

Lecture 16

(Stable Problems)

Definition 1 Problem P is called stable if $h(0) \in \mathbf{R}, \partial h(0) \neq \emptyset$.

Lemma 2 The set of solution of \mathbf{P}^* coincides with $\partial h^{**}(0)$.

Proof. Suppose p^* is a solution of \mathbf{P}^* , then

$$-h^*(p^*) = -\Phi(0, p^*) = \sup_{q^* \in Y} -\Phi(0, q^*) = h^{**}(0).$$

Fix $p \in Y$, then,

$$\sup_{q^* \in Y} \langle p, q^* \rangle - h^*(q^*) \geq h^*(p^*) + \langle p^*, p \rangle$$

i.e.:

$$h^{**}(p) \geq -h^*(p^*) + \langle p^*, p \rangle = h^{**}(0) + \langle p^*, p \rangle$$

Then, $p^* \in \partial h^{**}(0)$.

On the other hand, let $p^* \in \partial h^{**}(0)$, then

$$h^{**}(p) \geq h^{**}(0) + \langle p^*, p \rangle \quad \forall p \in Y$$

$$-h^{**}(0) \geq \langle p^*, p \rangle - h^{**}(p)$$

$$-h^{**}(0) \geq h^{***}(p^*) = h^*(p^*)$$

$$h^{**}(0) \leq -h^*(p^*)$$

$$\sup_{q^* \in Y} -h^*(q^*) \leq -h^*(p^*)$$

Therefore,

$$-h^*(p^*) = \sup_{q^* \in Y} -h^*(q^*)$$

Then, p^* is a solution of \mathbf{P}^* . ■

Proposition 3 P is stable iff P is normal and \mathbf{P}^* has a solution.

Proof. Suppose P is stable, then P is normal (since $\partial h(0) \neq \emptyset \implies h$ is l.s.c at 0). Furthermore, $p^* \in \partial h(0) = \partial h^{**}(0)$, therefore, p^* is a solution of \mathbf{P}^* by previous lemma. Conversely if P is normal and \mathbf{P}^* has a solution p^* , then

$$p^* \in \partial h^{**}(0) = \partial h(0),$$

since h is l.s.c at 0. Then P is stable. ■

Proposition 4 The Following Conditions are equivalent:

- (I) P and \mathbf{P}^* are normal and have some solutions,
- (II) P and \mathbf{P}^* are stable,
- (III) P is stable and has some solutions.

Proof. (I) \implies (II),

Assume (I), \mathbf{P}^* is normal and P has a solution $\implies \mathbf{P}^*$ is normal and \mathbf{P}^{**} has a solution, $\implies \mathbf{P}^*$ is stable. Similarly, P is normal and \mathbf{P}^* has a solution $\implies P$ is stable. (II) \implies (I) direct. (III) \implies (I) follows directly from previous proposition. ■

Proposition 5 A stability criterion.

Assume Φ is convex, that $\inf_{p \in \mathbf{P}} \Phi(u_0, p) \in \mathbf{R}$. $\Phi(u_0, \cdot)$ is bounded above at 0 for some $u_0 \in \mathbf{V}$. Then P is stable.

Proof.

$$h(p) = \inf_{u \in \mathbf{V}} \Phi(u, p) \leq \Phi(u_0, p),$$

and $h(0) \in \mathbf{R} \implies h$ is bounded above at 0, $\implies h$ is continuous at 0, $\implies \partial h(0) \neq \emptyset$. Then P is stable. ■