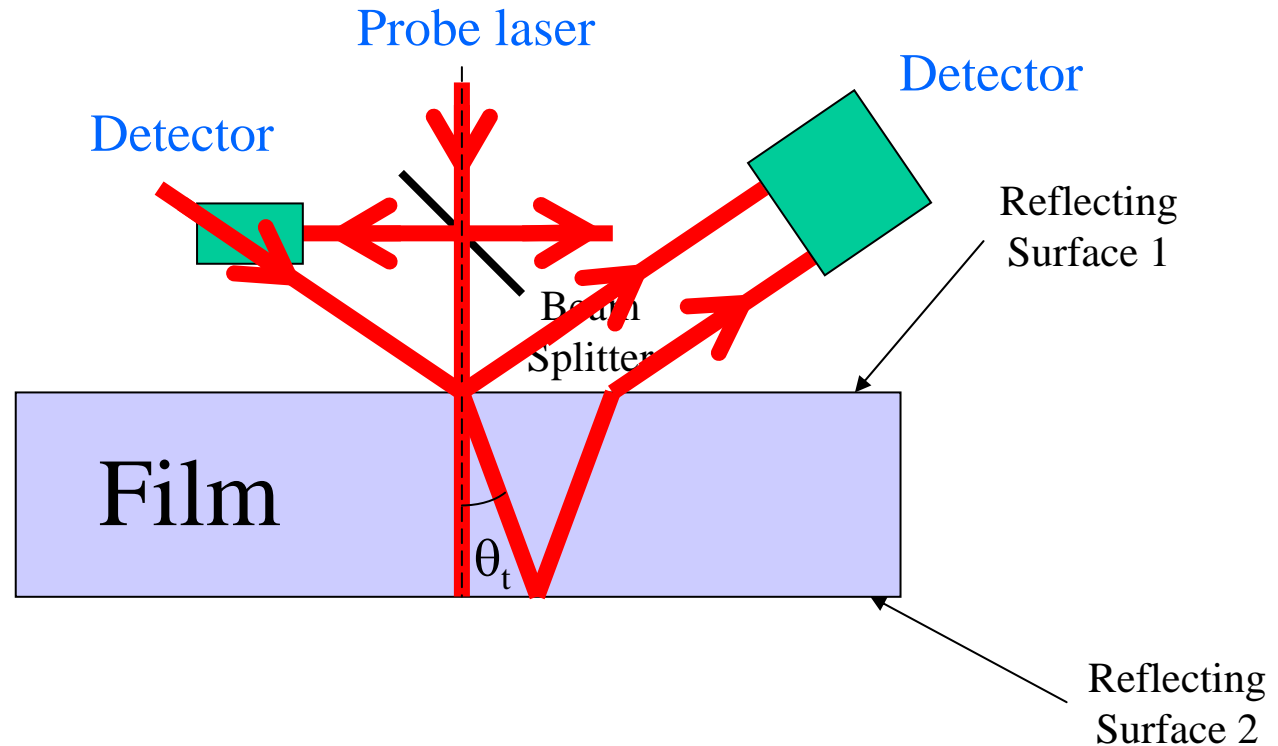
λ



Laser beam

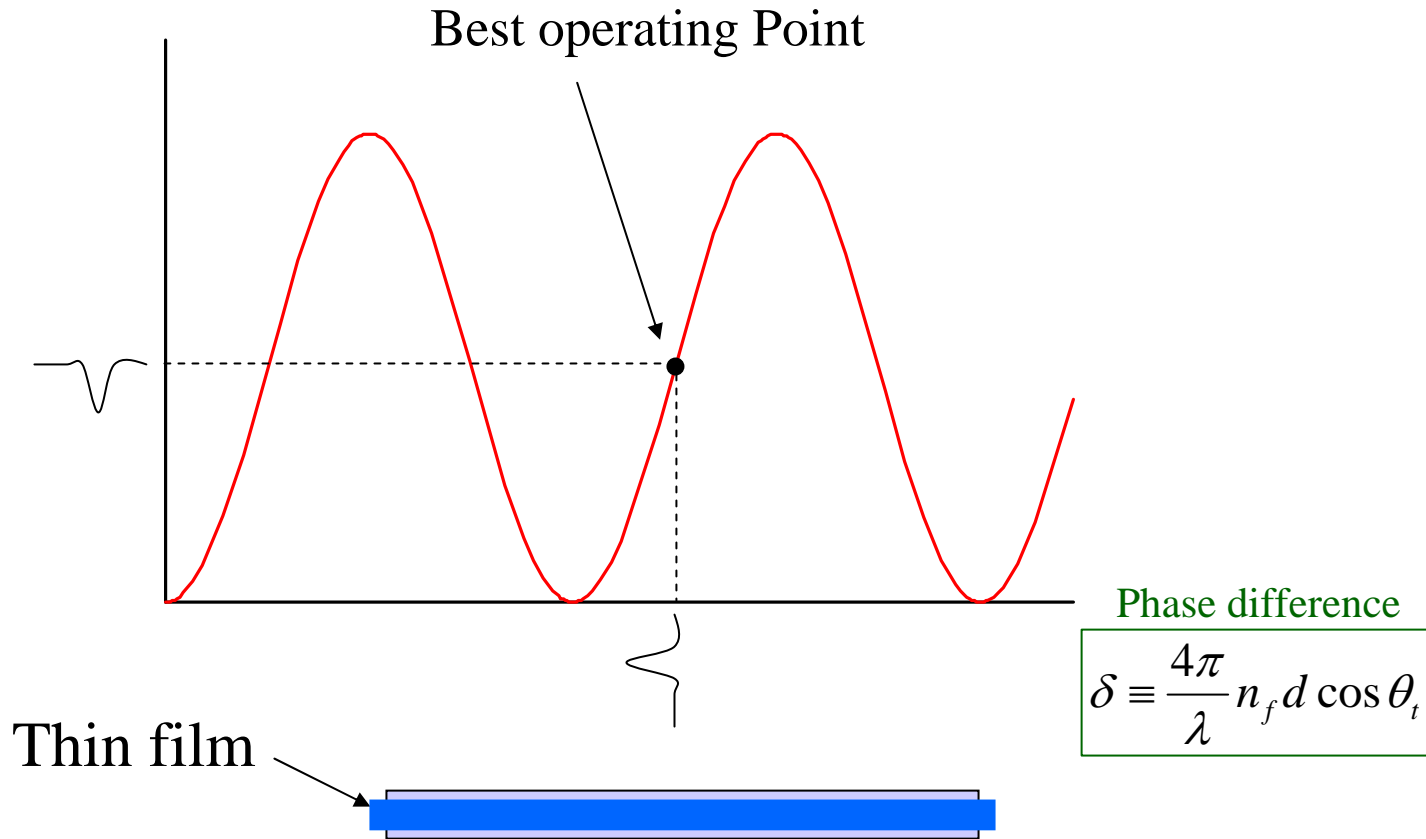
d

Fabry-Perót Interferometer = Thin film

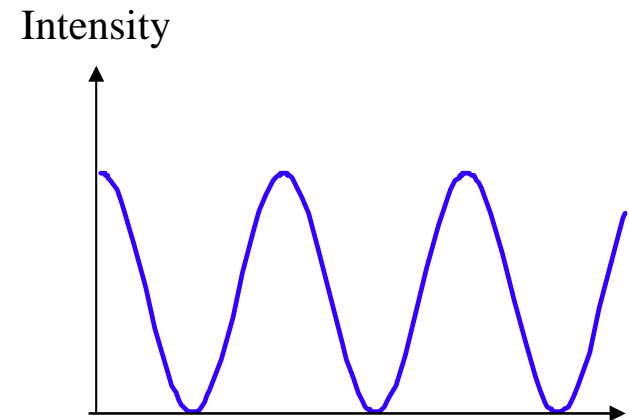
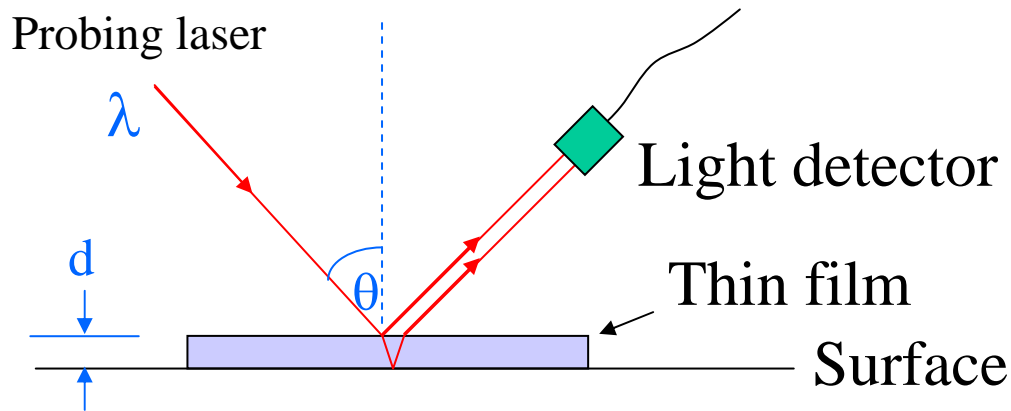


$$\text{Phase difference} \equiv \delta = \frac{4\pi}{\lambda} n_f d \cos \theta_t$$

