

## 8.3 Z-Transform

Similar to the Laplace Transform, we will develop a transform for the analysis and Synthesis (not in this course) of discrete system

Let

$$x_s(t) = \sum_{n=-\infty}^{\infty} x(nT) \delta(t - nT) = \sum_{n=-\infty}^{\infty} x(nT) \delta(t - nT)$$

Assuming:  $x(t) \equiv 0 \quad t < 0$

$$\Rightarrow x_s(t) = \sum_{n=0}^{\infty} x(nT) \delta(t - nT)$$

taking Laplace Transform,

$$X_s(s) = \int_0^{\infty} \sum_{n=0}^{\infty} x(nT) \delta(t - nT) e^{-st} dt$$

$$\Rightarrow x_s(t) = \sum_{n=0}^{\infty} x(nT) s(t-nT)$$

taking Laplace Transform,

$$X_s(s) = \int_0^{\infty} \sum_{n=0}^{\infty} x(nT) \delta(t-nT) e^{-st} dt$$

interchanging summation and integration,

$$X_s(s) = \sum_{n=0}^{\infty} x(nT) \int_0^{\infty} \delta(t-nT) e^{-st} dt = \sum_{n=0}^{\infty} x(nT) e^{-snT}$$

define  $z = e^{sT} \Rightarrow X_s(z) = \sum_{n=0}^{\infty} x(nT) z^{-n}$

**Z-Transform** of the  
Sequence samples  $x(nT)$

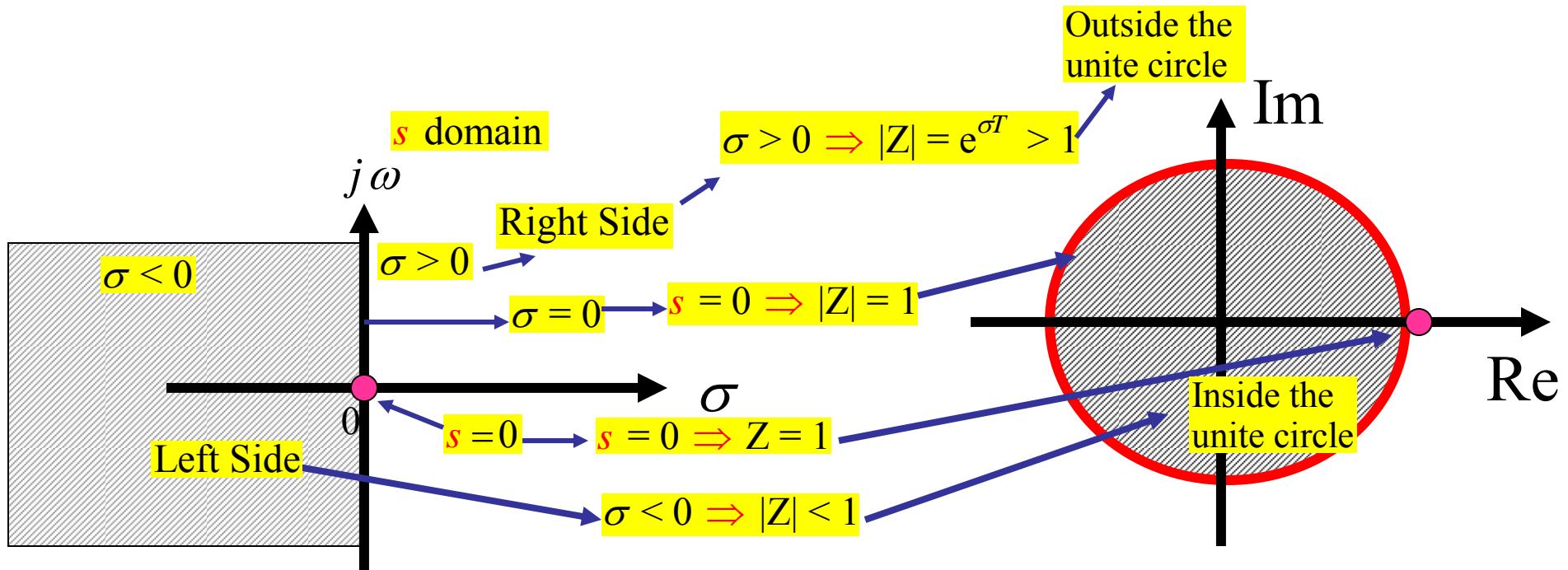
**Z-Transform** of the Sequence samples  $x(nT)$

$$X_s(z) = \sum_{n=0}^{\infty} x(nT) z^{-n}$$

The subscript "s" in  $X_s(z)$  can be deleted

$$X(z) = \sum_{n=0}^{\infty} x(nT) z^{-n}$$

Since  $s = \sigma + j\omega \Rightarrow z = e^{sT} = e^{\sigma T} e^{j\omega T} \Rightarrow |z| = e^{\sigma T}$



In the Z-transform,

$$X(z) = \sum_{n=0}^{\infty} x(nT)z^{-n} = x(0)z^0 + x(1)z^{-1} + x(2)z^{-2} + \dots$$

The coefficient  $x(nT)$  denotes the sample values and  $z^{-n}$  denote the Sample occurs n sample periods after  $t = 0$

Example  $10z^{-15}$  Mean a sample having a value 10  
Occurring 15 samples period after  $t = 0$

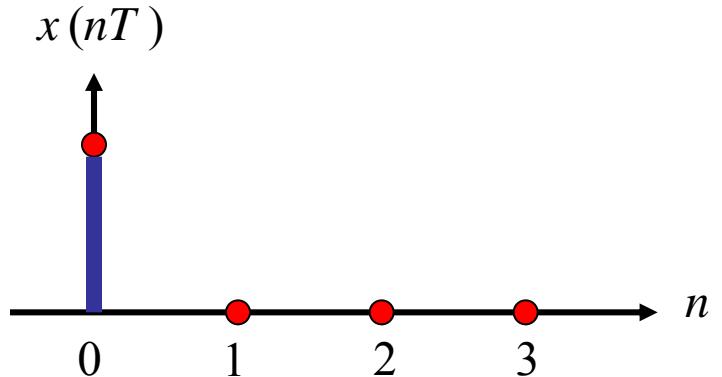
Note  $z = e^{sT}$  Which imply T-second shift

$z^{-n} = e^{-snT}$  Which imply  $nT$ -second shift

## Example 8-4

Define the unite impulse sequence by ,

$$x(nT) = \begin{cases} 1 & n=0 \\ 0 & n \neq 0 \end{cases} \triangleq \delta(nT)$$



Note : the unit impulse here (the discrete) is different from the impulse  $\delta(t)$

$$\delta(n)\Big|_{n=0} = 1 \quad \delta(t)\Big|_{t=0} = \infty$$

$$X(z) = \sum_{n=0}^{\infty} x(nT) z^{-n} = (1)z^0 + (0)z^{-1} + (0)z^{-2} + \dots = 1$$

$$\delta(t) \underset{\text{Laplace}}{\Leftrightarrow} 1$$

$$\delta(n) \underset{z}{\Leftrightarrow} 1$$

Since  $\delta(n-k) = \begin{cases} 1 & n=k \\ 0 & n \neq k \end{cases}$

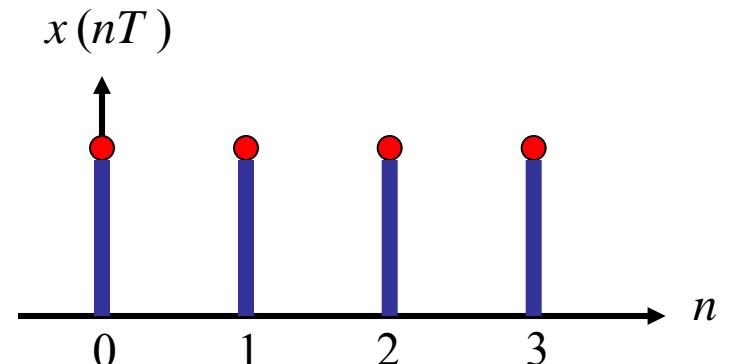
Thus  $x(nT) = \sum_{k=-\infty}^{\infty} x(kT) \delta(n-k)$

$$g(t_0) = \int_{-\infty}^{\infty} g(t) \delta(t - t_0) dt \quad \text{Sifting property}$$

