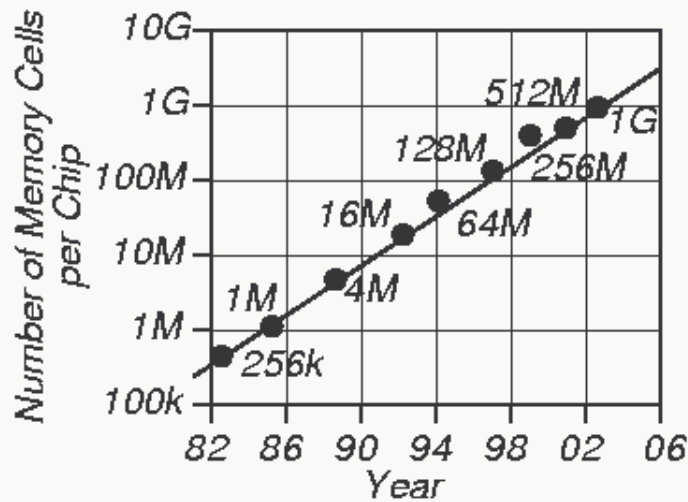


DIGITAL SYSTEM TESTING COE -545

Lecture – 20 Memory Testing

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Memory Cells Per Chip



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Slide Number 2

Test Time in Seconds (Memory Size n Bits)

Size n	Number of Test Algorithm Operations			
	n	$n \times \log_2 n$	$n^{3/2}$	n^2
1 Mb	0.06	1.26	64.5	18.3 hr
4 Mb	0.25	5.54	515.4	293.2 hr
16 Mb	1.01	24.16	1.2 hr	4691.3 hr
64 Mb	4.03	104.7	9.2 hr	75060.0 hr
256 Mb	16.11	451.0	73.3 hr	1200959.9 hr
1 Gb	64.43	1932.8	586.4 hr	19215358.4 hr
2 Gb	128.9	3994.4	1658.6 hr	76861433.7 hr

Memory cycle time = 60ns

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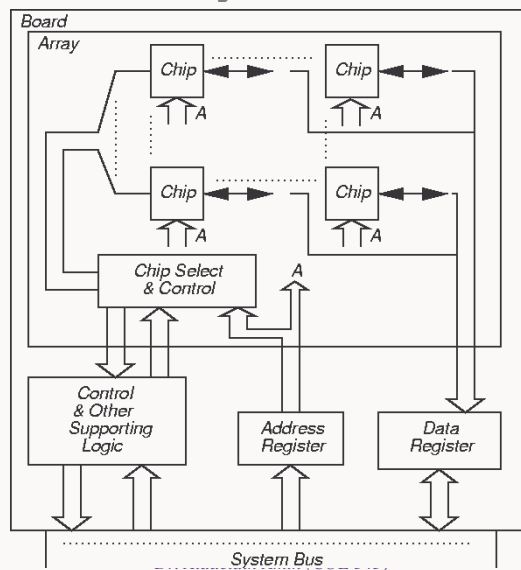
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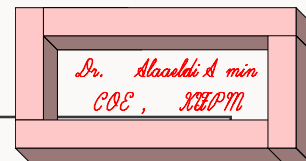
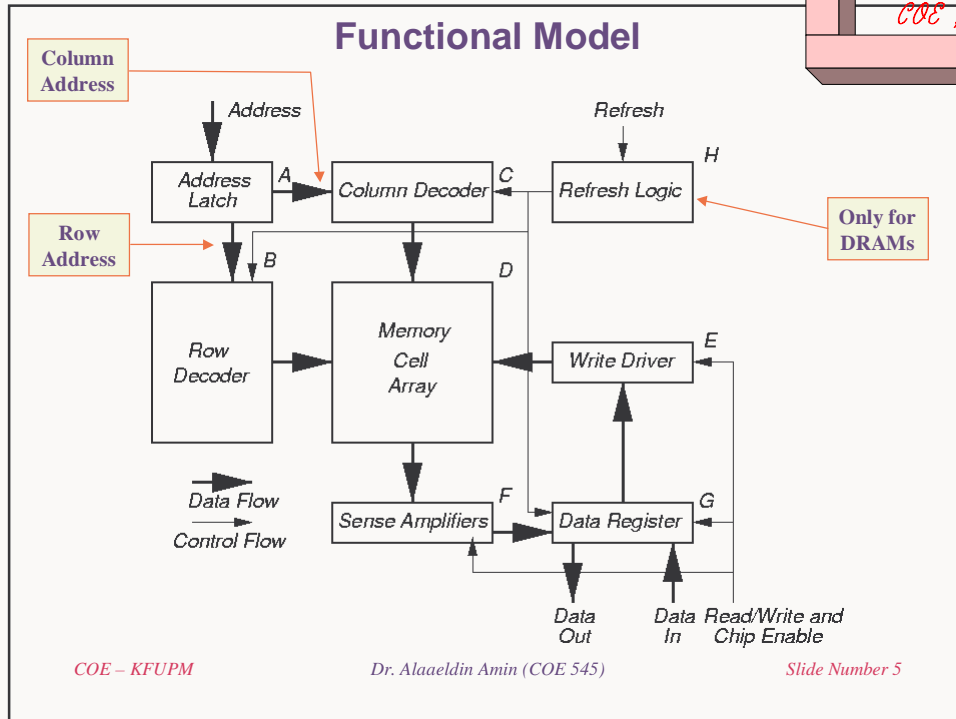
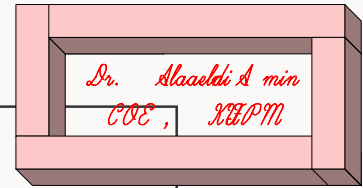
Memory Test Levels

