KING FAHD UNIVERSITY OF PETROLEUM & MINERALS Physics Department

PHYS 301 Final Exam (27 May, 2001) – Term 002

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Student's Name: _____

I.D. No: _____

Exam Time: 180 minutes Attempt all problems and show the details of your work

Problem #	Grade
1	/15
2	/10
3	/10
4	/20
5	/15
6	/15
7	/15
Total:	/100

Q1. (15 points)

A particle of mass m is thrown vertically upward with a speed v_0 into the air where it experiences a frictional force $f_R = -m\alpha v$. ($\alpha > 0$ and constant, also assume constant gravitational field during the motion of the particle).

(a) Show that the following relationship holds between the velocity of the particle and the time:

$$m\frac{dv}{dt} = -mg - m\alpha v \tag{1}$$

and integrate Eq. (1) to find v(t), knowing that $v(0) = v_0$.

- (b) Find the time needed for the particle to reach maximum height.
- (c) Find the maximum height (take y(0) = 0).
- (d) Study the limit when $\alpha \rightarrow 0$ (no air resistance) for both parts (b) and (c).

Q2. (15 points)

A simple pendulum consists of a mass m = 20 g, suspended from a fixed point by a weightless string of length l = 20 cm. The mass moves within a viscous medium with a retarding force of $f_R = 2m\sqrt{gl\dot{\theta}}$. The mass is pulled and angle

of 10^0 and then released from rest.

- (a) Find the general expression for the angular position of the mass, $\theta(t)$ in the case of small oscillations.
- (b) Using the initial conditions specified in the problem, calculate the constants involved in $\theta(t)$.
- (c) Calculate the speed of the mass at t = 2 s.

Q3. (10 points)

Calculate the **gravitational potential** at point P located a distance R from the axis of a thin rod of mass M and length L (see the figure).



A particle of mass m is attached to the end of a spring with spring constant k and unstretched length b. The mass is constrained to move inside a thin hallow frictionless tube. The tube is raised to an inclination angle θ at a constant rate ω ($\theta = 0$ at t = 0) as seen in the figure.



- (a) Find the Lagrangian of the system.
- (b) Show that the equation of motion of the mass m is given by

$$\ddot{r} + \Omega^2 r = \omega_o^2 b - g \sin \omega t ; \qquad \Omega^2 > 0$$

Identify Ω^2 , ω_0^2 , and state under what condition is $\Omega^2 > 0$.

(c) Solve the previous equation for the special case $\omega = \omega_0$ with the same initial conditions r = b and $\dot{r} = 0$ at t = 0.

Q5. (15 points)

Consider an Atwood machine consisting of a pulley of moment of inertia $I = (1/2)MR^2$ and two masses m_1 and m_2 hanging from a massless rope of fixed length l.

(a) Show that Lagrange equation can be written in the form

$$L = \frac{1}{2}(m_1 + m_2 + \frac{I}{R^2})\dot{y}^2 + m_1gy + m_2g(l - y)$$

- (b) Write the Hamiltonian of the system and Hamilton's equations of motion.
- (c) Calculate the acceleration of each mass if $m_1 = 3$ kg, $m_2 = 1$ kg, and M = 5 kg.

Q6. (15 points)

A particle of mass m is constrained to move on the inside surface of a smooth cone of half angle α , i.e., $z = r \cot \alpha$.



(a) Calculate the total mechanical energy of the system and show that it can be written in the form

$$E = \frac{1}{2}m * \dot{r}^2 + V_{eff}$$

where $m^* = \frac{m}{\sin^2 \alpha}$

and identify the expression of V_{eff} .

- (b) Study the approximate behavior of V_{eff} (look for extrema) and plot the curve V_{eff} versus r for r > 0.
- (c) Discuss the motion of the particle when $E_1 > V_{eff}^{\min}$ and when $E_2 = V_{eff}^{\min}$. What happens when $E < V_{eff}^{\min}$?

Q7. (15 points)

An object of unit mass orbits in a central potential U(r). Its orbit is $r = ae^{-b\theta}$, where a and b are constants.

- (a) Find the potential U as a function of r.
- (b) Find θ as a function of time.

Formula Sheet

$$x(t) = Ae^{-\beta t} \cos(\omega_1 t - \delta) \qquad \qquad \omega_1 = \sqrt{\omega_o^2 - \beta^2}$$

$$x(t) = e^{-\beta t} (A_1 e^{\omega_2 t} + A_2 e^{-\omega_2 t}) \qquad \qquad \omega_2 = \sqrt{\beta^2 - \omega_0^2}$$

$$x_{p}(t) = D\cos(\omega t - \delta) \qquad \qquad D = \frac{A}{\sqrt{(\omega_{o}^{2} - \omega^{2})^{2} + 4\omega^{2}\beta^{2}}}$$

$$\Phi = -G \int \frac{\rho}{r} dv \quad \text{or} \quad \Phi = -G \int \frac{\sigma}{r} dA \quad \text{or} \quad \Phi = -G \int \frac{\lambda}{r} dl$$
$$g = -G \int \frac{\rho}{r^2} dv \quad \text{or} \quad g = -G \int \frac{\sigma}{r^2} dA \quad \text{or} \quad g = -G \int \frac{\lambda}{r^2} dl$$
$$\oint \ \vec{g} \cdot d\vec{A} = -4\pi G M_{encl}$$

$$\frac{\partial f}{\partial y_i} = \frac{d}{dx} \left(\frac{\partial f}{\partial y'_i} \right) = 0 \qquad i = 1, 2, 3..., n \qquad ; \qquad \frac{\partial f}{\partial x} - \frac{d}{dx} \left(f - y' \frac{\partial f}{\partial y'} \right) = 0$$

$$L = T - U$$
 ; $\frac{\partial L}{\partial q_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = 0$; $H = \sum_i p_i \dot{q}_i - L$; $p_k = \frac{\partial L}{\partial \dot{q}_k}$

$$\dot{q}_k = \frac{\partial H}{\partial p_k}$$
; $\frac{\partial H}{\partial q_k} = -\dot{p}_k$; $-\frac{\partial L}{\partial t} = \frac{\partial H}{\partial t}$; $\frac{d^2}{d\theta^2}(\frac{1}{r}) + \frac{1}{r} = -\frac{\mu r^2}{l^2}F(r)$

$$E = T + U$$
 $\vec{F} = -\vec{\nabla}U$ $l = mr^2\dot{\theta} = const$

$$Ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots \qquad ; \qquad \int \frac{dy}{\sqrt{a^2 + y^2}} = Ln(y + \sqrt{y^2 + a^2})$$