

## Formula Sheet for EE406

**Energy of discrete time signal (DTS):**  $E = \sum_{n=-\infty}^{\infty} |x(n)|^2$

**Average power of discrete time signal (DTS):**  $P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x(n)|^2$

**Convolution sum formula for LTI system**

$$y(n) = x(n) * h(n) = h(n) * x(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) = \sum_{k=-\infty}^{\infty} h(k)x(n-k)$$

**Convolution sum formula for causal LTI system**

$$y(n) = \sum_{k=0}^{\infty} h(k)x(n-k) = \sum_{k=-\infty}^n x(k)h(n-k)$$

**Convolution sum formula for causal LTI system and the input is also causal**

$$y(n) = \sum_{k=0}^n h(k)x(n-k) = \sum_{k=0}^n x(k)h(n-k)$$

**Convolution sum formula for causal FIR system**

$$y(n) = \sum_{k=0}^{M-1} h(k)x(n-k)$$

**Convolution sum formula for causal IIR system**

$$y(n) = \sum_{k=0}^{\infty} h(k)x(n-k)$$

**Constant Coefficient Difference Equation (CCDE):**

$$y(n) = -\sum_{k=1}^N a_k y(n-k) + \sum_{k=0}^M b_k x(n-k)$$

$$\sum_{k=0}^N a_k y(n-k) = \sum_{k=0}^M b_k x(n-k)$$

**Direct Z-transform:**  $X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$

**Summation of finite Geometric Series:**  $\sum_{k=N_1}^{N_2} a^k = \begin{cases} \frac{a^{N_1} - a^{N_2+1}}{1-a}, & a \neq 1 \\ N_2 - N_1 + 1, & a = 1 \end{cases}$

**Summation of infinite Geometric Series:**  $\sum_{k=n}^{\infty} a^k = \frac{a^n}{1-a}, \quad |a| < 1$

**Summation of finite Arithmetic Series:**  $\sum_{k=N_1}^{N_2} K = \frac{1}{2} [(N_2 + N_1)(N_2 - N_1 + 1)]$

**The system function of CCDF:**  $H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^M b_k z^{-k}}{1 + \sum_{k=1}^N a_k z^{-k}}$

**Partial Fraction Expansion (PFE): Distinct Poles: real or complex conjugate**

$$\frac{X(z)}{z} = \frac{A_1}{(z-p_1)} + \frac{A_2}{(z-p_2)} + \dots + \frac{A_N}{(z-p_N)}$$

$$A_k = \left. \frac{X(z)}{z} (z-p_k) \right|_{z=p_k}$$

**Inverse z-transform for PFE: Distinct Poles: real**

$$z^{-1} \left\{ \frac{A_k}{(1-p_k z^{-1})} \right\} = \begin{cases} A_k (p_k)^n u(n), & \text{causal} \\ -A_k (p_k)^n u(-n-1), & \text{noncausal} \end{cases}$$

**Inverse z-transform for PFE: Distinct Poles: complex conjugate (causal)**

$$z^{-1} \left\{ \frac{A_k}{(1-p_k z^{-1})} + \frac{A_k^*}{(1-p_k^* z^{-1})} \right\} = 2|A_k| (r_k)^n \cos(\beta_k n + \alpha_k) u(n)$$

$$A_k = |A_k| e^{j\alpha_k}$$

$$p_k = r_k e^{j\beta_k}$$

**Partial Fraction Expansion (PFE): Multiple-order Poles**

$$\frac{1}{(z - p_k)^m} = \frac{A_{1k}}{(z - p_k)} + \frac{A_{2k}}{(z - p_k)^2} + \dots + \frac{A_{mk}}{(z - p_k)^m} = \sum_{s=1}^m \frac{A_{sk}}{(z - p_k)^s}$$

$$A_{sk} = \frac{1}{(m-s)!} \left\{ \frac{d^{m-s}}{dz^{m-s}} \left[ \frac{X(z)}{z} (z - p_k)^m \right] \right\}_{z=p_k}, \quad s = 1, 2, \dots, m$$

### **Inverse z-transform for PFE: Double-order Poles: causal**

$$z^{-1} \left\{ \frac{p_k z^{-1}}{(1 - p_k z^{-1})^2} \right\} = n (p_k)^n u(n)$$

### **Fourier Series of Discrete-time Periodic Signals (DTFS)**

$$\text{Analysis: } C_k = \frac{1}{N} \sum_{n=0}^{N-1} x(n) e^{-j 2\pi kn/N}$$

$$\text{Synthesis: } x(n) = \sum_{k=0}^{N-1} C_k e^{j 2\pi kn/N}$$

### **Fourier Transform of Discrete-time Periodic Signals (DTFT)**

$$\text{Analysis: } X(\omega) = X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$\text{Synthesis: } x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\omega) e^{j\omega n} d\omega$$

**The frequency response of a system**  $H(\omega) = |H(\omega)| e^{j\theta(\omega)} = \sum_{k=-\infty}^{\infty} h(k) e^{-j\omega k}$

### **The frequency response of a LTI system described by CCDE**

$$H(\omega) = H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{Y(\omega)}{X(\omega)} = \frac{\sum_{k=0}^M b_k e^{-j\omega k}}{\sum_{k=0}^N a_k e^{-j\omega k}}$$

### **The response of a relaxed LTI system to an input signal, $x(n)$ , with a single frequency, $\omega_k$ is**

$$y(n) = A e^{j\omega_k n} H(\omega_k)$$

$$\text{Where } x(n) = A e^{j\omega_k n}$$

### **The system response to a cosine input signal, $x(n)$ , with a single frequency, $\omega_k$ is**

$$y(n) = A |H(\omega_k)| \cos(\omega_k n + \theta(\omega_k))$$

$$\text{Where } x(n) = A \cos(\omega_k n)$$

**The system response to a sine input signal,  $x(n)$ , with a single frequency,  $\omega_k$  is**

$$y(n) = A |H(\omega_k)| \sin(\omega_k n + \theta(\omega_k))$$

$$\text{Where } x(n) = A \sin(\omega_k n)$$

**Discrete Fourier Transform (DFT) of Discrete-time finite Signals of length  $N$**

$$\text{Analysis: } X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn}, \quad 0 \leq k \leq N-1$$

$$\text{Synthesis: } x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) W_N^{-kn}, \quad 0 \leq n \leq N-1$$

$$\text{Where } W_N = e^{-j(2\pi/N)}$$

**Matrix relation of DFT**

$$\overline{X} = \overline{D}_N \overline{x}$$

$$\overline{x} = \overline{D}_N^{-1} \overline{X} = \frac{1}{N} \overline{D}_N^* \overline{X}$$

$$\overline{X} = \begin{bmatrix} X(0) \\ X(1) \\ \vdots \\ X(N-1) \end{bmatrix}, \quad \overline{x} = \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}, \quad \text{and } \overline{D}_N = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N^1 & W_N^2 & \cdots & W_N^{N-1} \\ 1 & W_N^2 & W_N^4 & \cdots & W_N^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{N-1} & W_N^{2(N-1)} & \cdots & W_N^{(N-1)(N-1)} \end{bmatrix}$$

**Time domain relation between DTFT,  $x(n)$ , and DFT,  $y(n)$**

$$y(n) = \sum_{m=-\infty}^{\infty} x(n + mN), \quad 0 \leq n \leq N-1$$

**Circular convolution of two finite sequences**

$$x_3(m) = \sum_{n=0}^{N-1} x_1(n) x_2((m-n)_N), \quad 0 \leq m \leq N-1$$