
COE 561
**Digital System Design &
Synthesis**
Library Binding

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[Adapted from slides of Prof. G. De Micheli: Synthesis & Optimization of Digital Circuits]

Outline

- Modeling and problem analysis
- Rule-based systems for library binding
- Heuristic Algorithms for library binding
- Decomposition and partitioning
- Structural matching/covering
- Tree-based matching
- Tree-based covering
- Boolean matching/covering

Library Binding

- **Given an unbound logic network and a set of library cells**
 - Transform into an interconnection of instances of library cells.
 - Optimize area, (under delay constraints.)
 - Optimize delay, (under area constraints.)
 - Optimize power, (under delay constraints.)
- **Called also *technology mapping***
 - Method used for re-designing circuits in different technologies.

Library Models

- **A cell library is a set of primitive gates including combinational, sequential, and interface elements.**
- **Each cell is characterized by**
 - Its function.
 - Input/output terminals.
 - Area, delay, capacitive load.
- **Combinational elements**
 - Single-output functions: e.g. AND, OR, NAND, NOR, INV, XOR, XNOR, AOI.
 - Compound cells: e.g. adders, encoders.
- **Sequential elements**
 - Flip-flops, registers, counters.
- **Miscellaneous**
 - Tri-state drivers.
 - Schmitt triggers.

Major Approaches

■ Rule-based systems

- Mimic designer activity.
- Handle all types of cells including multiple-output, sequential and interface elements.
- Requires creation and maintenance of set or rules.
- Slower execution.

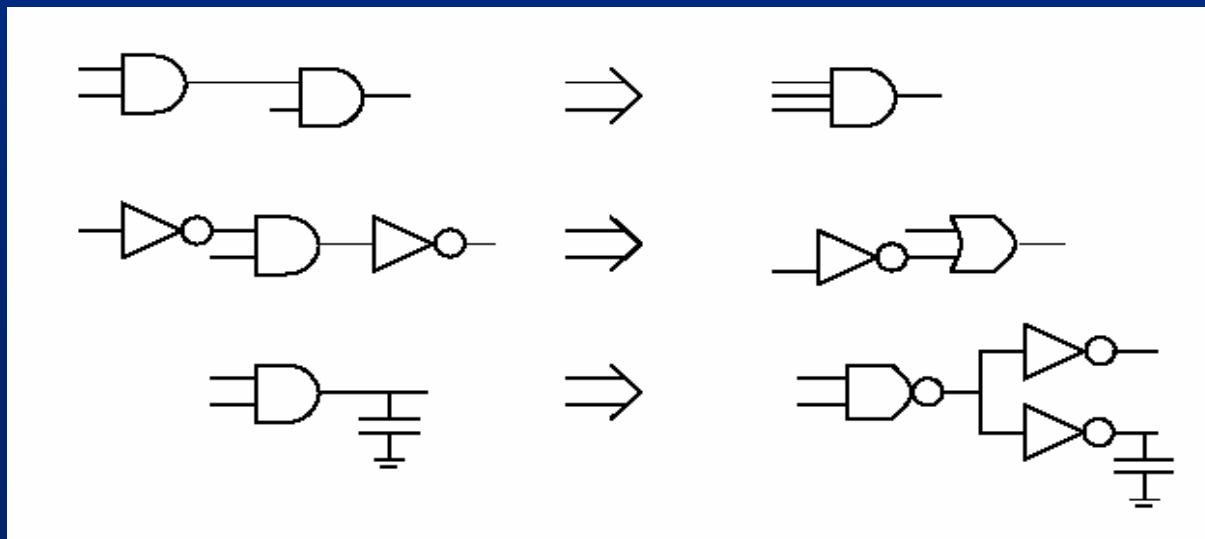
■ Heuristic algorithms

- Restricted to single-output combinational cells.
- Implementation of registers, input/output circuits and drivers straightforward.

■ Most tools use a combination of both.

Rule-Based Library Binding

- Binding by stepwise transformations.
- Data-base
 - Set of patterns associated with best implementation.
- Rules
 - Select subnetwork to be mapped.
 - Handle high-fanout problems, buffering, etc.



Rule-Based Library Binding

- Execution of rules follows a priority scheme.
- Search for a sequence of transformations.
- A greedy search is a sequence of rules each decreasing cost.
- Search space
 - Breadth (options at each step).
 - Depth (look-ahead).
- Meta-rules determine dynamically breadth and depth.
- Advantages
 - Applicable to all kinds of libraries.
- Disadvantages
 - Large rule data-base
 - Completeness issue.
 - Data-base updates.