## Example 8-5

Define the unite step by the sample values

$$x(nT) = 1 \quad n \geq 0$$



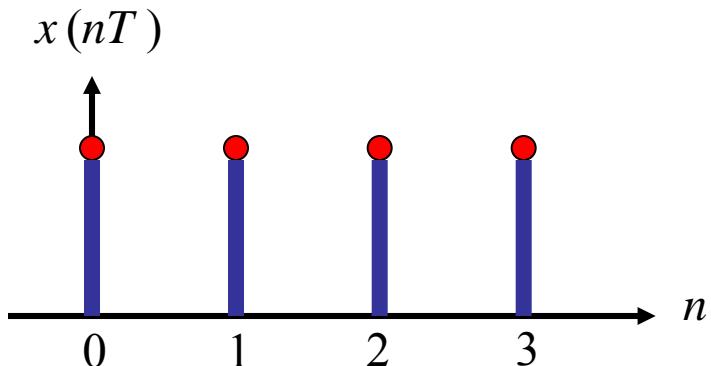
$$X(z) = \sum_{n=0}^{\infty} x(nT) z^{-n} = \sum_{n=0}^{\infty} z^{-n}$$

since  $\sum_{n=0}^{\infty} x^n = \frac{1}{1-x}$  for  $|x| < 1$

$$\Rightarrow X(z) = \sum_{n=0}^{\infty} z^{-n} = \sum_{n=0}^{\infty} (z^{-1})^n = \frac{1}{1-(z^{-1})} = \frac{z}{z-1}$$

$$|z^{-1}| < 1 \Rightarrow |z| > 1$$

$$x(nT) = 1 \quad n \geq 0$$



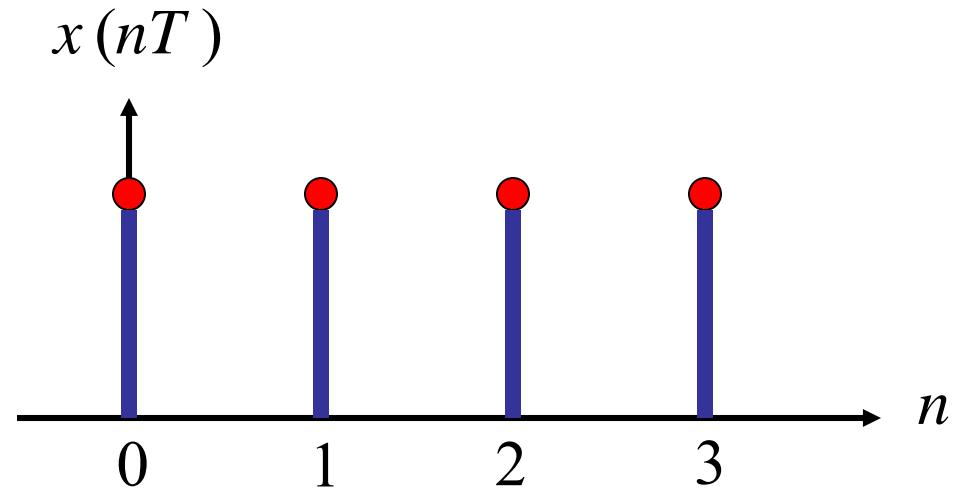
$$X(z) = \frac{z}{z-1} \quad |z^{-1}| < 1 \Rightarrow |z| > 1$$

Note  $X(z)$  has a pole at  $z=1$

$z=1$  correspond to  $s=0$

step function  $u(t) \Leftrightarrow \frac{1}{s}$  has a pole at  $s=0$

$$x(nT) = 1 \quad n \geq 0$$



The discrete unit step defined above is not simply a sampled  $u(t)$  unless  $u(0) = 1$

$u(t)$  is not continuous at  $t = 0$

The discrete unit step is denoted  $u(n)$

## Z- Transform Properties

### (1) Linearity

Z- Transform is Linear operator

$$\text{If } \mathbf{x}_1(nT) \Leftrightarrow X_1(z) \quad \mathbf{x}_2(nT) \Leftrightarrow X_2(z)$$

$$\text{Then } \mathbf{A}\mathbf{x}_1(nT) + \mathbf{B}\mathbf{x}_2(nT) \Leftrightarrow \mathbf{A}X_1(z) + \mathbf{B}X_2(z)$$

### Proof

$$\begin{aligned} Z[\mathbf{A}\mathbf{x}_1(nT) + \mathbf{B}\mathbf{x}_2(nT)] &= \sum_{n=0}^{\infty} [\mathbf{A}\mathbf{x}_1(nT) + \mathbf{B}\mathbf{x}_2(nT)] z^{-n} \\ &= \sum_{n=0}^{\infty} \mathbf{A}\mathbf{x}_1(nT) z^{-n} + \sum_{n=0}^{\infty} \mathbf{B}\mathbf{x}_2(nT) z^{-n} \\ &= \mathbf{A} \sum_{n=0}^{\infty} \mathbf{x}_1(nT) z^{-n} + \mathbf{B} \sum_{n=0}^{\infty} \mathbf{x}_2(nT) z^{-n} \\ &= AX_1(z) + BX_2(z) \end{aligned}$$

## (2) Initial value and Final value theorem

**Initial value theorem**     $x(0) = \lim_{z \rightarrow \infty} X(z)$

**Proof**     $X(z) = \sum_{n=0}^{\infty} x(nT) z^{-n} = x(0) + \sum_{n=1}^{\infty} x(nT) z^{-n}$

$$\begin{aligned}\lim_{z \rightarrow \infty} X(z) &= \lim_{z \rightarrow \infty} x(0) + \lim_{z \rightarrow \infty} \sum_{n=1}^{\infty} x(nT) z^{-n} \\ &= x(0) + \sum_{n=1}^{\infty} x(nT) \lim_{z \rightarrow \infty} \frac{1}{z^n} \\ &= x(0) + \sum_{n=1}^{\infty} x(nT)(0) \quad \boxed{= x(0)}\end{aligned}$$

## Final value theorem

$$x(\infty) = \lim_{z \rightarrow 1} (1 - z^{-1}) X(z) = \lim_{z \rightarrow 1} \frac{z-1}{z} X(z)$$

**Proof** ( Difficult to show)

## Inverse Z-Transform

Since

$$X(z) = \sum_{n=0}^{\infty} x(nT)z^{-n} = x(0)z^0 + x(1)z^{-1} + x(2)z^{-2} + \dots$$

Therefore , if we can put  $X(z)$  into the form shown above,

Then we can determine  $x(nT)$  by inspection

$x(nT)$  will be the coefficients of the polynomial of  $X(z)$

### Example 8-8

$$X(z) = \frac{z^2}{(z-1)(z-0.2)} = \frac{z^2}{z^2 - 1.2z + 0.2} = \frac{1}{1 - 1.2z^{-1} + 0.2z^{-2}}$$

Using polynomial division, we get

$$X(z) = 1 + 1.2z^{-1} + 1.24z^{-2} + 1.248z^{-3} + \dots$$

Therefore

$$x(0) = 1 \quad x(1) = 1.2 \quad x(2) = 1.24 \quad x(3) = 1.248$$

The disadvantage of this method is that ,  
we do not get  $x(nT)$  in **closed form**

$$X(z) = \frac{z^2}{(z-1)(z-0.2)} = \frac{z^2}{z^2 - 1.2z + 0.2} = \frac{1}{1 - 1.2z^{-1} + 0.2z^{-2}}$$

$$X(z) = 1 + 1.2z^{-1} + 1.24z^{-2} + 1.248z^{-3} + \dots$$

$$x(0)=1 \quad x(1)=1.2 \quad x(2)=1.24 \quad x(3)=1.248$$

**From Initial value theorem**

$$x(0) = \lim_{z \rightarrow \infty} X(z) = \lim_{z \rightarrow \infty}(1) + \lim_{z \rightarrow \infty}(1.2z^{-1}) + \lim_{z \rightarrow \infty}(1.24z^{-2}) + \lim_{z \rightarrow \infty}(1.248z^{-3}) + \dots = 1$$

