

Delay Models in Data Networks

Chapter 3

Introduction and Goals

- Average end-end delays
 - Most important performance measure in a data network
 - Sum of delays on each link
 - Strongly influences choice of flow control and routing algorithms
 - Focus: subnet → network layer
 - Components of link delay:
 - Processing delay
 - Queuing delay
 - Transmission delay
 - Propagation delay
 - Our focus: queuing and transmission delays
- Goals:
- Analysis of system (network) load and performance characteristics
 - Response time
 - Throughput
 - Performance tradeoffs are often not intuitive
 - Queuing theory often makes analysis very straightforward
 - Examples:
 - How to analyze changes in network workloads? Should I add new terminals? How much?
 - What percentage of calls will be blocked? Adding more lines would solve the problem?

Outline of Topics

- Review of probability theory and random variables
- Review of stochastic processes
- Queuing models
- Little's theorem
- Analysis of single queue models
- Network of queues
- Jackson's theorem

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Background Needed for Queuing Analyses

- Basic probability theory
 - Basic definitions
 - Conditional probability
- Random variable concepts
 - Discrete random variables and their characteristics
 - Continuous random variables and their characteristics
 - Joint distributions
- Stochastic processes
 - Poisson processes
 - Markov processes
- Goal of this review:
 - Provide a brief review of topics useful to us
 - Set stage for queuing analyses → delay models in data networks

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Review of Probability Theory and Random Variables

Basic Definitions

- Experiment
 - A process whose outcome is not known with probability 1
- Sample space
 - Ω = set of all possible outcomes
- Sample point
 - Outcomes themselves are sample points in Ω
- Example:
 - A coin flipping experiment
 - $\Omega = \{H, T\}$
- Example:
 - Tossing a die:
 - $\Omega = \{1, 2, \dots, 6\}$

Axioms of Probability

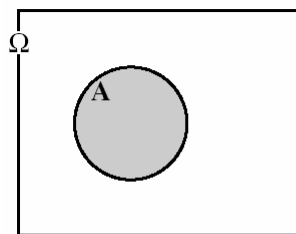
- Common axioms:
 1. $0 \leq \Pr[A] \leq 1$ for each event A
 2. $\Pr[\Omega] = 1$
 3. $\Pr[\emptyset] = 0$
 4. $\Pr[A \cup B] = \Pr[A] + \Pr[B]$ if A and B are mutually exclusive
- Important rules
 1. $\Pr[\bar{A}] = 1 - \Pr[A]$
 2. $\Pr[A \cap B] = 0$ if A and B are mutually exclusive
 3. $\Pr[A \cup B] = \Pr[A] + \Pr[B] - \Pr[A \cap B]$
 4. $\Pr[A \cup B \cup C] = \Pr[A] + \Pr[B] + \Pr[C] - \Pr[A \cap B] - \Pr[A \cap C] - \Pr[B \cap C] + \Pr[A \cap B \cap C]$
- Can be understood through Venn Diagrams

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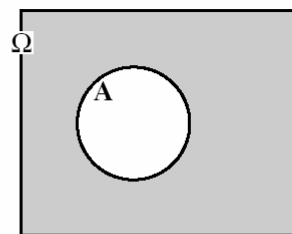
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Venn Diagrams



(a) A



(b) \bar{A}

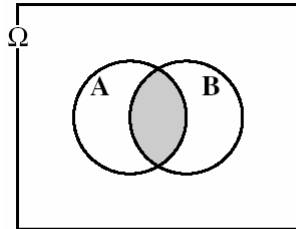
Complementation

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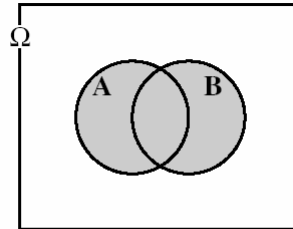
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Venn Diagrams



(c) A AND B
 $A \cap B$



(d) A OR B
 $A \cup B$

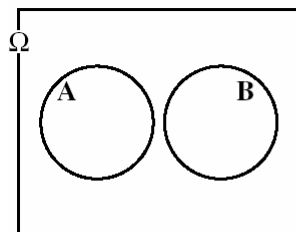
Intersection

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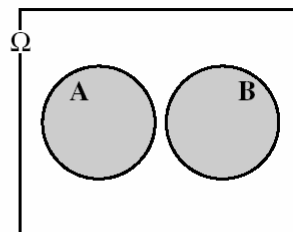
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Venn Diagrams



(e) A AND B
 $A \cap B$



(f) A OR B
 $A \cup B$

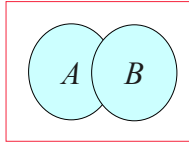
Mutual Exclusivity

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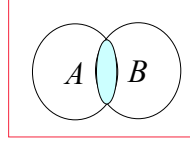
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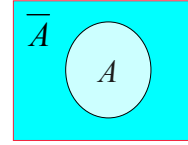
Mutually Exclusive Events



$$A \cup B$$

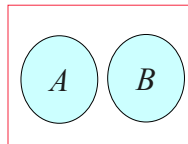


$$A \cap B$$



$$\bar{A}$$

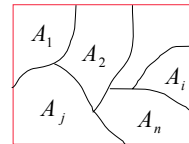
- If $A \cap B = \phi$, the empty set, then A and B are said to be mutually exclusive (M.E).
- A partition of Ω is a collection of mutually exclusive subsets of Ω such that their union is Ω .



