

Phys 301  
HomeWork Solution  
Chapter 2

Pb#9.

(a) No resisting force

motion along the y-axis:  $F = ma = m \frac{dv}{dt} = -mg$

$$\int dv = -g \int dt \Rightarrow \boxed{v = -gt + v_0} \quad (1)$$

$v_0$  is the initial velocity of the particle at  $t=0$ .

At maximum height  $v=0 = -gt_m + v_0 \Rightarrow \boxed{t_m = \frac{v_0}{g}} \quad (2)$

(b) Resistive force  $F_r = -k v$

motion along the y-axis:  $F = ma = m \frac{dv}{dt} = -mg - k m v$

$$\int \frac{dv}{kv+g} = - \int dt$$

$$\frac{1}{k} \ln(kv+g) = -t + C$$

$$\Rightarrow kv+g = e^{-kt+kc}$$

$$t=0 \quad v=v_0 \Rightarrow kv_0+g = e^{kc}$$

$$\Rightarrow kc = \ln(kv_0+g)$$

$$\Rightarrow c = \frac{1}{k} \ln(kv_0+g)$$

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$$\Rightarrow kv + g = e^{-kt} (kv_0 + g)$$

$$v = -\frac{g}{k} + \frac{(kv_0 + g)}{k} e^{-kt} \quad \text{--- (3)}$$

at maximum height  $v = 0$

$$-\frac{g}{k} + \frac{(kv_0 + g)}{k} e^{-kt_m} = 0$$

$$\Rightarrow \frac{g}{kv_0 + g} = e^{-kt_m}$$

$$\Rightarrow kt_m = \ln\left(\frac{kv_0}{g} + 1\right)$$

For small values of  $k$   $\ln\left(1 + \frac{kv_0}{g}\right) = \frac{kv_0}{g} - \frac{1}{2}\left(\frac{kv_0}{g}\right)^2 + \frac{1}{3}\left(\frac{kv_0}{g}\right)^3$

$$\Rightarrow t_m = \frac{v_0}{g} \left[ 1 - \frac{kv_0}{2g} + \frac{1}{3}\left(\frac{kv_0}{g}\right)^2 + \dots \right] \quad \text{--- (4)}$$

when  $k \rightarrow 0$   $t_m \rightarrow \frac{v_0}{g}$  (equation 2).

you can also integrate  $t$  from  $0 \rightarrow t$  and  $v$  from  $v_0 \rightarrow 0$

$$\int_{v_0}^0 \frac{dv}{g + kv} = - \int_0^t dt$$

Pb #23  $F(t) = kt e^{-\alpha t}$

$$F = ma \Rightarrow a = \frac{F}{m} = \frac{kt}{m} e^{-\alpha t}$$

$$a = \frac{dv}{dt} \Rightarrow v = \int_0^t a dt = \frac{k}{m} \int_0^t t e^{-\alpha t} dt$$

integrating by part setting  $u = t$   $dv = e^{-\alpha t} dt$

$$\int u dv = uv - \int v du$$

$$\int t e^{-\alpha t} dt = -\frac{t}{\alpha} e^{-\alpha t} + \frac{1}{\alpha} \int_0^t e^{-\alpha t} dt$$

$$= -\frac{t}{\alpha} e^{-\alpha t} - \frac{1}{\alpha^2} e^{-\alpha t} \Big|_0^t$$

$$= -\frac{t}{\alpha} e^{-\alpha t} - \frac{1}{\alpha^2} e^{-\alpha t} + \frac{1}{\alpha^2}$$