**Final value theorem**  $x(\infty) = \lim_{z \rightarrow 1} (1-z^{-1})X(z) = \lim_{z \rightarrow 1} \frac{z-1}{z} X(z)$

$$x(\infty) = \lim_{z \rightarrow 1} \frac{z-1}{z} \frac{z^2}{(z-1)(z-0.2)} = \lim_{z \rightarrow 1} \frac{z}{(z-0.2)} = 1.25$$

## Using the Z-Transform Table

Example 8-9

Let  $X(z) = \frac{1}{1 - 1.2z^{-1} + 0.2z^{-2}}$  Find  $x(n)$  ?

$$X(z) = \frac{z^2}{z^2 - 1.2z + 0.2} = \frac{z^2}{(z-1)(z-0.2)}$$

Since the degree of the **Numerator** equal the degree of the **denominator**

Polynomial division  $X(z) = 1 + \frac{1.2z - 0.2}{(z-1)(z-0.2)}$

$$= 1 + \frac{1.25}{z-1} - \frac{0.05}{z-0.2}$$

This form is not available on the table

$$\text{Now } \frac{X(z)}{z} = \frac{z}{(z-1)(z-0.2)}$$

Now the degree of the **Numerator** less than the degree of the **denominator**

Using partial fraction , we have

$$\frac{X(z)}{z} = \frac{1.25}{z-1} - \frac{0.05}{z-0.2} \Rightarrow X(z) = \frac{1.25z}{z-1} - \frac{0.25z}{z-0.2}$$

$$X(z) = \frac{1.25}{1-z^{-1}} - \frac{0.25}{1-0.2z^{-1}}$$

$$\Rightarrow x(nT) = 1.25 - 0.25(0.2)^n \quad n \geq 0$$

Table 8-1

$$x(0) = 1$$

$$x(1) = 1.2$$

$$x(2) = 1.24$$

$$x(3) = 1.248$$

⋮

$$x(\infty) = 1.25 \longrightarrow \text{It was shown previously using the final value theorem}$$

## Delay Operator

Since  $X(z) = \sum_{n=0}^{\infty} x(n)z^{-n}$        $x(n) = 0 \quad n < 0$

The Z-transform of  $x(n-k)$  is

$$Z[x(n-k)] = \sum_{n=0}^{\infty} [x(n-k)]z^{-n}$$

Let  $m = n - k$

$$\Rightarrow Z[x(n-k)] = \sum_{m=-k}^{\infty} [x(m)]z^{-(m+k)} = \sum_{m=-k}^{\infty} [x(m)]z^{-m-k}$$

Since  $x(n)$  is assumed 0 for  $n < 0$ , then  $x(m) = 0$  for  $m < 0$

$$\Rightarrow Z[x(n-k)] = \sum_{m=0}^{\infty} [x(m)]z^{-m-k} = z^{-k} \sum_{m=0}^{\infty} [x(m)]z^{-m}$$

Since  $x(nT)$  is assumed 0 for  $n < 0$ , then  $x(mT) = 0$  for  $m < 0$

$$\begin{aligned} Z[x(n-k)] &= \sum_{m=-k}^{\infty} [x(m)]z^{-m-k} = \sum_{m=0}^{\infty} [x(m)]z^{-m-k} \\ &= z^{-k} \sum_{m=0}^{\infty} [x(m)]z^{-m} = z^{-k} X(z) \end{aligned}$$

Therefore, delay by  $k$  samples periods is equivalent to multiplication by  $z^{-k}$

Note, the similarity in Laplace domain,

$$x(t-t_0)u(t-t_0) \Leftrightarrow X(s)e^{-st_0}$$

## Example 8-10

In this example we will show the effect of multiplying  $X(z)$  by  $z^{-2}$

From Example 8-9, we have ,

$$X(z) = \frac{z^2}{(z-1)(z-0.2)} \quad \xrightarrow{\text{red arrow}} \quad \begin{aligned} x(0) &= 1 \\ x(1) &= 1.2 \\ x(2) &= 1.24 \\ x(3) &= 1.248 \\ &\vdots \\ x(\infty) &= 1.25 \end{aligned}$$

Now let  $Y(z) = z^{-2}X(z) = \frac{1}{(z-1)(z-0.2)}$

$$Y(z) = \frac{1}{(z-1)(z-0.2)}$$

$$\frac{Y(z)}{z} = \frac{1}{z(z-1)(z-0.2)} = \frac{5}{z} + \frac{1.25}{z-1} - \frac{6.25}{z-0.2}$$

$$\Rightarrow Y(z) = 5 + \frac{1.25z}{z-1} - \frac{6.25z}{z-0.2}$$

$$y(nT) = 5\delta(nT) + 1.25 - 6.25(0.2)^n \quad \rightarrow \quad \begin{array}{l} y(0)=0 \\ y(1)=0 \\ y(2)=1 \\ y(3)=1.2 \\ y(4)=1.24 \end{array}$$

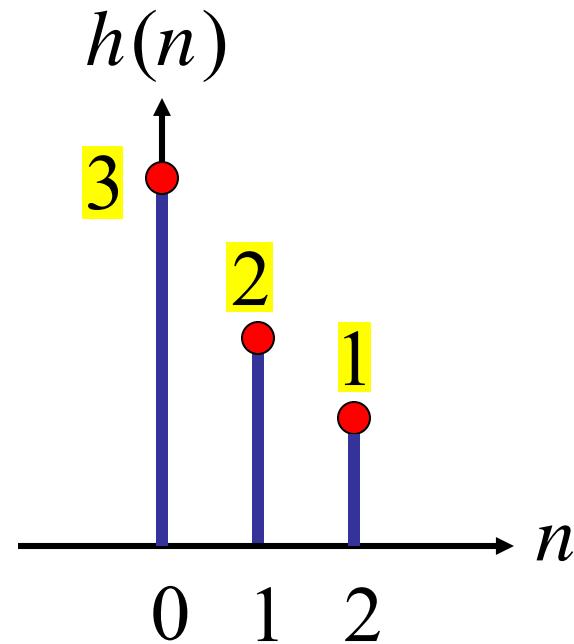
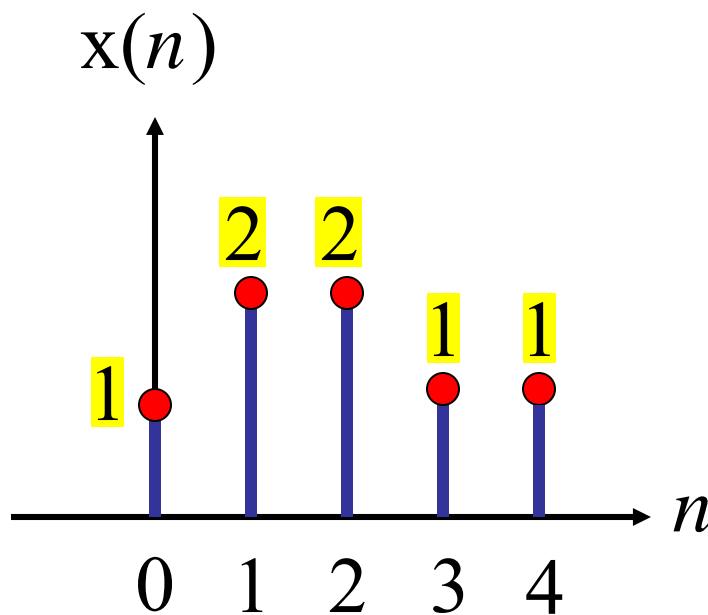
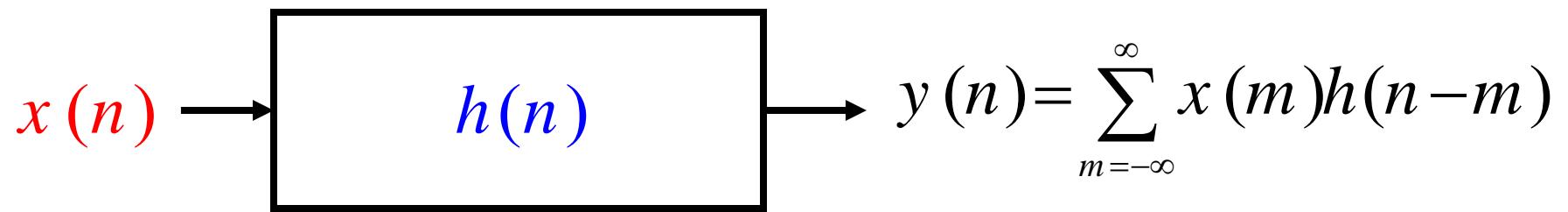
Since  $x(0)=1$