$$A \cap B = \phi$$

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$$A_i \cap A_j = \phi, \text{ and } \bigcup_{i=1}^n A_i = \Omega.$$



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Conditional Probability

- The conditional probability of an event A, given that event B has occurred is:

$$\Pr[A | B] = \frac{\Pr[A \cap B]}{\Pr[B]}$$

When $\Pr[B] \neq 0$

- When A and B are independent events
 - $\Pr[A \cap B] = \Pr[A]\Pr[B]$

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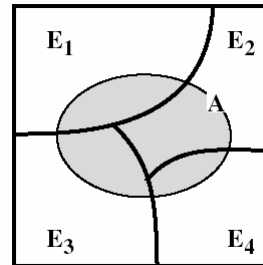
Total Probability

- Given a set of **mutually exclusive events** E_1, E_2, \dots, E_n covering all possible outcomes, and

$$E_i \cap E_j = \emptyset \text{ for } i \neq j \quad \bigcup_{i=1}^n E_i = \Omega$$

- Given an **arbitrary event** A , then:

$$\Pr[A] = \sum_{i=1}^n \Pr[A | E_i] \Pr[E_i]$$



- Baye's theorem** is applied when entire sample space can be subdivided into n mutually exclusive events

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Baye's Theorem

- Let E_1, E_2, \dots, E_n covering all possible outcomes, such that

$$E_i \cap E_j = \emptyset \text{ for } i \neq j \quad \bigcup_{i=1}^n E_i = \Omega$$

Let A be an event such that $\Pr[A] \neq 0$. Then for any other event E_j where $j = 1, 2, \dots, n$

$$\Pr[E_j | A] = \frac{\Pr[A | E_j] \Pr[E_j]}{\sum_{i=1}^n \Pr[A | E_i] \Pr[E_i]}$$

- Qualitatively, Baye's theorem provides the probability that an event really occurred provided the evidence in favor of it
 - $\Pr[A]$ represents the **a-priori probability** of event A

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Example: Baye's Theorem

- Hit & run accident involving a taxi
- 85% of taxis are yellow, 15% are blue
- Eyewitness reported that the taxi involved in the accident was blue (event WB)
- Data shows that eyewitnesses are correct on car color 80% of the time
- What is the probability that the taxi was blue?

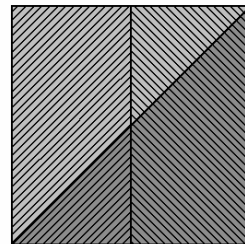
$$\begin{aligned} \Pr[\text{Blue} | \text{WB}] &= \frac{\Pr[\text{WB} | \text{Blue}] \Pr[\text{Blue}]}{\Pr[\text{WB} | \text{Blue}] \Pr[\text{Blue}] + \Pr[\text{WB} | \text{Yellow}] \Pr[\text{Yellow}]} \\ &= \frac{(0.8)(0.15)}{(0.8)(0.15) + (0.2)(0.85)} = 0.41 \end{aligned}$$

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Bayes's Theorem: Another Example



- Network injects errors (flips bits)
- Assume $\Pr[S1] = \Pr[S0] = p = 0.5$
- Assume $\Pr[R1] = \Pr[R0] = (1-p) = 0.5$
- Given error injection, such that $\Pr[R0 | S1] = p_a$ and $\Pr[R1 | S0] = p_b$, then :

 = S0: 0 sent  = R0: 0 received
 = S1: 1 sent  = R1: 1 received

$$\Pr[S1 | R0] = \frac{\Pr[R0 | S1] \cdot \Pr[S1]}{\Pr[R0 | S1] \cdot \Pr[S1] + \Pr[R0 | S0] \cdot \Pr[S0]} = \frac{p_a p}{p_a p + (1 - p_b)(1 - p)}$$

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Random Variables

- Association of real numbers with events
- A random variable X is a function that assigns a real number to every outcome in a sample space, and satisfies the following conditions:
 1. The set $\{X \leq x\}$ is an event for every x
 2. $\Pr[X = \infty] = \Pr[X = -\infty] = 0$
- A random variable can be one of two types:
 - Continuous or
 - Discrete

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Random Variables (Cont'd)

- A variable is called a random variable (RV) if it takes one of a specified set of values with a specified probability
- Formally, a non-negative integer-valued random variable X has:
 - A range in $\{0, 1, 2, 3, \dots\}$ and
 - A probability mass function $p_k = P\{X=k\}$ for $k=0, 1, 2, \dots$
 - We want to allow $k=\infty$ as X might represent waiting time; thus:

$$p_\infty = P\{X = \infty\} = 1 - \sum_{k=0}^{\infty} p_k = 1 - P\{X < \infty\} = 1 - \text{Finite Probability}$$