Algorithms for Library Binding

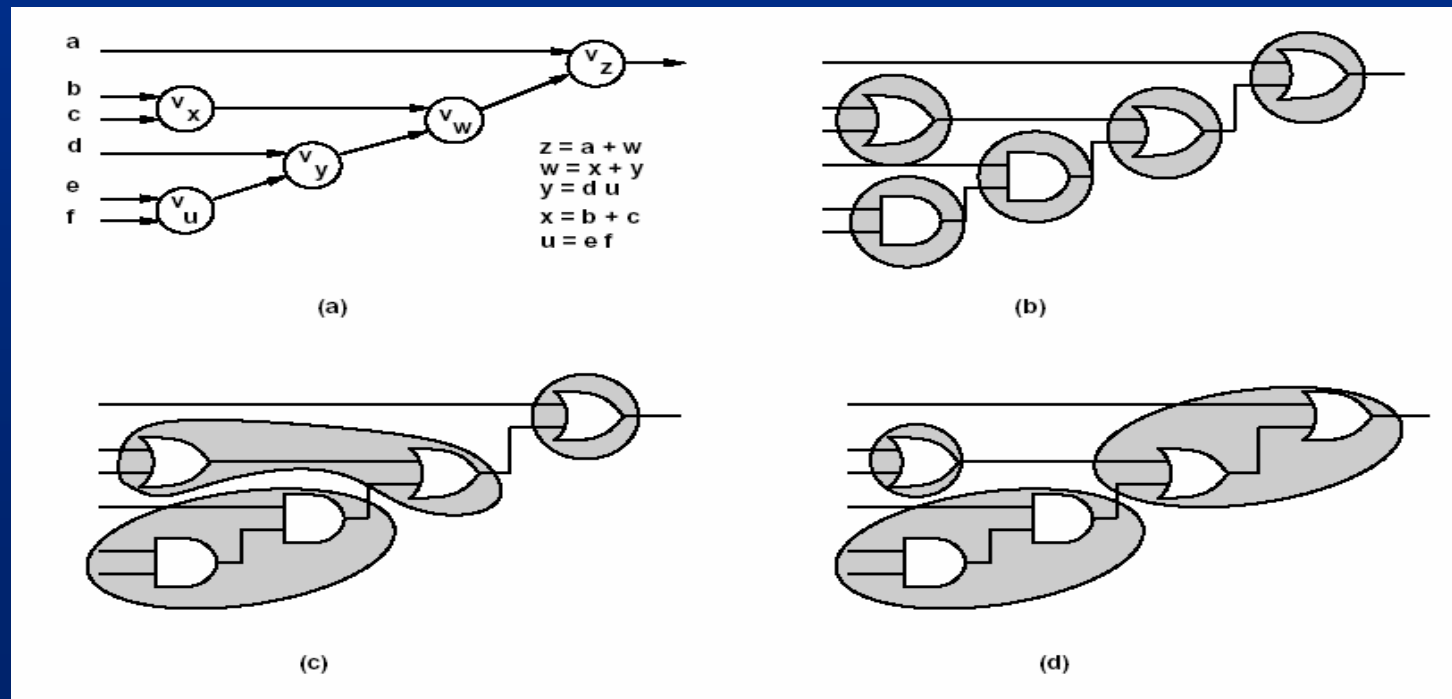
- **Mainly for single-output combinational cells.**
- **Fast and efficient**
 - Quality comparable to rule-based systems.
- **Library description/update is simple**
 - Each cell modeled by its function or equivalent pattern.
- **Involves two steps**
 - **Matching**
 - A cell matches a subnetwork if their terminal behavior is the same.
 - Input-variable assignment problem.
 - **Covering**
 - A cover of an unbound network is a partition into subnetworks which can be replaced by library cells.

Matching


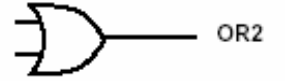

- Given two single-output combinational functions $f(x)$ and $g(x)$ with same number of support variables.
- f matches g if there exists a permutation P such that $f(x) = g(P x)$.
- **Example**
 - $f = ab + c$; $g = p + qr$.
 - By assigning $\{q, r, p\}$ to $\{a, b, c\}$, f is equal to g .
 - f and g have a **Boolean match**.
 - By representing functions f and g by their AND-OR decomposition graphs, f and g have a **structural match** since their graphs are *isomorphic*.
- Must ensure that vertices bound to inputs of a matched cell are outputs of other matched cells.

Assumptions

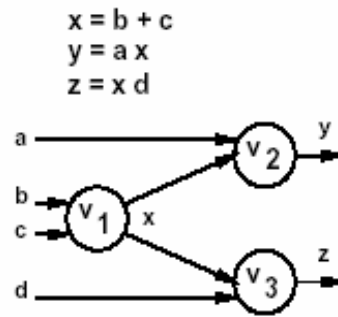
- **Network granularity is fine.**
 - Decomposition into base functions: 2-input NAND, NOR, INV.
- **Trivial binding**
 - Replacement of each vertex by base cell.



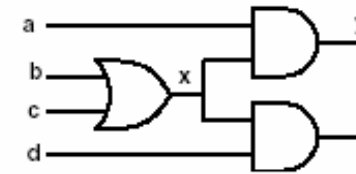
Example ...

Library		Cost
	AND2	4
	OR2	4
	OA21	5

(a)

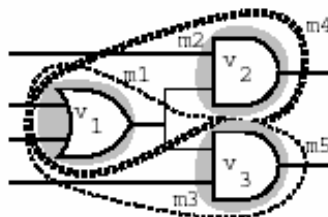


(b)

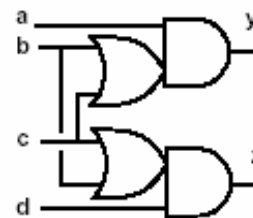


(c)

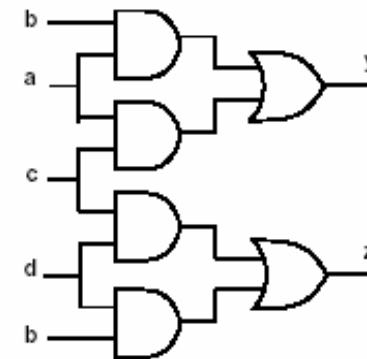
- m1: {v1,OR2}
- m2: {v2,AND2}
- m3: {v3,AND2}
- m4: {v1,v2,OA21}
- m5: {v1,v3,OA21}



(d)



(e)



(f)

... Example

Vertex covering

- Covering v_1 : $(m_1 + m_4 + m_5)$.
- Covering v_2 : $(m_2 + m_4)$.
- Covering v_3 : $(m_3 + m_5)$.

Input compatibility

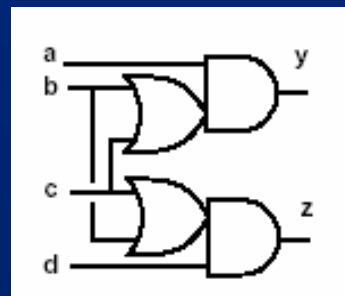
- Match m_2 requires m_1 : $(m_2' + m_1)$.
- Match m_3 requires m_1 : $(m_3' + m_1)$.

