

EE 380: Home Work #6

E8.11 The Bode plot is shown in Figure E8.11. The frequency when $20 \log_{10} |G_C G(j\omega)| = 0$ is $\omega = 9.9$ rad/sec.

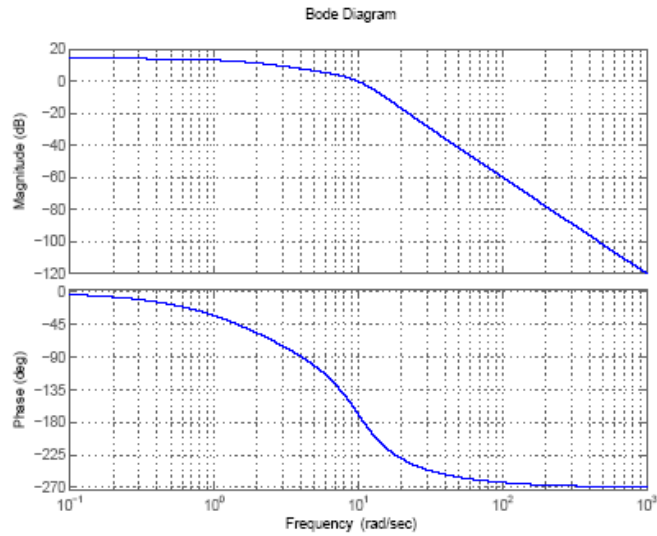


FIGURE E8.11
Bode Diagram for $G_C(s)G(s) = \frac{1000}{(s^2+10s+100)(s+2)}$.

P8.1

(d) The transfer function is

$$G_C(s)G(s) = \frac{30(s+8)}{s(s+2)(s+4)}.$$

The polar plot is shown in Figure P8.1d. A summary of the magnitude and phase angles for

$$\omega = 1, 0.1, 0.8, 1.6, 3.2, 12.8, \infty$$

can be found in Table P8.1d.

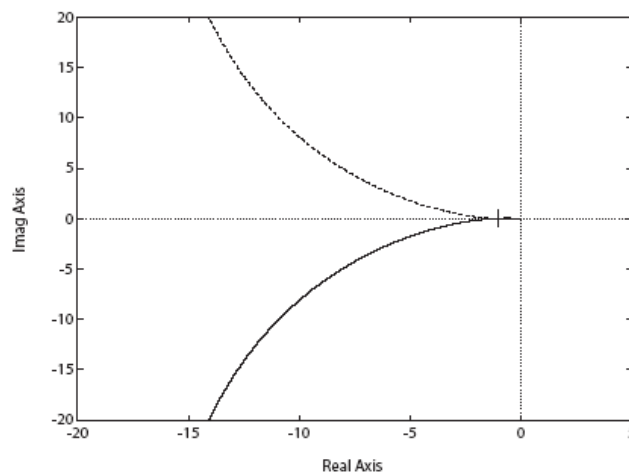


FIGURE P8.1

ω	0	0.1	0.8	1.6	3.2	12.8	∞
$ GH(j\omega) $	∞	299.6	34.3	13.9	4.4	0.20	0
$\phi(deg)$	-90°	-93.6°	-117.4°	-139.1°	-163.8°	-185.8°	-180°

TABLE P8.1 CONTINUED: (d) Magnitudes and phase angles for $G_c(s)G(s) = \frac{30(s+8)}{s(s+2)(s+4)}$.

P8.16 (a) The unit step input response is shown in Figure P8.16. The closed-

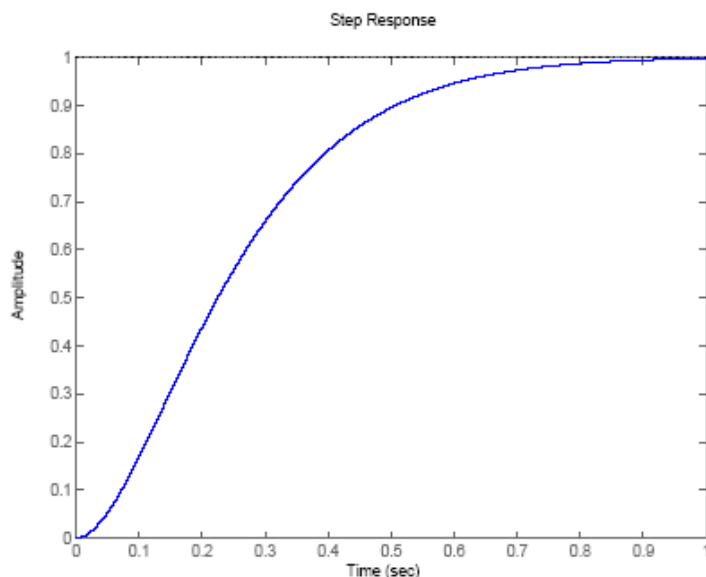


FIGURE P8.16

Unit step input response for $T(s) = \frac{53.5}{s^2 + 14.1s + 53.5}$.

loop transfer function is

$$T(s) = \frac{Y(s)}{R(s)} = \frac{53.5}{s^2 + 14.1s + 53.5} .$$

(b) The system bandwidth is $\omega_B = 4.95$ rad/sec.

P8.23 The transfer function is

$$G(s) = \frac{100(s+20)(s+8000)}{(s+1)(s+80)(s+500)} .$$

The system is type 0 and the steady-state error to a unit step input is

$$e_{ss} = \frac{1}{1 + K_p} = 0.0025$$

since

$$K_p = \lim_{s \rightarrow 0} G(s) = 400 .$$

AP8.4 The Bode plot is shown in Figure AP8.4.

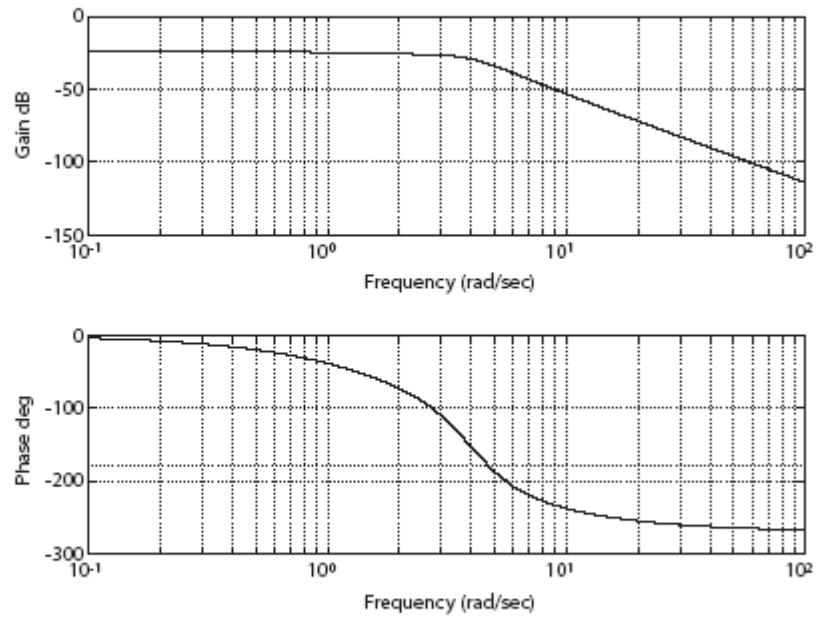


FIGURE AP8.4

Bode plot for $GH(s) = \frac{0.0625}{(0.5s+1)(0.0625s^2+0.2s+1)}$.