

CH 16 Oscillations الاقتران

- Simple harmonic motion
 - displacement
 - velocity
 - acceleration
 - Force law
 - energy
- Angular simple harmonic motion.
- Pendulums
 - simple pendulum.
 - physical pendulum.
- Simple harmonic motion and uniform circular motion.

الحركة التوافقية البسيطة :- Simple harmonic motion

Displacement

The motion of an object is a simple harmonic motion (SHM), if the object's displacement is given by

$$x(t) = x_m \cos(\omega t + \phi)$$

↑ displacement at time t
 ↑ Amplitude (maximum displacement)
 ↑ Angular frequency
 ↑ time
 ↑ phase constant (phase angle)

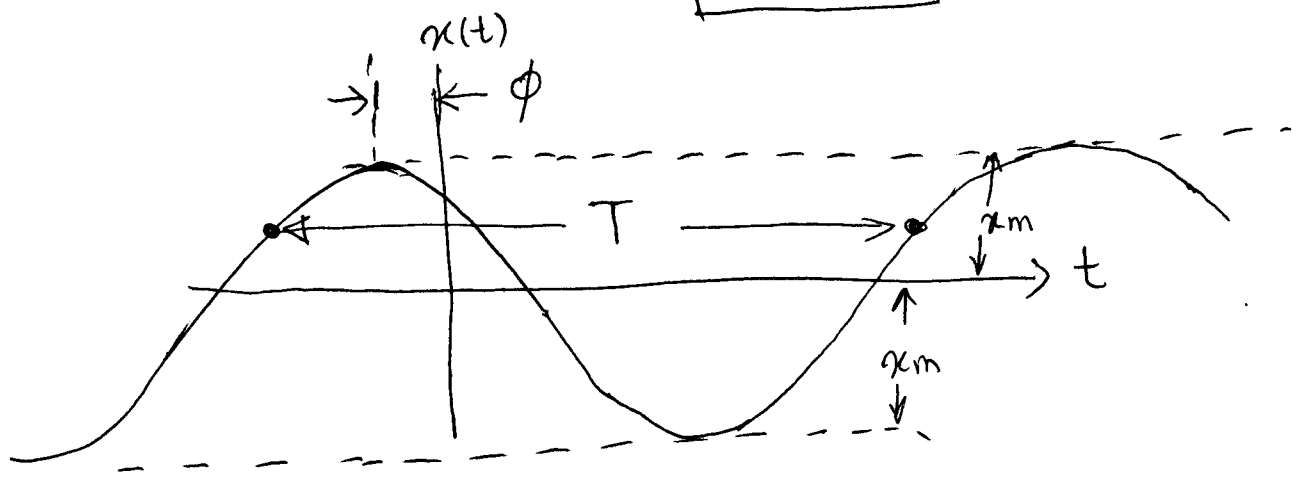
x_m
 ω
 ϕ

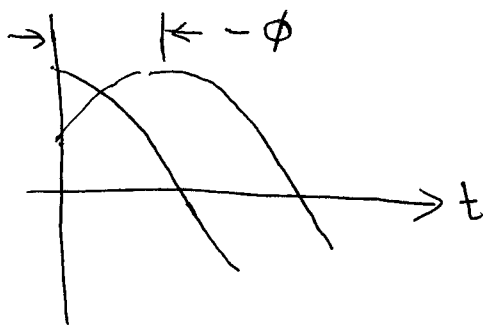
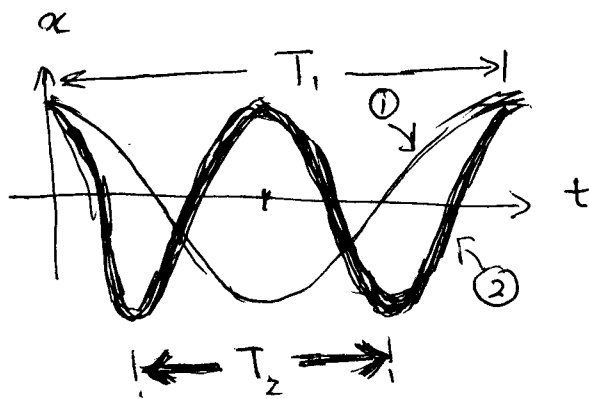
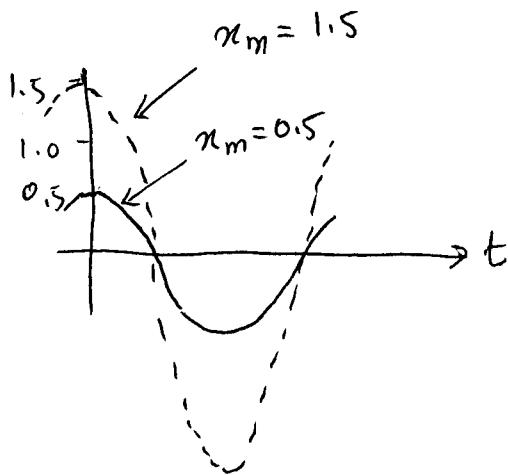
} constants
 } omega
 } phi