- Important property of a finite RV (i.e., $p_\infty=0$):

$$\sum_{k=0}^{\infty} p_k = 1$$

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Random Variables: Examples

- Example: assigning a value to each outcome of an experiment
 - Consider the experiment of **rolling a pair of dice**
 - $\Omega = \{(1,1), (1,2), \dots, (6,6)\}$
 - X is a random variable corresponding to the sum of a pair (i,j) , that is $X = i + j$ for all i, j in the range of 1, ..., 6.
 - For example, $X = 7$ for (4, 3) pair
- Example:
 - Consider **flipping of two coins**
 - $\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$
 - X is a random variable corresponding to the number of heads
 - Then, $X = 1$ for either of (H, T) or (T, H) outcomes

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Characteristics of a Random Variable

- **Continuous random variables** can be described by:
 - Either a **distribution function** or
 - A **density function**
- **Discrete random variables** are described by a probability function $P_x(k)$
- Random variable characteristics:
 - Mean value
 - Second moment
 - Variance
 - Standard deviation

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CDF and PDF of a RV

- The **Cumulative Distribution Function (CDF)**:
CDF of a random variable maps a given value x to the probability of the variable taking a values less than or equal to x

$$F(x) = P\{X \leq x\}$$

- **Probability Density Function (PDF)**:
PDF of a RV X is given as a derivative of its CDF: $f(x) = \frac{dF(x)}{dx}$

Given a PDF $f(x)$, the probability of X to be in the interval (x_1, x_2) is given as:

$$P\{x_1 < X \leq x_2\} = F(x_2) - F(x_1) = \int_{x_1}^{x_2} f(x) dx$$

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Characteristics of a CDF

- The CDF of a RV X is represented as $F(x)$ and is defined for each real number x as:

$$F(x) = P(X \leq x) \text{ for } -\infty < x < \infty$$

- **Properties:**

1. $F(x)$ is in range of $(0, 1)$: $0 \leq F(x) \leq 1, \forall x$
2. $F(x)$ is non-decreasing: If $x_1 < x_2$ then $F(x_1) \leq F(x_2)$
3. Limiting values: $\lim_{x \rightarrow \infty} F(x) = 1$ and $\lim_{x \rightarrow -\infty} F(x) = 0$

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Probability Mass Function (PMF)

- For discrete RVs, the CDF is not continuous
 - Cannot be differentiated
- PMF is used instead of PDF for discrete RVs
- Let X be a discrete RV that can take n distinct values:
 - $X \in \{x_1, x_2, \dots, x_n\}$ with probabilities $\{p_1, p_2, \dots, p_n\}$, respectively
 - The PMF maps x_i to p_i as:
 $f(x_i) = p_i$
- The probability of X being in the interval (x_1, x_2) can be computed as:

$$P\{x_1 < X \leq x_2\} = F(x_2) - F(x_1) = \sum_{x_1 < X \leq x_2} p_i$$

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Discrete RV

- Definition:**
 - X is a discrete RV if it can take on at most a countable number of values $\{x_1, x_2, \dots, x_n\}$ such that
 $p(x_i) = P(X = x_i)$ for $i = 1, 2, \dots$ and $\sum_{i=1}^{\infty} p(x_i) = 1$
- PMF** of a discrete RV X :
 - If $I = [a, b]$ such that $a \leq b$ and a, b are real number, then
 $P(X \in I) = \sum_{a \leq x_i \leq b} p(x_i)$
- CDF** of a discrete random variable X is given as:
 $F(x) = \sum_{x_i \leq x} p(x_i), \forall -\infty < x < \infty$
- Necessary and sufficient conditions for a function $f(x)$ to be a discrete density:

$$f(x) \geq 0 \text{ and } \sum_{\text{all } x} f(x) = 1$$

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Example: Discrete RV

- Inventory system
 - Let x be the size of demand for a product (a discrete RV)
 - $x = 1, 2, 3, 4$ with probabilities $1/6, 1/3, 1/3,$ and $1/6,$ respectively
- PMF:
 - $P(X=1) = 1/6 = p(1)$
 - $P(X=2) = 1/3 = p(2)$
 - $P(X=3) = 1/3 = p(3)$
 - $P(X=4) = 1/6 = p(4)$
- CDF: $F(x) = 0 + \sum_{x_i \leq x} p(x_i) + 0$
 - $P[x \leq 1] = p(1) = 1/6$
 - $P[x \leq 2] = p(1) + p(2) = 1/2$
 - $P[x \leq 3] = p(1) + p(2) + p(3) = 5/6$
 - $P[x \leq 4] = 1$

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Continuous RVs

- Definition:
 - A random variable x is continuous if there exists a non-negative function $f(x)$ such that for any set of real numbers B
 - 1) $P(X \in B) = \int_B f(x) dx$ and
 - 2) $\int_{-\infty}^{\infty} f(x) dx = 1$
 - $f(x)$ is called **Probability Density Function (PDF)** for x
 - $f(x)$ is not a probability as in the case of a PMF
- For any real number x :
$$P(X = x) = P(X \in [x, x]) = \int_x^x f(y) dy = 0$$
- Interpretation of $f(x)$:
$$\text{For } \Delta x > 0, P(X \in [x, x + \Delta x]) = \int_x^{x + \Delta x} f(y) dy$$