Chip,
Array, &
Board



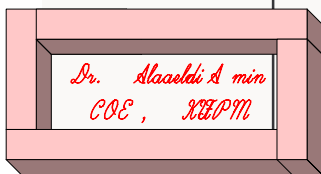
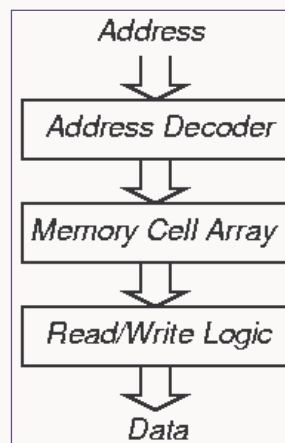
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Slide Number 4



Simplified Functional Model

- Need to Consider Faults in these 3 Blocks Only
- Faults in the Read/Write Logic will be Manifested as Array Faults
- Need to Consider Faults in 2 Blocks Only
 - Memory Array
 - Address Decoder
- Need to Adopt Suitable Fault Models



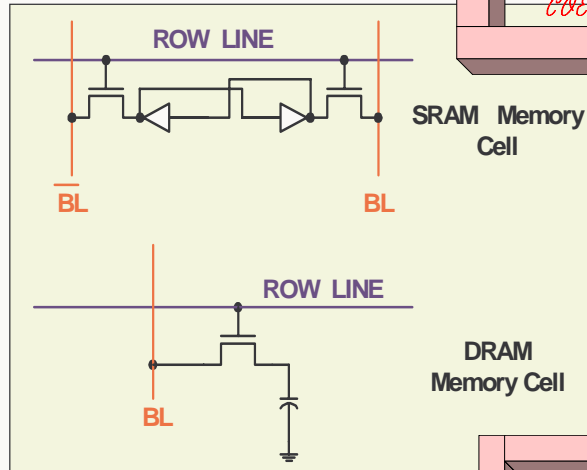
Memory Cells

SRAM Cell

- Cross Coupled Inverters with 2 Access Transistors (6T-Cell)
- One Row (Word) Line and 2 Bit (Column) Lines
- Static Storage of Data → No Need For Refresh

DRAM Cell

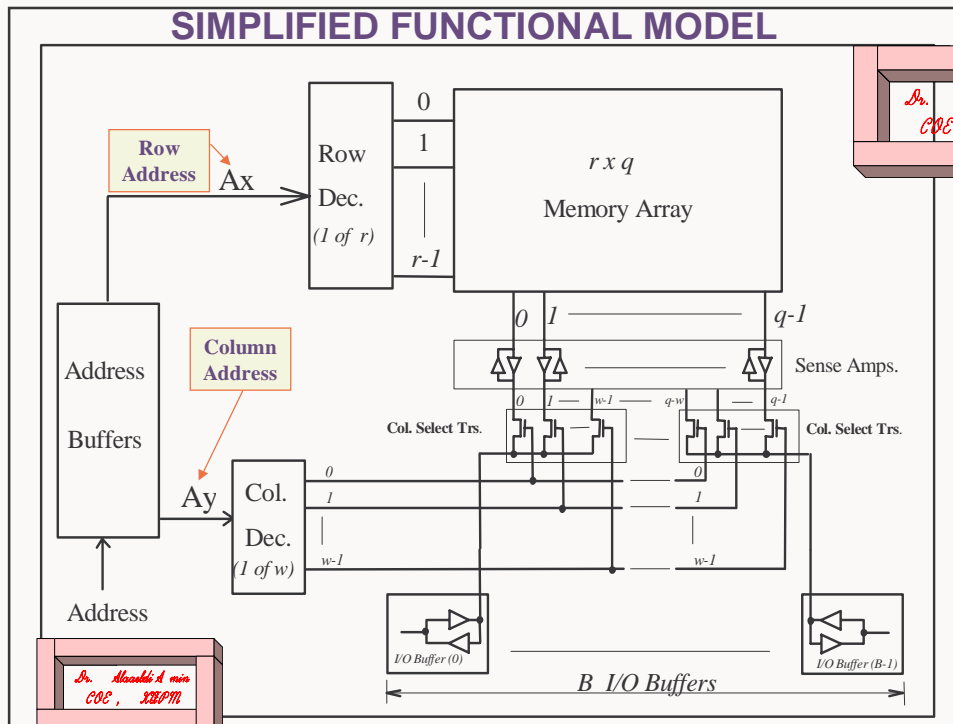
- A Capacitor and An Access Transistor
- One Row (Word) Line and 1 Bit (Column) Lines
- Dynamic Storage of Data (Charge on a Capacitor) → Stored Data Refresh Required



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Slide Number 7

SIMPLIFIED FUNCTIONAL MODEL



SIMPLIFIED FUNCTIONAL MODEL

- Memory Array r Rows & q Columns
- Addresses \Rightarrow Row Address (A_x) + Column Address (A_y)
- A_x Selects A Single ROW in the Array (Row Decoder)
- Data OF All Cells On the Selected Row Are Passed to The Array Columns Which Are Sensed By Sense Amplifiers.
- Only Data of the Selected Word Are Passed to The Output Buffers By the Column-Select Transistor Which Are Accessed By The Column Address A_y (Through Column Decoder)
- Each Row contains w words of B bits each ($q = w \times B$)
- Each Row is Partitioned into B **groups** (0, 1, 2, ..., B-1)
- Each Group Consists of w Memory Cells.
- Each word on a row contributes one cell to each *Group* (*Group i* Consists of Memory Cells Corresponding to the *i*th Bit of ALL the w Words on this Row).
- The $q \times r$ array consists of r rows of q cells each.