Overall binate clause

- $(m_1 + m_4 + m_5)(m_2 + m_4)(m_3 + m_5)(m_2' + m_1)(m_3' + m_1) = 1$

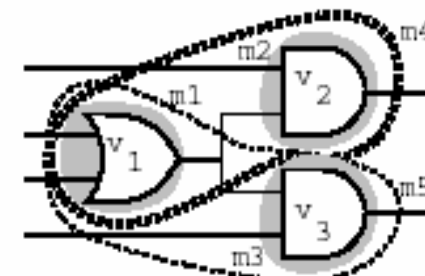
Optimum solution: $m_1' m_2' m_3' m_4 m_5$

- Cost=10



Library		Cost
	AND2	4
	OR2	4
	OA21	5

$m_1: \{v_1, OR2\}$
 $m_2: \{v_2, AND2\}$
 $m_3: \{v_3, AND2\}$
 $m_4: \{v_1, v_2, OA21\}$
 $m_5: \{v_1, v_3, OA21\}$



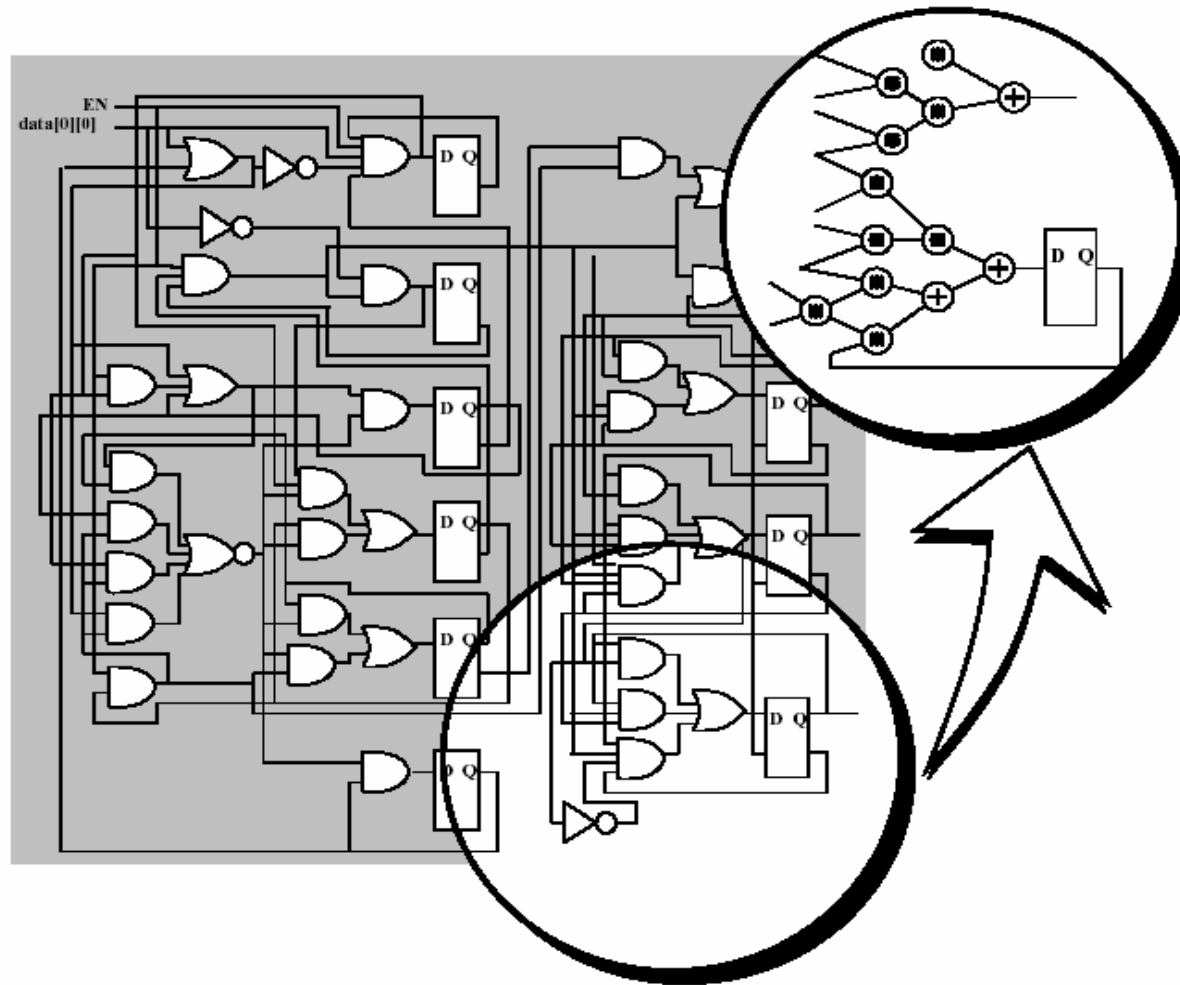
Heuristic Algorithms

- To render covering problem tractable, network is decomposed and partitioned.
- **Decomposition**
 - Cast network and library in standard form.
 - Decompose into base functions.
 - Example: NAND2 and INV.
 - Guarantees that each vertex is covered by at least one match.
- **Partitioning**
 - Break network into cones called *subject graphs*.
 - Reduce to many multi-input single-output subnetworks.
- **Covering**
 - Cover each subnetwork by library cells.

