

# Speeding up Effect-Cause Defect Diagnosis using a Small Dictionary

# Outline

2

- Introduction
- Types of Defect Diagnostics Method
- Effect-Cause Defect Diagnosis
- Proposed Work
- Experimental Results

# Introduction

3

- With 90nm and smaller feature size designs, the dominant defect type has changed from the random particle defect to the *design-specific systematic defect*.
- High accuracy and throughput is needed to identify design-specific defects for a large number of dies within a short time.

# Types of Defect Diagnostic Methods

4

## ***1. Cause-Effect Diagnosis:***

- pre-computes and stores the faulty responses of modeled faults in a dictionary.
- The observed failure responses are compared with the pre-computed failure responses in the dictionary.
- The faults whose pre-computed failure responses have the closest match with the observed failure responses will be chosen as final candidates.

# Types of Defect Diagnostic Methods

5

## ***1. Cause-Effect Diagnosis:***

- Fast diagnosis but requires large memory
- Can reduce memory by using pass/fail dictionaries, but may lose diagnosis accuracy due to information loss.

# Types of Defect Diagnostic Methods

6

## **2. *Effect-Cause Diagnosis:***

- Only simulates the potential fault candidates obtained by back tracing from failing outputs.
- does not need a large memory to store pre-computed faulty responses, yet maintains a very high diagnosis accuracy.
- Very slow to diagnose a failing chip due to a large number of fault simulations used during diagnosis

# Effect-Cause Defect Diagnosis Procedure

7

There are two phases:

- **Phase 1:** a set of candidate fault sites are determined from the failing test patterns
- **Phase 2:** candidate sites are ranked by fault simulating the candidates using passing patterns

# Phase 1

8

- Each failing test pattern  $p$ , back tracing is used to find a set of faults  $Q$
- The faults in  $Q$  are simulated to find subset  $Q'$
- A minimum set covering algorithm is used to find a subset  $S$ , of minimum size, of the set of faults  $Q'$