Operating point



Tuning the phase difference



Phase difference

$$\delta \equiv \frac{4\pi d n_f}{\lambda} \cos \theta_t$$

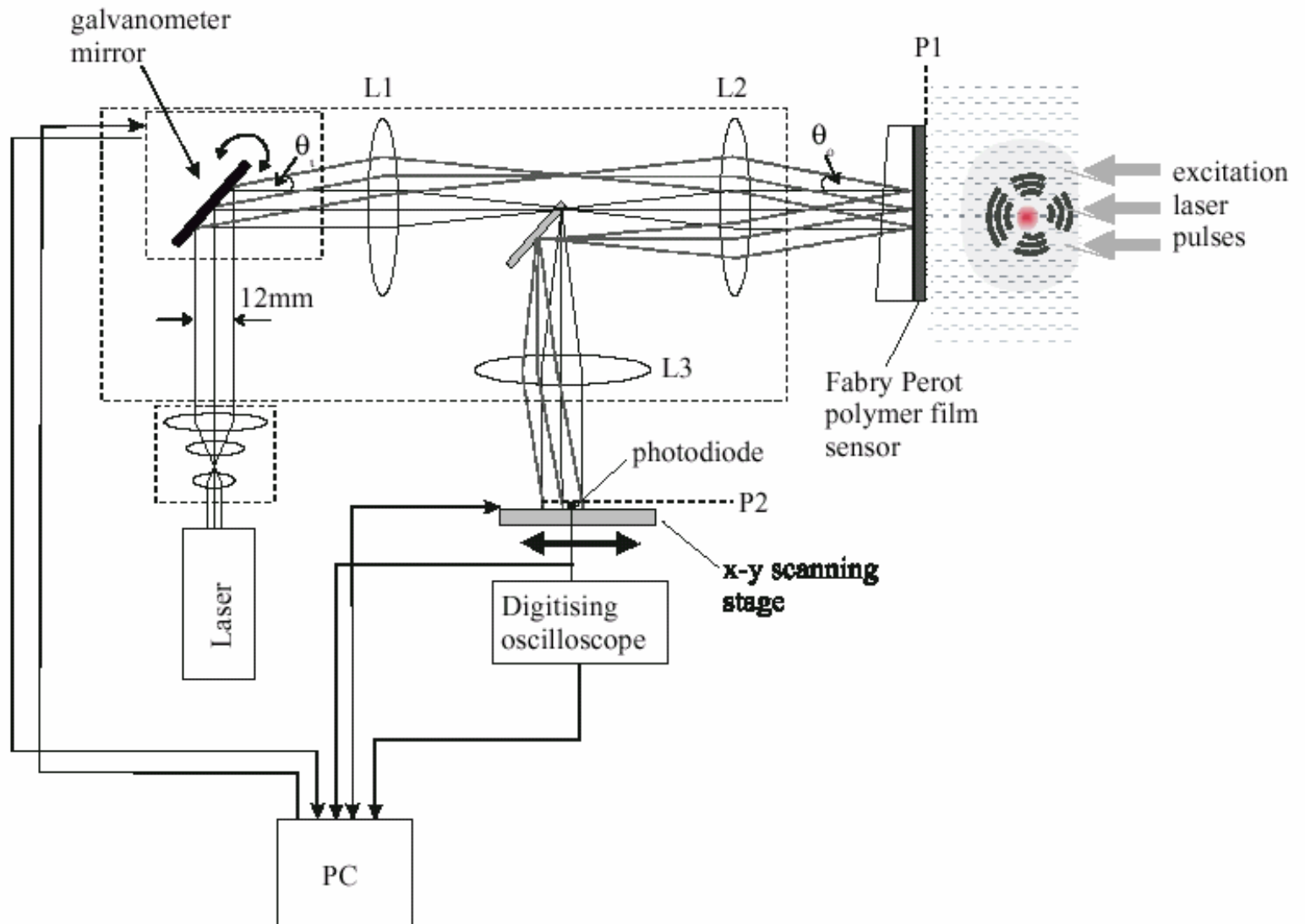
Change θ

Steering optics
complicated
Fast

Change λ

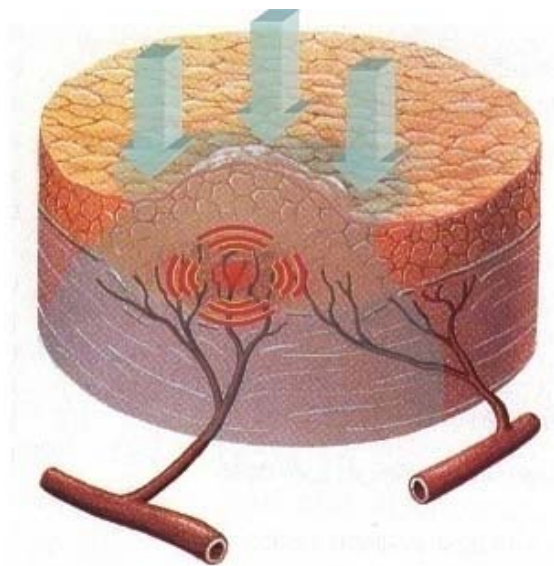
tunable lasers
Expensive
slow

Tuning with angle

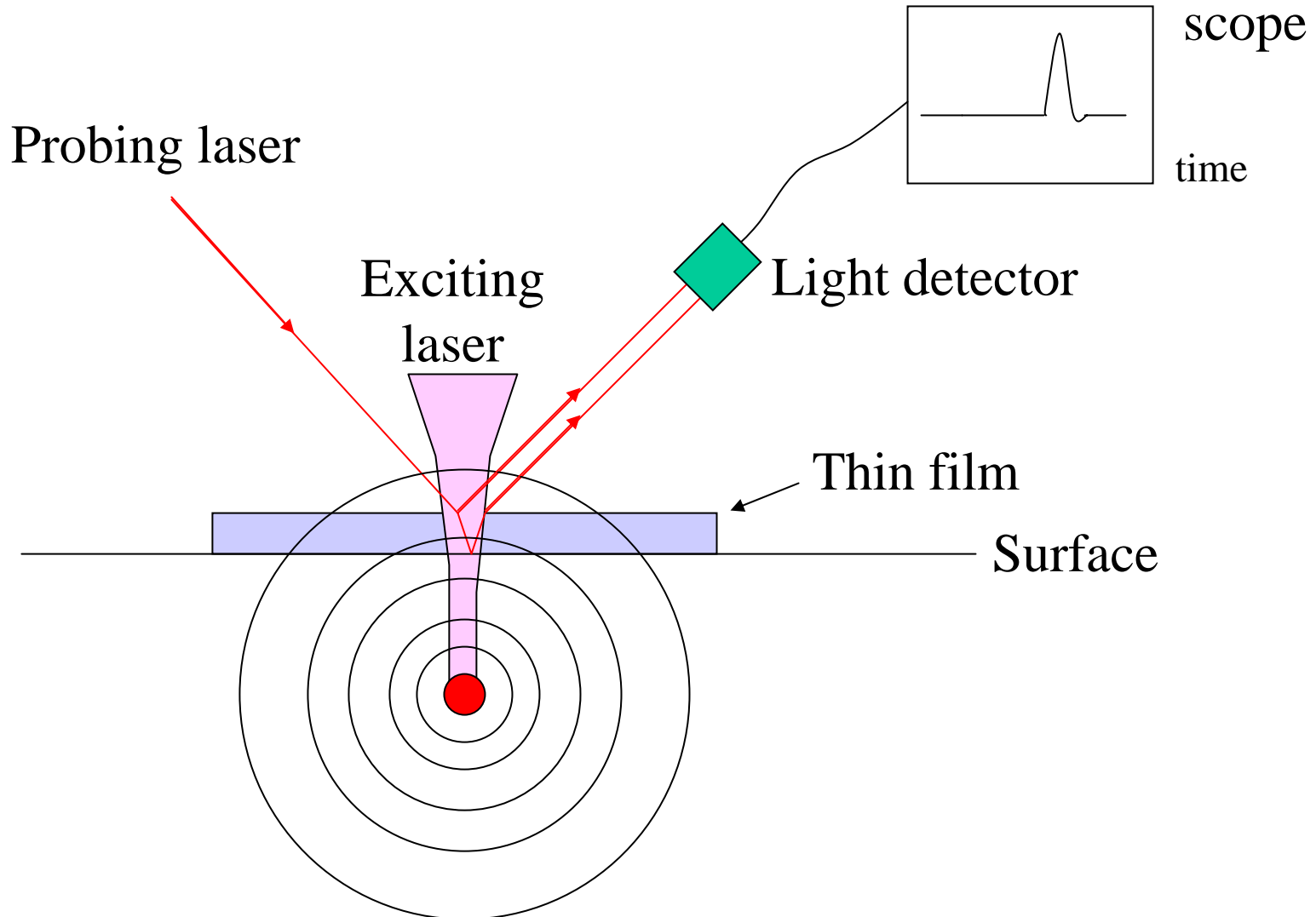


Applications of thin film-ultrasonic sensor at UCL?

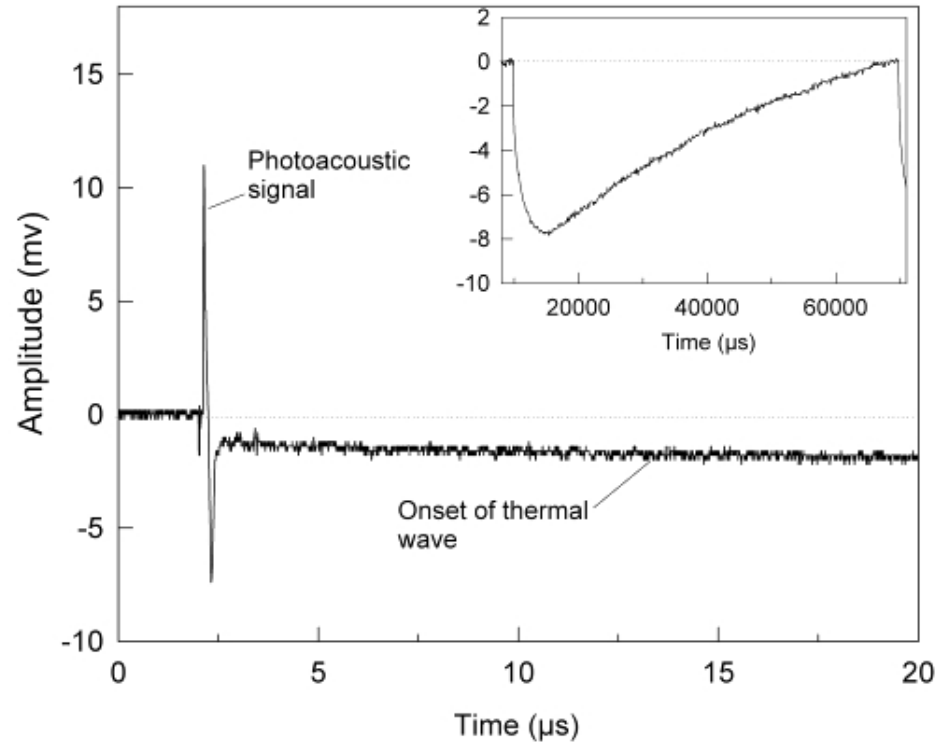
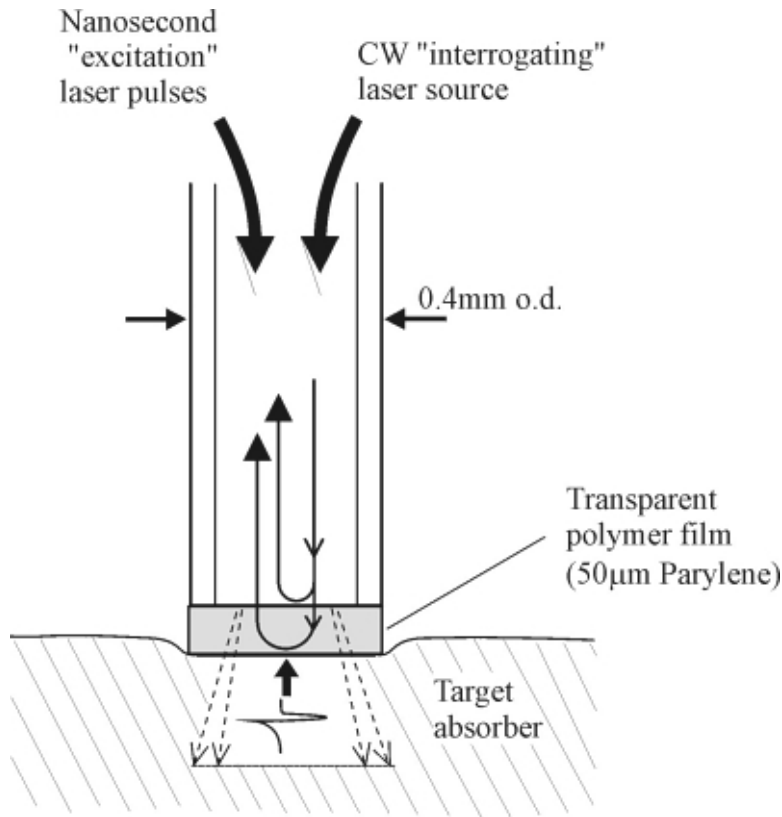
Imaging near-surface blood vessels



How to image near-surface blood vessels?

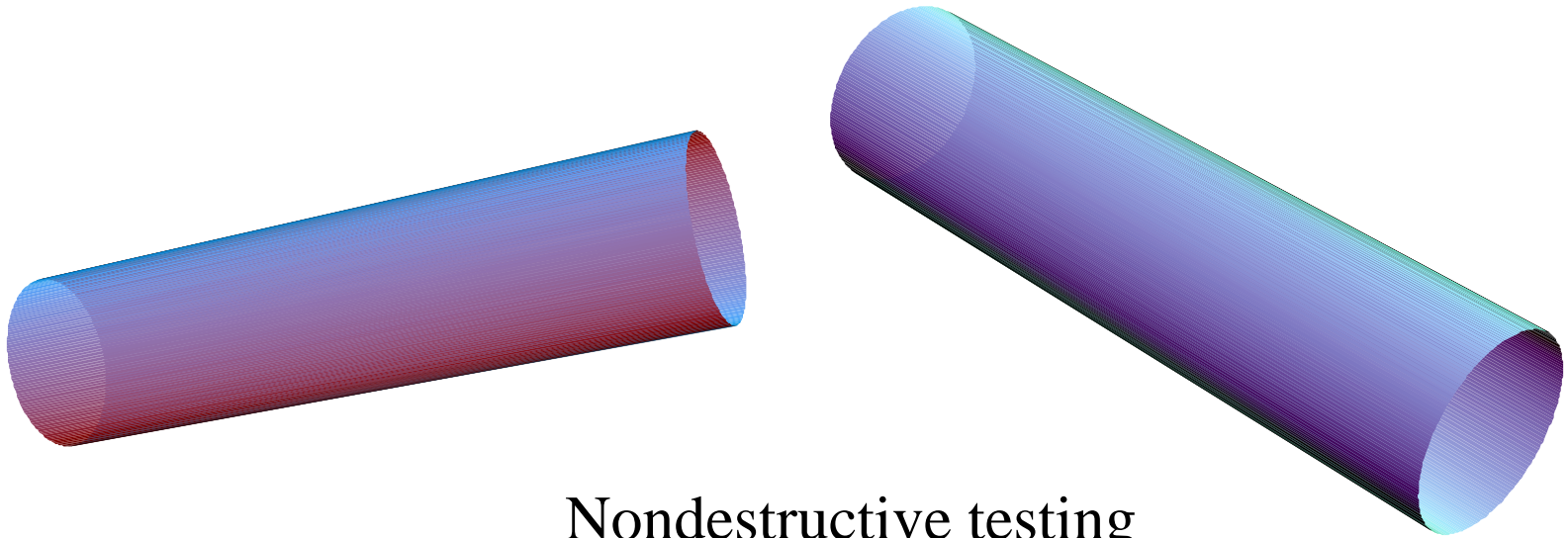


Another application: hydrophone



Sought application

Can we use a layer of paint
or a film glued on a pipe
as an ultrasonic sensor?