$\Rightarrow$

$$v(t) = \frac{k}{m} \left[ \frac{1}{\alpha^2} - \frac{1}{\alpha} e^{-\alpha t} \left( t + \frac{1}{\alpha} \right) \right]$$

$$x(t) = \int_0^t v(i) dt = \frac{k}{m} \left[ \frac{1}{\alpha^2} \int_0^t dt - \frac{1}{\alpha} \int_0^t t e^{-\alpha t} dt - \frac{1}{\alpha^2} \int_0^t e^{-\alpha t} dt \right]$$

as before

$$x(t) = \frac{k}{m} \left[ \frac{t}{\alpha^2} - \frac{1}{\alpha} \left( \frac{1}{\alpha^2} - \frac{1}{\alpha} e^{-\alpha t} \left( 1 + \frac{1}{\alpha} \right) \right) + \frac{1}{\alpha^3} (e^{-\alpha t} - 1) \right]$$

$$x(t) = \frac{k}{m} \left[ \frac{t}{\alpha^2} - \frac{2}{\alpha^3} + \frac{1}{\alpha^2} e^{-\alpha t} \left( t + \frac{2}{\alpha} \right) \right]$$

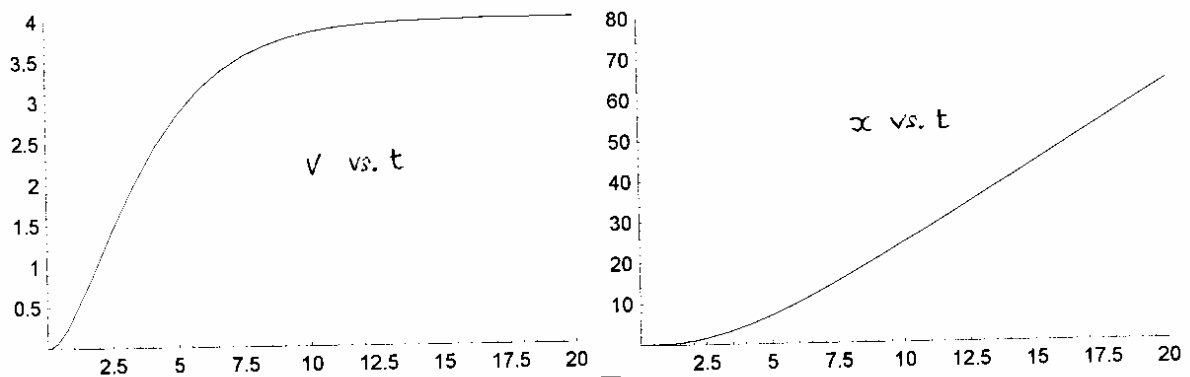
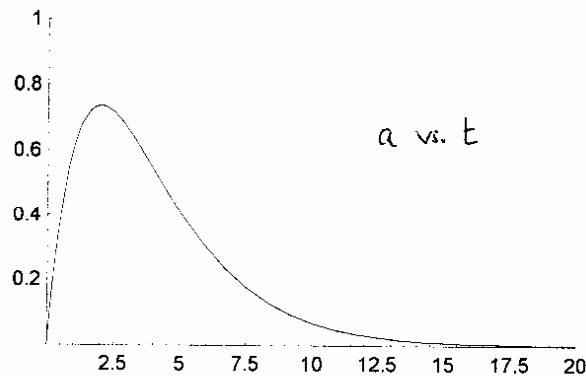
Substitute  $m = 1 \text{ kg}$   $k = 1 \text{ N/s}$  and  $\alpha = 0.5 \text{ s}^{-1}$

$$a(t) = t e^{-\frac{t}{2}} \quad (1)$$

$$v(t) = 4 - 2(t+2) e^{-\frac{t}{2}} \quad (2)$$

$$x(t) = -16 + 4t + 4(t+4) e^{-\frac{t}{2}} \quad (3)$$

You can plot these functions using any plotting software. I have used Mathematica to plot these graphs.



Pb #31

See example 2.10 for details.