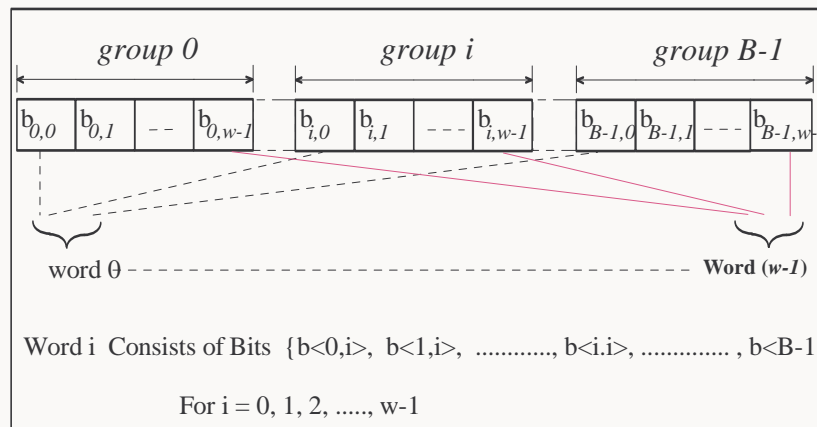
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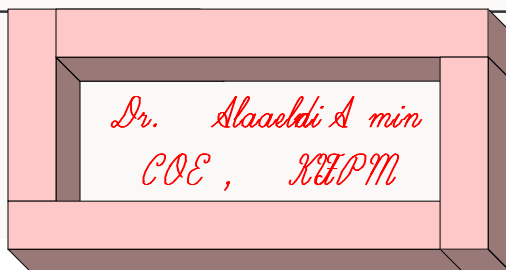


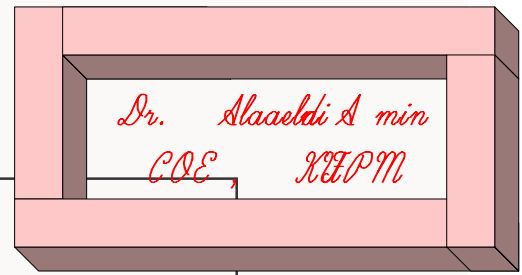
SIMPLIFIED FUNCTIONAL MODEL



- Each Row contains w words of B bits each ($q = w \times B$)
- Each Row is Partitioned into B **groups** (0, 1, 2, ..., B-1)
- Each Group Consists of w Memory Cells.
- Each word on a row contributes one cell to each *Group* (*Group i* Consists of Memory Cells Corresponding to the *i*th Bit of ALL the w Words on this Row).
- The $q \times r$ array consists of r rows of q cells each.

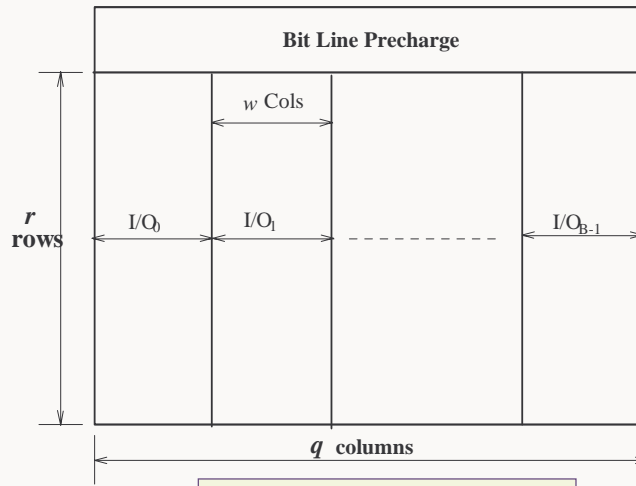
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Memory Array Architecture

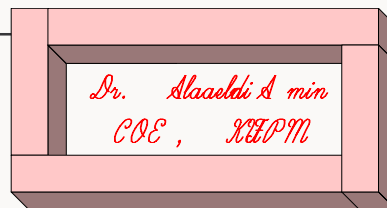
- The Memory Array Is modeled as a set of B blocks,
- Each Block Interfaces One I/O buffer.
- Each I/O Block Consists of w Columns
- Each Column Has r Memory Cells
- The i^{th} I/O Block Consists of All the i^{th} Groups on All r rows.



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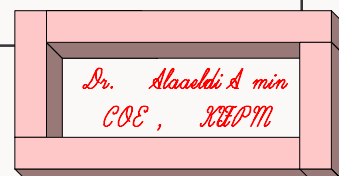
Memory Array Fault Models

- Fault Models Have to Be **Realistic** Representation of Physical Defects or Fault Effects
- The Fault Model Should Be **Efficient**:
 - Covers Large Class of Physical Failures
 - Has Low Complexity
- Memory Fault Models Are Classified Into 3 Categories
 - Single Cell Fault Model (Stuck & Transition Faults)
 - Two-Cell Fault Model (Coupling Faults)
 - K-Cell Fault Model
 - ❖ K-Cells Clustered in a Physical Neighborhood (Pattern Sensitive Faults)
 - ❖ K-Cells May Be Located Anywhere (K-Coupling, Bridging & State Coupling Faults).

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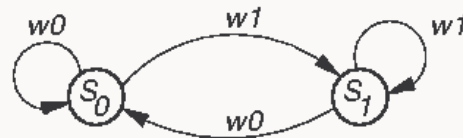
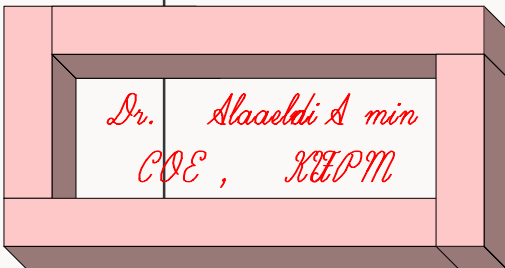


Stuck-at Faults

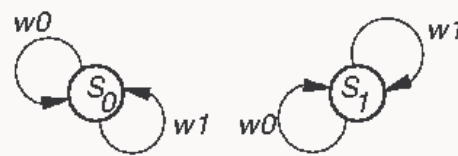
- **Condition:** For each cell, must read a 0 and a 1.

Notation

- SA0 $\Rightarrow \langle \forall / 0 \rangle$
- SA1 $\Rightarrow \langle \forall / 1 \rangle$



(a) State diagram of a good cell.



(b) SA0 fault.

(c) SA1 fault.