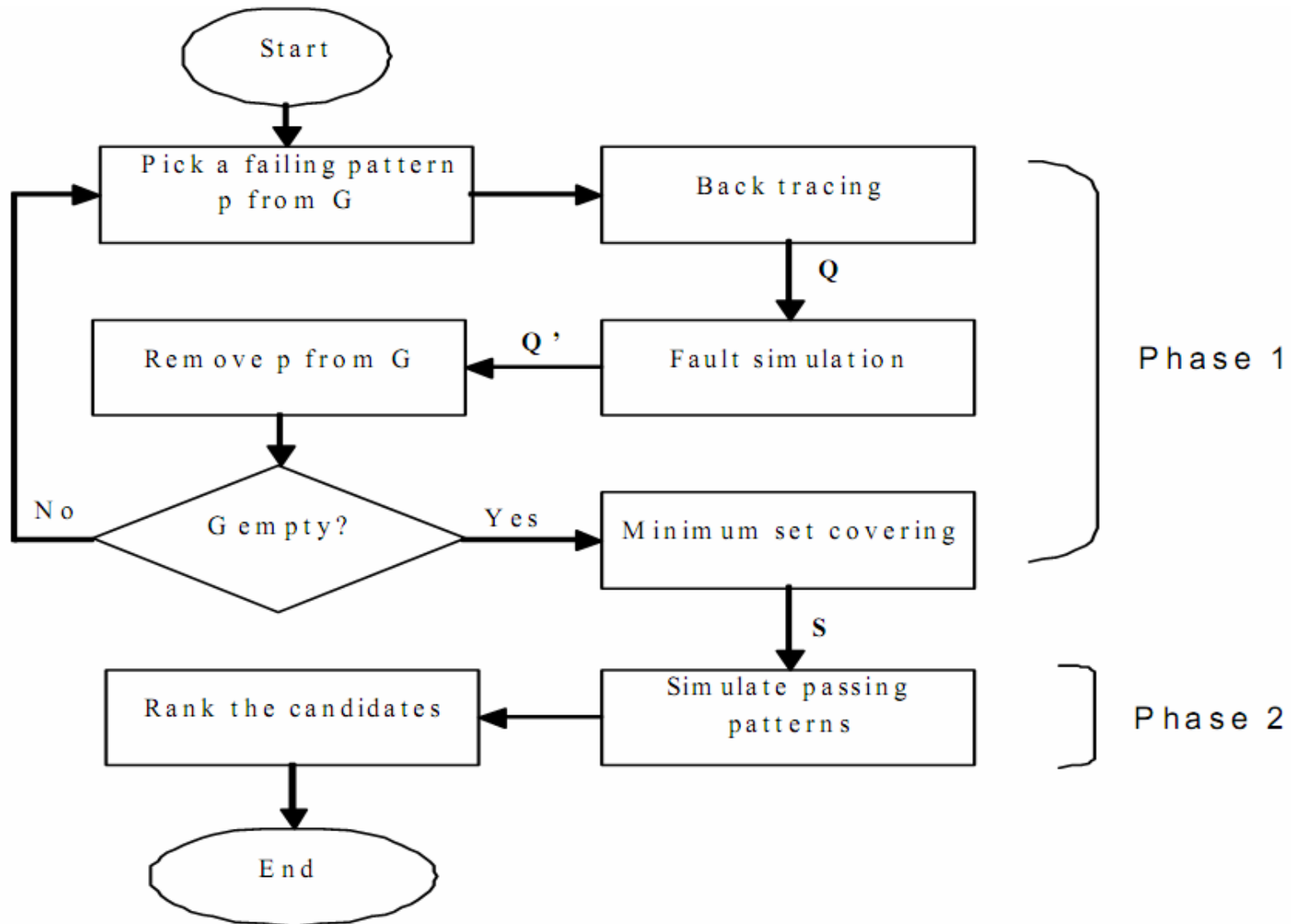
# Phase 2

9

- The fault candidates in  $S$  are simulated over all the passing patterns to find the number of passing pattern mismatches for each candidate.
- Pattern mismatch occurs whenever a candidate fault is detected by a passing pattern
- Candidates are ranked based on a score that is calculated from the number of passing and failing patterns matches or mismatches.

# Effect-Cause Defect Diagnosis Flow

10



# Problems of Effect-Cause Diagnosis

11

**There are two run time intensive steps:**

1. **Phase1:** back tracing and fault simulation time in the first phase for faults in  $Q$  to obtain the faults in  $Q'$ . Back tracing uses a version of CPT and identified faults trigger a large number of events during fault simulation
2. **Phase2:** simulating faults in  $S$  using all passing patterns

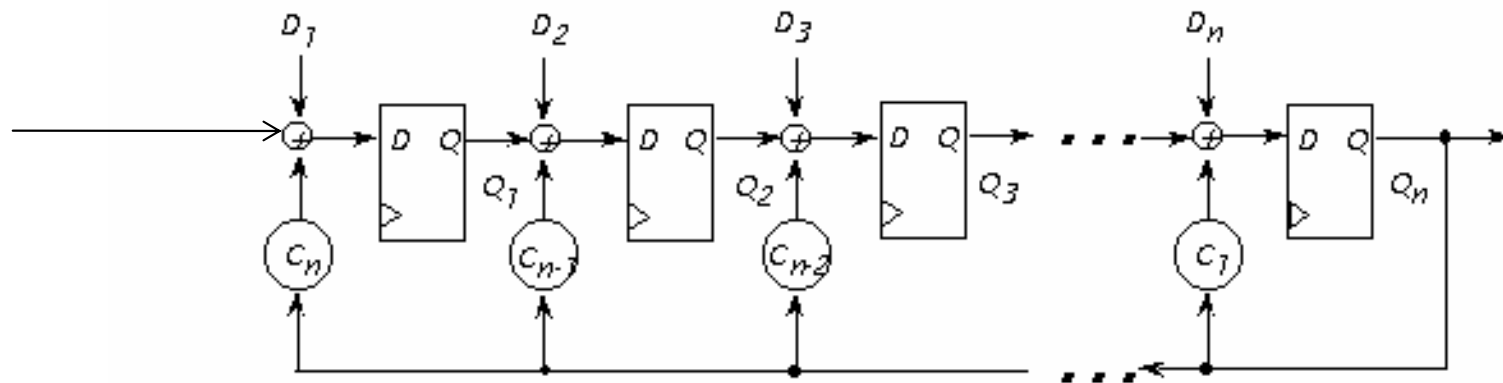
# The Proposed Method

12

- Combine dictionary based diagnosis with effect-cause diagnosis to speed-up diagnosis.
- use a dictionary of small size to determine an initial list of candidates that explain a failing pattern thus avoiding back tracing.