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Continuous RVs: CDF

- The distribution function $F(x)$ of a continuous RV X is given by:

$$F(x) = P(X \in [-\infty, x]) = \int_{-\infty}^x f(y)dy, \forall -\infty < x < \infty$$

- Then, $f(x) = F'(x)$

- If $I = (a, b)$ where $a, b \in \mathfrak{R}$ such that $a < b$, then

$$P(x \in I) = \int_a^b f(y)dy = F(b) - F(a)$$

- If $\Delta x > 0$ then

$$P(X \in [x, x + \Delta x]) = \int_x^{x+\Delta x} f(y)dy = F(x + \Delta x) - F(x)$$

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Example: Continuous RV

- A **uniform RV** on interval $[0, 1]$ has PDF:

$$f(x) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- Also, if $0 \leq x \leq 1$ then the CDF is computed as:

$$F(x) = \int_0^x f(y)dy = \int_0^x 1 \cdot dy = x$$

- If $0 \leq x \leq x + \Delta x \leq 1$ then

$$\begin{aligned} P(X \in [x, x + \Delta x]) &= \int_x^{x+\Delta x} f(y)dy = F(x + \Delta x) - F(x) \\ &= x + \Delta x - x = \Delta x \end{aligned}$$

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Another Example: Continuous RV

- An exponential RV with mean β and PDF given as:

$$f(x) = \frac{1}{\beta} e^{-\frac{x}{\beta}} \text{ for } x \geq 0$$

- Then, the CDF is derived as:

$$\begin{aligned} F(x) &= \int_0^x f(y) dy = \int_0^x \frac{1}{\beta} e^{-y/\beta} dy \\ &= \frac{1}{\beta} \left| \beta e^{-y/\beta} \right|_0^x = e^0 - e^{-x/\beta} \\ &= 1 - e^{-x/\beta} \text{ for } x \geq 0 \end{aligned}$$

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Joint Distributions

- Instead of a single RV, we may have to deal with n RVs simultaneously: x_1, x_2, \dots, x_n

- Example: service times in a queue S_1, S_2, \dots, S_n
- Example: Delays in a queue D_1, D_2, \dots, D_n

- Let $n=2$

- If X, Y are discrete RVs, then let $p(x, y) = P(X = x, Y = y) \quad \forall x, y$
then $p(x, y)$ is called joint probability mass function of X and Y

- Marginal PMFs of X and Y :

- If X and Y are independent:

$$\begin{aligned} & p(x, y) = p_x(x) p_y(y) \quad \forall x, y \\ \text{where} & \\ & p_x(x) = \sum_y p(x, y) \quad \text{and} \\ & p_y(y) = \sum_x p(x, y) \end{aligned}$$

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Example: Joint Distributions

- Suppose that X and Y are jointly discrete RVs with

$$p(x, y) = \begin{cases} \frac{xy}{27} & \text{for } x = 1, 2; y = 2, 3, 4 \\ 0 & \text{Otherwise} \end{cases}$$

- Then, we can calculate marginal PMFs as:

$$p_X(x) = \sum_{y=2}^4 \frac{xy}{27} = \frac{2x}{27} + \frac{3x}{27} + \frac{4x}{27} = \frac{x}{3} \text{ for } x = 1, 2$$

$$p_Y(y) = \sum_{x=1}^2 \frac{xy}{27} = \frac{y}{27} + \frac{2y}{27} = \frac{y}{9} \text{ for } y = 2, 3, 4$$

$$\therefore p_X(x)p_Y(y) = \frac{xy}{27} = p(x, y) \quad \forall x, y$$

$\Rightarrow X$ and Y are independent

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Continuous Joint Distribution

- Definition:**

- X and Y are jointly continuous if there exists a non-negative function $f(x, y)$, called joint PDF of X and Y , such that for all sets of real numbers A and B ,

$$P(X \in A, Y \in B) = \int_B \int_A f(x, y) dx dy$$

- Independence:**

- X and Y are independent if

$$f(x, y) = f_X(x)f_Y(y) \quad \forall x, y$$

where **marginal PDFs of X and Y** are given as:

$$f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy$$

$$f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$$

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Example: Continuous Joint Distribution

- X and Y are jointly continuous RVs with

$$f(x, y) = \begin{cases} 24xy & \text{for } x \geq 0, y \geq 0, \text{ and } x + y \leq 1 \\ 0 & \text{Otherwise} \end{cases}$$

- Then, marginal PDFs are given as:

$$f_X(x) = \int_0^{1-x} 24xy dy = 12x(1-x)^2 \quad \text{for } 0 \leq x \leq 1$$

$$f_Y(y) = \int_0^{1-y} 24xy dx = 12y(1-y)^2 \quad \text{for } 0 \leq y \leq 1$$

$$\therefore f\left(\frac{1}{2}, \frac{1}{2}\right) = 24\left(\frac{1}{2}\right)\left(\frac{1}{2}\right) = 6 \neq f_X\left(\frac{1}{2}\right)f_Y\left(\frac{1}{2}\right) = 9/4$$