Solutions are given by equation 2.78

$$x - x_0 = A \cos \alpha t + B \sin \alpha t$$

$$y - y_0 = \dot{y}_0 t$$

$$z - z_0 = -B \cos \alpha t + A \sin \alpha t$$

• where  $\alpha = \frac{qB_0}{m}$

at  $t=0$   $\dot{z} = \dot{z}_0$  and  $\dot{x} = \dot{x}_0$

$$\Rightarrow \alpha B = \dot{x}_0$$

$$\alpha A = \dot{z}_0$$

• 
$$\Rightarrow \begin{cases} x - x_0 = \frac{\dot{z}_0}{\alpha} \cos \alpha t + \frac{\dot{x}_0}{\alpha} \sin \alpha t \\ y - y_0 = \dot{y}_0 t \\ z - z_0 = -\frac{\dot{x}_0}{\alpha} \cos \alpha t + \frac{\dot{z}_0}{\alpha} \sin \alpha t \end{cases}$$

Note that  $(x - x_0)^2 + (z - z_0)^2 = \left( \frac{\dot{z}_0^2}{\alpha^2} + \frac{\dot{x}_0^2}{\alpha^2} \right) (\underbrace{\cos^2 \alpha t + \sin^2 \alpha t}_1)$

In the  $x-z$  plane the motion is circular with

a radius  $r = \frac{1}{\alpha} \sqrt{\dot{z}_0^2 + \dot{x}_0^2} = \frac{m}{qB_0} \sqrt{\dot{x}_0^2 + \dot{z}_0^2}$

Pb # 38.

$$v(x) = \alpha x^{-n}$$

$$v(x) = 0 \quad \text{when } x=0 \quad \text{at } t=0$$

$$\begin{aligned} (a) \quad F(x) &= m a = m \frac{dv}{dt} = m \left( \frac{dv}{dx} \right) \left( \frac{dx}{dt} \right) = m \left( \frac{dv}{dx} \right) v \\ &= m \left( -n \alpha x^{-n-1} \right) \left( \alpha x^{-n} \right) \end{aligned}$$

$$\boxed{F(x) = -m n \alpha^2 x^{-(2n+1)}}$$

$$(b) \quad v(x) = \frac{dx}{dt} = \alpha x^{-n} \Rightarrow x^n dx = \alpha dt$$

$$\int x^n dx = \int \alpha dt \Rightarrow \frac{x^{n+1}}{n+1} = \alpha t + C$$

$$x^{n+1} = (n+1)\alpha t \Rightarrow \boxed{x(t) = \left[ (n+1)\alpha t \right]^{\frac{1}{n+1}}}$$

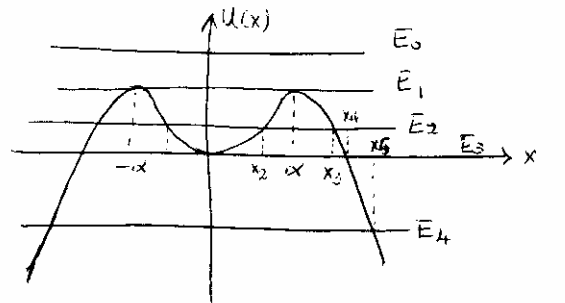
$$(c) \quad \boxed{F(t) = -m n \alpha^2 \left[ (n+1)\alpha t \right]^{-\frac{2n+1}{n+1}}}$$

Pb # 43.

$$F(x) = -kx + k \frac{x^3}{\alpha^2} \quad k > 0$$

$$F(x) = - \frac{\partial U}{\partial x} \Rightarrow U(x) = - \int F(x) dx$$

$$U(x) = + \frac{1}{2} k x^2 - \frac{1}{4} k \frac{x^4}{\alpha^2}$$

plot of  $U(x)$  vs  $x$ For small  $x$  values

$$U(x) \rightarrow \frac{1}{2} k x^2$$

For large  $x$  values,

$$U(x) \rightarrow -\frac{1}{4} k \frac{x^4}{\alpha^2}$$

Let us look for equilibrium points:

$$\frac{\partial U}{\partial x} = kx - \frac{kx^3}{\alpha^2} = 0 \Rightarrow x k \left(1 - \frac{x^2}{\alpha^2}\right) = 0$$

$$\Rightarrow x = 0 \quad \text{or} \quad x^2 = \alpha^2 \Rightarrow x = \pm \alpha$$