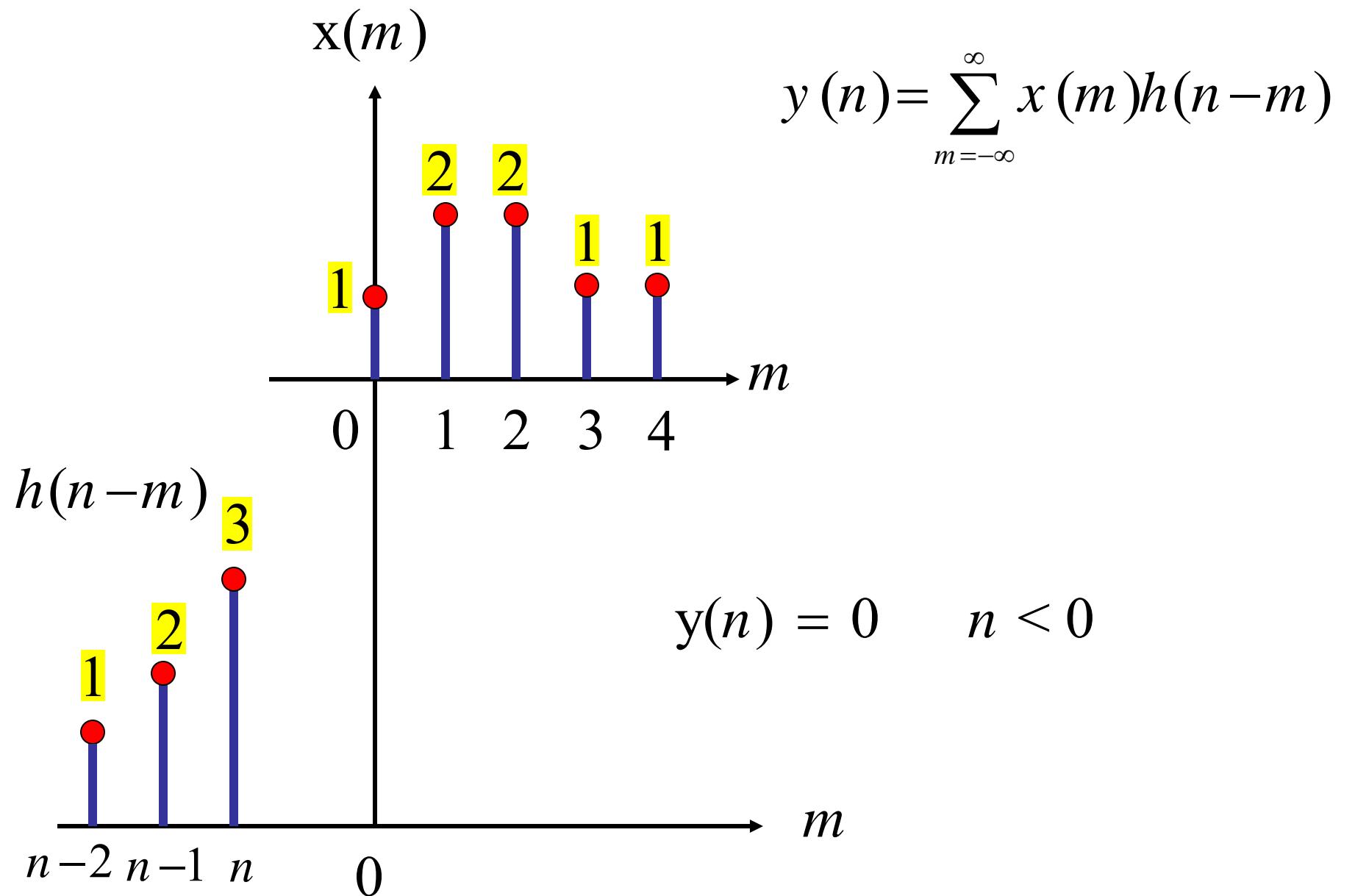
$x(1)=1.2$	$\Rightarrow y(n)=x(n-2)$
$x(2)=1.24$	
$x(3)=1.248$	

$\rightarrow$  multiplying  $X(z)$  by  $z^{-2}$  lead to delay by  $2T$

## Example 8-12 (Discrete Convolution)

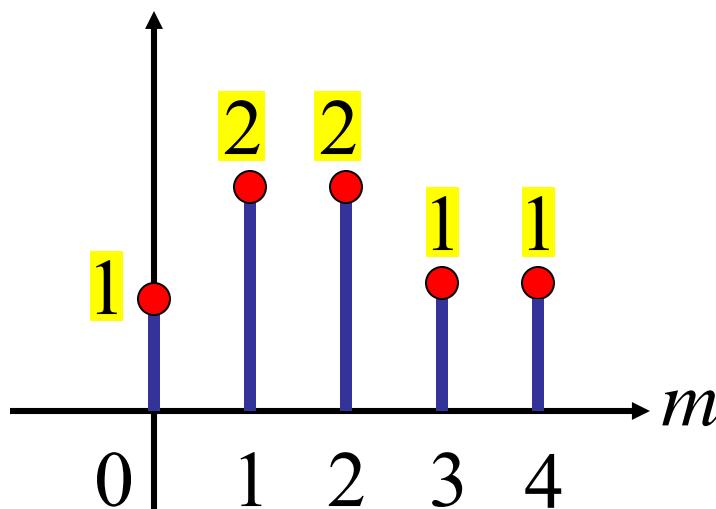
Let the input to a discrete-time system and the unit impulse response