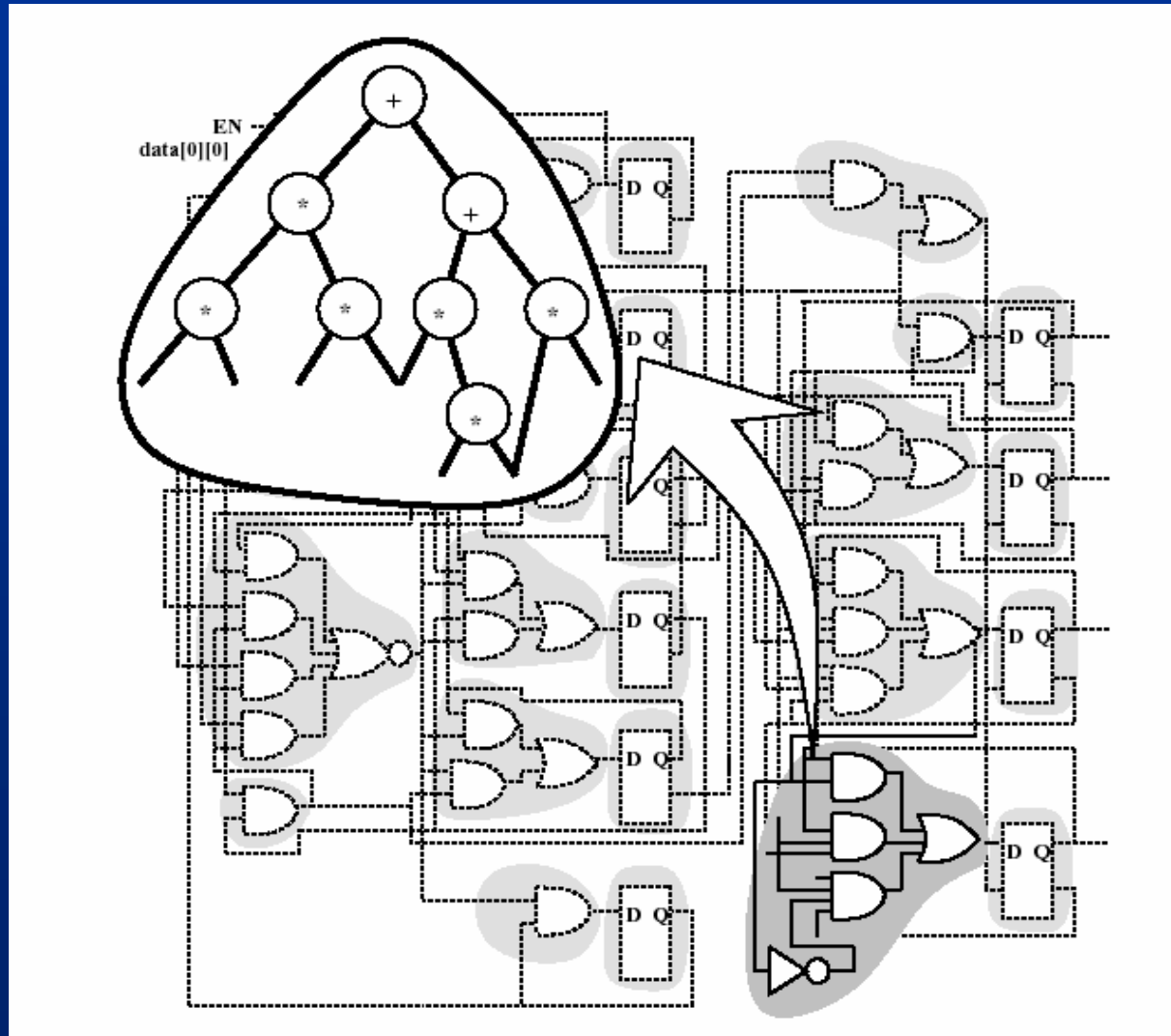
Partitioning

- **Rationale for partitioning**
 - Size of each covering problem is smaller.
 - Covering problem becomes tractable.
- **Used to isolate combinational portions from sequential elements and I/Os.**
- **Partitioning of combinational circuits**
 - Mark vertices with multiple fanout.
 - Edges whose tails are marked vertices define partition boundary.

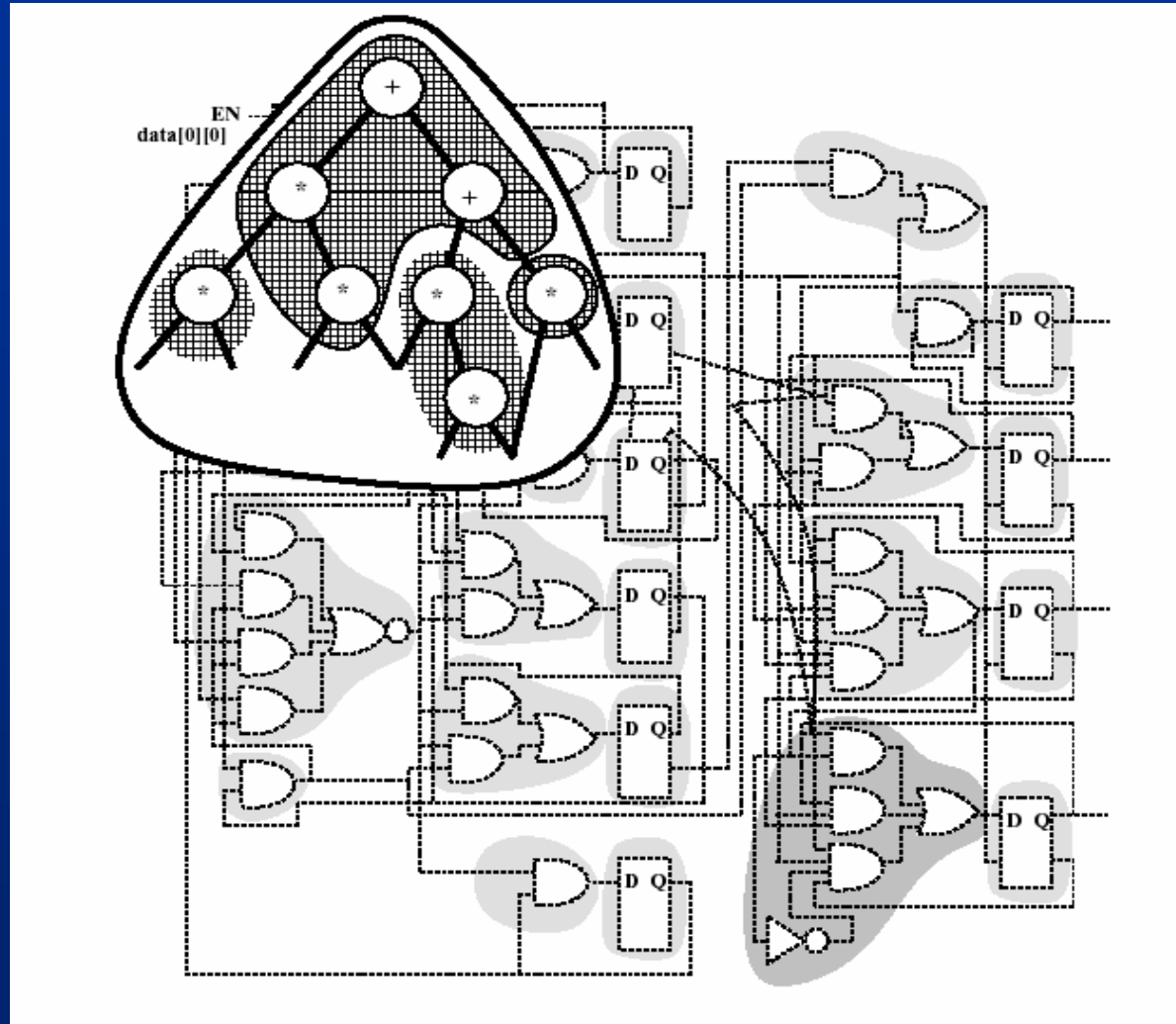
Decomposition



Partitioning



Covering



Matching

■ Structural matching

- Model functions by patterns.
 - Example: trees, dags (**fanout only at the inputs**).
- Both subject graph and library cells cast into comparable form (subject and pattern graphs).
- Rely on pattern matching techniques.
- Some library cells may have more than one pattern graph.