# Multiple Input Single Register (MISR)

13



# Creating the Small Dictionary

14

- The small dictionary is based on signatures  
→ it is like a hash table
- Signatures are computed using a MISR for each fault and test pattern that detects fault
- The identification of each output error is represented by a 32 bit integer and is fed to MISR
- Unique signatures are only stored for each fault
- MISR is 32-bits long with primitive polynomial  $1 + x + x^{29} + x^{31} + x^{32}$  and seed is set to 0's.

# Example

15

- Test Pattern:  $T = \{T1, T2, T3, T4\}$
- Fault  $f$  is detected by  $T1, T3, T4$
- $T1, T3$  is observed at output 3 and 15
- $T4$  is observed at output 7 and 10
- 3 and 15 is fed to MISR to get signature 0000000E
- 7 and 10 is fed to MISR to get signature 00000009
- Fault  $f$  in the dictionary now only has:  
    {0000000E, 00000009}

# Creating Dictionary continued...

16

- Also in the dictionary, each clock is assigned 1 bit to indicate whether it is associated with the scan cells where the effects of a fault are observed

- Size of dictionary:

$$= 32 \cdot U \cdot F + F \cdot C$$

where,

F: the number of faults

U: average number of unique signatures

C: number of clocks in the circuit



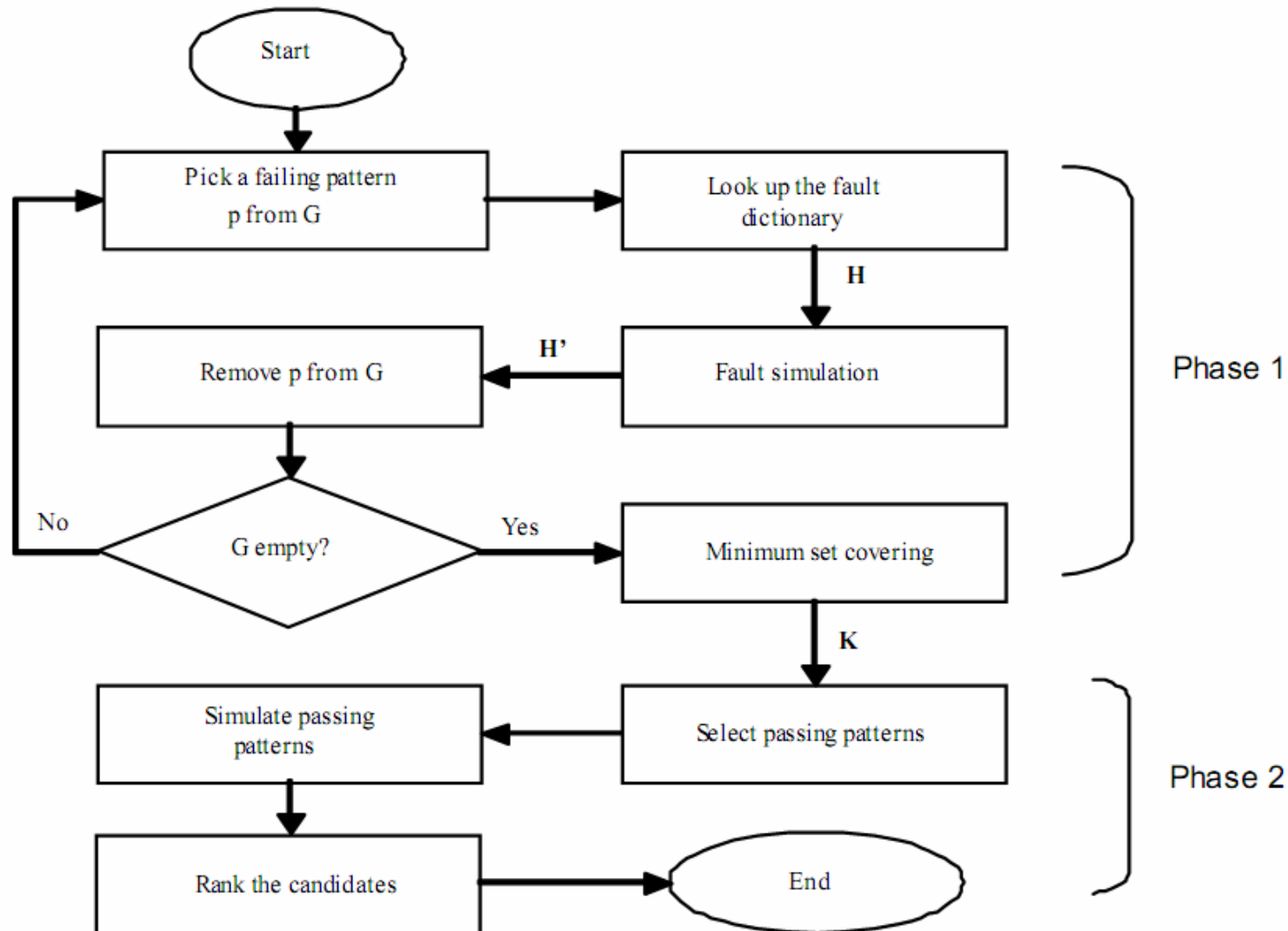
# Speeding Up the Effect-Cause Diagnosis