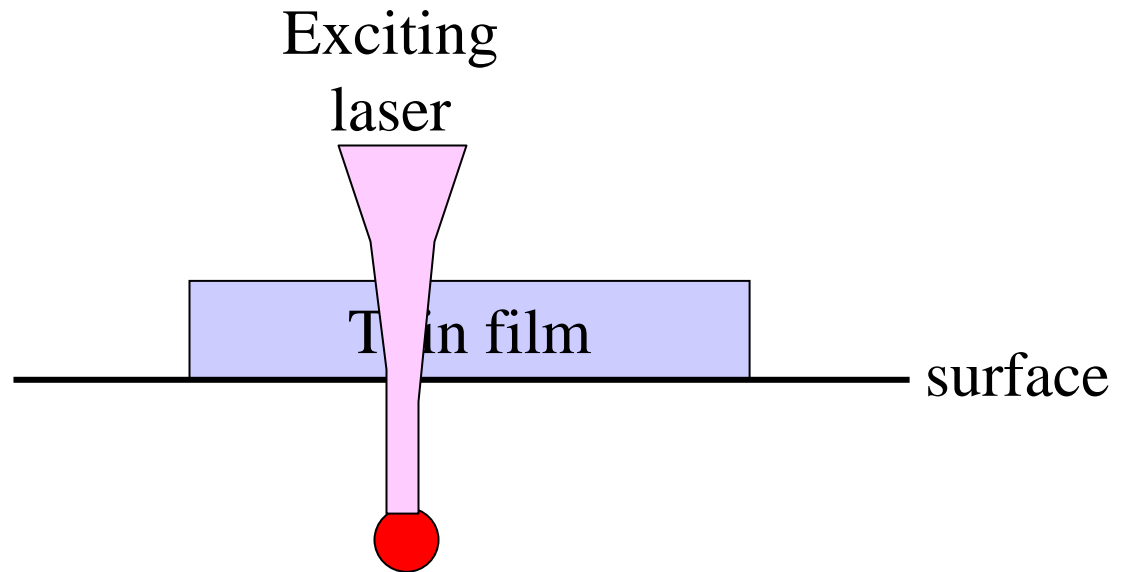


Nondestructive testing
of pipelines

Features of thin-film ultrasonic sensor

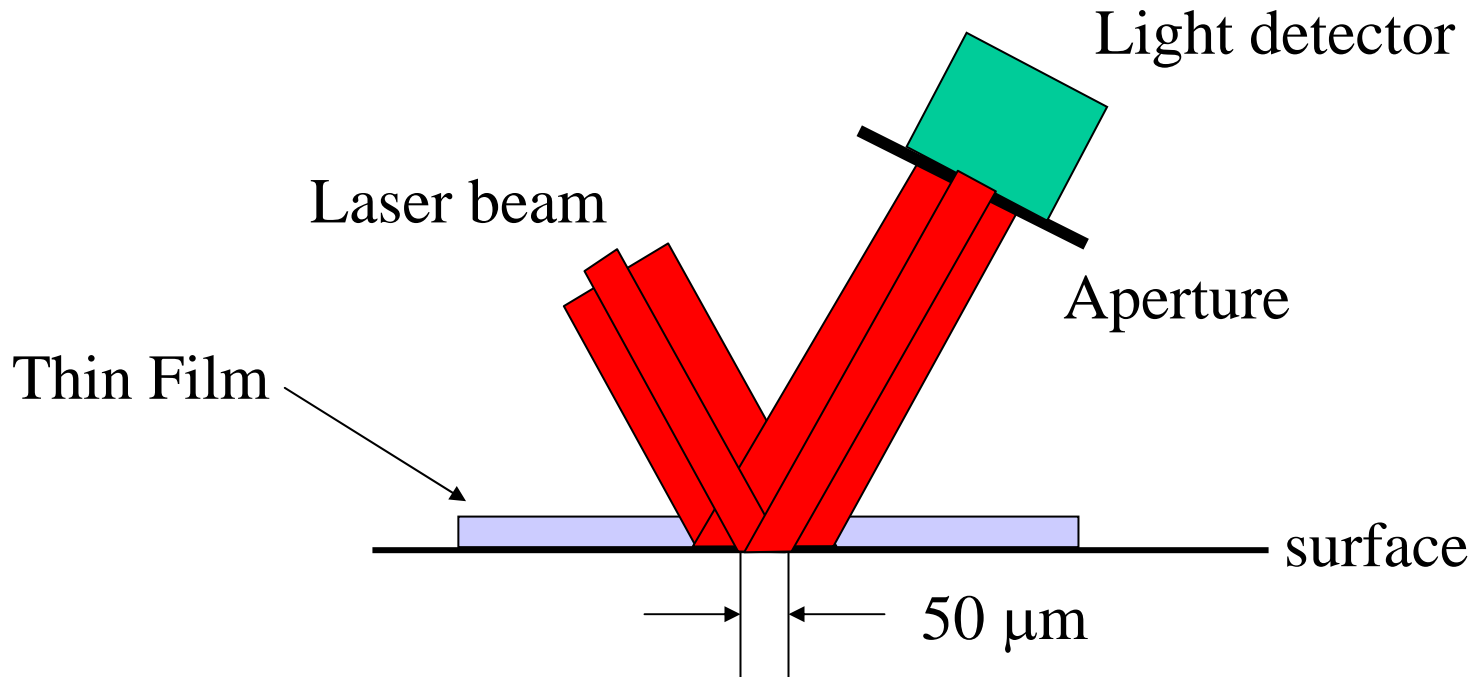
- Used with the exciting pulsed laser
- High spatial resolution
- Broadband (high temporal resolution)
- Sensitive

Used with exciting pulsed laser

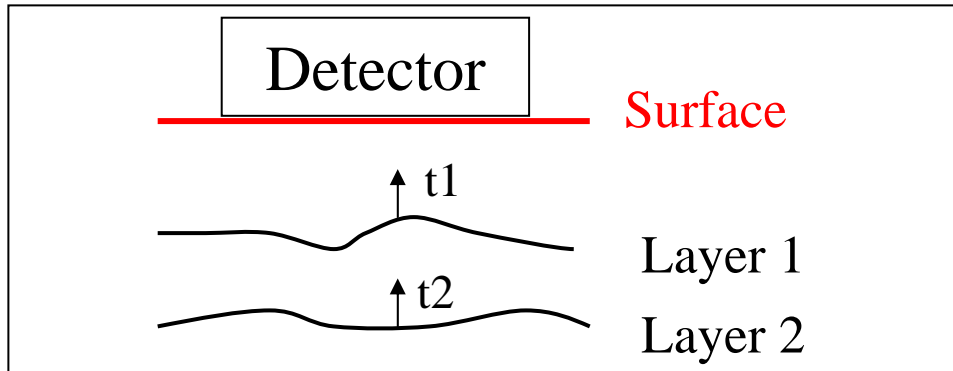


High Spatial Resolution

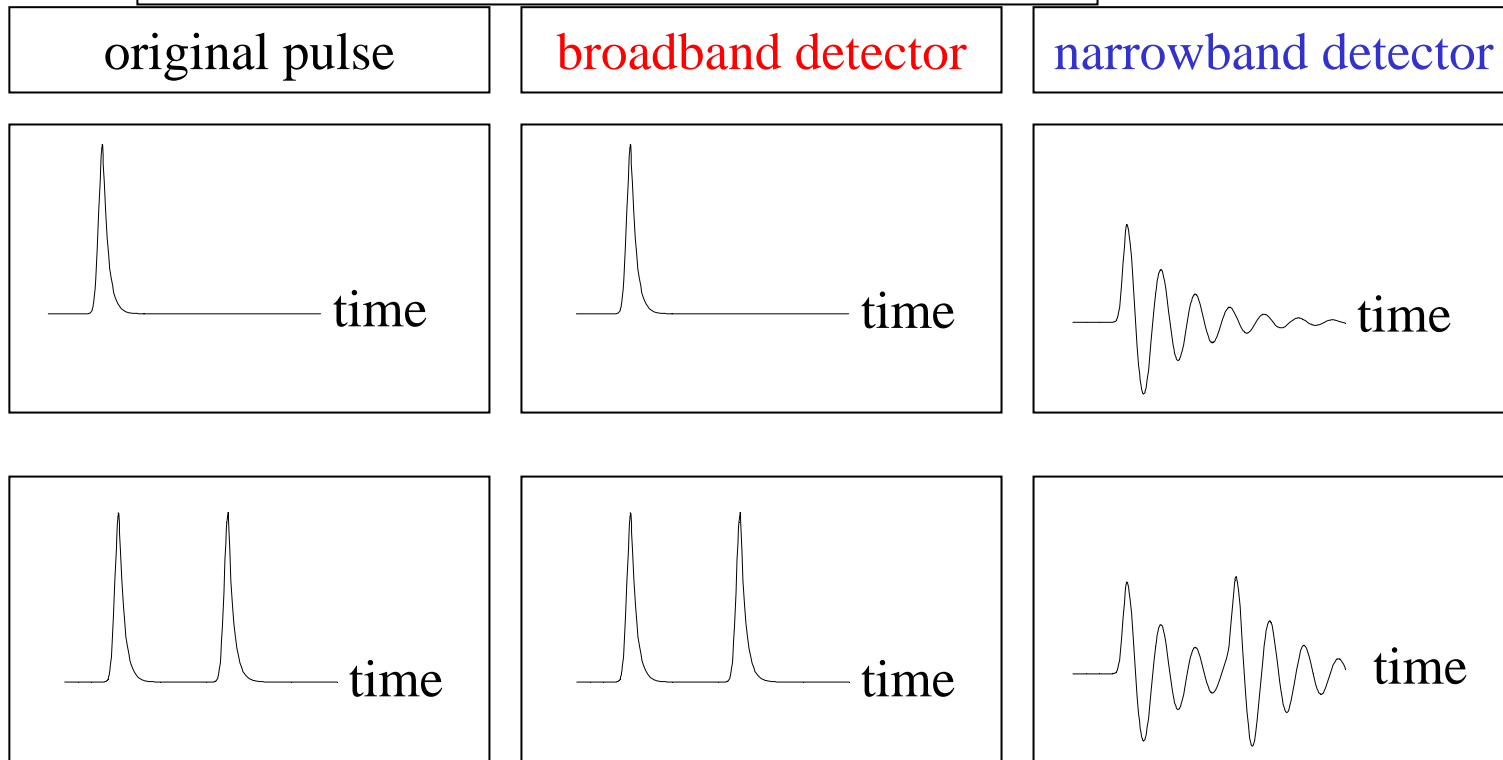
Limited by interrogating laser spot size



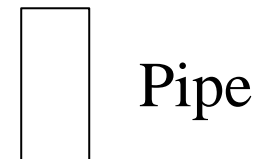
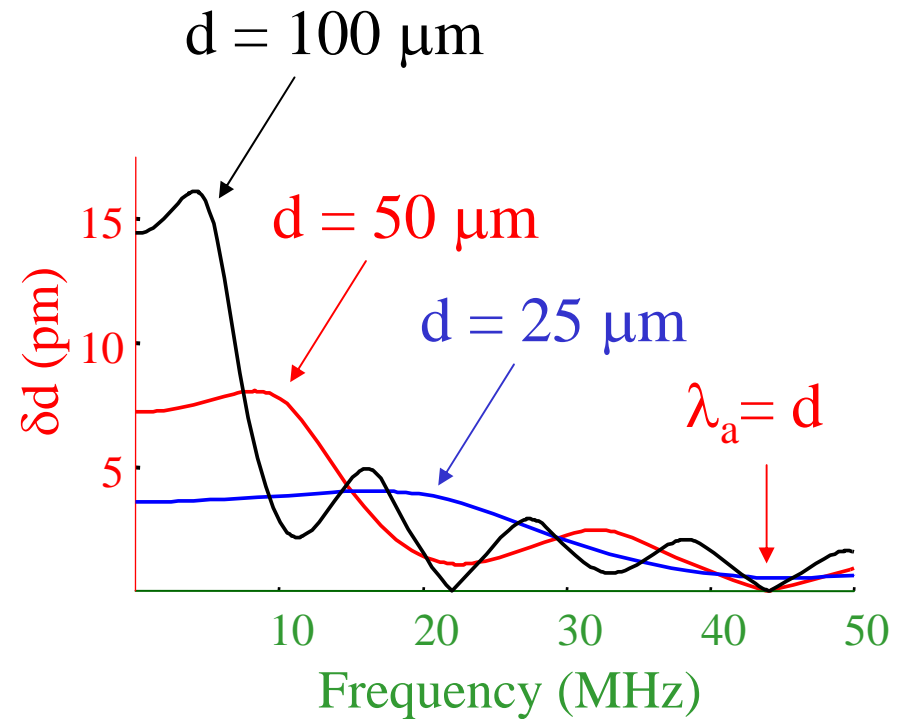
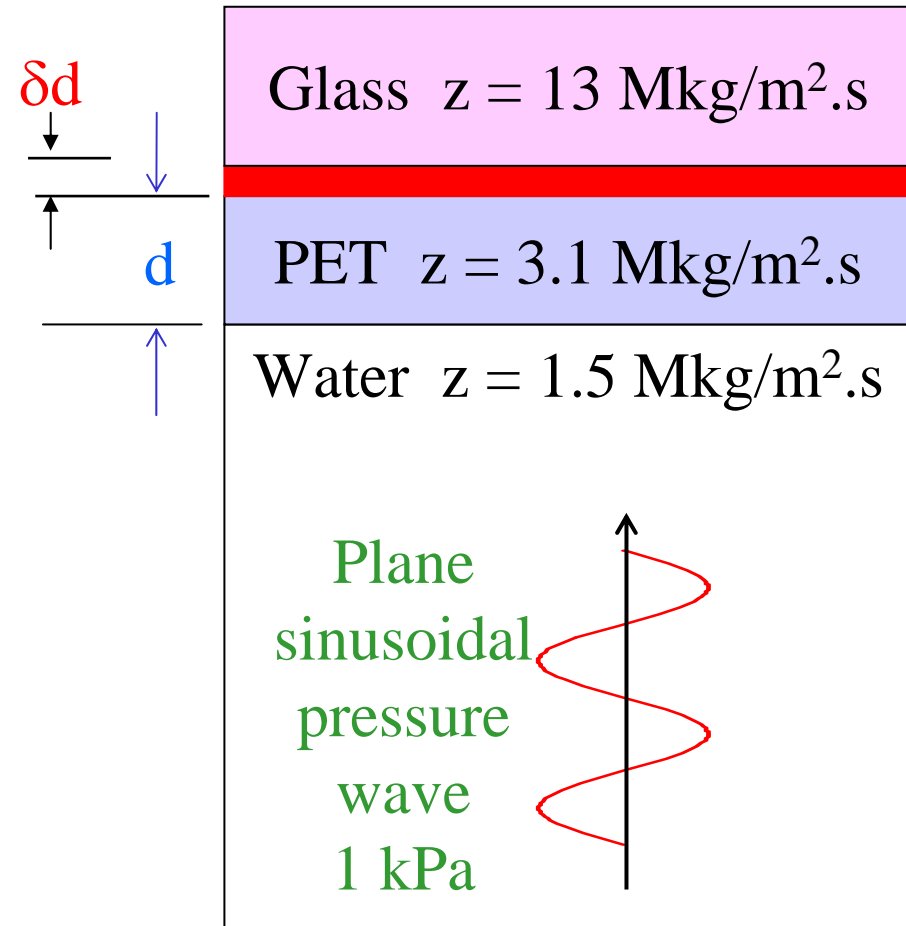
Broadband detection?