■ Boolean matching

- Use Boolean models.
- Solve *tautology* problem to check equivalence of two functions.
- More powerful.

Boolean versus Structural Matching

■ Example

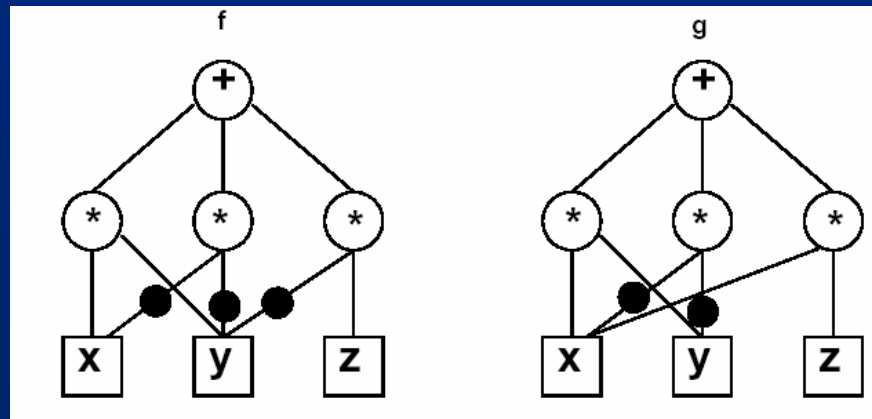
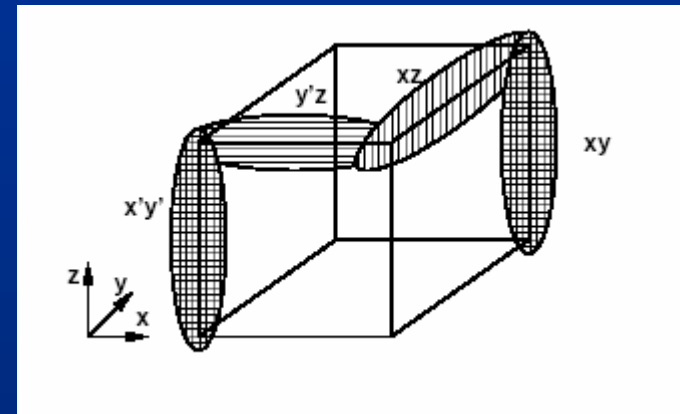
- $f = xy + x'y' + y'z$
- $g = xy + x'y' + xz$

■ Function equality is a tautology

- Boolean match.

■ Patterns are different

- No structural match.



Structural Matching and Covering

■ Expression patterns

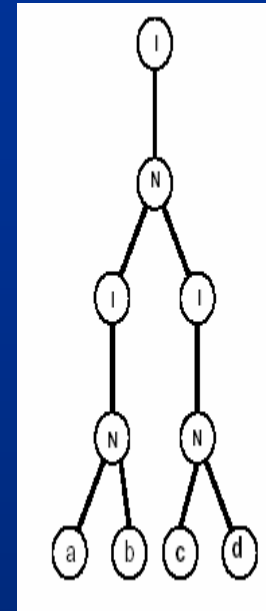
- Represented by dags using a decomposition of 2-inp NAND and INV.

■ Identify pattern dags in network

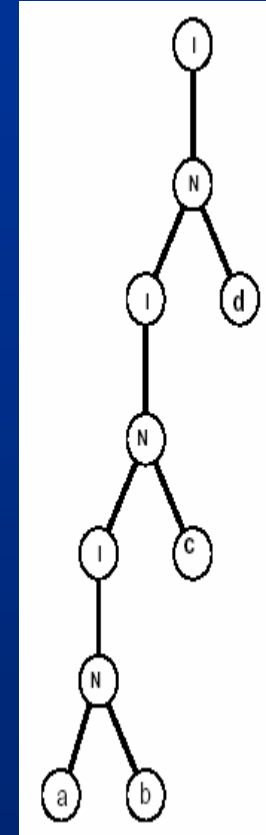
- Matching by sub-graph isomorphism.

■ Simplification

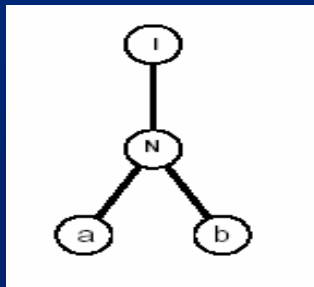
- Use tree patterns.
- Most library cells can be represented as trees.
- Tree matching & tree covering is linear.



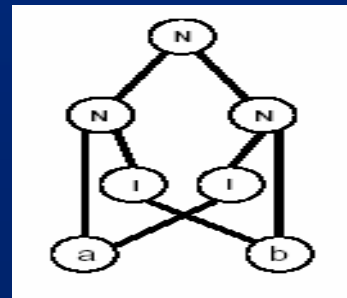
$$F = a b c d$$



$$F = a b c d$$



$$F = a b$$



$$F = a \oplus b$$

Tree-Based Matching ...