$$\omega = \frac{2\pi}{T} = 2\pi f$$

↑ Angular frequency (rad/s)
 ↑ period
 ↑ frequency (Hertz = Hz = Oscillation per second)

$$T = \frac{1}{f}$$





Decreasing ϕ shifts the curve right ward.

Velocity

$$v(t) = \frac{dx(t)}{dt} = -\omega x_m \sin(\omega t + \phi)$$

$$v(t) = -v_m \sin(\omega t + \phi)$$

$$v_m = \omega x_m$$

velocity amplitude.

acceleration

$$a(t) = \frac{dv(t)}{dt} = -\omega^2 x_m \cos(\omega t + \phi)$$

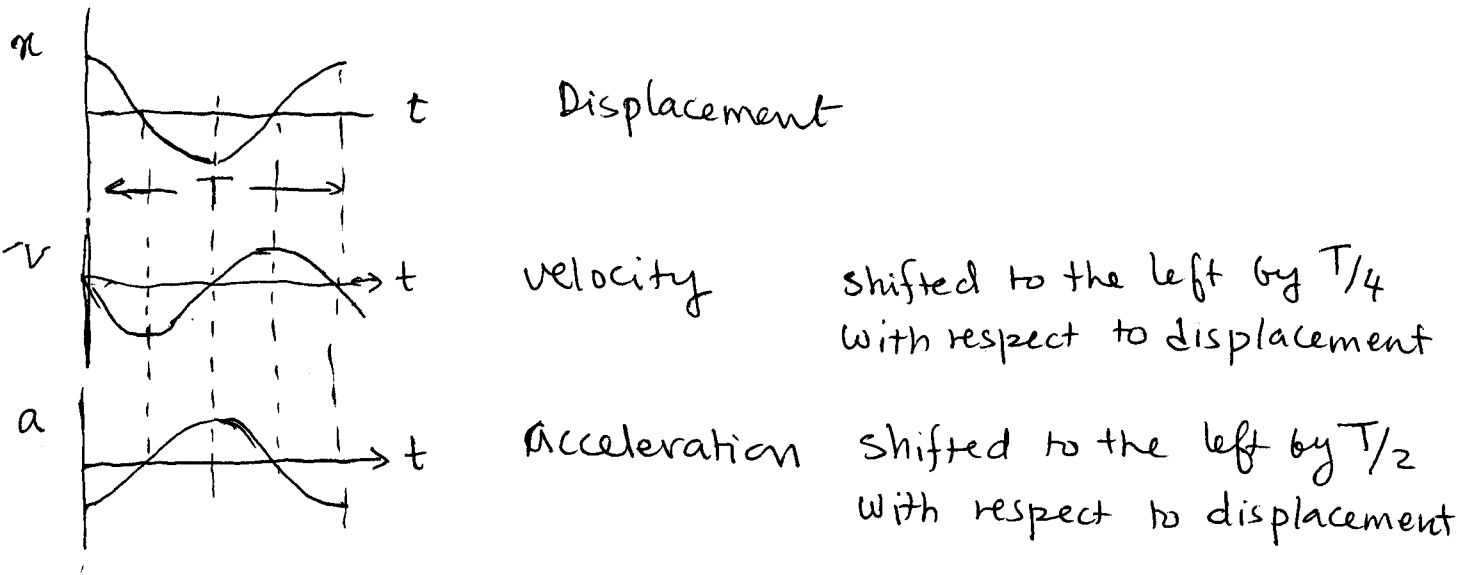
$$a(t) = -a_m \cos(\omega t + \phi)$$

$$a_m = \omega^2 x_m$$

$$a(t) = -\omega^2 x(t)$$

In simple harmonic motion,

$$a(t) = -\omega^2 x(t)$$



Force Law :-

For simple harmonic motion $a(t) = -\omega^2 x(t)$

From Newton's second law $F = ma$

$$F = m(-\omega^2 x)$$

$$F = -m\omega^2 x$$

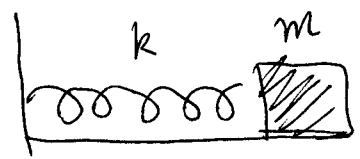
Hook's Law

$$k = m\omega^2$$

spring constant

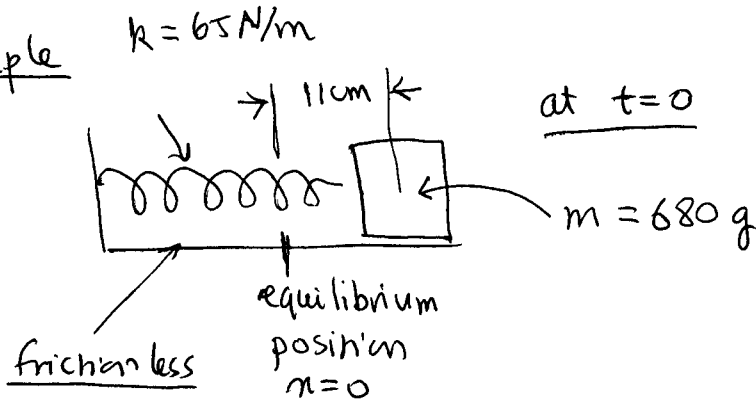
angular frequency

mass



$$\omega = \sqrt{\frac{k}{m}}$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

Example

Q what is the angular frequency, the frequency and the period of the motion?

A $\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{65}{0.680}} = 9.8 \text{ rad/sec}$