Three equilibrium points:

$$x_0 = 0$$

$$x_1 = \alpha$$

$$x_2 = -\alpha$$

Are these equilibrium points stable or unstable?

$$\left. \frac{\partial^2 U}{\partial x^2} \right|_0 = k - 3 \frac{kx^2}{\alpha^2} \Big|_0 = k > 0 \Rightarrow \text{stable}$$

$$\left. \frac{\partial^2 U}{\partial x^2} \right|_{\pm\alpha} = -k - 3 \frac{k\alpha^2}{\alpha^2} = -2k < 0 \Rightarrow \text{unstable}$$

For  $E = E_0$ , the motion is unbounded.

For  $E = E_1$ , if the particle is at a point of unstable equilibrium it may remain there but if perturbed slightly it will move away from equilibrium.

Let us calculate the value of  $E_1$ !

$$\frac{dU}{dx} = kx - \frac{kx^3}{\alpha^2} = 0 \Rightarrow x_{1,2} = \pm \alpha \quad x_0 = 0$$

$$\bullet \quad U(\pm\alpha) = \frac{1}{2}k\alpha^2 - \frac{1}{4}k\alpha^2 = \frac{1}{4}k\alpha^2 = E_1$$

For  $E = E_2$  the particle is either bounded and oscillates between  $-x_2$  and  $x_2$  or it comes from  $\pm\infty$  to  $\pm x_3$  and returns to  $\pm\infty$ .

For  $E = E_3$ , the particle is either at the stable

● equilibrium point  $x = 0$  or beyond  $\pm x_4$ .

For  $E = E_4$ , the particle comes from  $\pm\infty$  to  $\pm x_5$  and returns to  $\pm\infty$ .



Pb#52.

Since this is a vertical motion under gravity, then

$$v = -gt + u \ln\left(\frac{m_0}{m}\right) \quad (\text{see text book or notes})$$

$$v = \frac{dy}{dt} = -gt + u \ln\left(\frac{m_0}{m}\right)$$

$$\Rightarrow \int_0^y dy = -g \int_0^t t dt + u \int_0^t \ln\left(\frac{m_0}{m}\right) dt$$

but  $dt = -\frac{dm}{\alpha}$  ( $\alpha$ : burn out rate)

$$\Rightarrow y = -\frac{1}{2}gt^2 + \frac{u}{\alpha} \int_{m_0}^m \ln\left(\frac{m_0}{m}\right) dm \quad (y_0 = 0)$$

$\int \ln\left(\frac{a}{x}\right) dx = x \left[1 + \ln\left(\frac{a}{x}\right)\right]$  so we have

$$y = -\frac{1}{2}gt^2 - \frac{u}{\alpha} \left[ m + m \ln\left(\frac{m_0}{m}\right) \right]_{m_0}^m$$

$$= -\frac{1}{2}gt^2 - \frac{u}{\alpha} \left[ m + m \ln\left(\frac{m_0}{m}\right) - m_0 \right]$$

$$y = -\frac{1}{2}gt^2 - \frac{u(m-m_0)}{\alpha} - \frac{u}{\alpha} m \ln\left(\frac{m_0}{m}\right)$$

$$\boxed{y = -\frac{1}{2}gt^2 + ut - \frac{u}{\alpha} m \ln\left(\frac{m_0}{m}\right)}$$

at burn out  $t = t_b$  and  $y = y_b$

This is equation 2.133 in the text book!

At the top of the path

$$v_f = 0 = v_B - g t_f \Rightarrow t_f = \frac{v_B}{g}$$

$$y_f - y_0 = v_0 t_f - \frac{1}{2} g t_f^2$$

$$y_f = \frac{v_B^2}{g} - \frac{1}{2} g \frac{v_B^2}{g^2} = \frac{v_B^2}{2g}$$

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$$- t_f \quad 2.1$$
$$y_f$$

$$- t_b$$
$$y_b$$