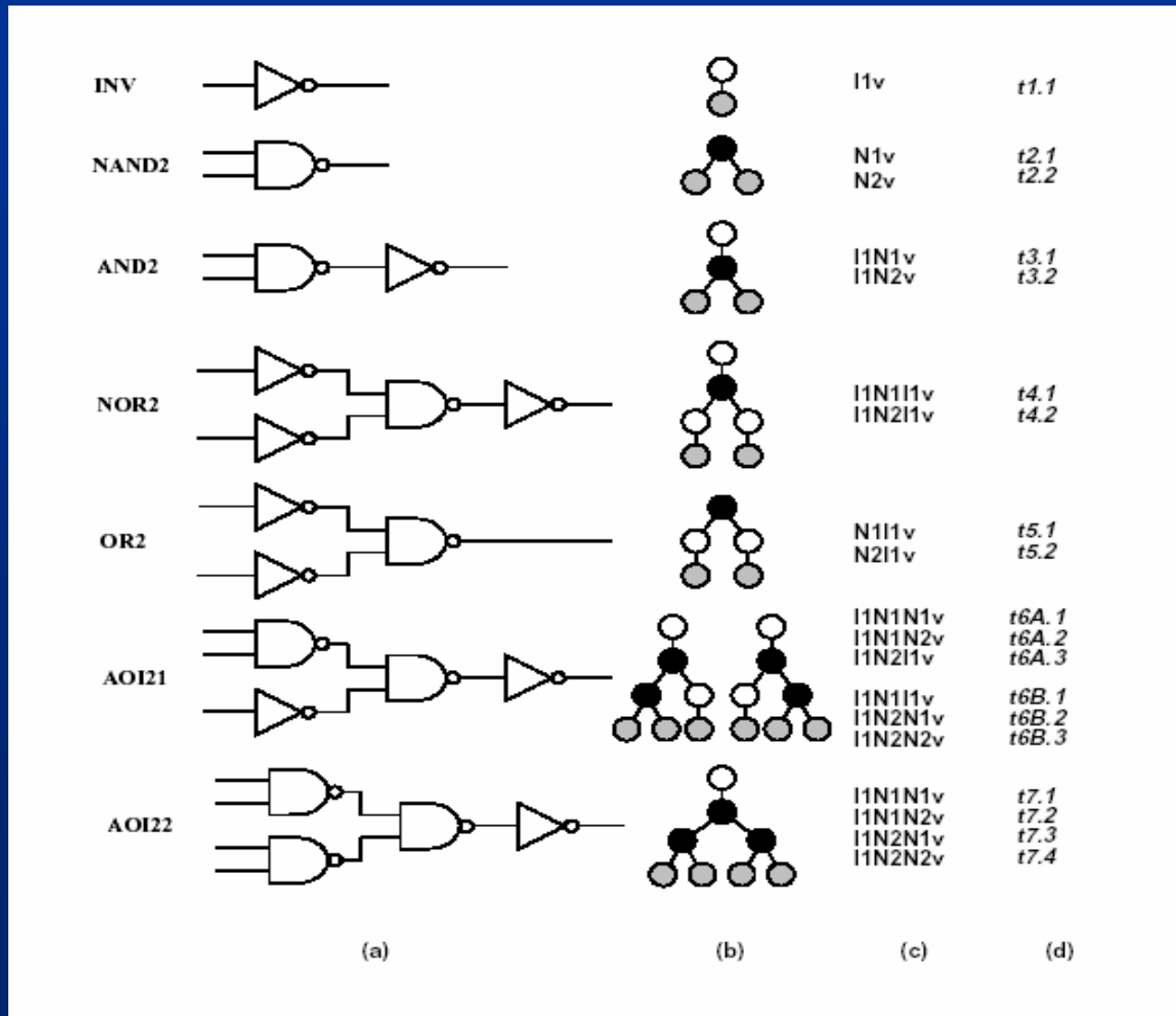
■ Network

- Partitioned and decomposed
 - NOR2 (or NAND2) + INV.
 - Generic base functions.
- Each partition called Subject tree.

■ Library

- Represented by trees.
- Possibly more than one tree per cell.
- Pattern recognition
 - Simple binary tree match.
 - Aho-Corasick automaton.