↑ convert to kg.

$$f = \frac{\omega}{2\pi} = 1.6 \text{ Hz}$$

$$T = \frac{1}{f} = 0.64 \text{ s}$$

Q what is the amplitude of the motion?

A $x_m = 11 \text{ cm.}$

Q what is the maximum speed of the block and where is the block when it occurs?

A $v_m = \omega x_m = (9.8 \text{ rad/s})(0.11 \text{ m}) = 1.1 \text{ m/s}$

↑ convert to m

this happens when $x = 0$

Q what is the maximum acceleration of the block?

A $a_m = \omega^2 x_m = (9.8 \text{ rad/s})^2 (0.11 \text{ m}) = 11 \text{ m/s}^2$

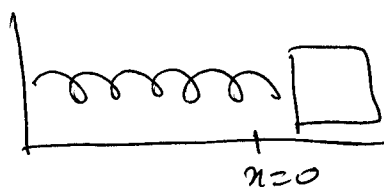
Q what is the phase constant of the motion?

A at $t = 0$, $x = 11 \text{ cm}$
 $x(t) = x_m \cos(\omega t + \phi)$

$$0.11 = 0.11 \cos(\phi)$$

$$1 = \cos(\phi) \Rightarrow \phi = 0$$

Example



At $t = 0$

$$x = -8.50 \text{ cm}$$

$$v = -9.20 \text{ m/s}$$

$$a = 47.0 \text{ m/s}^2$$

Q what is the angular frequency of the system?

A

$$x(0) = x_m \cos \phi$$

$$v(0) = -\omega x_m \sin \phi$$

$$a(0) = -\omega^2 x_m \cos \phi$$

$$\frac{a(0)}{x(0)} = \frac{-\omega^2 x_m \cos \phi}{x_m \cos \phi} = -\omega^2$$

$$\omega = \sqrt{-\frac{a(0)}{x(0)}} = \sqrt{-\frac{47.0}{-8.50}} = 23.5 \text{ rad/s}$$

Q what is the phase constant and amplitude?