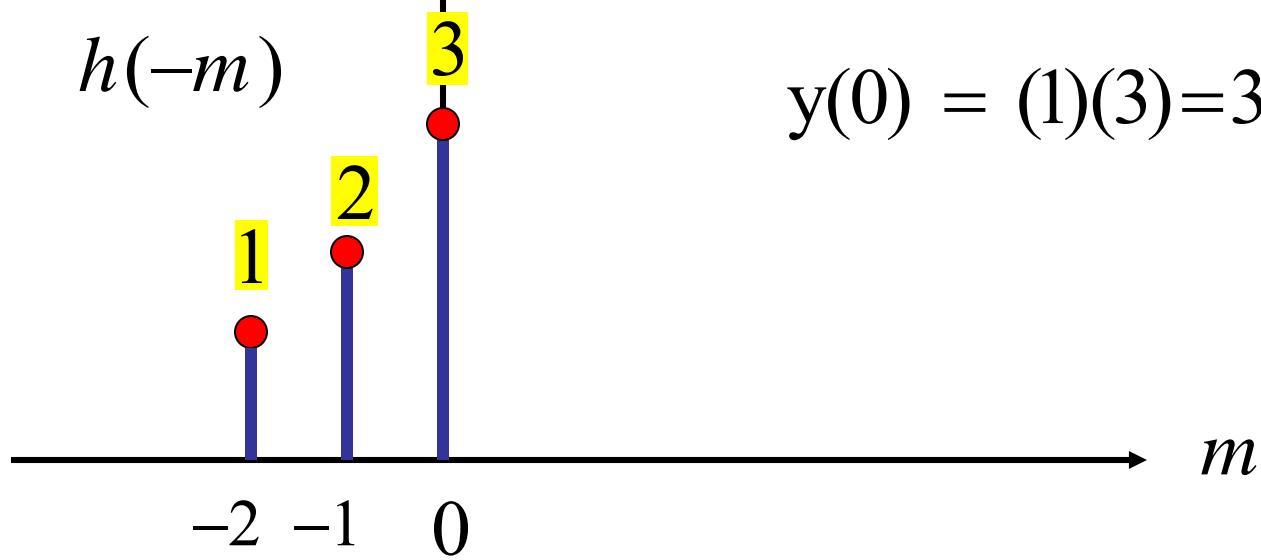
$$n = 0$$

$$x(m)$$



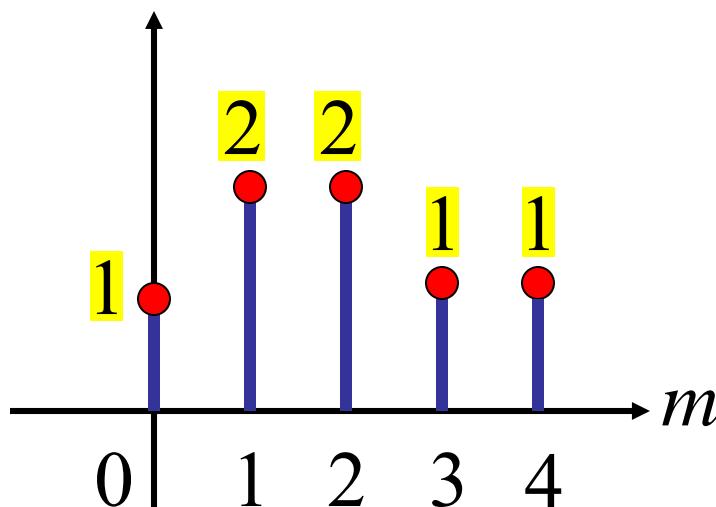
$$h(-m)$$

$$y(0) = (1)(3)=3$$



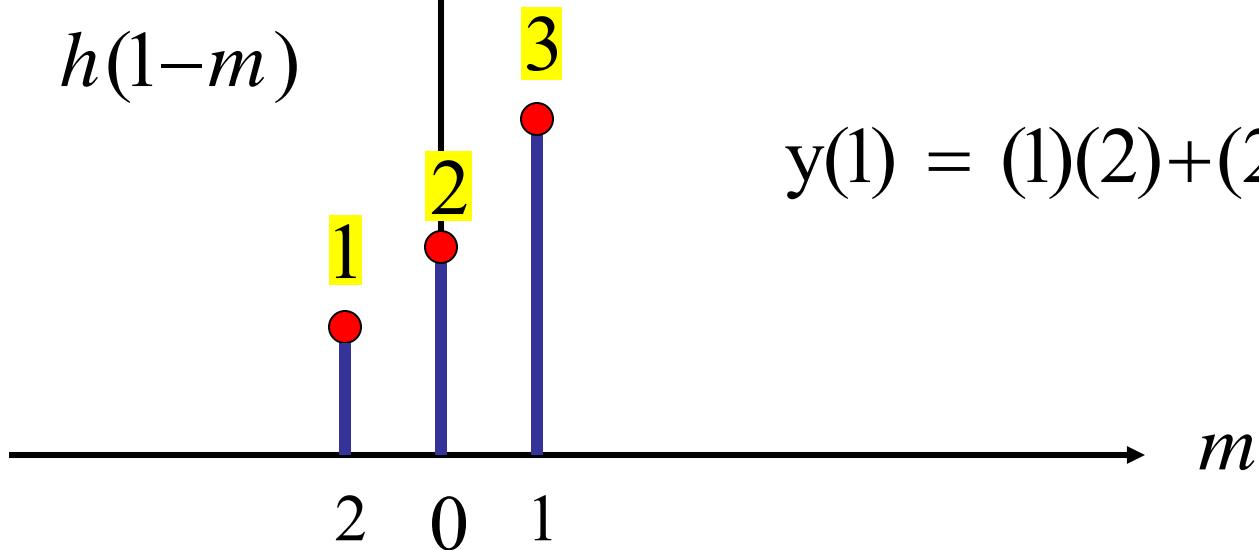
$$n = 1$$

$$x(m)$$



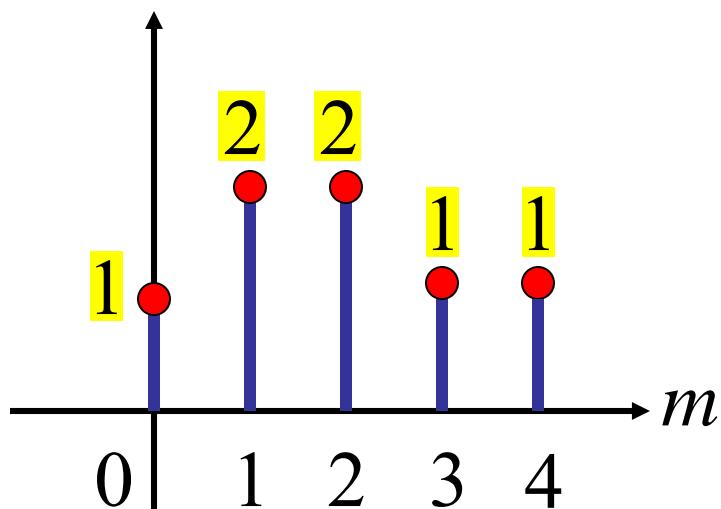
$$h(1-m)$$

$$y(1) = (1)(2)+(2)(3)=8$$

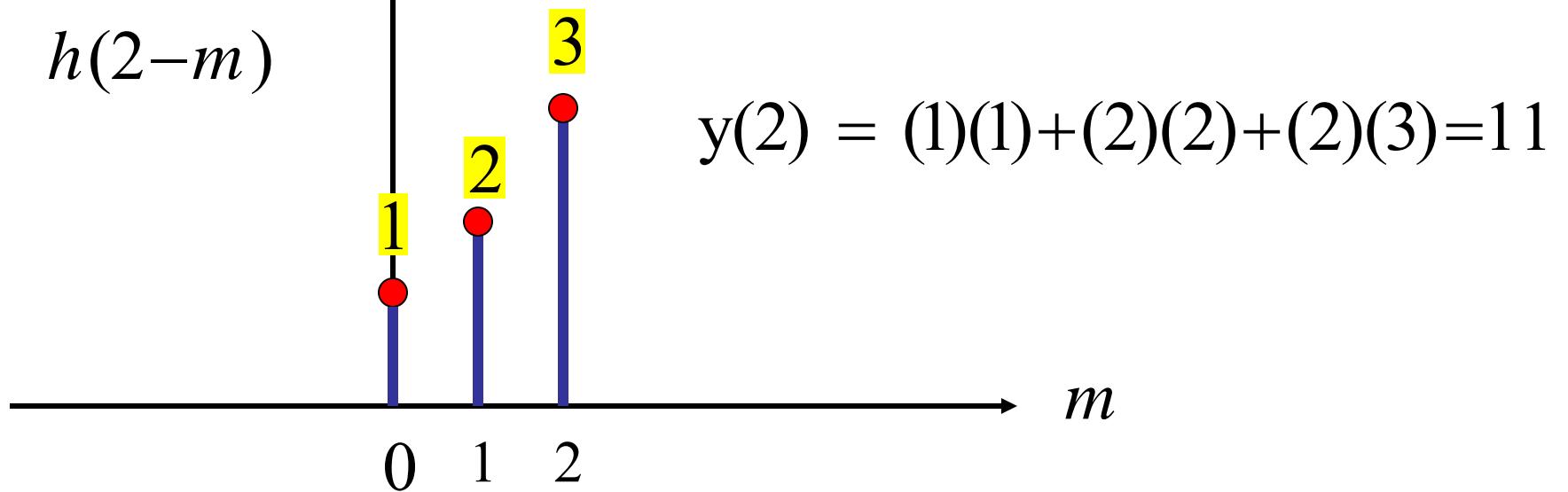


$$n = 2$$

$$x(m)$$



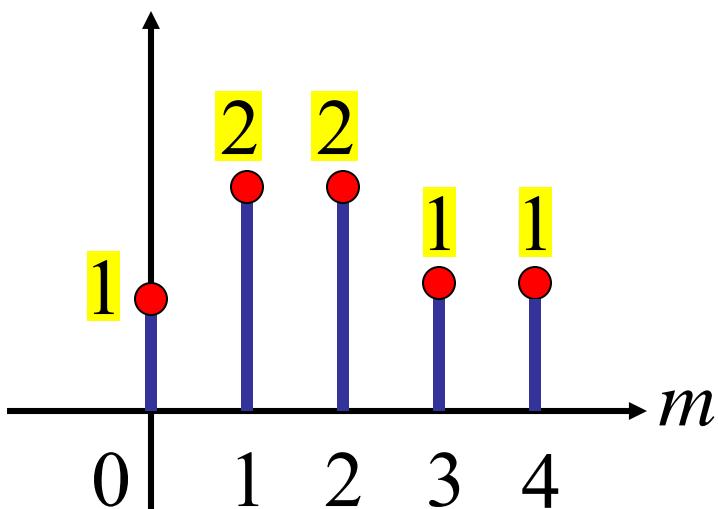
$$h(2-m)$$



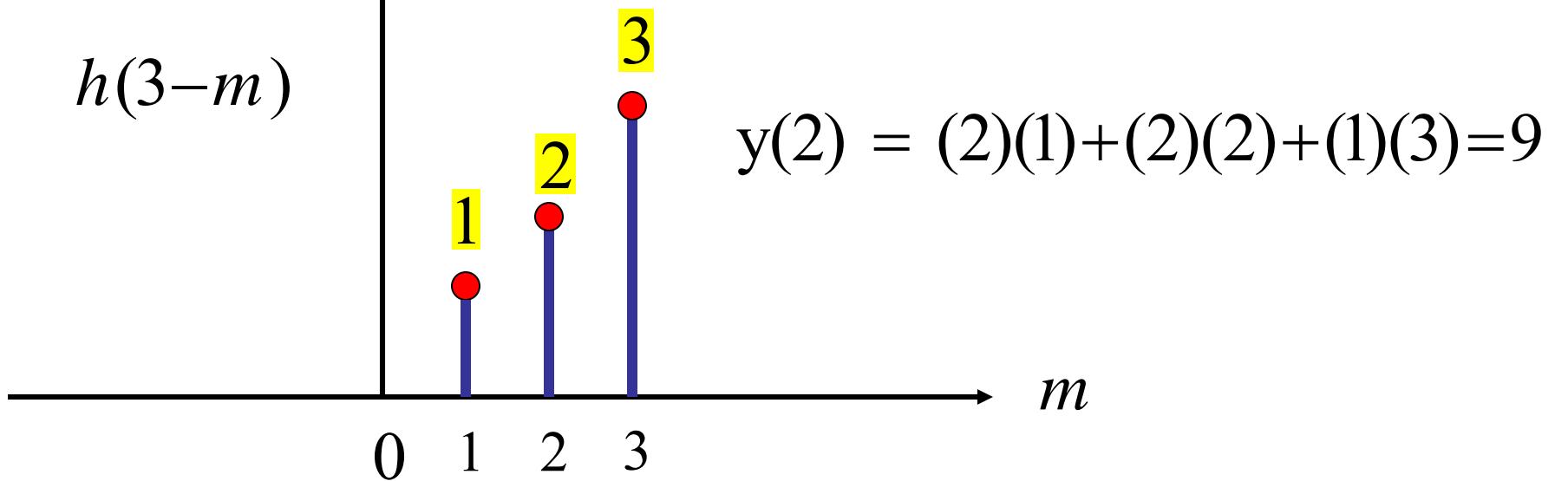
$$y(2) = (1)(1)+(2)(2)+(2)(3)=11$$

$$n = 3$$

$x(m)$

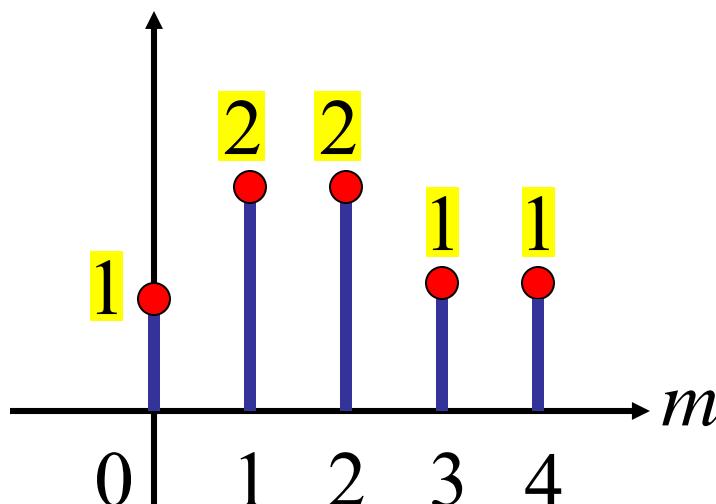


$h(3-m)$

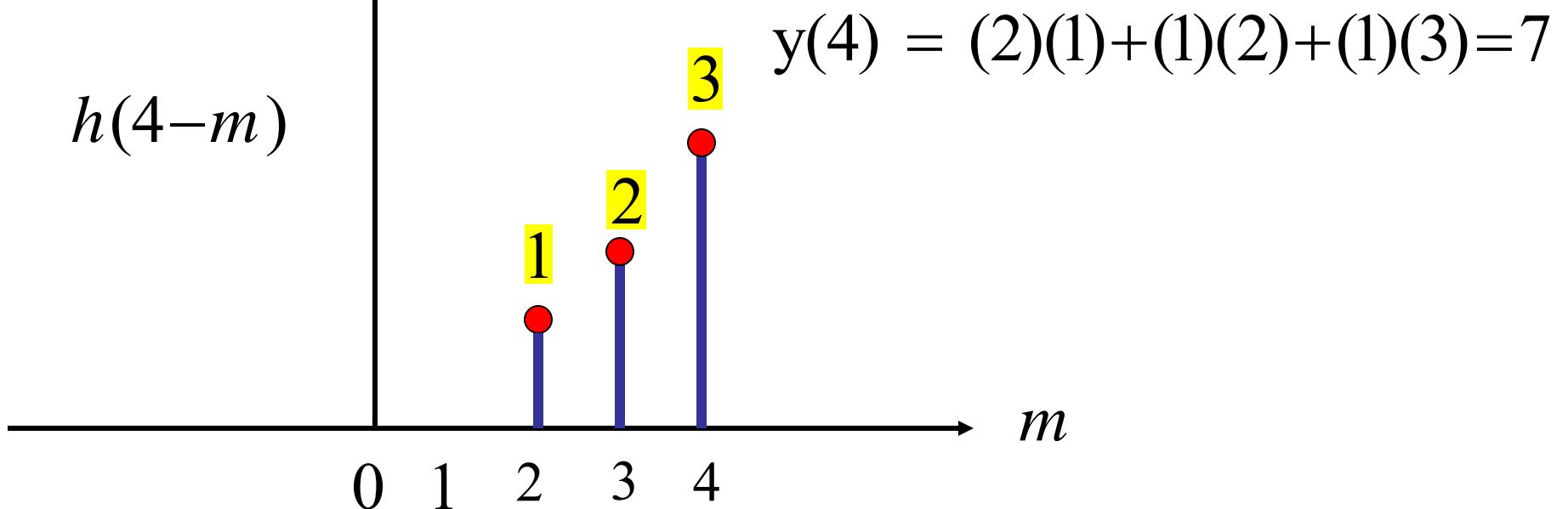


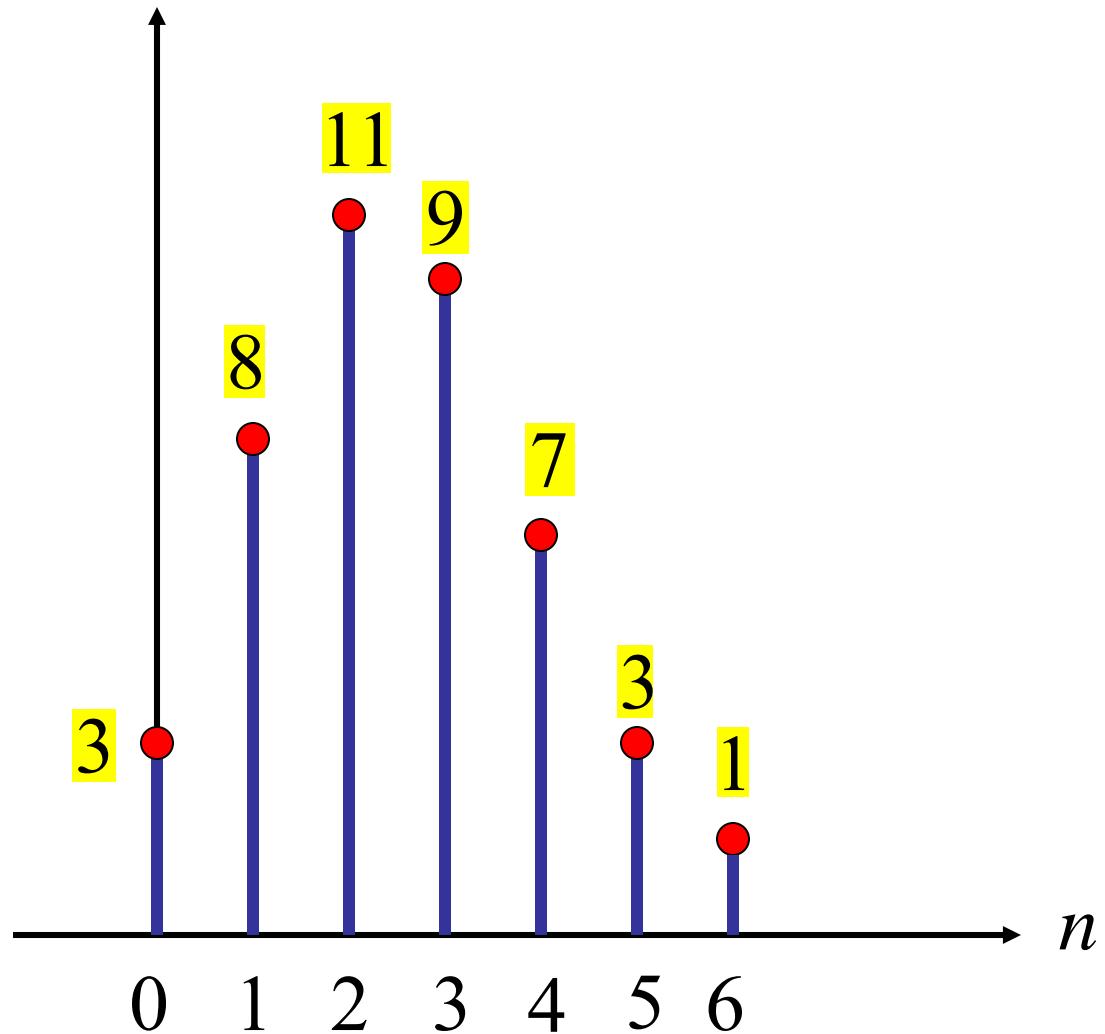
$$n = 4$$

$$x(m)$$



$$h(4-m)$$



$y(n)$ 

**Example 8-13**

$$x(n) = \left(\frac{1}{2}\right)^n u(n) \quad h(n) = \left(\frac{1}{3}\right)^n u(n)$$

$$y(n) = \sum_{m=-\infty}^{\infty} x(m)h(n-m) = \sum_{m=-\infty}^{\infty} \left(\frac{1}{2}\right)^m u(m) \left(\frac{1}{3}\right)^{n-m} u(n-m)$$

Since  $u(m) = 0$  for  $m < 0$  and since  $u(n-m) = 0$  for  $m > n$