Simple Library



... Tree-Based Matching

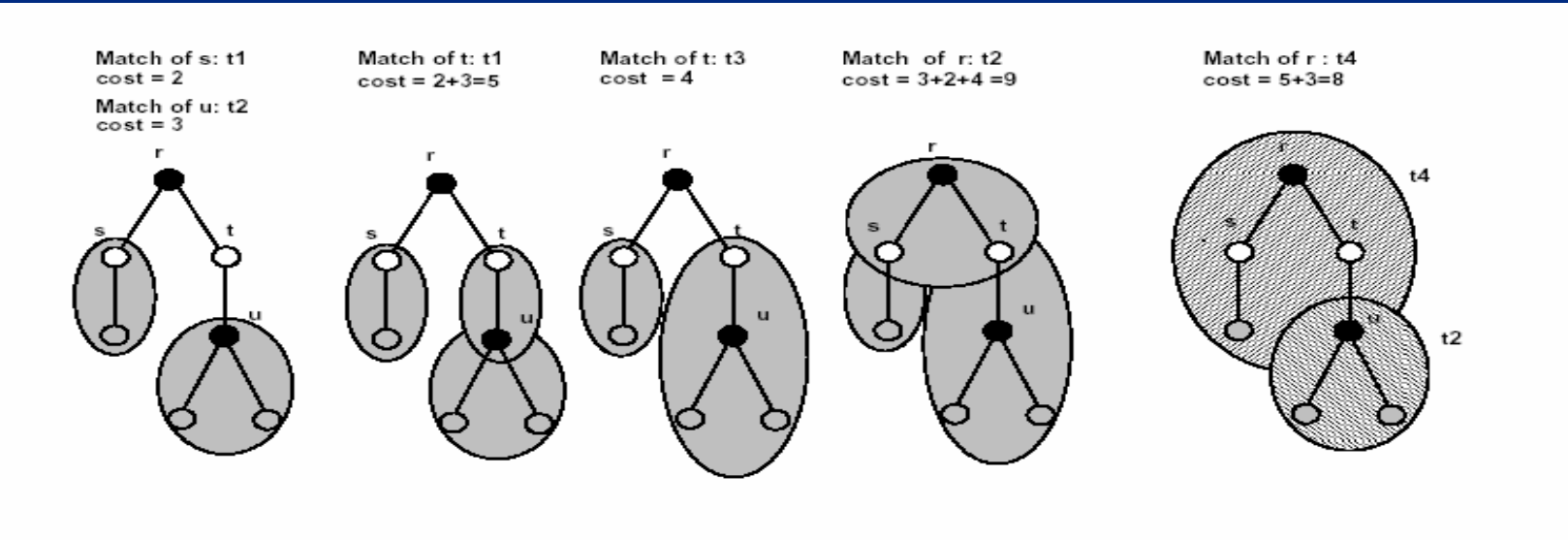
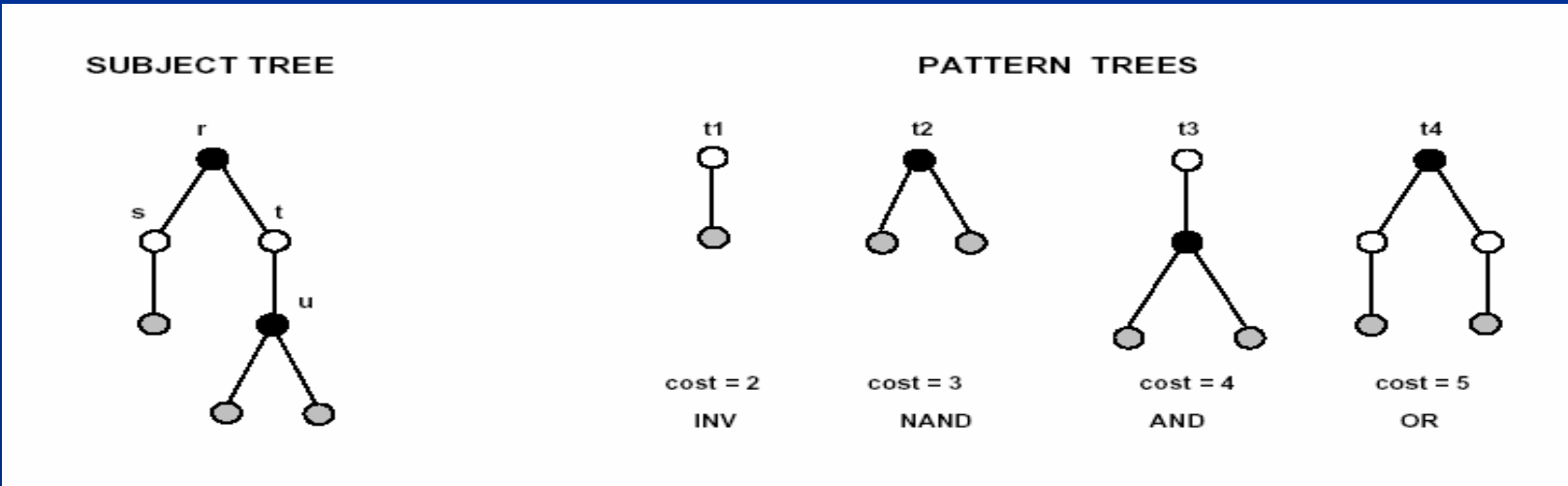
```
MATCH(u, v) {  
    if (u is a leaf) return (TRUE);           /* Leaf of the pattern graph reached */  
    else {  
        if (v is a leaf) return (FALSE);     /* Leaf of the subject graph reached */  
        if (degree(v) ≠ degree(u)) return(FALSE); /* Degree mismatch */  
        if (degree(v) == 1) {                /* One child each: visit subtree recursively */  
            uc = child of u ; vc = child of v ;  
            return (match(uc, vc) )  
        }  
        else {                                 /* Two children each: visit subtrees recursively */  
            ul = left-child of u ; ur = right-child of u ;  
            vl = left-child of v ; vr = right-child of v ;  
            return (MATCH(ul, vl) · MATCH(ur, vr) + MATCH(ur, vl) · MATCH(ul, vr));  
        }  
    }  
}
```

Tree-Based Covering

- **Dynamic programming**
 - Visit subject tree bottom-up.
- **At each vertex attempt to match**
 - Locally rooted subtree.
 - Check all library cells for a match.
- **Optimum solution for the subtree.**

```
TREE_COVER(T(V, E)) {  
    Set the cost of the internal vertices to -1;  
    Set the cost of the leaf vertices to 0;  
    while (some vertex has negative weight) do {  
        Select a vertex  $v \in V$  whose children have all nonnegative cost;  
         $M$  = set of all matching pattern trees at vertex  $v$ ;  
         $\text{cost}(v) = \min_{m \in M(v)} (\text{cost}(m) + \sum_{u \in L(m)} \text{cost}(u) )$ ;  
    }  
}
```


Example



Minimum Area Cover Example

- **Minimum-area cover.**
- **Area costs**
 - INV:2; NAND2:3;
AND2:4; AOI21:6.
- **Best choice**
 - AOI21 fed by a NAND2 gate.

Network	Subject graph	Vertex	Match	Gate	Cost
		X	t2	NAND2(b,c)	3
		y	t1	INV(a)	2
		Z	t2	NAND2(x,d)	$2 * 3 = 6$
		W	t2	NAND2(y,z)	$3 * 3 + 2 = 11$
		0	t1	INV(w)	$3 * 3 + 2 * 2 = 13$
			t3	AND2(y,z)	$2 * 3 + 4 + 2 = 12$
			t6B	AOI21(x,d,a)	$3 + 6 = 9$

Minimum Delay Cover

- **Dynamic programming approach.**
- **Cost related to gate delay.**
- **Delay modeling**
 - Constant gate delay: straightforward.
 - Load-dependent delay
 - Load fanout unknown.
- **Minimum delay cover with constant delays**
 - The cell tree is isomorphic to a subtree with leaves L .
 - The vertex is labeled with the cell cost plus the **maximum** of the labels of L .

Minimum Delay Cover Example

- Inputs data-ready times are 0 except for $t_d = 6$
- Constant delays
 - **INV:2; NAND2:4; AND2:5; AOI21:10.**
- Compute data-ready times bottom-up
 - $t_x = 4; t_y = 2; t_z = 10; t_w = 14.$
- Best choice
 - **AND2, two NAND2 and an INV gate.**

Network	Subject graph	Vertex	Match	Gate	Cost
		x	t_2	NAND2(b,c)	4
		y	t_1	INV(a)	2
		z	t_2	NAND2(x,d)	$6 + 4 = 10$
		w	t_2	NAND2(y,z)	$10 + 4 = 14$
		o	t_1	INV(w)	$14 + 2 = 16$
			t_3	AND2(y,z)	$10 + 5 = 15$
			t_{6B}	AOI21(x,d,a)	$10 + 6 = 16$

Minimum Delay Cover Load-Dependent Delays

■ Model

- For most libraries, input capacitances are a finite small set.
- Label each vertex with all possible load values.