50 μm resolution ~
30 MHz bandwidth

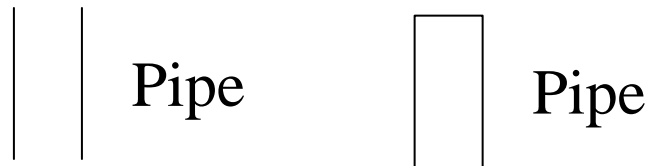
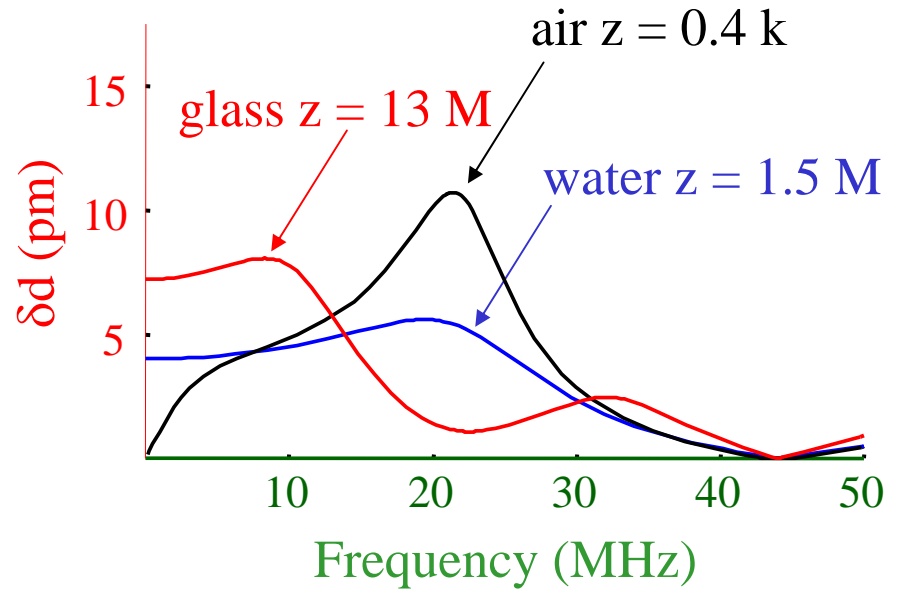
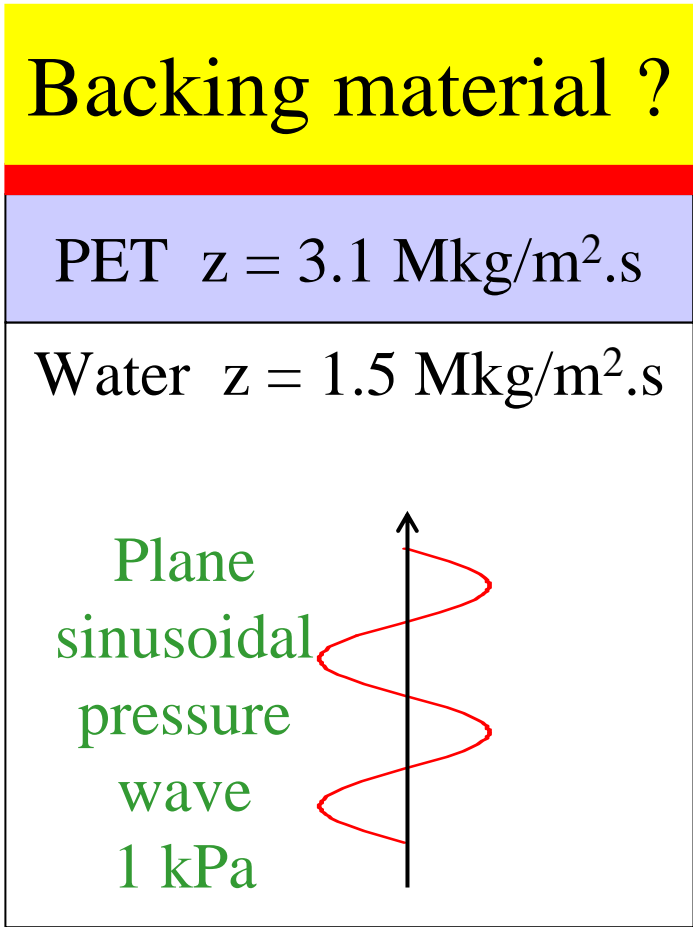


Band of detection – Simple model

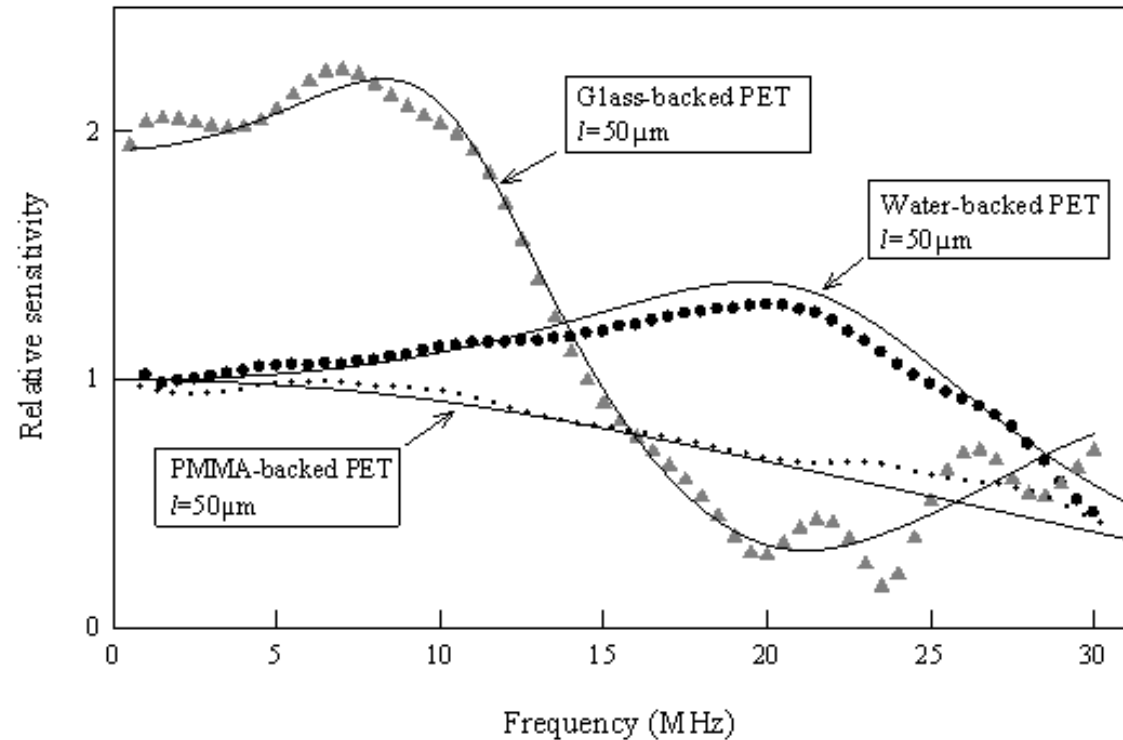
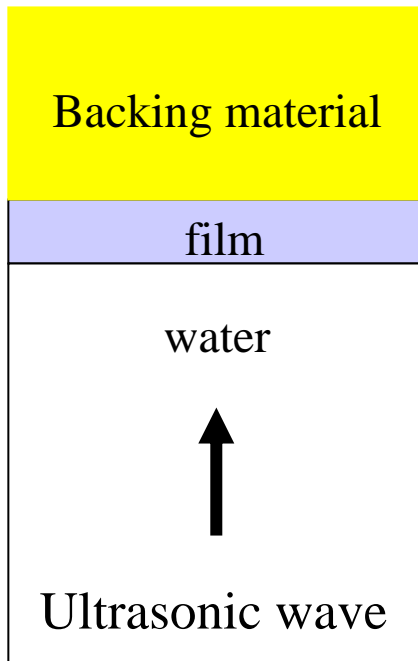


Band of detection – Different backing

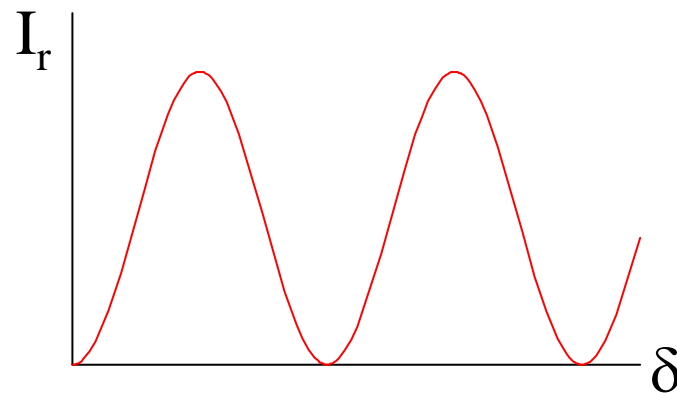
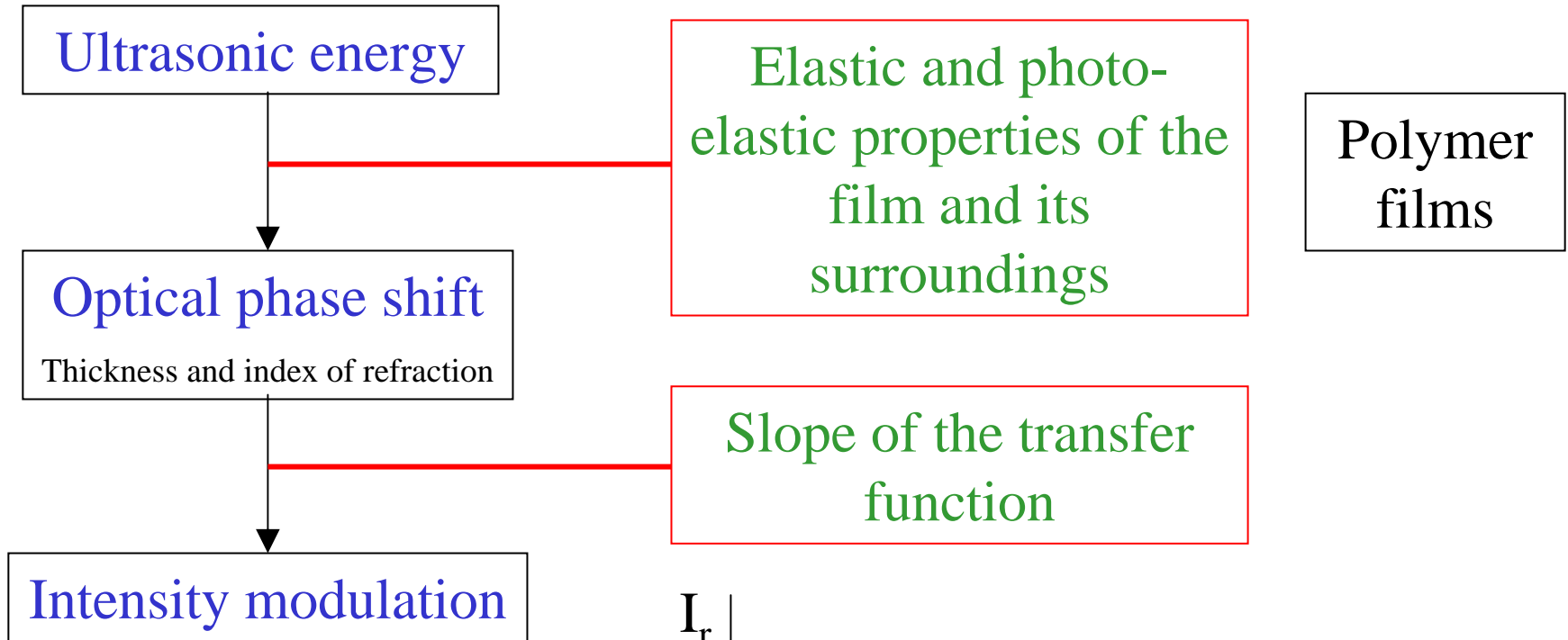
$d = 50 \mu\text{m}$