$$y(n) = \sum_{m=0}^n \left(\frac{1}{2}\right)^m \left(\frac{1}{3}\right)^{n-m} = \sum_{m=0}^n \left(\frac{1}{2}\right)^m \left(\frac{1}{3}\right)^{-m} \left(\frac{1}{3}\right)^n = \left(\frac{1}{3}\right)^n \sum_{m=0}^n \left(\frac{3}{2}\right)^m$$

**Using the summation formula**

$$\sum_{m=0}^{N-1} x^m = \frac{1-x^N}{1-x}$$

$$\rightarrow y(n) = \left(\frac{1}{3}\right)^n \frac{1 - \left(\frac{3}{2}\right)^{n+1}}{1 - \frac{3}{2}} = 3\left(\frac{1}{2}\right)^n - 2\left(\frac{1}{3}\right)^n \quad n \geq 0$$

# Stability

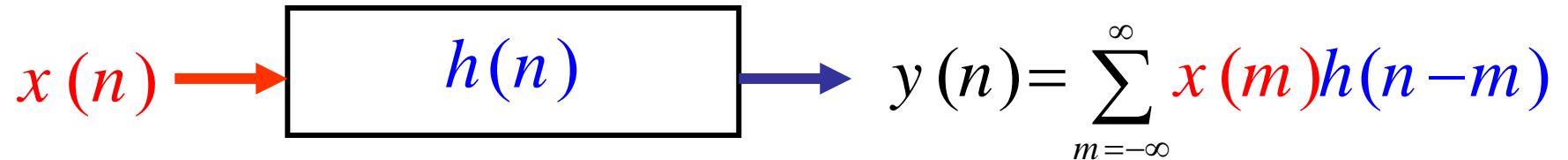
Recall from Chapter 2

$$x(t) \rightarrow \boxed{h(t)} \rightarrow y(t) = x(t) * h(t)$$
$$= \int_{-\infty}^{\infty} h(\lambda)x(t - \lambda)d\lambda$$

For the system to be **Bounded Input Bounded Output (BIBO)**

$$\int_{-\infty}^{\infty} |h(t)| dt < \infty$$

## Now for discrete-time system



For the system to be **Bounded Input Bounded Output (BIBO)**

$$\text{If } |x(n)| < \infty \quad \text{then} \quad |y(n)| < \infty$$

$$|y(n)| = \left| \sum_{m=-\infty}^{\infty} x(m)h(n-m) \right| \leq \sum_{m=-\infty}^{\infty} |x(m)h(n-m)|$$

for a bounded input  $|x(n)| \leq M < \infty$  for all  $n$

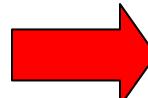