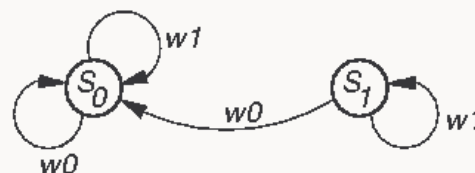
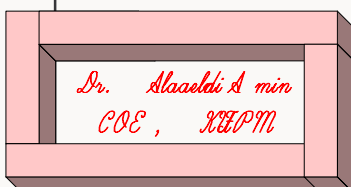
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Transition Faults (TF)

- Considered As a Special Case of *Stuck-At Faults*.
- Cell Fails to Perform a $0 \rightarrow 1$ Transition (**UP-TF**)
- Notation $\Rightarrow \langle \uparrow / 0 \rangle$.
- Cell Fails to Perform a $1 \rightarrow 0$ Transition (**Down-TF**)
- Notation $\Rightarrow \langle \downarrow / 1 \rangle$

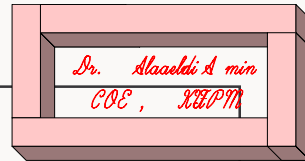


$\langle \uparrow / 0 \rangle$ transition fault

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Coupling Faults

Coupling Fault (CF): Transition in bit j causes unwanted change in bit i

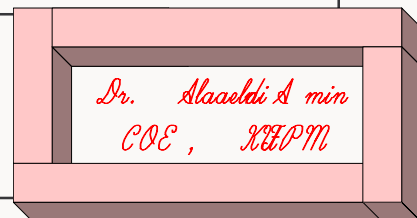
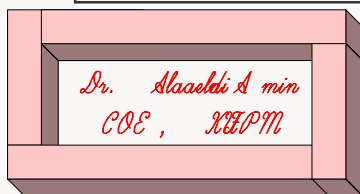
- **2-Coupling Fault:** Involves 2 cells, special case of k -Coupling Fault
 - Must restrict k cells to be practical
- **Inversion and Idempotent CFs** -- special cases of 2-Coupling Faults
- **Inversion Coupling Fault (CFin)** A Transition Write into the Coupling Cell **INVERTS** Contents of The Coupled Cell.
 - Notation $\Rightarrow \langle \uparrow; \downarrow \rangle$ OR $\langle \downarrow; \uparrow \rangle$
- **Idempotent Coupling Fault (CFid)** A Transition Write into the Coupling Cell **Forces** Contents of The Coupled Cell A Particular State
 - Notation $\Rightarrow \langle \uparrow; 1 \rangle, \langle \uparrow; 0 \rangle$ OR $\langle \downarrow; 1 \rangle, \langle \downarrow; 0 \rangle$

K- Coupling Fault: Same As 2-Coupling Cells BUT, Fault Occurs ONLY IFF Remaining (K-2) Cells Have a Particular State (Pattern)

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Bridging Faults

Bridging Faults:

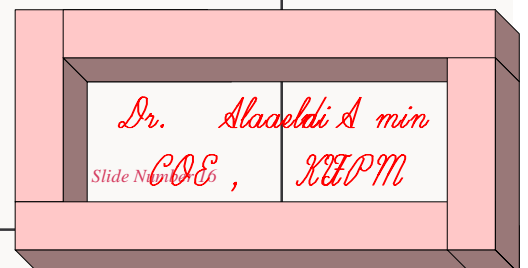
- **Bridging Fault (BF)** is a **SHORT** Between Two Lines, e.g, Row-Lines, Bit-Lines, etc.)
- Two Types of BFs (**AND-Bridging**) and (**OR-Bridging**)
- **AND-Bridging Notation** $\Rightarrow \langle 0, 0 / 0, 0 \rangle, \langle 0, 1 / 0, 0 \rangle \langle 1, 0 / 0, 0 \rangle \langle 1, 1 / 1, 1 \rangle$
- **OR-Bridging Notation** $\Rightarrow \langle 0, 0 / 0, 0 \rangle, \langle 0, 1 / 1, 1 \rangle \langle 1, 0 / 1, 1 \rangle \langle 1, 1 / 1, 1 \rangle$

State- Coupling Faults:

- Coupling Is **NOT** Due to a Transition Write But Rather Depends On the State of the Coupling Cell.
- Notation $\Rightarrow \langle 0; 0 \rangle, \langle 0; 1 \rangle \langle 1; 0 \rangle \langle 1; 1 \rangle$

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Pattern Sensitive Faults (PSF)

- A Memory Cell has a PSF iff its Content Is Affected By Contents of Other Memory Cells in its Physical Neighborhood.
- Affected Cell is Referred To as the Base Cell
- The Cells Affecting the Base Cell → Deleted Neighborhood
- The Base Cell and its Deleted Neighborhood is Referred to as the NEIGHBORHOOD

Classes OF Neighborhoods of Size n :

- Unrestricted PSF Neighborhood \equiv K-Coupling ($K = n$) \Rightarrow Impractical Tests $O(n2^n)$.
- Restricted Neighborhood (Neighborhood Pattern Sensitive Faults, or NPSF)
 - Restrictions on Neighborhood Size, (5-Cell or 9-Cell)
 - Restrictions on The physical Position of the Deleted Neighborhood Cells wrt the Base Cell

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Pattern Sensitive Faults (PSF)

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Classes OF Neighborhoods of Size n :