$\therefore X$ and Y are NOT independent

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Mean or Expected Values of a RV

- For a discrete RV X , we have already seen that:

$$\text{Mean } \mu = E(X) = \sum_{j=1}^{\infty} x_j p_X(x_j)$$

- For a continuous RV X :

$$\text{Mean } \mu = E(X) = \int_{-\infty}^{\infty} xf(x) dx$$

- Properties:

(1) $E[CX] = C E[X]$ for $C \in \mathfrak{R}$ and is a constant

(2) $E\left[\sum_{i=1}^n C_i X_i\right] = \sum_{i=1}^n C_i E[X_i]$ even when x_i 's are dependent

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Example: Expected Values

- **Discrete case:**

- Let x be a discrete RV such that

$$X = \begin{cases} 1 & \text{w.p. } 1/6 \\ 2 & \text{w.p. } 1/3 \\ 3 & \text{w.p. } 1/3 \\ 4 & \text{w.p. } 1/6 \end{cases}$$

- Then, $\mu = E[X] = 1(1/6) + 2(1/3) + 3(1/3) + 4(1/6) = 5/2$

- **Continuous case:**

- $X \sim U[0, 1]$ with PDF $f(x)$ given as:

$$f(x) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- Then

$$\mu = E[X] = \int_0^1 x dx = 1/2$$

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Variance of a RV

- For a RV x and its mean μ , $(x-\mu)^2$ represents the square of distance between them
- The expected value of above quantity is called the **variance of x** and is given as:

$$Var(X) = E[(X-\mu)^2] = \sum_{i=1}^n p_i (X_i - \mu)^2 = \int_{-\infty}^{\infty} (X_i - \mu)^2 f(X) dX$$

- The summation is for discrete RVs while integral is used for continuous RVs
- Variance is traditionally denoted by σ^2
- The square root of variance is known as **standard deviation** and is denoted by σ

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Properties of Variance

- Variance of a RV X is given as

$$\sigma^2 = E[(X_i - \mu_i)^2] = E[X_i^2] - \mu_i^2$$

- $\text{Var}(X) \geq 0$
- $\text{Var}(CX) = C^2 \text{Var}(X)$

- Also,

$$\text{Var}\left[\sum_{i=1}^n X_i\right] = \sum_{i=1}^n \text{Var}(X_i) \text{ if } X_i \text{'s are independent}$$

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Example: Variance

- **Discrete RV**

- $X = 1, 2, 3, 4$ w.p. $1/6, 1/3, 1/3,$ and $1/6$, respectively
- Find $E[X^2]$: $E[X^2] = \sum_{i=1}^4 x^2 p_x = 43/6$
- Then calculate $\text{Var}(X) = E[X^2] - \mu^2 = 43/6 - (5/2)^2 = 11/12$

- **Continuous RV**

- $X \sim U[0, 1]$ with pdf $f(x) = 1$ for $0 \leq x \leq 1$ and 0 elsewhere

$$E[X^2] = \int_0^1 x^2 f(x) dx = 1/3$$

- Then calculate $\text{Var}(X) = E[X^2] - \mu^2 = 1/3 - (1/2)^2 = 1/12$

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C.O.V. and Covariance of a RV

- The ratio of the standard deviation to the mean is called the **Coefficient of Variation (C.O.V.)**:

$$\text{C.O.V.} = \frac{\text{Standard deviation}}{\text{Mean}} = \frac{\sigma}{\mu}$$

- **Covariance:**

Given two RVs X and Y with means μ_X and μ_Y , their covariance is:

$$\text{Cov}(X, Y) = \sigma_{XY} = E[(X - \mu_X)(Y - \mu_Y)] = E(XY) - E(X)E(Y)$$

- For independent variables, covariance is zero as $E(XY) = E(X)E(Y)$
- Zero covariance does not necessarily mean independent variables

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Correlation Coefficient of a RV

- The normalized value of covariance is called the **correlation coefficient** or simply the **correlation**

$$\text{Correlation}(X, Y) = \rho_{XY} = \frac{\sigma_{XY}^2}{\sigma_X \sigma_Y}$$

- The correlation always lies between -1 and 1

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Mean and Variance of Sums of RVs

- Let X_1, X_2, \dots, X_n be n RVs. If a_1, a_2, \dots, a_n are n arbitrary constants (weights), then

$$E(a_1X_1 + a_2X_2 + \dots + a_nX_n) = a_1E(X_1) + a_2E(X_2) + \dots + a_nE(X_n)$$

- For independent variables:

$$Var(a_1X_1 + a_2X_2 + \dots + a_nX_n) = a_1^2Var(X_1) + \dots + a_n^2Var(X_n)$$