17

- Obtain the initial list of candidate faults using the small dictionary instead of back tracing.
  1. For each failing pattern  $\mathbf{p}$ , compress the failure data with a 32 bit MISR to get a compressed signature  $\mathbf{R}$
  2. Search the dictionary we created to find a set  $\mathbf{H}$  of candidates whose unique compressed signatures contain  $\mathbf{R}$ .
  3.  $\mathbf{H}$  is then simulated to get a subset of candidates  $\mathbf{H}'$  which is equal to  $\mathbf{Q}'$

# Speeding Up the Effect-Cause Diagnosis

18



# Reasons for Speed-Up

19

1. Backward path tracing is not used to determine the initial set of candidates
2. The numbers of events triggered by the faults in the initial set of candidates  $H$  is typically much smaller than that in the initial set of candidates  $Q$  obtained in the standard diagnosis procedures

# Experimental Results

20

- The size of the proposed dictionary is considerably smaller than of a pass/fail dictionary

Design	Ckt1	Ckt2	Ckt3	Ckt4
#gates	313K	506K	2025K	5.3M
#faults	631K	1210K	4172K	8701K
#patterns	5000	6951	1000	1000
#clks	11	36	30	5
#aus	17.6	14.0	10.0	17.0
#pfd	394M	1052M	522M	1100M
#sd	45M	73M	123M	600M

- #aus: average number of unique signatures
- #pfd: size of pass/fail dictionary
- #sd: size of the proposed dictionary

# Experimental Results

21

Circuit	Ckt1	Ckt 2	Ckt 3	Ckt 4
AVG Q	134	51	210	794
AVG H	197	141	154	219
AVG Q/AVG H	0.68	0.36	1.36	3.6
EVE Q	2046.4K	380K	72.4M	2680M
EVE H	45.6k	48K	143K	1.1M
EVE Q/EVE H	45	7.9	506	2436
AVE SF	10.5	2.6	24	211
AVE SP	6.3	8.9	1	1
AVE	8	7.8	9.6	48
Median	6.6	4.4	7.9	31

- AVG Q: average number of faults in Q for all test vectors
- AVG H: average number of faults in H for all test vectors
- EVE Q: average number of events triggered by faults in Q
- EVE H: average number of events triggered by faults in H
- AVE SF: average speed-up of phase 1
- AVE SP: average speed-up of phase 2
- AVE: average speed-up factor of the complete diagnostic procedure

**QUESTIONS?**