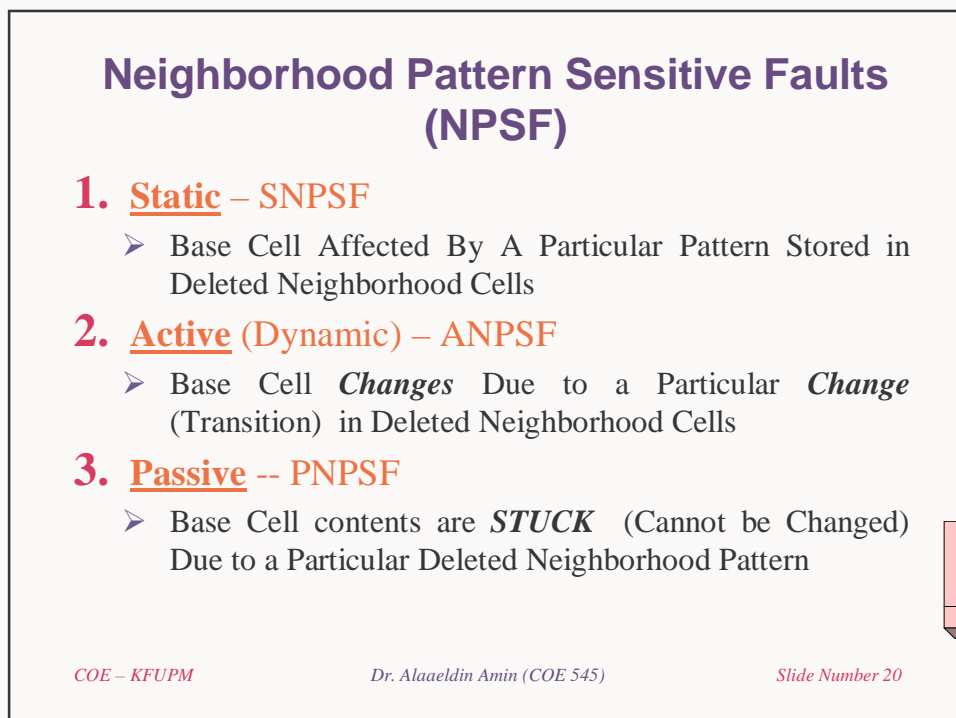
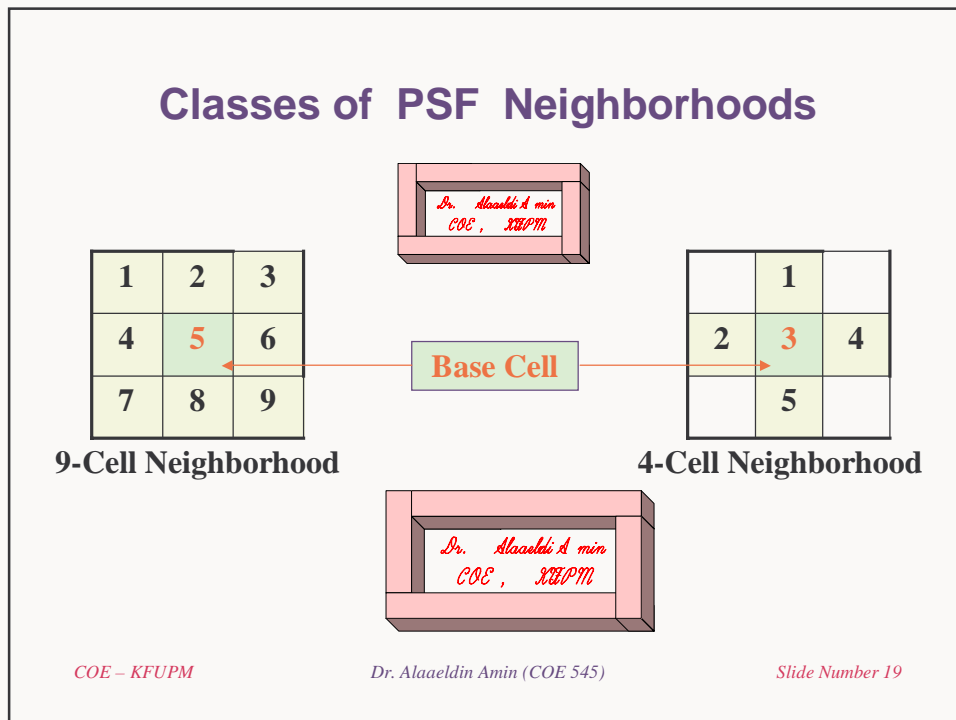
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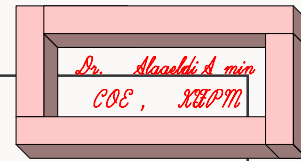
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NPSF Justification

- Memory Cells Have Been Shrinking in Size & Dimensions
- Memory Cells Getting Physically Closer ⇒ Electrically Interact With One Another Through:
 - Signal Coupling
 - Leakage From One Cell to Another
- Most Other Fault Classes (e.g. Stuck and Coupling Faults) Can Be Considered as Special Types of PSFs.

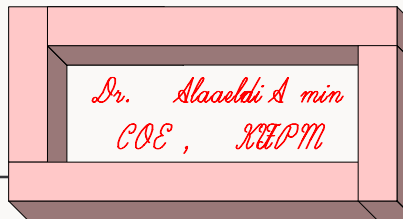
Faults in Read / Write Logic

- These Are Mapped into Faults in the Memory Array
- **Example** A Stuck-Fault in R/W Logic Shows As SAF in Large Clusters of Array Cells

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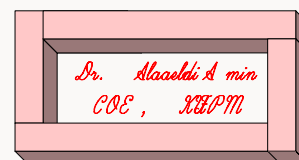
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Address Decoder Faults (ADFs)

- **Address decoding Fault assumptions:**
 - Decoder does not become sequential
 - Same behavior during both read & write
- Multiple ADFs must be tested for
- CMOS stuck-open faults