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Commonly Used Types of RVs

- Bernoulli
- Geometric
- Binomial
- Exponential
- Poisson

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Bernoulli RVs

- It is the simplest discrete distribution
- A Bernoulli RV x can take only two values, usually denoted as failure ($x=0$) and success ($x=1$)
 - If, $P\{\text{success}\} = P\{X=1\} = p$; then
 $P\{\text{failure}\} = P\{X=0\} = q = 1-p$
 - PMF:
$$f(x) = \begin{cases} 1-p & \text{if } X=0 \\ p & \text{if } X=1 \\ 0 & \text{Otherwise} \end{cases}$$
 - Mean: $E(x) = p$
 - Variance: $\text{Var}(x) = p(1-p)$
- Examples of models using Bernoulli RVs:
 - A computer system is up or down
 - A network packet reaches its destination or is lost

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Geometric RVs

- This is the distribution of number of trials up to and including the first success in a sequence of Bernoulli trials
- Key characteristics:
$$\begin{aligned} \text{PMF: } f(x) &= (1-p)^{x-1} p && \text{for } x = 1, 2, \dots, \infty \\ \text{CDF: } F(x) &= 1 - (1-p)^x \\ \text{Mean: } E(x) &= \frac{1}{p} \\ \text{Variance: } \text{Var}(x) &= \frac{1-p}{p^2} \end{aligned}$$
- Geometric distribution is the discrete equivalent of exponential distribution
 - It has memoryless property
 - Results of past attempts does not affect the outcome of future attempts
- Examples:
 - Number of local queries to a database between successive accesses to the remote database
 - Number of packets successfully transmitted between those requiring retransmission

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Memoryless Property of Geometric Distribution

- Memoryless

$$P[X > x + \Delta x | X > x] = P[X > \Delta x] \text{ for all } x, \Delta x \geq 0$$

$$P[X > \Delta x] = P[X > x + \Delta x, X > x] / P[X > x]$$

$$P[X > x + \Delta x] = P[X > x] P[X > \Delta x]$$

- $P[X > n] = p(1-p)^n [1 + (1-p) + (1-p)^2 + \dots]$
 $= p(1-p)^n \{1 / [1 - (1-p)]\} = (1-p)^n$

- $P[X > n+m, X > n] / P[X > n] = (1-p)^{n+m} / (1-p)^n = (1-p)^m$
 $\Rightarrow P[X > n+m | X > n] = P[X > m]$

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Exponential RV

- It is the only continuous distribution with memoryless property
- Key characteristics:

$$\text{PDF: } f(\tau) = \lambda e^{-\lambda\tau} \quad \text{for } \frac{1}{\lambda} > 0 \text{ and } 0 \leq \tau \leq \infty$$

$$\text{CDF: } F(\tau) = 1 - e^{-\lambda\tau}$$

$$\text{Mean: } E(\tau) = \frac{1}{\lambda}$$

$$\text{Variance: } \text{Var}(\tau) = \frac{1}{\lambda^2}$$

- Examples:
 - Time between successive requests to a device
 - Time between failures of a device

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Exponential RV (Cont'd)

- Exponential RV T is the continuous version of Geometric RV X :
 $P_X(j) = p(1-p)^{j-1}$
- $P_T(t = j/n) = p(1-p)^{j-1} = p(1-p)^{nt-1}$
- Assume $n \rightarrow \infty$, $p \rightarrow 0$, and $np \rightarrow \lambda$, $1/n \rightarrow \Delta t$
 $P_T(t = j/n) \rightarrow (\lambda/n)(1-\lambda/n)^{nt} \rightarrow \lambda e^{-\lambda \Delta t}$
- $P[T > t] = \int_t^{\infty} \lambda e^{-\lambda t} dt = e^{-\lambda t}$
- $P[T > t + \Delta t | T > t] = P[T > t + \Delta t] / P[T > t]$
 $= e^{-\lambda(t + \Delta t)} / e^{-\lambda t} = e^{-\lambda \Delta t} = P[T > \Delta t]$
- $E[T] = \int_0^{\infty} \lambda e^{-\lambda t} t dt = 1/\lambda$
- $\text{Var}[T] = E[T^2] - E[T]^2 = 1/\lambda^2$

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Binomial RV

- The number of successes X in a sequence of n Bernoulli trials has a binomial distribution
- It has two parameters:
 - p = probability of success in a trial, $0 < p < 1$
 - n = number of trials; n must be a positive integer
- Key characteristics:
 - PMF: $f(X) = \binom{n}{X} p^X (1-p)^{n-X}$ for $X = 0, 1, \dots, n$
 - Mean: $E(X) = np$
 - Variance: $\text{Var}(X) = np(1-p)$
- Examples:
 - Number of processors that are up in a multiprocessor system
 - Number of packets that reach destination without loss

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Binomial RV (Cont'd)

- n independent trials.
 - X represents the number of success that occur in n trials. X is a Binomial RV with parameters (n, p) .
- Using CRC to test n frames:
 - Each frame is error-free with probability p , independent of the results of other tests.
 - X equals the number of error-free frames in the tests.
- Binomial RV denotes the probability of x success among n trials
- Question: Compute $E[Y]$ and $\text{Var}[Y]$?