$$|y(n)| \leq \sum_{m=-\infty}^{\infty} M |h(n-m)| = M \sum_{m=-\infty}^{\infty} |h(n-m)|$$

Thus the system output is bounded if  $\sum_{m=-\infty}^{\infty} |h(n-m)| < \infty$

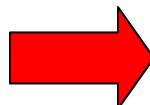
### Example 8-14

$$h(n) = \left[ 4\left(\frac{1}{3}\right)^n - 3\left(\frac{1}{4}\right)^n \right] u(n)$$

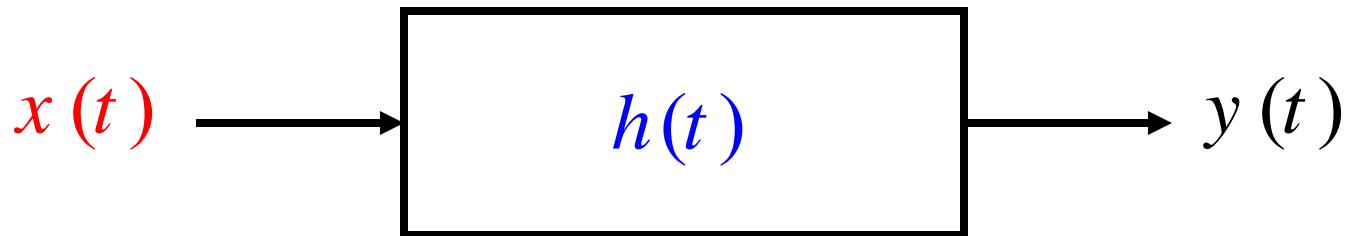
Is The system  $h(n)$  is **Bounded Input Bounded Output (BIBO)**

Since  $h(n) \geq 0$    $|h(n)| = h(n)$

$$\begin{aligned} \sum_{n=-\infty}^{\infty} |h(n-m)| &= \sum_{n=0}^{\infty} \left[ 4\left(\frac{1}{3}\right)^n - 3\left(\frac{1}{4}\right)^n \right] = \sum_{n=0}^{\infty} 4\left(\frac{1}{3}\right)^n - \sum_{n=0}^{\infty} 3\left(\frac{1}{4}\right)^n \\ &= \frac{4}{1-\frac{1}{3}} - \frac{3}{1-\frac{1}{4}} = 2 < \infty \end{aligned}$$

 The system is **Bounded Input Bounded Output (BIBO)**

## For a continuous-time system



A differential equation can be used to model a continuous-time system

$$a_n \frac{dy^n(t)}{dt^n} + a_{n-1} \frac{dy^{n-1}(t)}{dt^{n-1}} + \dots + a_0 y(t) = b_m \frac{dx^m(t)}{dt^m} + b_{m-1} \frac{dx^{m-1}(t)}{dt^{m-1}} + \dots + b_0 y(t)$$