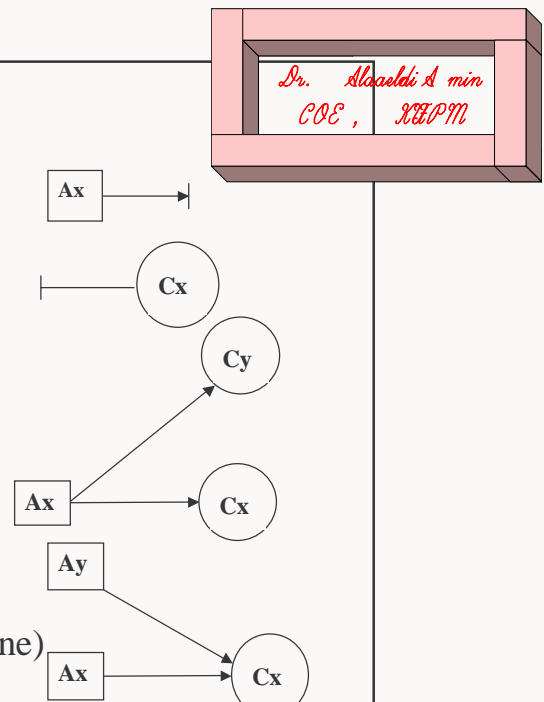
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Address Decoder Faults (Functional Fault Model)

- Address Accessing No Cell
- Inaccessible Cell
- One Address Accessing Many Cells (One-To-Many)
- More Than One Address Accessing One Cell (Many -To- One)



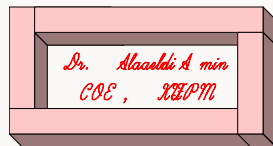
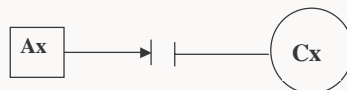
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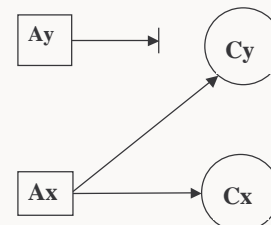
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Address Decoder Fault Combinations

- Some Address (Ax) Does Not Access its Own Cell (Cx)



- One-To-Many & Singular Address



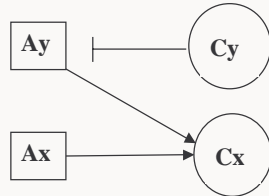
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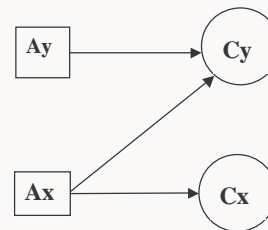
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Address Decoder Fault Combinations

- Many-To-One && Inaccessible Cell



- One-To-Many && Many-To-One



- CMOS Stuck_Open Faults

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Test Algorithms

1. AD-HOC Algorithms (Traditional Tests), e.g. M-Scan, Checker-Board, GALPAT, etc.
2. Fault Model Based Algorithms
3. Random Tests

NOTATION:

- B The number of bits (cells) in a memory word
- N The Number of Address bits (total of 2^N addresses)
- n The total number of bits (cells) in the memory
- K The size of the neighborhood
- A An address
- C A cell
- M A set of cells, words or addresses
- R A read operation
- W A write operation

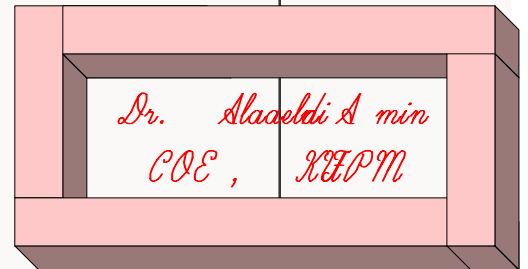
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March Test Notation

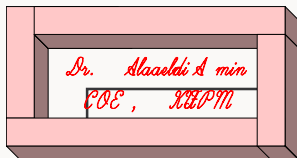
- r0 -- Read a 0 from a memory location
- r1 -- Read a 1 from a memory location
- w0 -- Write a 0 to a memory location
- w1 -- Write a 1 to a memory location
- ↑ -- Write a 1 to a cell containing 0
- ↓ -- Write a 0 to a cell containing 1
- ⇕ -- Complement the cell contents
- ↑↑ -- Increasing memory addressing
- ↓↓ -- Decreasing memory addressing



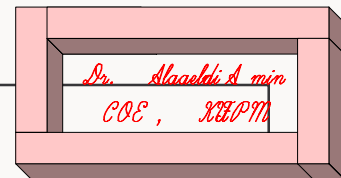
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Traditional Tests



1- MSCAN Test

- Writing 0s and 1s to the memory.

For i=0 to n-1

```
{ W(i) = 0
  R(i) (=0)
  W(i) = 1
  R(i) (=1)
}
```

{↑↑ (W0, R0, W1, R1) }

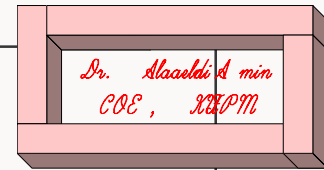
Evaluation

- Low Fault Coverage
- No Decoder Faults detected (Pass if all Addresses Map to a Single Cell)
- O(n) Complexity

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Checkerboard Tests

Step 1.

$$W(i, j) = 0 \quad \forall i+j = \text{even}$$

$$W(i, j) = 1 \quad \forall i+j = \text{odd}$$

Step 2.

$$R(i, j) = 0 \quad \forall i+j = \text{even}$$

$$R(i, j) = 1 \quad \forall i+j = \text{odd}$$

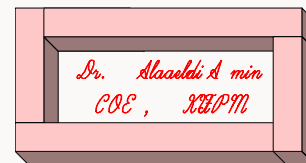
Step 3.

Repeat steps 1 & 2

Interchanging 0's and 1's.

0	1	0	1
1	0	1	0
0	1	0	1
1	0	1	0

1	0	1	0
0	1	0	1
1	0	1	0
0	1	0	1



Checkerboard Tests

Step 1.

$$W(i, j) = 0 \quad \forall i+j = \text{even}$$

$$W(i, j) = 1 \quad \forall i+j = \text{odd}$$

Step 2.

$$R(i, j) = 0 \quad \forall i+j = \text{even}$$

$$R(i, j) = 1 \quad \forall i+j = \text{odd}$$

Step 3.

