

## A Solution of Exam II

1.  $A^{-1} = \frac{1}{10} \begin{bmatrix} 2 & 1 \\ -4 & 3 \end{bmatrix}$ . Then  $X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A^{-1}b = \frac{1}{10} \begin{bmatrix} 2 & 1 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

$\Rightarrow X = \begin{bmatrix} 0.3 \\ -1.1 \end{bmatrix}$ .  $x_1 = 0.3$  and  $x_2 = -1.1$ .

2. Given  $A = \begin{bmatrix} 2 & 0 & -1 \\ 1 & 0 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ . We find  $A^{-1}$

$[A : I]_{3 \times 3} = \left[ \begin{array}{ccc|ccc} 2 & 0 & -1 & 1 & 0 & 0 \\ 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 3 & 0 & 1 & 0 \\ 2 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{array} \right]$

$\xrightarrow{-2R_1 + R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 0 & -7 & 1 & -2 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_2 \leftrightarrow R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & -7 & 1 & -2 & 0 \end{array} \right]$

$\xrightarrow{7R_2 + R_3 \rightarrow R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 7 & 0 & 1 & -2 & 7 \\ 0 & 0 & -7 & 1 & -2 & 0 \end{array} \right] \xrightarrow{\frac{1}{7}R_2, \frac{1}{-7}R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 0 & \frac{1}{7} & -\frac{2}{7} & 1 \\ 0 & 0 & 1 & -\frac{1}{7} & \frac{2}{7} & 0 \end{array} \right]$

$\xrightarrow{-3R_3 + R_1} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{3}{7} & \frac{1}{7} & 0 \\ 0 & 1 & 0 & \frac{1}{7} & -\frac{2}{7} & 1 \\ 0 & 0 & 1 & -\frac{1}{7} & \frac{2}{7} & 0 \end{array} \right] \Rightarrow A^{-1} = \begin{bmatrix} \frac{3}{7} & \frac{1}{7} & 0 \\ \frac{1}{7} & -\frac{2}{7} & 1 \\ -\frac{1}{7} & \frac{2}{7} & 0 \end{bmatrix}$

3. Given  $v_1 = (3, 1, 0)$ ,  $v_2 = (0, 1, 0)$ , and  $v_3 = (-1, 0, 0)$ .

These vectors are linearly dependent as:

$$v_1 = v_2 - 3v_3$$

and thus they do not form a basis for  $\mathbb{R}^3$ .

Another solution

$$|v_1, v_2, v_3| = 0.$$

4. The set  $W = \{ (x_1, x_2, x_3, x_4) \in \mathbb{R}^4 : x_1 \cdot x_2 = 0 \}$  is not a subspace as it does not satisfy the closure property in addition,

for example:  $w_1 = (1, 0, 0, 0)$  and  $w_2 = (0, 1, 0, 0)$  are in  $W$

but  $w_1 + w_2 = (1, 1, 0, 0) \notin W$  because  $1 \cdot 1 = 1 \neq 0$ .

5. We find a basis for the solution space of the system: 2.

$$(1) \begin{cases} x_1 - 3x_2 - x_3 = 0 \\ x_1 + 3x_2 - 3x_3 = 0 \end{cases}$$

The augmented matrix is:

$$\left( \begin{array}{ccc|c} 1 & -3 & -1 & 0 \\ 1 & 3 & -3 & 0 \end{array} \right) \xrightarrow{-R_1 + R_2} \left( \begin{array}{ccc|c} 1 & -3 & -1 & 0 \\ 0 & 6 & -2 & 0 \end{array} \right)$$

The leading variables are  $x_1$  and  $x_2$  while  $x_3$  is a free variable. Put  $\boxed{x_3 = t}$ ,  $t \in \mathbb{R}$ .

$$\Rightarrow 6x_2 = 2x_3 \Rightarrow \boxed{x_2 = \frac{1}{3}t}$$

Similarly,  $x_1 - 3x_2 - x_3 = 0 \Rightarrow x_1 = 3\left(\frac{1}{3}t\right) + t \Rightarrow \boxed{x_1 = 2t}$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = t \begin{pmatrix} 2 \\ \frac{1}{3} \\ 1 \end{pmatrix} \quad \therefore \text{Any solution of (1) is a scalar multiplication of } \begin{pmatrix} 2 \\ \frac{1}{3} \\ 1 \end{pmatrix}.$$

That is Solution Space =  $\text{Span} \left\{ \begin{pmatrix} 2 \\ \frac{1}{3} \\ 1 \end{pmatrix} \right\}$ .