$$\frac{v(0)}{x(0)} = \frac{-\omega x_m \sin \phi}{x_m \cos \phi} = -\omega \tan \phi$$

$$\tan \phi = -\frac{v(0)}{\omega x(0)} = \frac{-0.920}{(23.5)(-0.085)} = -0.461$$

see 02,01

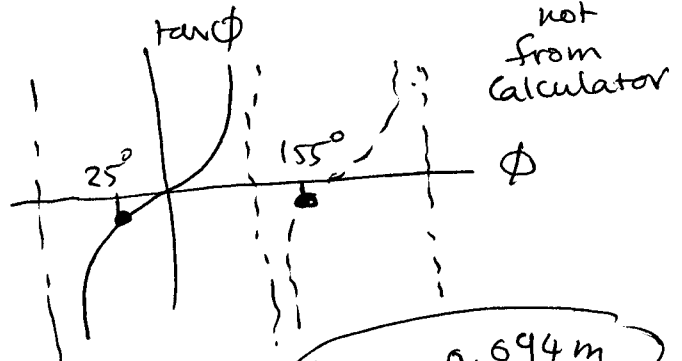
$$\phi = \tan^{-1}(-0.461)$$

$$\phi = -25^\circ$$

OR

$$\phi = 180^\circ + (-25^\circ) = 155^\circ$$

which one is correct?



we know that

$$x(t) = x_m \cos \phi$$

$$x_m = \frac{x(t)}{\cos \phi}$$

↑
always positive

for $\phi = -25^\circ$

$$x_m = -0.094 \text{ m}$$

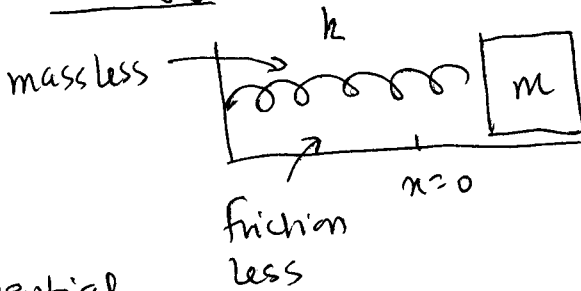
not acceptable

for $\phi = 155^\circ$

$$x_m = 0.094 \text{ m}$$

so $\phi = 155^\circ$ and $x_m = 0.094 \text{ m}$

Energy



elastic potential energy

$$\rightarrow U = \frac{1}{2} k x^2 = \frac{1}{2} k x_m^2 \cos^2(\omega t + \phi)$$

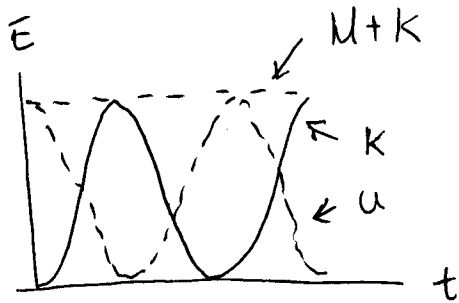
Kinetic energy

$$\rightarrow K = \frac{1}{2} m v^2 = \frac{1}{2} m (-\omega x_m \sin(\omega t + \phi))^2$$

$$= \frac{1}{2} m \omega^2 x_m^2 \sin^2(\omega t + \phi)$$

Mechanical energy

$$\rightarrow E = U + K = \frac{1}{2} k x_m^2$$



Angular simple harmonic motion :