Band of detection – Experimental results



Sensitivity



Strategy to Increase Sensitivity

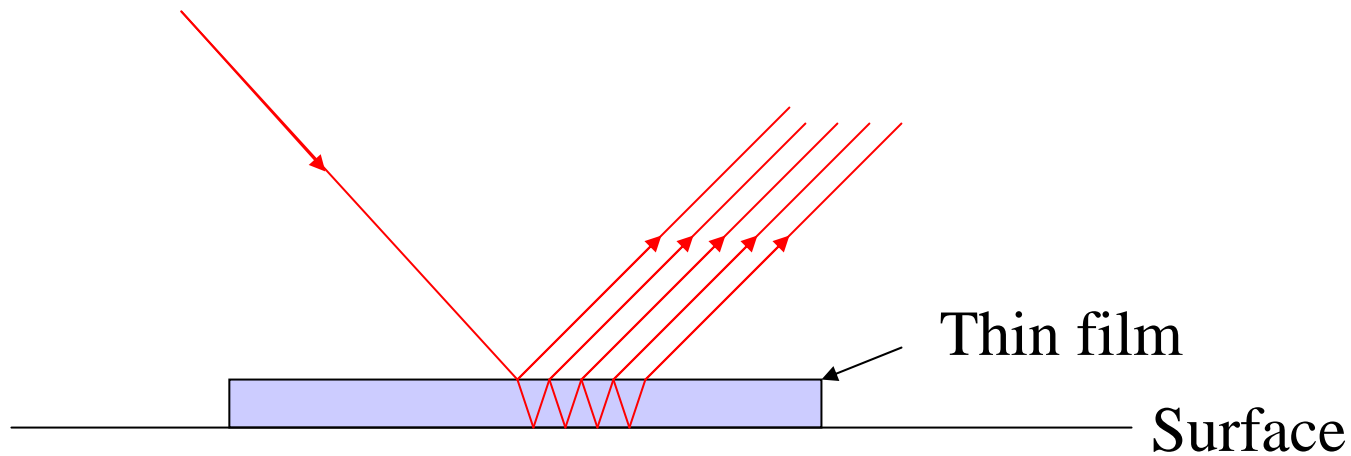
High reflectivity

High laser power

Higher Sensitivity: Higher Reflectivity

Thin film with high reflectivity coatings

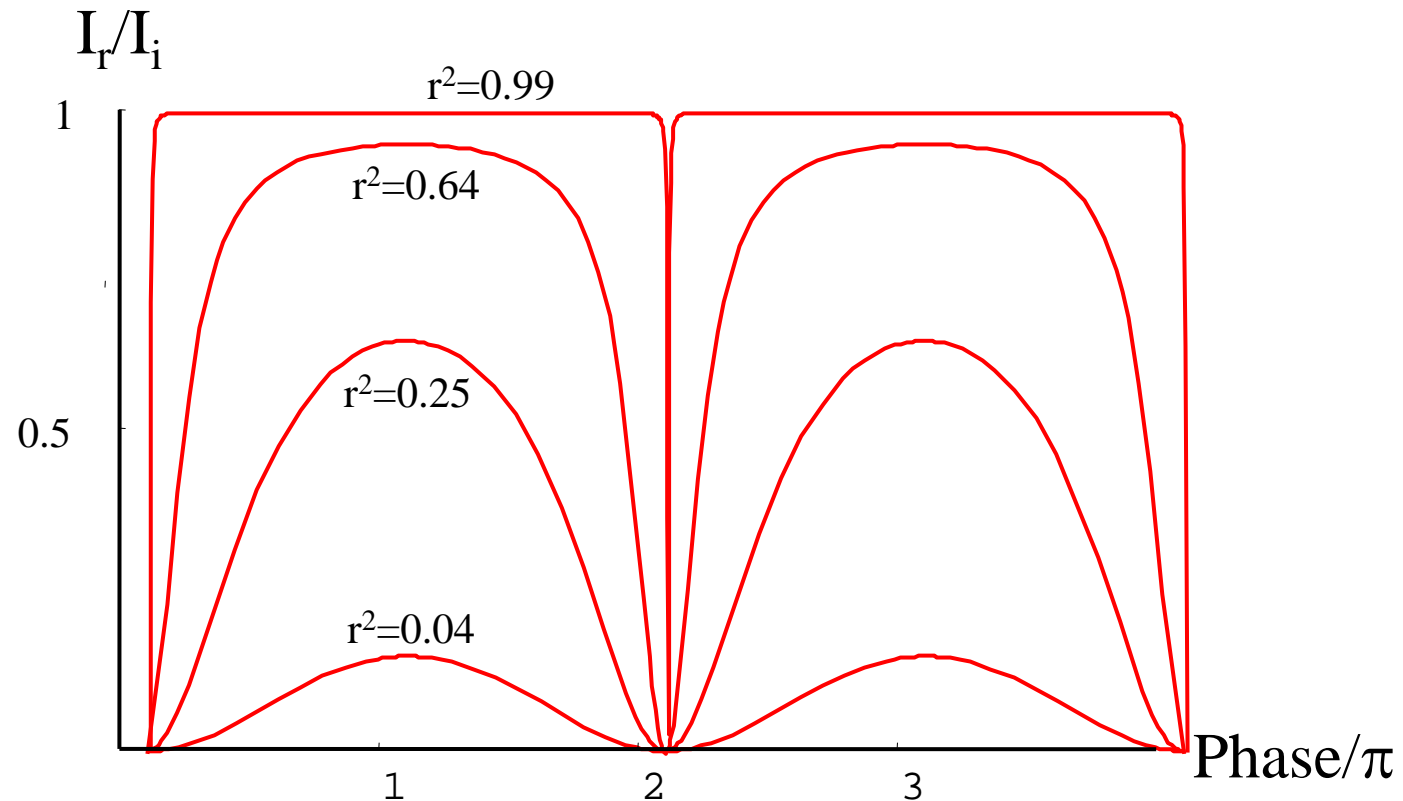
Probing laser



$$I_r = I_i \left(1 - \frac{1}{1 + F \sin^2 \left(\frac{\delta}{2} \right)} \right)$$

$$F = \frac{4r^2}{(1 - r^2)^2}$$

Higher Sensitivity: Higher Reflectivity



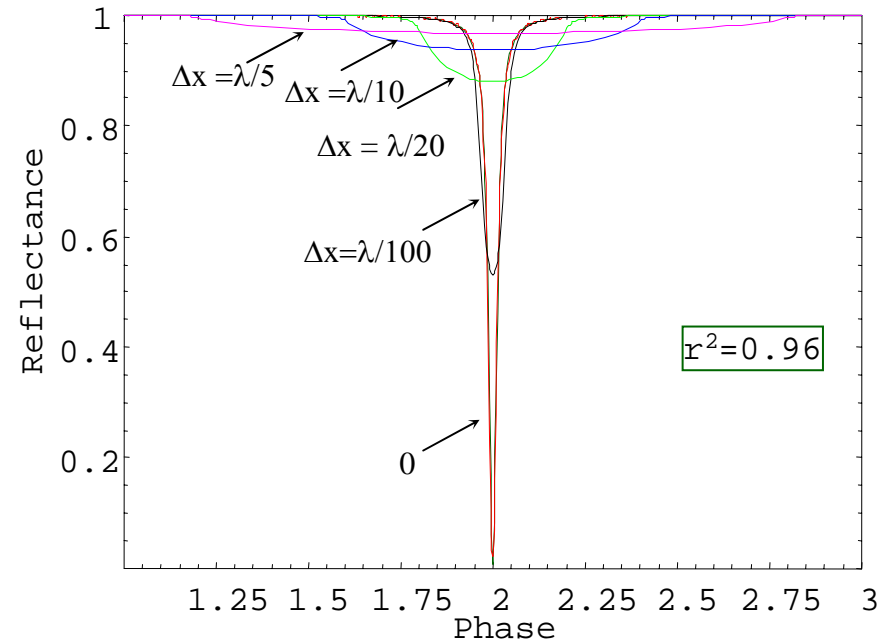
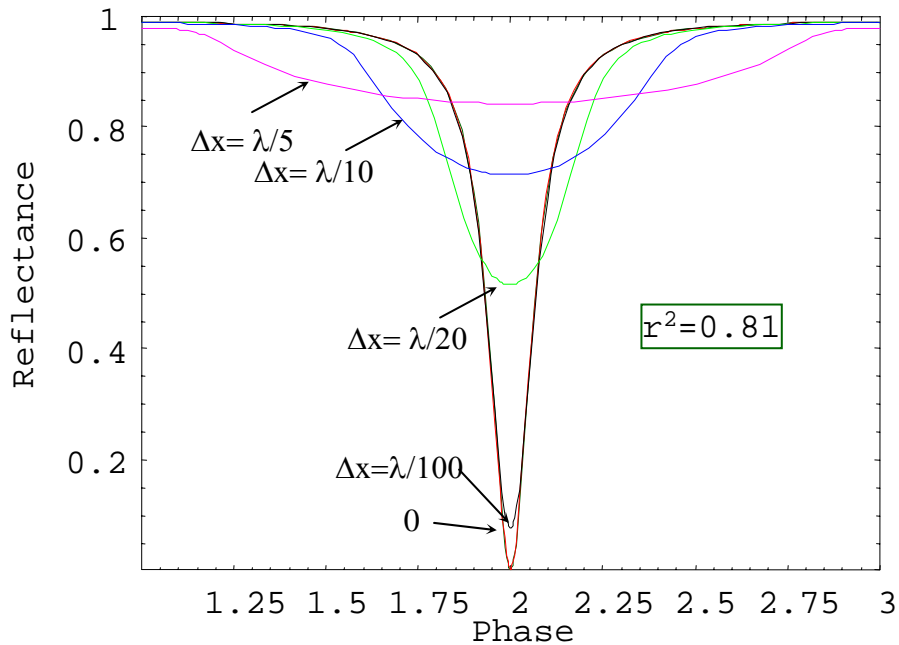
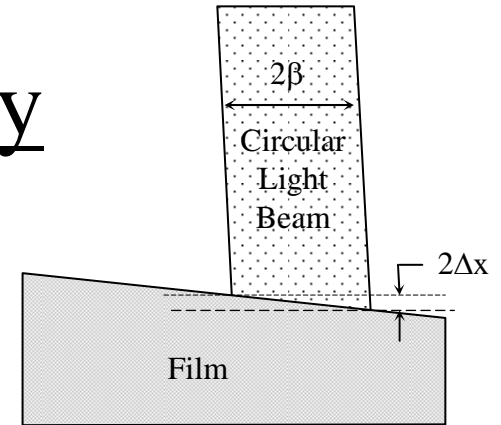
Theoretical gain in sensitivity

Amplitude reflectivity coefficient r	Reflectance at one surface r^2	Gain in sensitivity compared to uncoated film
0.9	0.81	66
0.97	0.95	250
0.999	0.998	6253

Practical limitations of sensitivity

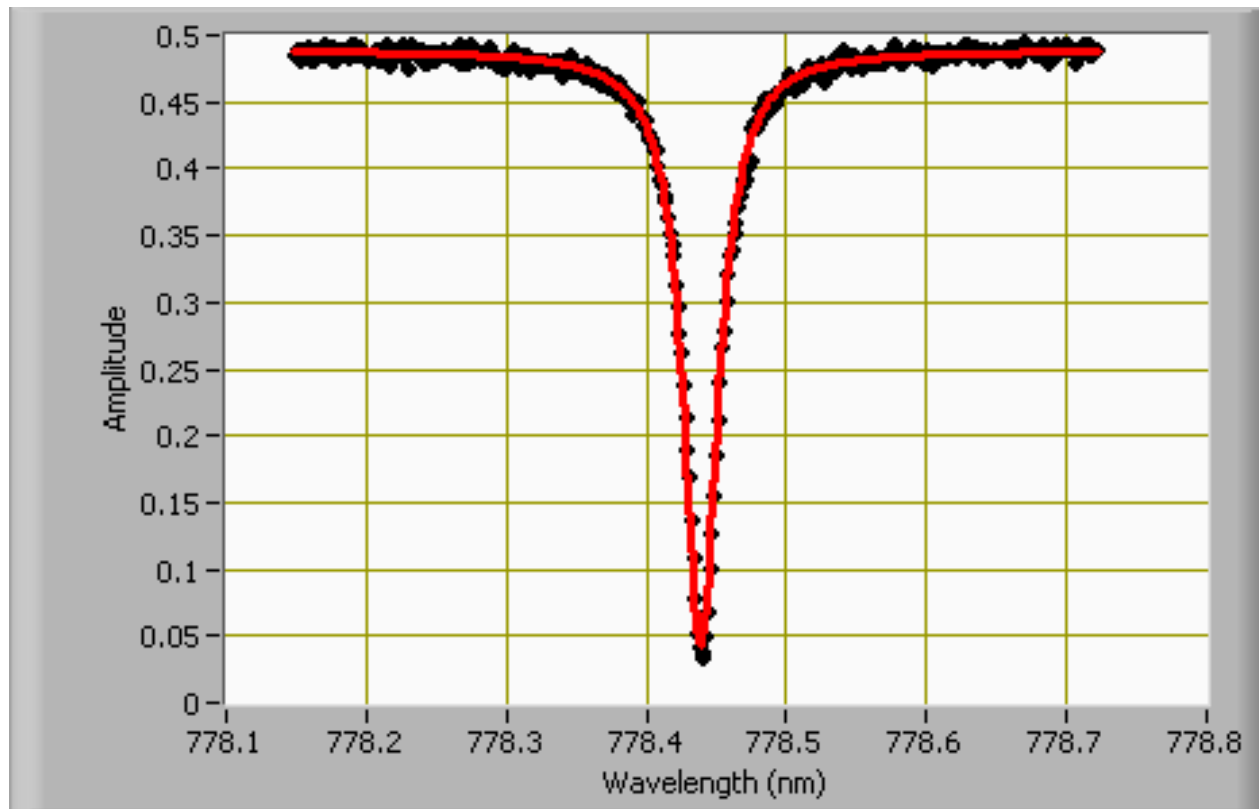
- Quality of the reflecting surfaces
- Parallelism of the two surfaces
- Optical beam diffraction

