

Pb # 8.

$$a) \quad E_{rot} = \frac{\hbar^2}{2I_{cm}} l(l+1) \quad l = 0, 1, 2, \dots$$

$$I_{cm} = \mu R_0^2 \quad \mu = \frac{m_1 m_2}{m_1 + m_2} = \frac{1u \times 35u}{(1+35)u} = \frac{35u}{36}$$

$$\mu = 0.972 \times 1.6605 \times 10^{-27} = 1.6 \times 10^{-27} \text{ Kg}$$

$$R_0 = 0.128 \text{ nm}$$

$$\Rightarrow I_{cm} = 1.6 \times 10^{-27} \times (0.128 \times 10^{-9})^2 = 2.62 \times 10^{-47} \text{ Kg} \cdot \text{m}^2$$

$$l=0 \quad E_{rot} = 0$$

$$l=1 \quad E_{rot} = \frac{\hbar^2}{2I_{cm}} 2 = \frac{\hbar^2}{I_{cm}} = \frac{(1.05 \times 10^{-34})^2}{2.62 \times 10^{-47}}$$

$$= 4.20 \times 10^{-22} \text{ J} = \boxed{2.63 \times 10^{-3} \text{ eV}}$$

$$l=2 \quad E_{rot} = \frac{\hbar^2}{2I_{cm}} 6 = 2.63 \times 10^{-3} \times 3 = \boxed{7.89 \times 10^{-3} \text{ eV}}$$

$$l=3 \quad E_{rot} = \frac{\hbar^2}{2I_{cm}} 12 = 2.63 \times 10^{-3} \times 6 = \boxed{15.78 \times 10^{-3} \text{ eV}}$$

b)

$$U = \frac{1}{2} k x^2$$

↑ displacement from equilibrium position

$$0.15 \times 1.6 \times 10^{-19} = \frac{1}{2} k (0.01 \times 10^{-9})^2 \Rightarrow k = 480 \text{ N/m}$$

$$k = \mu \omega^2 \Rightarrow \omega = \sqrt{\frac{k}{\mu}} = \sqrt{\frac{480}{1.6 \times 10^{-27}}} = 5.5 \times 10^{14} \frac{\text{rad}}{\text{s}}$$

$$f = \frac{\omega}{2\pi} = \boxed{8.72 \times 10^{13} \text{ Hz}}$$