$\Rightarrow \left\{ \begin{pmatrix} 2 \\ \frac{1}{3} \\ 1 \end{pmatrix} \right\}$  is a basis for the solution space of our system.

6. We show that  $y = x^3$  is a solution of the differential equation:  $x^3 y^{(3)} - 3x^2 y'' + 6xy' - 6y = 0$ . (2)

First:  $y = x^3 \Rightarrow y' = 3x^2 \Rightarrow y'' = 6x \Rightarrow y^{(3)} = 6$ .

Substitution in (2) results:  $x^3(6) - 3x^2(6x) + 6x(3x^2) - 6x^3 = (6 - 18 + 18 - 6)x^3 = 0$ .

$\Rightarrow \underline{y = x^3}$  is a solution of (2).

7. We verify:  $f(x) = e^x$  and  $g(x) = \sin x$  are linearly independent on  $[0, 10]$  by two methods.

• Method 1: We show that  $W(f, g) \neq 0$  at some point

$$x \in [0, 1]. \quad W(f, g) = \begin{vmatrix} e^x & \sin x \\ e^x & \cos x \end{vmatrix} = e^x (\cos x - \sin x)$$

Then  $W(f, g) = 1 \neq 0$  when  $x = 0 \Rightarrow f$  &  $g$  are linearly independent.

Method 2: Since  $\frac{f(x)}{g(x)} = \frac{e^x}{\sin x} \neq \text{constant} \Rightarrow f \& g$  are linearly independent.

8. We solve:  $2y'' + 4y' = 0$  with  $y(1) = -1, y'(1) = 0$ .

The characteristic equation is:  $2r^2 + 4r = 0 \Rightarrow 2r(r+2) = 0$   
 $\Rightarrow r = 0$  or  $r = -2 \Rightarrow$  The general solution:  $y(x) = c_1 + c_2 e^{-2x}$ .

Now:  $\because y(1) = -1 \Rightarrow -1 = c_1 + c_2 e^{-2}$

and  $\because y'(1) = 0, y'(x) = -2c_2 e^{-2x} \Rightarrow 0 = -2c_2 e^{-2} \Rightarrow c_2 = 0$

$\Rightarrow c_1 = -1 \Rightarrow y(x) = -1$

9. We find a particular solution of:

$$y'' - y = e^{2x} - x \quad (1)$$

Consider  $y_p$  in the form:  $y_p = Ae^{2x} + Bx$

$$\Rightarrow y_p' = 2Ae^{2x} + B$$

$$\Rightarrow y_p'' = 4Ae^{2x}$$

Substituting  $y_p$  &  $y_p''$  in (1) gives:

$$4Ae^{2x} - Ae^{2x} - Bx = e^{2x} - x$$

$$\Rightarrow 3Ae^{2x} - Bx = e^{2x} - x$$

$$\Rightarrow 3A = 1 \quad \text{and} \quad -B = -1$$

$$\Rightarrow A = \frac{1}{3} \quad \text{and} \quad B = 1$$

Then

$$y_p(x) = \frac{1}{3} e^{2x} + x$$

10: Since  $(D-2)^3 y = 0$

$\Rightarrow$  ch. equation is:  $(r-2)^3 = 0$

and the general solution is:

$$y(x) = c_1 e^{2x} + c_2 x e^{2x} + c_3 x^2 e^{2x}$$

$$= e^{2x} (c_1 + c_2 x + c_3 x^2)$$

11. The ch. equation is:

$y''' - 2y'' + 2y' = 0$  is

$$r^3 - 2r^2 + 2r = 0 \Rightarrow r(r^2 - 2r + 2) = 0$$

$$\Rightarrow r = 0 \quad \text{or} \quad r = \frac{2 \pm \sqrt{4-8}}{2}$$

$$\Rightarrow r = 0 \quad \text{or} \quad r = 1 \pm i$$

$\Rightarrow$  the general solution is:

$$y(x) = c_1 + e^x (c_2 \cos x + c_3 \sin x)$$