Practical limitations of sensitivity

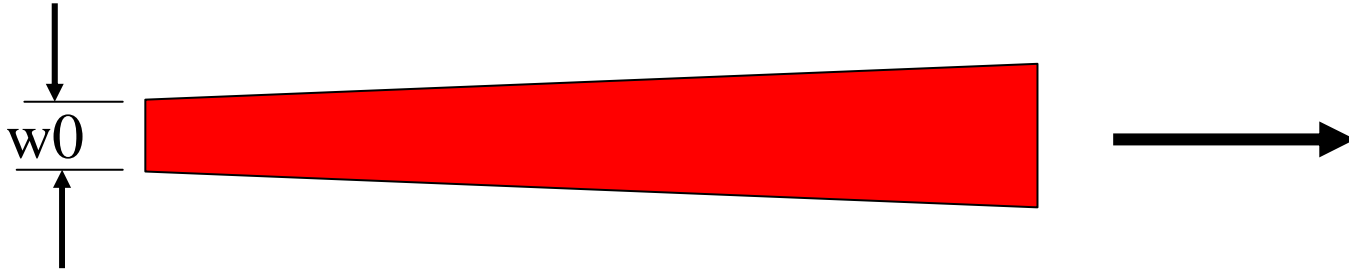


Practical limitations of sensitivity: experiment

Etalon : flatness and parallelism are $\lambda/100$ over 10 mm diameter
 $d = 100 \mu\text{m}$



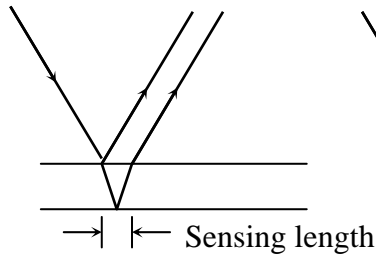
Practical limitations of sensitivity: beam diffraction



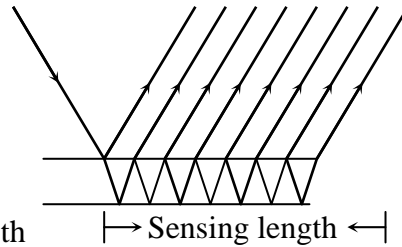
$$\text{Diffraction angle } \theta \sim \frac{\lambda}{w_0}$$

For beam waist of $50 \mu\text{m}$, parallelism of $\lambda/100$ over 10 mm is more important than beam diffraction for an etalon of $100 \mu\text{m}$ thickness and 0.95 reflectivity

High reflectivity and walk off?

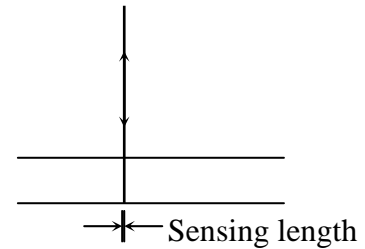


Low reflectivity



High reflectivity

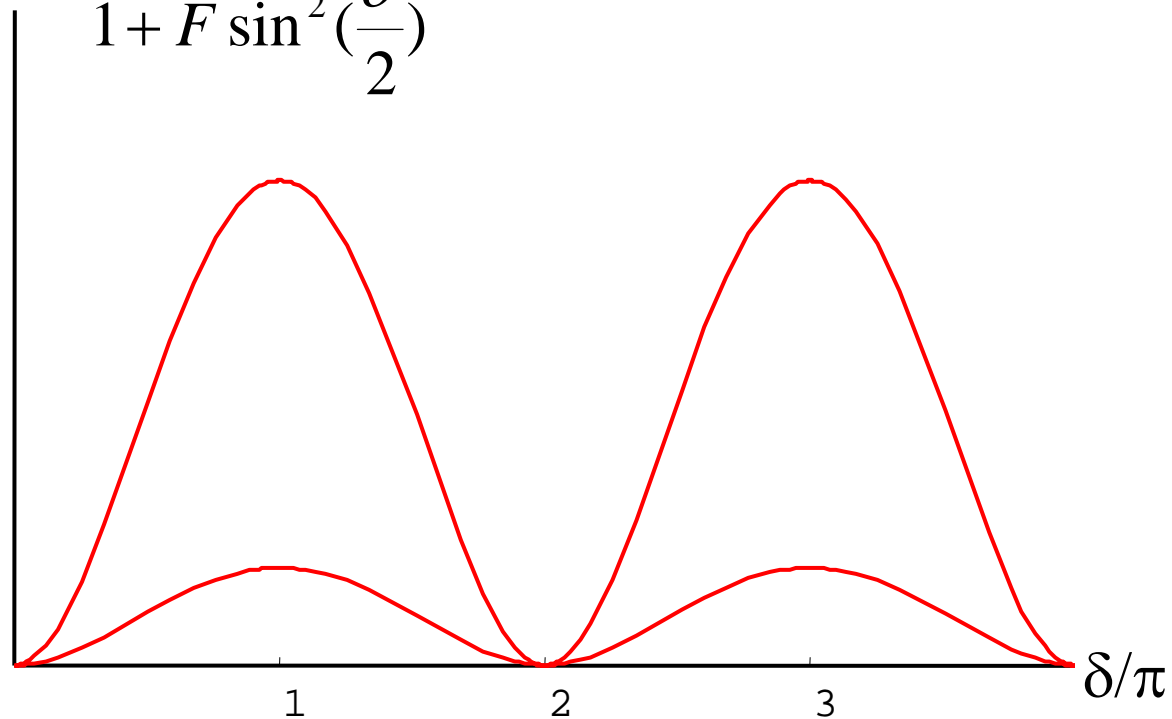
Oblique incidence



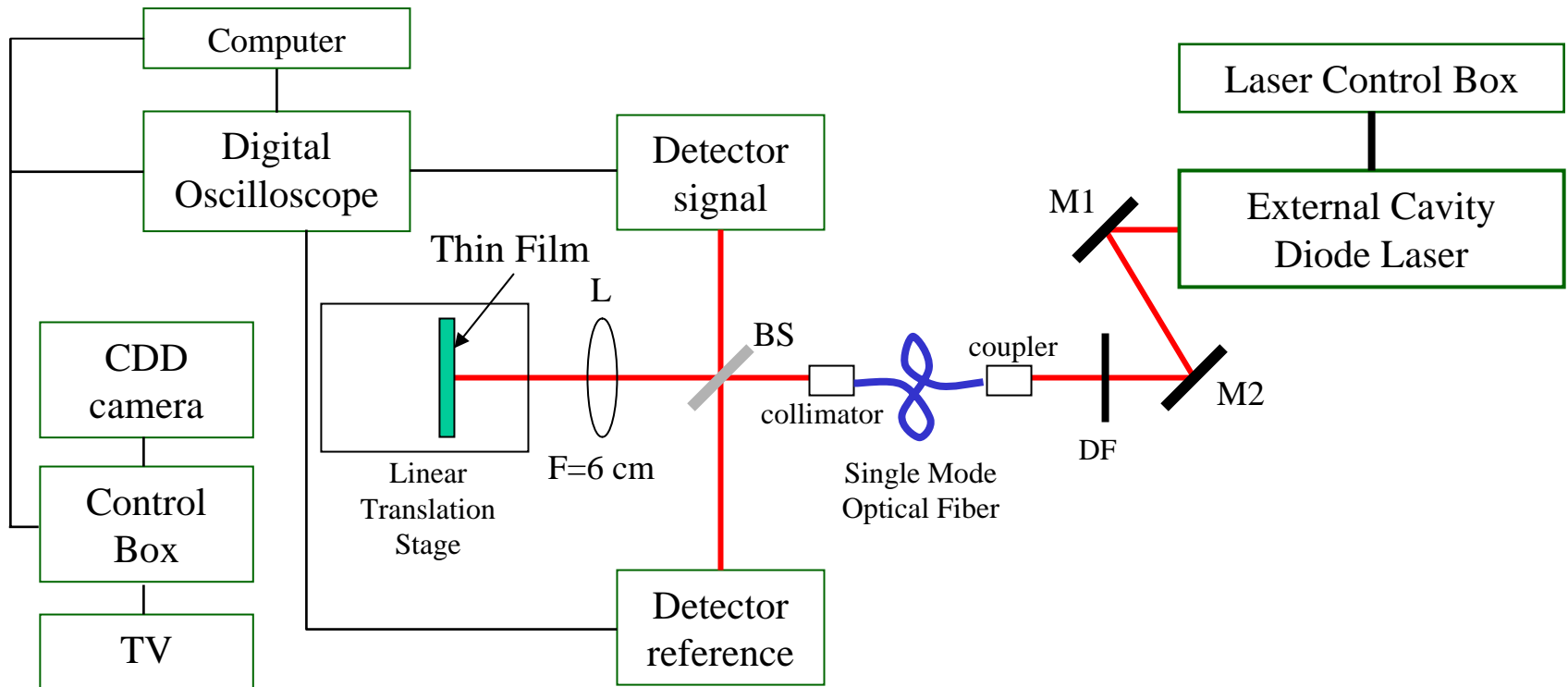
Normal incidence

Higher Sensitivity: Higher Laser Power

$$I_r = I_i \left(1 - \frac{1}{1 + F \sin^2\left(\frac{\delta}{2}\right)} \right)$$



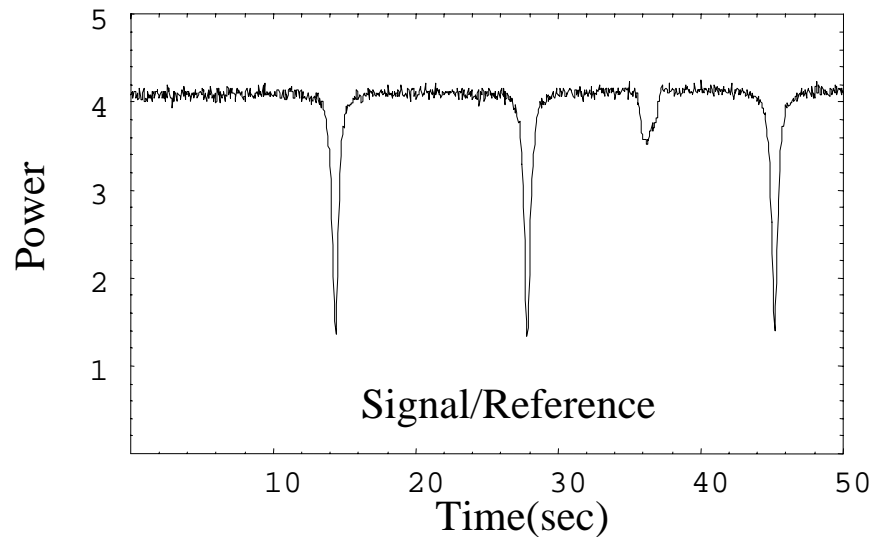
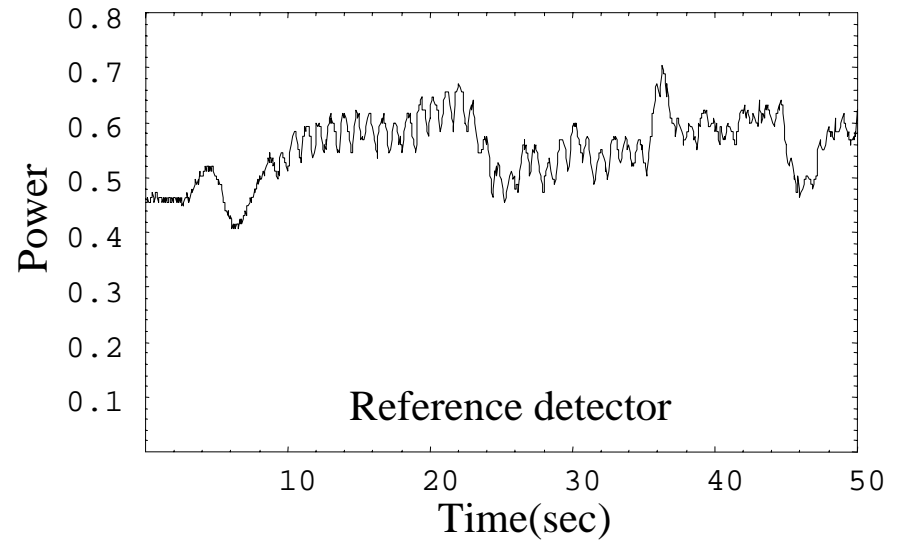
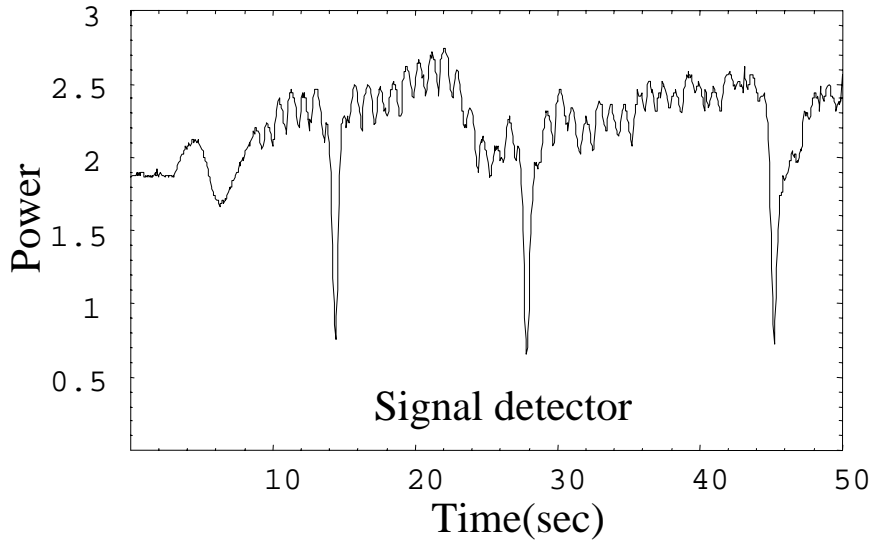
Experimental Setup