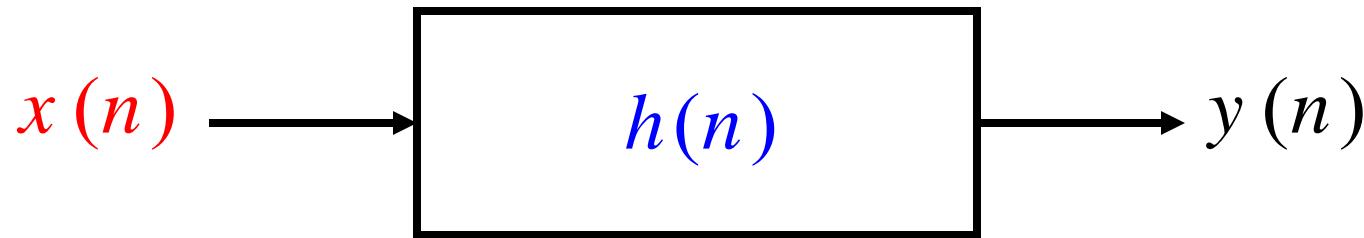
Now if we take the Laplace Transform of both side (Assuming Zero initial Conditions)

$$a_n s^n Y(s) + a_{n-1} s^{n-1} Y(s) + \dots + a_0 Y(s) = b_m s^m X(s) + b_{m-1} s^{m-1} X(s) + \dots + b_0 X(s)$$

The transfer function  $H(s)$  defined,

$$H(s) \triangleq \left. \frac{Y(s)}{X(s)} \right|_{\substack{\text{all initial} \\ \text{conditions} \\ \text{are zero}}} = \frac{b_m s^m + b_{m-1} s^{m-1} + \dots + b_0}{a_n s^n + a_{n-1} s^{n-1} + \dots + a_0}$$

## For a discrete-time system



A difference equation can be used to model a discrete-time system

$$\begin{aligned} y(n) + K_1 y(n-1) + K_2 y(n-2) + \cdots + K_m y(n-m) \\ = L_0 x(n) + L_1 x(n-1) + L_2 x(n-2) + \cdots + L_r x(n-r) \end{aligned}$$

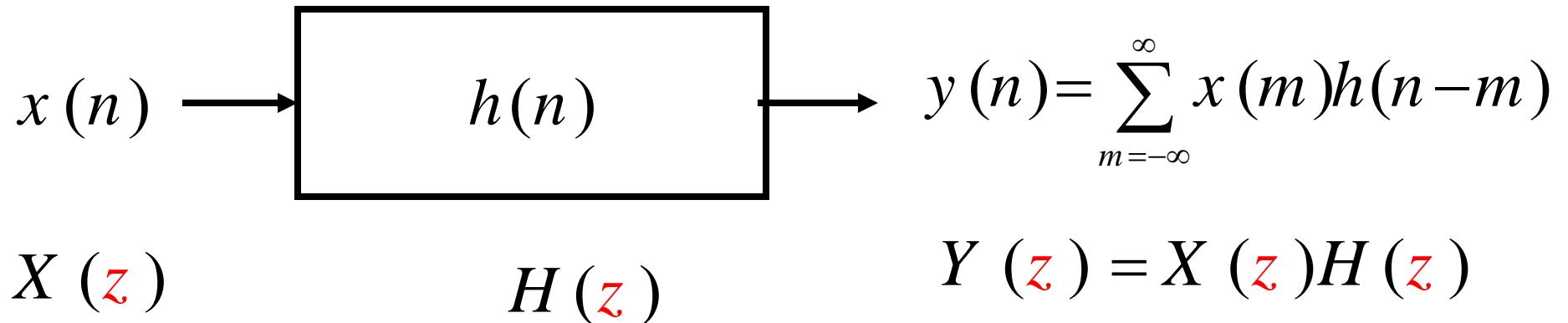
Now if we take the Z-Transform of both side

$$\begin{aligned} Y(z) + K_1 z^{-1} Y(z) + K_2 z^{-2} Y(z) + \cdots + K_m z^{-m} Y(z) \\ = L_0 X(z) + L_1 z^{-1} X(z) + L_2 z^{-2} X(z) + \cdots + L_r z^{-r} X(z) \end{aligned}$$

The transfer function  $H(z)$  defined,

$$H(z) \triangleq \frac{Y(z)}{X(z)} = \frac{L_0 + L_1 z^{-1} + L_2 z^{-2} + \cdots + L_r z^{-r}}{1 + K_1 z^{-1} + K_2 z^{-2} + \cdots + K_m z^{-m}}$$

**For a discrete-time system**



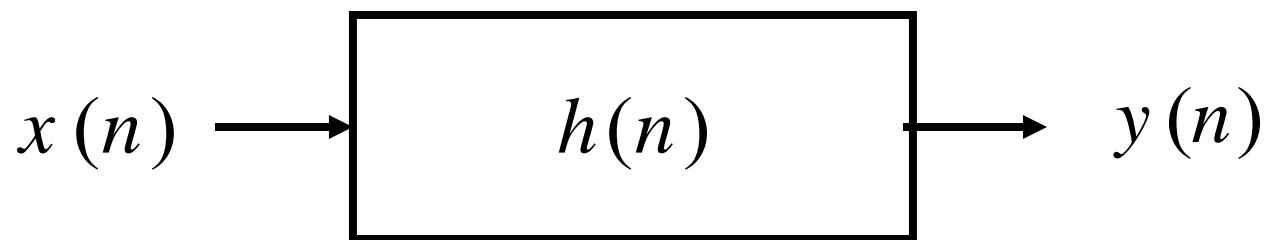
**From Example 8-13**

$$x(n) = \left(\frac{1}{2}\right)^n u(n) \quad h(n) = \left(\frac{1}{3}\right)^n u(n)$$

**Using discrete convolution**

$$y(n) = \sum_{m=-\infty}^{\infty} x(m)h(n-m) = 3\left(\frac{1}{2}\right)^n - 2\left(\frac{1}{3}\right)^n \quad n \geq 0$$

Now we will find  $y(n)$  using the Z-transform

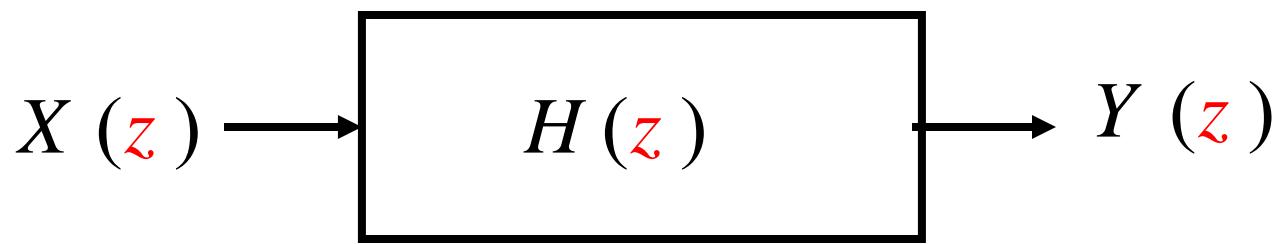


$$x(n) = \left(\frac{1}{2}\right)^n u(n) \quad h(n) = \left(\frac{1}{3}\right)^n u(n)$$

$$X(z) = \frac{z}{z - (1/2)} \quad H(z) = \frac{z}{z - (1/3)}$$

$\rightarrow Y(z) = X(z)H(z) = \left( \frac{z}{z - (1/2)} \right) \left( \frac{z}{z - (1/3)} \right)$

$$\frac{Y(z)}{z} = \frac{z}{(z - (1/2))(z - (1/3))} = \frac{3}{(z - (1/2))} - \frac{2}{(z - (1/3))}$$



$$\frac{Y(z)}{z} = \frac{3}{(z - (1/2))} - \frac{2}{(z - (1/3))}$$

$$Y(z) = \frac{3z}{(z - (1/2))} - \frac{2z}{(z - (1/3))}$$

$y(n) = 3\left(\frac{1}{2}\right)^n - 2\left(\frac{1}{3}\right)^n \quad n \geq 0$