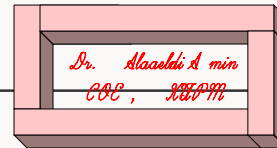
Repeat steps 1 & 2

Interchanging 0's and 1's.

Evaluation

- Low Deterministic Fault Coverage
- No Decoder Faults detected (Pass if all Addresses Map to a 4 Cells)
- O(n) Complexity

0	1
1	0



Marching Test

Step 1. Initialize

$W(i) = 0 \quad \forall i=0, n-1$

Step 2. For $i=0$ to $n-1$

{ $R(i) (=0)$;

$W(i) =1$;

$R(i) (=1)$ }

Step 3. For $i=n-1$ to 0

{ $R(i) (=1)$;

$W(i) =0$;

$R(i) (=0)$ }

Step 4. Repeat steps 1, 2, 3 Interchanging 0's and 1's.

{ $\uparrow (W0) \uparrow (R0, W1, R1) \downarrow$
 $(R1, W0, R0)$ }

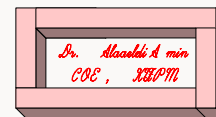
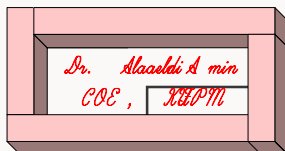
Evaluation

- Simple
- Moderate Fault Coverage
- Detects *All STUCK* Faults and *Decoder Faults*
- Does not detect all single coupling faults
- $O(n)$ Complexity

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Theorem: Detection of Address Decoder Faults

- A March test satisfying conditions 1 & 2 detects all address decoder faults.

Condition	March element
1	$\uparrow (rx, \dots, w \bar{x})$
2	$\downarrow (r \bar{x}, \dots, wx)$

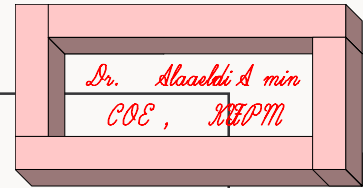
- ... Means any # of read or write operations
- wx element Must Precede condition 1

□ $x \in \{0, 1\}$

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Slide Number 32

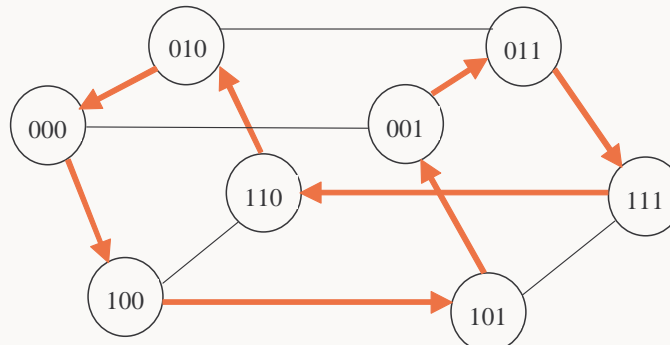


Testing For SNPSFs

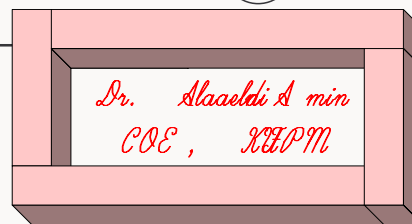
Fault Detection Condition

- Each Base Cell Must be Read in State 0 and State 1 for All Possible Patterns of its Deleted Neighborhood
- For a Neighborhood of Size k , There Are 2^k Static Neighborhood Patterns.
- To Minimize the Total Number of WRITE Cycles, a **Hamiltonian Sequence** is used (2^k Write Operations) {Remember that only 1Bit Can be Written at a Time}
- **Hamiltonian Sequence** Is a k -Bit Sequence Where Each Pattern Differs by 1-Bit From the Preceding One (Hamming Distance = 1)

**Hamiltonian
Tour for $k=3$**
Each Vertex
Visited once



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Testing For Active/Dynamic (ANPSFs)

Fault Detection Condition for ANPSFs

- Each Base Cell Must be Read in State 0 and State 1 for All Possible **Changes** in its Deleted Neighborhood.
- For a Neighborhood of Size k , $k2^k$ Patterns are Required {Every Vertex has k **adjacent** Vertices}.

Fault Detection Condition for PNPSFs

- Each Base Cell Must be Written and Read in State 0 and State 1 for All Possible Patterns of its Deleted Neighborhood.
- For a Neighborhood of Size k , There are 2^k Passive Neighborhood Patterns (PNPs).
- To Minimize The Number of Operations, ANPSFs and PNPSFs, Can be Tested Together Using an **Eulerian Sequence** ($k2^k$ Patterns).

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Testing For Active/Dynamic (ANPSFs)

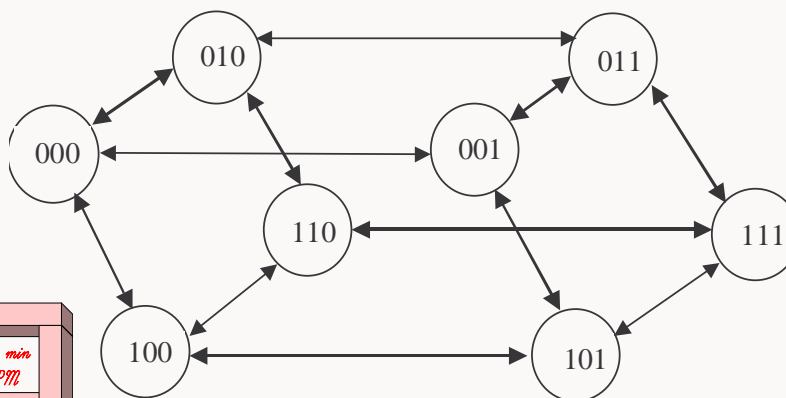
- A *k*-bit *Eulerian* Graph is Constructed with a Vertex for each *k*-Bit Pattern.
- Two Vertices are Connected iff their corresponding patterns differ by exactly one bit.
- When Two Vertices X, Y, are Connected, They are Connected by Exactly Two Directed Arcs
- An *Eulerian* Sequence is a Tour Through an *Eulerian* Graph Such that Each Directed Arc is Traversed Exactly Once.
- A *Hamiltonian* Sequence is a Tour Through an Eulerian Graph Such That Every Vertex is Visited Exactly Once.