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Binomial RV (Cont'd)

- $E[Y] = E[X_1 + X_2 + \dots + X_n]$
 $= E[X_1] + E[X_2] + \dots + E[X_n] = np$
- $\text{Var}[Y] = \text{Var}[X_1 + X_2 + \dots + X_n]$
 $= \text{Var}[X_1] + \text{Var}[X_2] + \dots + \text{Var}[X_n] = np(1-p)$
- If $n \rightarrow \infty$, $p \rightarrow 0$, and $np \rightarrow \alpha$, then a Binomial RV approximates a Poisson RV.

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Poisson RV

- It is a limiting form of binomial RV
- Probability model of a Poisson RV: phenomena that occur randomly in time
- Key characteristics:
 - PMF: $f(x) = P\{X=x\} = \lambda^x \frac{e^{-\lambda}}{x!}$ for $X = 0, 1, 2, \dots, \infty$
 - Mean: $E(X) = \lambda$
 - Variance: $\text{Var}(X) = \lambda$
- Examples:
 - Arrival of information requests at a WWW server
 - Initiation of telephone calls

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Poisson RV (Cont'd)

- An arrival
- A Poisson model:
 - An average arrival rate λ and a time interval T .
 - The number of arrivals X has a Poisson PMF with $\alpha = \lambda T$.
- Question: Compute $E[X]$ and $\text{Var}[X]$?
- $\phi_X(s) = e^{-\alpha} [1 + (\alpha e^s / 1!) + (\alpha^2 e^{2s} / 2!) + \dots]$
 $= e^{-\alpha} e^{\alpha e^s} = e^{\alpha(e^s - 1)}$
- $E[X] = \phi'_X(s) \big|_{s=0} = \alpha$
- $\text{Var}[X] = \{\phi''_X(s) - [\phi'_X(s)]^2\} \big|_{s=0} = \alpha$
- Relationship between Poisson RV and Binomial RV?

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Binomial RV \Rightarrow Poisson RV

- Binomial RV ($n \rightarrow \infty$, $p \rightarrow 0$, and $np \rightarrow \alpha$)

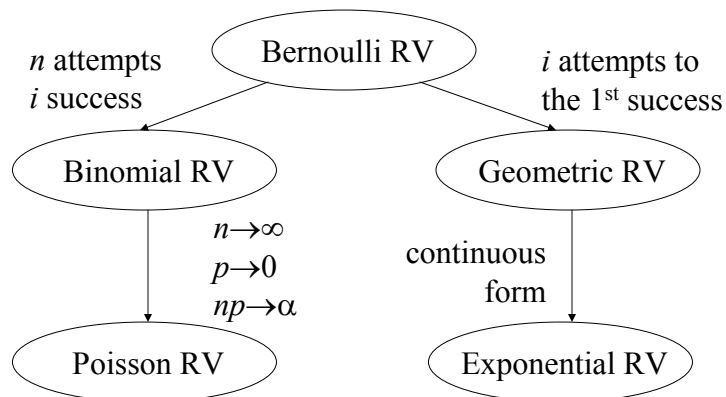
$$\begin{aligned}
 P_{\text{Binomial}}[X=i] &= \binom{n}{i} p^i (1-p)^{n-i} \\
 &= \frac{n!}{i!(n-i)!} \left(\frac{\alpha}{n}\right)^i \left(1-\frac{\alpha}{n}\right)^{n-i} \\
 &= \underbrace{\frac{n(n-1)\dots(n-i+1)}{i!}}_{\rightarrow 1} \left(\frac{\alpha}{n}\right)^i \underbrace{\left(1-\frac{\alpha}{n}\right)^n}_{\rightarrow e^{-\alpha}} \underbrace{\left(1-\frac{\alpha}{n}\right)^{-i}}_{\rightarrow 1} \\
 \Rightarrow P_{\text{Binomial}}[X=i] &\rightarrow e^{-\alpha} \frac{\alpha^i}{i!} \\
 \bullet E_{\text{Binomial}}[X] &= np \rightarrow E_{\text{Poisson}}[X] = \alpha \\
 \bullet \text{Var}_{\text{Binomial}}[X] &= np(1-p) \rightarrow \text{Var}_{\text{Poisson}}[X] = \alpha
 \end{aligned}$$

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Relationship of RVs



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Probability Distributions—Relevance to Networks

- Service times of queues (t_{trans}) in packet switching routers can be effectively modeled as **exponential**
- Arrival pattern of packets at a router is often **Poisson** in nature
 - and, arrival interval is exponential
- **Central Limit Theorem**: the distribution of a very large number of independent RVs is approximately **normal**, independent of individual distributions

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Probability Functions

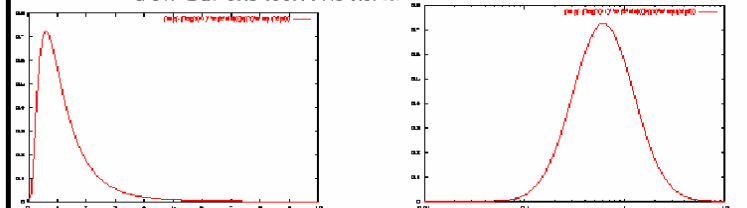
Log Normal dists

- A random variable X is lognormally distributed if $\log(X)$ is normally distributed:

$$f(x) = \frac{e^{-(\log(x-\mu)/m)^2/(2\sigma^2)}}{(x-\mu)\sigma\sqrt{2\pi}}$$

- where μ is the shape parameter, σ is the location parameter and m is the scale parameter.