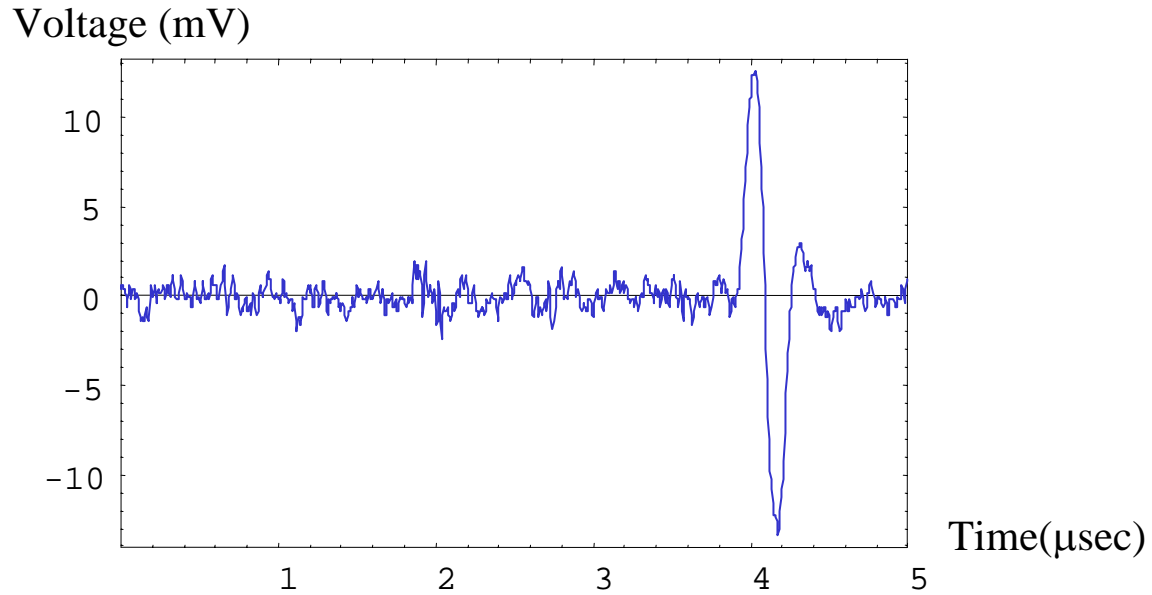
Experimental Setup



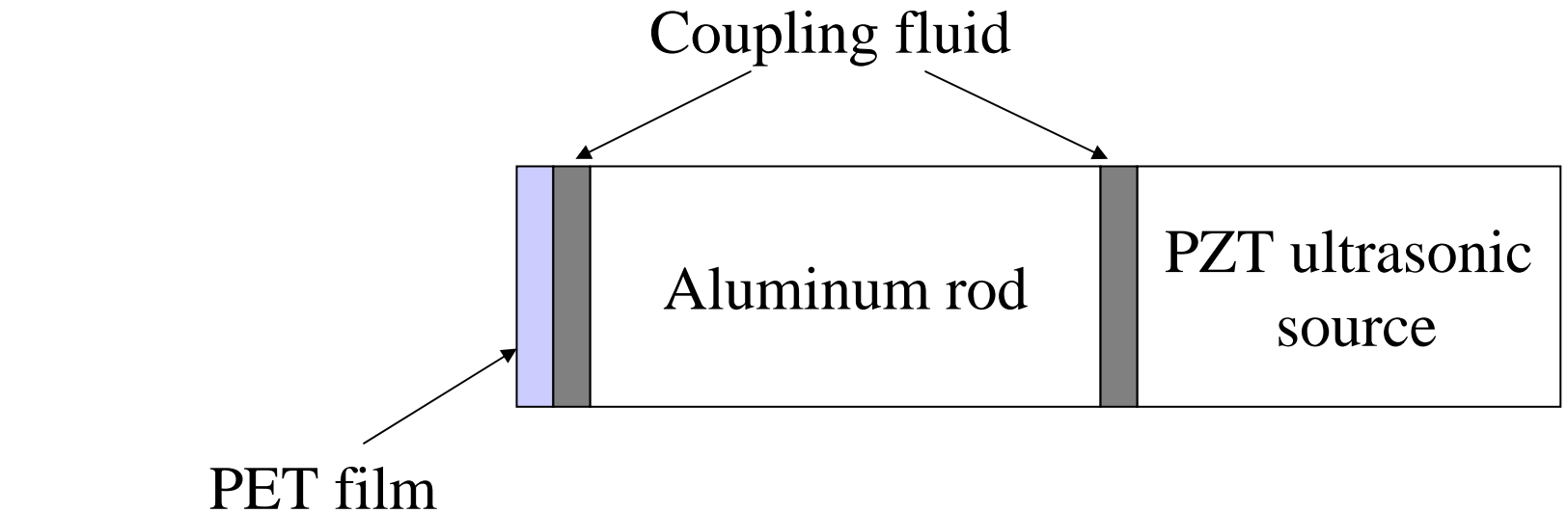
Typical Transfer Function



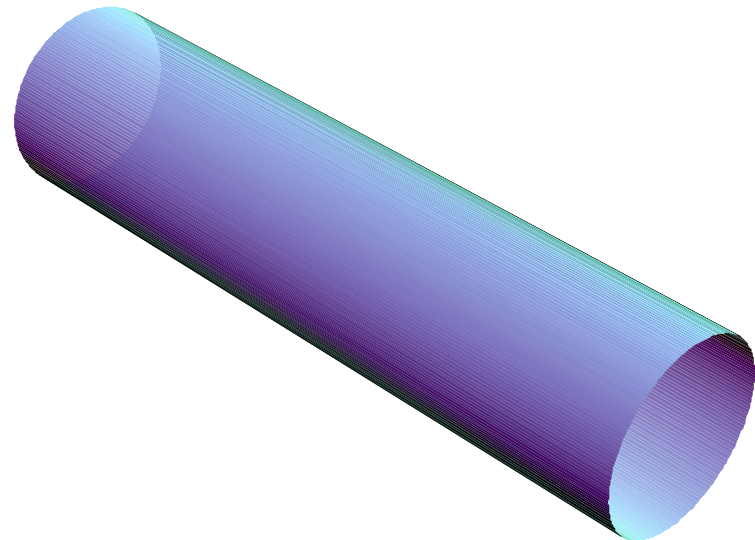
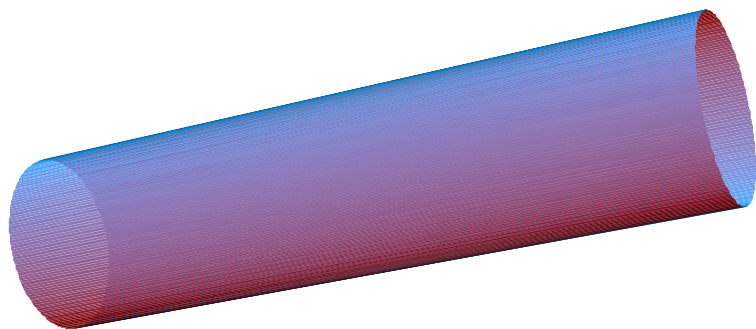
Typical ultrasonic pulse from the setup



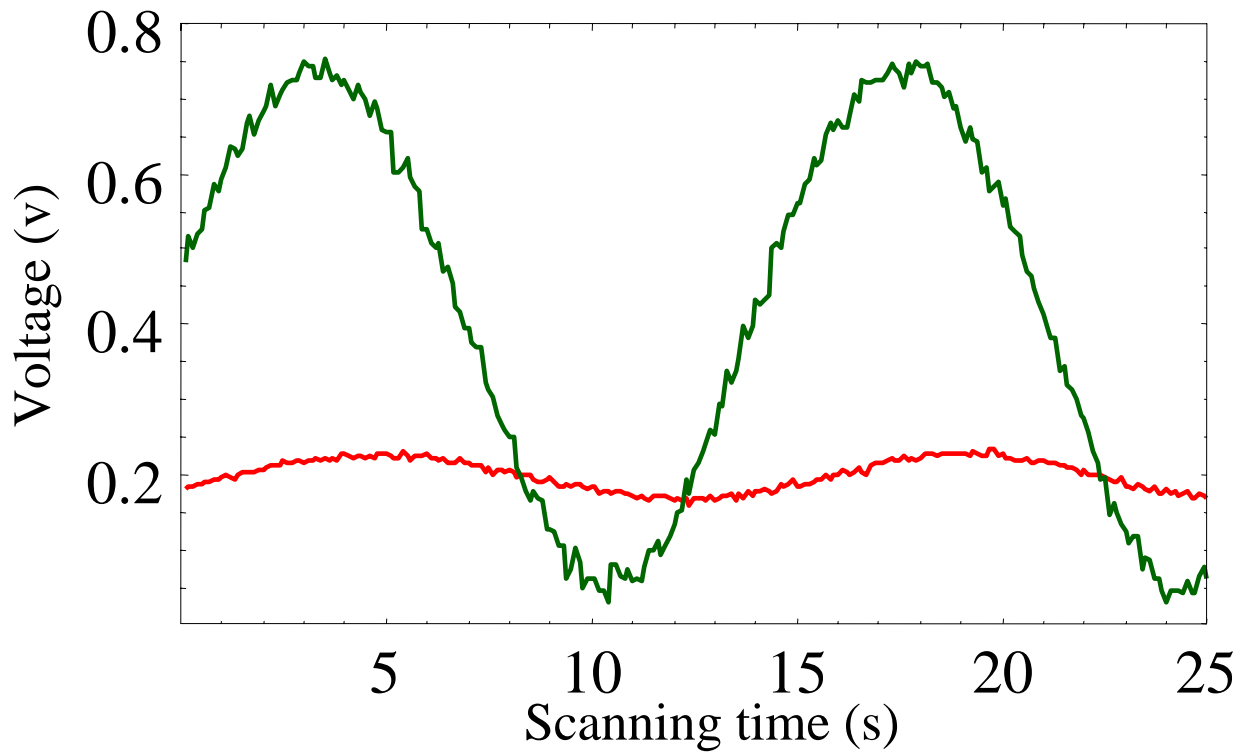
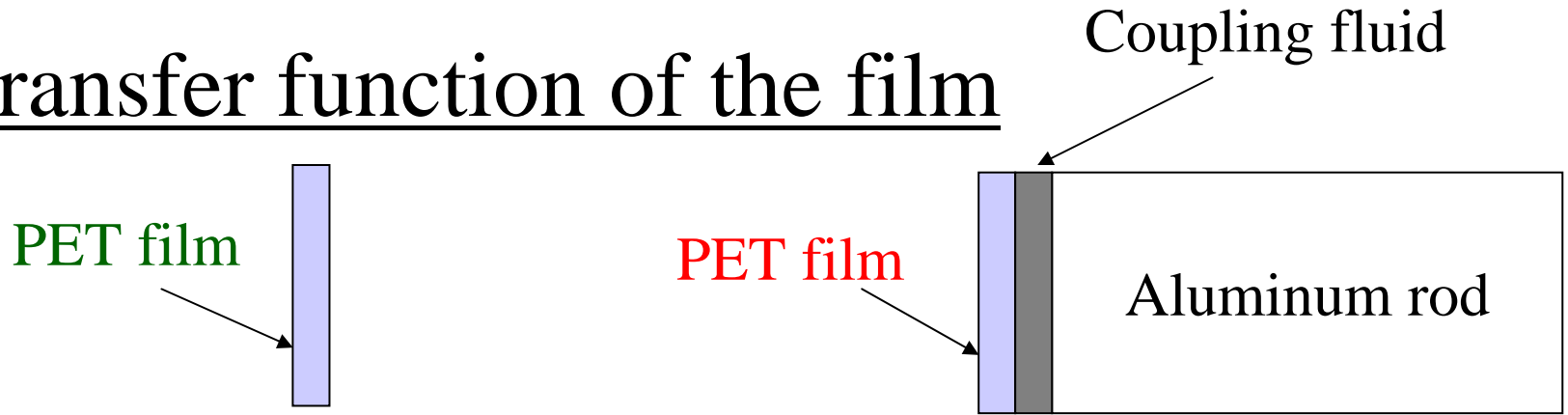
Film on metallic surfaces



Overhead projector transparency!