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Slide Number 35

Testing For Active/Dynamic (ANPSFs)



3-Bit Eulerian Graph (k=3)

Every ARC in the Graph is Visited ONCE

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SNPSF Test Algorithm

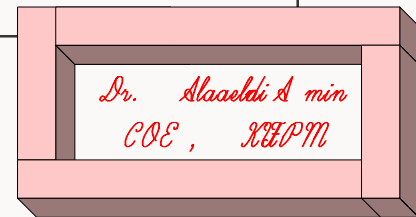
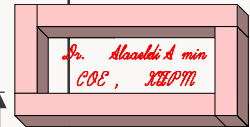
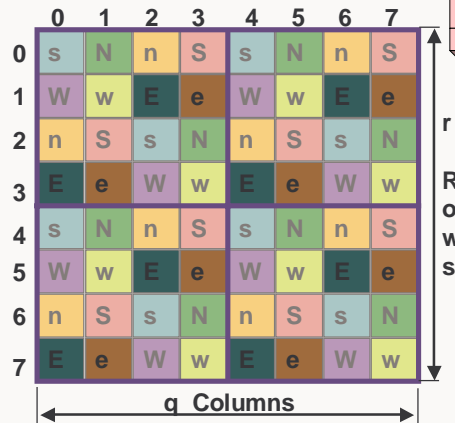
1. Initialize The Whole Array to 0's
(n writes)
2. Consider n,e,w,s as Base Cells & N,E,W,S as their deleted Neighborhood
3. Write into the Deleted Neighborhood Cells the 16 Possible Pattern Combinations, In the order given by a Hamiltonian Sequence (Final Pattern Will Be 0000). ($n/2 * 2^{k-1}$ Writes)
4. After Each New Pattern is Written into the Deleted Neighborhood, The State of the Base Cells is Verified by a A READ(0) Operation ($n/2 * 2^k$ Reads)
5. Write 1's into the Base Cells
 n,e,w,s ($n/2$ writes)

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Slide Number 37

Memory Array Tiling



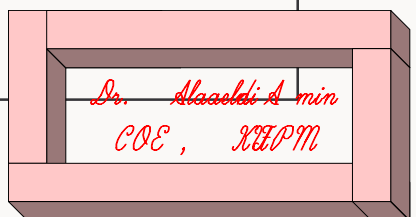
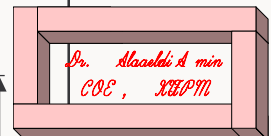
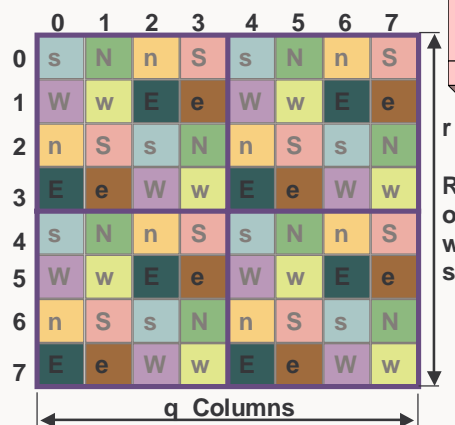
SNPSF Test Algorithm

6. Write into the Deleted Neighborhood Cells the 16 Possible Pattern Combinations, In the order given by a Hamiltonian Sequence (Final Pattern Will Be 0000). ($n/2 * 2^{k-1}$ Writes)
7. After Each New Pattern is Written into the Deleted Neighborhood, The State of the Base Cells is Verified by a A READ(1) Operation ($n/2 * 2^k$ Reads)
8. Repeat Steps 2-7 Considering N,E,W,S as Base Cells & n,e,w,s as their deleted Neighborhood
 - The Algorithms is $O(2^k n)$
 - To test For ANPSF's and PNPSF's, An Eulerian Sequence is Followed instead of the Hamiltonian Sequence. This Makes Algorithms $O(k2^k n)$

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Memory Array Tiling



RAMs with Built In Self Test (BIST)

BIST Logic Structure

1- Control Logic

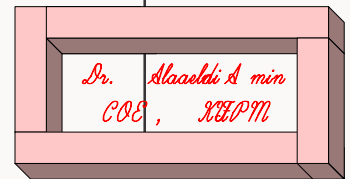
- ❖ Initiates, Stops, and Supervises The Test Sequence (Test Algorithm)

2- Address Generation Logic

- ❖ Generates Required Address Sequence

3- Data-Generation & Response-Verification Logic

4- Test Trigger Logic



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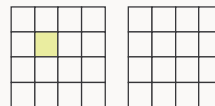
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Slide Number 39

BIST RAM Test Architectures

1- Single-Array Single-Bit (SASB)

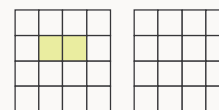
- ❖ A Single Bit in A Single Array of the RAM Chip is Tested at a Time



Single Array Single Bit (SASB)

2- Single-Array Multiple-Bit (SAMB)

- ❖ Multiple Bits (e.g. a Full Row) in A Single Array of the RAM Chip are Tested at a Time



Single Array Multiple Bit (SAMB)

3- Multiple-Array Single-Bit (MASB)

- ❖ Single Bits in Multiple Arrays of the RAM Chip are Tested at a Time



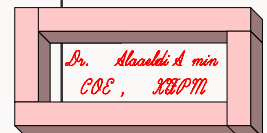
Multiple Array Single Bit (MASB)

4- Multiple-Array Multiple-Bit (MAMB)

- ❖ Multiple Bits (e.g. a Full Row) in Multiple Arrays of the RAM Chip are Tested at a Time



Multiple Array Multiple Bit (MAMB)



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