$F \rightarrow \tau$

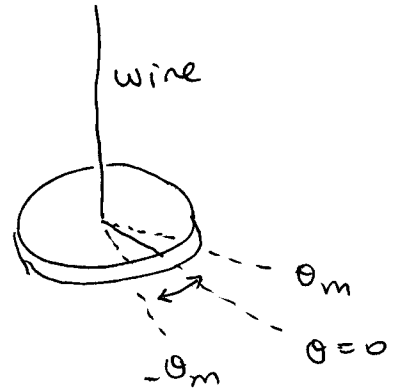
$x \rightarrow \theta$

$m \rightarrow I$

$k \rightarrow k$
 ↑
 kappa

spring constant

torsion constant



$k = m \omega^2$
 $\kappa = I \omega^2$

$F = -kx \Rightarrow \tau = -\kappa \theta$

$T = 2\pi \sqrt{\frac{m}{k}} \Rightarrow T = 2\pi \sqrt{\frac{I}{\kappa}}$

Example

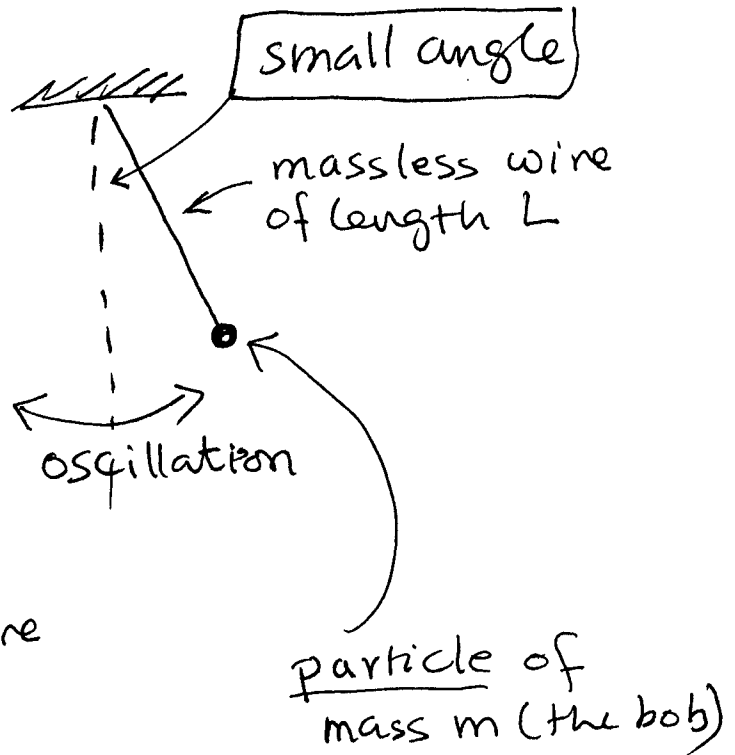
Pendulums

Simple pendulum

$$T = 2\pi \sqrt{\frac{L}{g}}$$

↑
period of oscillation

←
Length of the wire



Physical pendulum

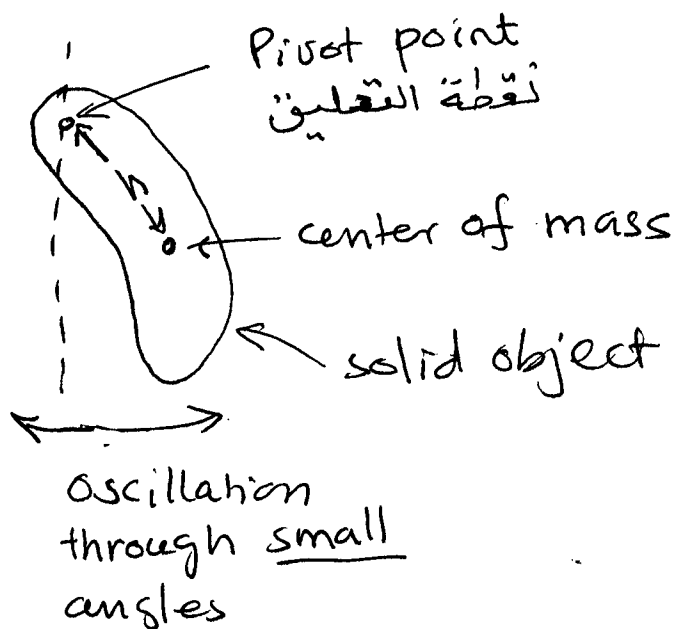
$$T = 2\pi \sqrt{\frac{I}{mgh}}$$

↑
period of oscillation

←
moment of inertia of the solid object about the pivot point

↑
mass of the solid object

↑
distance between pivot point and the center of mass

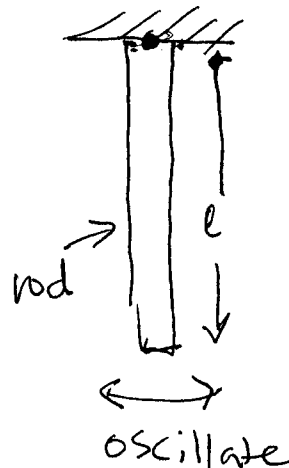


moment of inertia of the solid object about the pivot point

distance between pivot point and the center of mass

Example

Q what is the period of oscillation



A

$$T = 2\pi \sqrt{\frac{I}{mg\bar{h}}}$$

$$= 2\pi \sqrt{\frac{\frac{1}{3} mL^2}{mg \frac{L}{2}}}$$

$$= 2\pi \sqrt{\frac{2L}{3g}}$$

Parallel-axis theorem

$$\frac{1}{12} mL^2 + m\left(\frac{L}{2}\right)^2 = \frac{1}{3} mL^2$$

moment of Inertia about com.

center of mass

Simple harmonic motion and uniform circular motion

Simple harmonic motion is the projection of uniform circular motion on a diameter of the circle in which the later motion occurs