✦ distributions look like normal in the log plot



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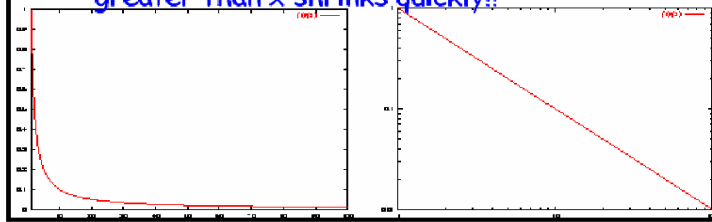
Probability Functions

Power Laws

- Experiments that have trials whose distributions have the general form:

$$P[X > x] \approx c x^{-a} \quad x \rightarrow \infty, a, c > 0$$

- As x increases, the probability that X is greater than x shrinks quickly!!



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Probability Functions

Power Laws

- Pareto:** the simplest power law distribution

$$f(x) = \frac{ab^a}{x^{a+1}}, \quad x \geq b, \quad a > 0, \quad b > 0$$

- \Rightarrow cumulative distribution function (cdf)

$$P[X \leq x] = 1 - \frac{b^a}{x^a}$$

- \Rightarrow complementary cumulative distribution function (ccdf)

$$P[X > x] = \frac{b^a}{x^a}$$



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Probability Functions

Properties of the Pareto

• a determines the mean and variance

• b determines minimum value x can take

$$E[x] = \begin{cases} \infty & a \leq 1 \\ \frac{ab}{(1-a)} & a > 1 \end{cases}$$

$$\text{var}[x] = \begin{cases} \infty & a \leq 2 \\ \frac{ab^2}{(a-1)^2(a-2)} & a > 2 \end{cases}$$

Note: $1 < a < 2 \Rightarrow$ finite mean, infinite variance!

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3-1-59

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Probability Functions

Pareto

- Pareto studied the distribution of incomes.
 - ✦ Few people have a lot of money, many are poor.
- Pareto distributions are concerned with how many events are larger than x : this number is an inverse power of x .

$$P[X > x] = \frac{b^a}{x^a}$$

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3-1-60

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Probability Functions

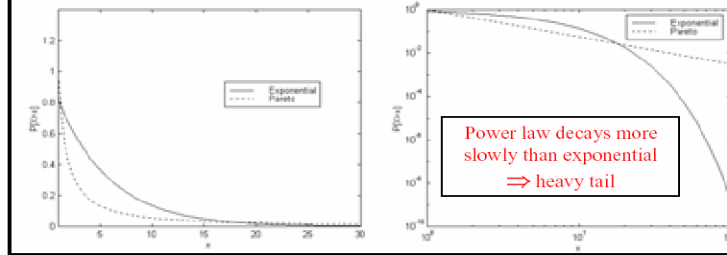
"Signature" of a Power Law

- Consider a log-log plot of $P[X > x]$ vs. x

$$P[X > x] = \frac{b^a}{x^a}$$

$$\log(P[X > x]) = \log\left(\frac{b^a}{x^a}\right) = -a \log(x) + a \log(b)$$

- Straight line with slope $-a$



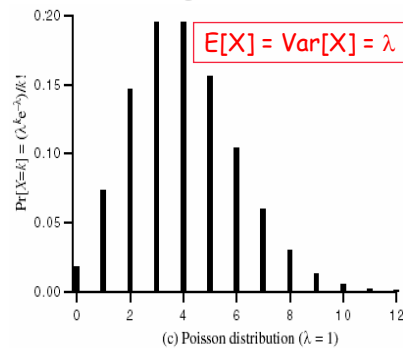
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Probability Distributions

Poisson Distribution

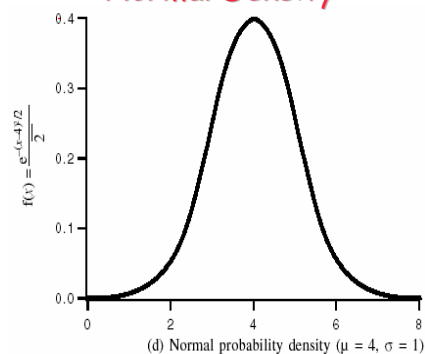


$$\Pr[X=k] = \frac{\lambda^k}{k!} e^{-\lambda}$$

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3-1-62

Normal Density



$$f(x) = \frac{e^{-(x-\mu)^2/2\sigma^2}}{\sigma\sqrt{2\pi}}$$

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