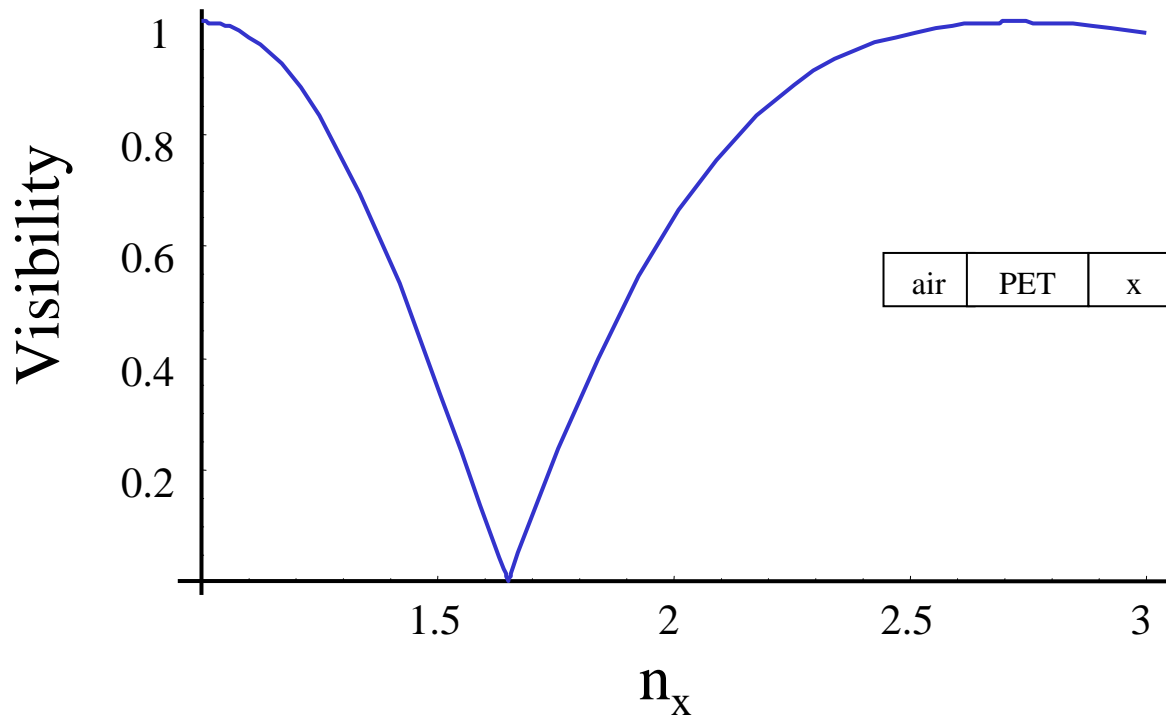
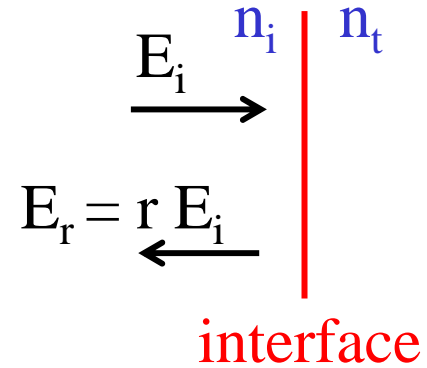


Transfer function of the film



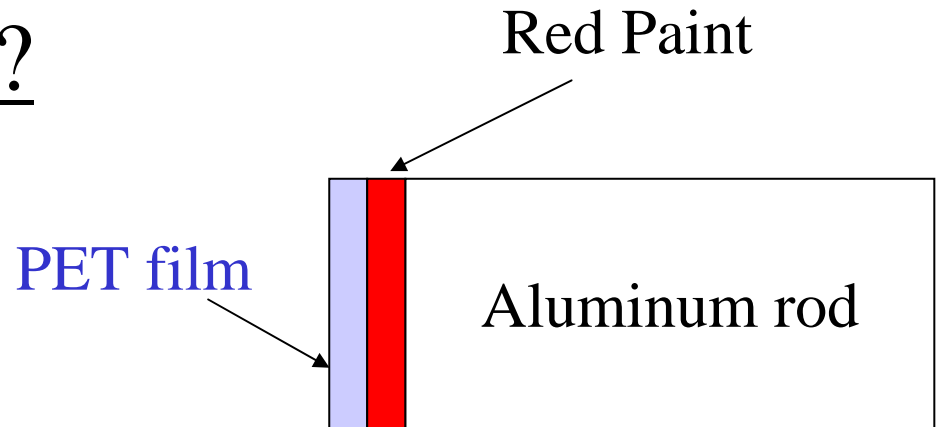
Why lost visibility?

$$r = \frac{n_i - n_t}{n_i + n_t}$$

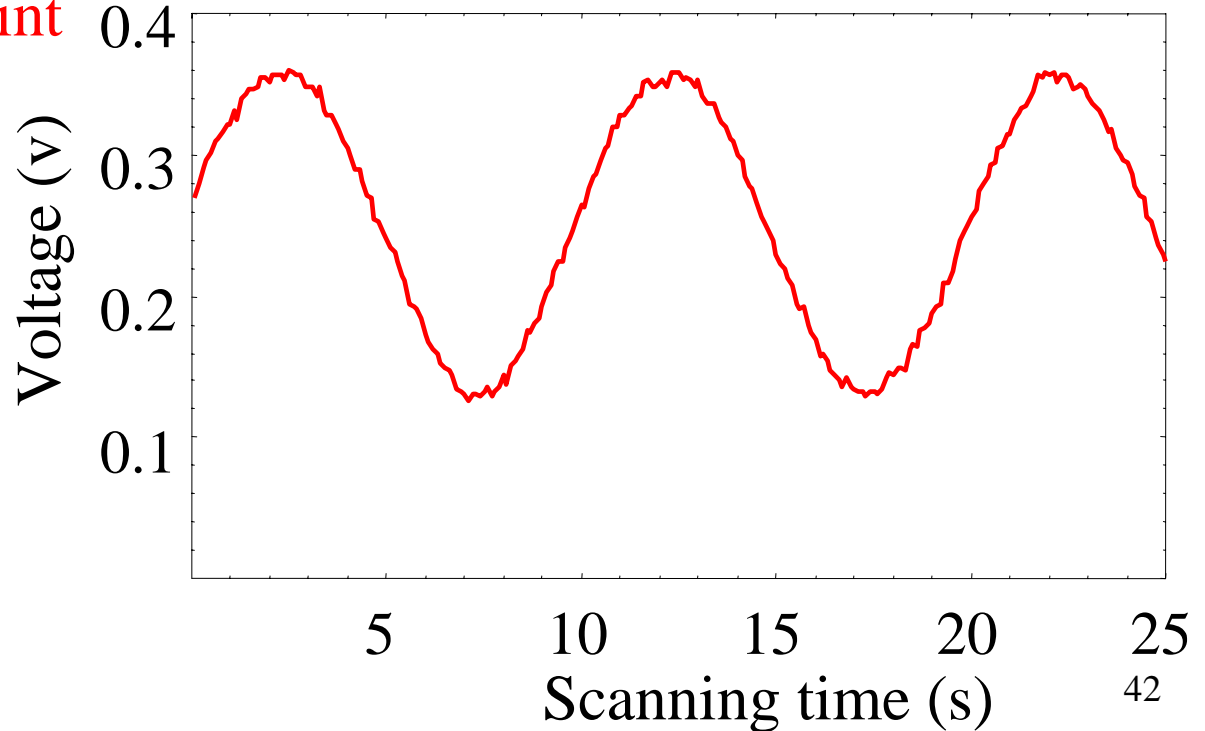


Increase visibility?

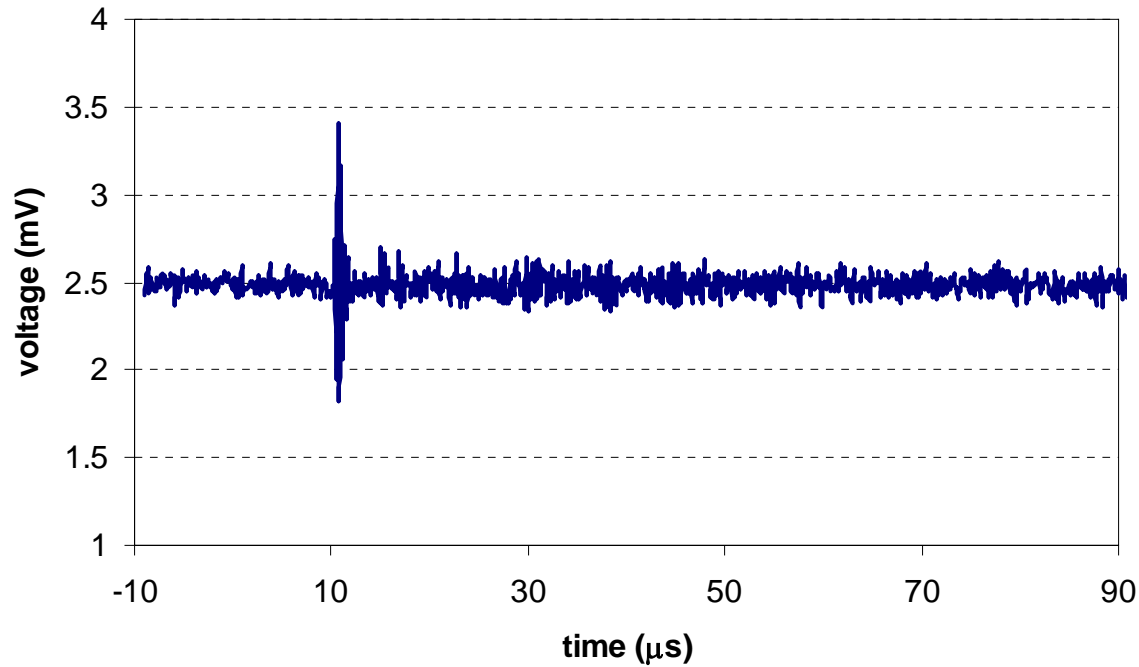
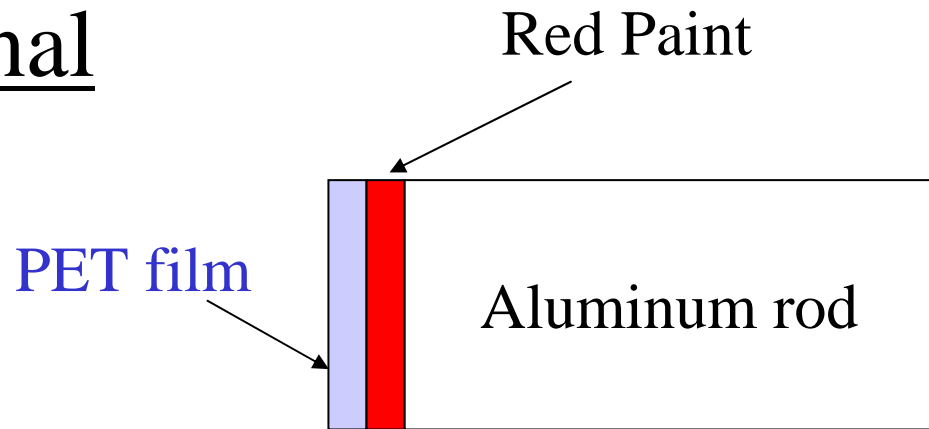
- Use coating layers
Expensive
- Use colored coupling material



Red paint



Ultrasonic Signal



$$d = 120 \mu\text{m}$$
$$\delta d = 0.3 \text{ nm}$$

Thank You For Your Listening

- KFUPM
Physics Department
- Al-Yammamah Programme
BAe Systems
The British Council
- University College London
Department of Physics and Bioengineering
Lasers and Endoscopy Group
Dr. Paul Beard