■ Dynamic programming approach

- Compute an array of solutions for each vertex corresponding to different loads.
- For each match, arrival time is computed for each load value.
- For each input to a matching cell the best match for the given load is selected.

■ Optimum solution, when all possible loads are considered.

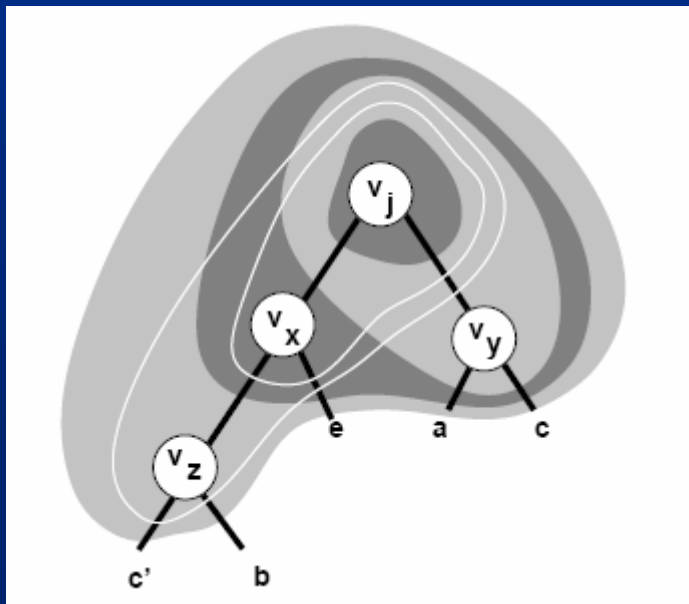
Example

- **Inputs data-ready times are 0 except for $t_d = 6$**
- **Load-dependent delays**
 - INV: $1+l$; NAND2: $3+l$;
AND2: $4+l$; AOI21: $9+l$;
SINV: $1+0.5l$.
- **Loads**
 - INV: 1; NAND2: 1;
AND2: 1; AOI21: 1;
SINV: 2.
- **Assume output load is 1**
 - Same solution as before.
- **Assume output load is 5**
 - Solution uses SINV cell.

Network	Subject graph	Vertex	Match	Gate	Cost				
					Load=1	Load=2	Load=5		
		X	t_2	NAND2(b,c)	4	5	8		
		y	t_1	INV(a)	2	3	6		
		Z	t_2	NAND2(x,d)	10	11	14		
		W	t_2	NAND2(y,z)	14	15	18		
		0	t_1	INV(w)			20		
			t_3	AND2(y,z)			19		
			t_6B	AOI21(x,d,a)			20		
						SINV(w)			18.5

Boolean Matching/Covering

- Decompose network into base functions.
- When considering vertex v_j
 - Construct clusters by local elimination.
 - Several functions associated with v_j .
- Limit size and depth of clusters.



$$\begin{aligned} j &= x y; & x &= e + z; \\ y &= a + c; & z &= c' + b; \end{aligned}$$

$$\begin{aligned} f_{j,1} &= x y; \\ f_{j,2} &= x (a + c); \\ f_{j,3} &= (e + z) y; \\ f_{j,4} &= (e + z) (a + c) \\ f_{j,5} &= (e + c' + b) y; \\ f_{j,6} &= (e + c' + b) (a + c); \end{aligned}$$

Boolean Matching: P-Equivalence

- Cluster function $f(x)$: sub-network behavior.
- Pattern function $g(y)$: cell behavior.
- **P-equivalence**
 - Exists a permutation operator P , such that $f(x) = g(P x)$ is a tautology?
- **Approaches**
 - Tautology check over all input permutations.
 - Multi-rooted pattern ROBDD capturing all permutations.

Signatures and Filters ...

- **Drastically reduce the number of permutations to be considered.**
- **Capture some properties of Boolean functions.**
- **If signatures do not match, there is no match.**
- **Used as filters to reduce computation.**
- **Signatures**
 - **Unateness.**
 - **Symmetries.**
- **Any pin assignment must associate**
 - **unate (binate) variables in $f(x)$ with unate (binate) variables in $g(y)$.**
- **Variables or groups of variables**
 - **that are interchangeable in $f(x)$ must be interchangeable in $g(y)$.**

... Signatures and Filters ...

- Cluster and pattern functions must have the same number of unate and binate variables to match.
- If there are b binate variables, an upper bound on number of variable permutations is $b! (n-b)!$
 - (instead of $n!$)
- **Example**
 - $g = s_1 s_2 a + s_1 s_2' b + s_1' s_3 c + s_1' s_3' d.$
 - $n=7$ variables; 4 unate and 3 binate.
 - Only $3! 4! = 144$ variable orders and corresponding OBDDs. need to be considered in worst case.
 - Compare this with overall number of permutations
 - $7!=5040$

... Signatures and Filters ...

- A **symmetry set** is a set of variables that are pairwise interchangeable.
- A **symmetry class** is an ensemble of symmetry sets with the same cardinality.
- A **symmetry class** C_i has symmetry sets with cardinality i .
- A necessary condition for two functions to match is having symmetry classes of the same cardinality for each i .
- **Example**
 - $F = x_1 x_2 x_3 + x_4 x_5 + x_6 x_7$
 - Symmetry sets: (x_1, x_2, x_3) , (x_4, x_5) , (x_6, x_7)
 - $C_2 = \{(x_4, x_5), (x_6, x_7)\}$; $|C_2|=2$
 - $C_3 = \{(x_1, x_2, x_3)\}$; $|C_3|=1$

... Signatures and Filters ...

- **Symmetry classes can be used to determine non-redundant variable orders**
 - All variables in a given symmetry set are equivalent.
 - Number of permutations required is $\prod_{i=1 \text{ to } n} (|C_i|!)$.
- **Example**
 - $F = x_1 x_2 x_3 + x_4 x_5 + x_6 x_7$
 - Number of permutations = $2! = 2$ variable orders.
 - $(x_1, x_2, x_3, x_4, x_5, x_6, x_7)$
 - $(x_1, x_2, x_3, x_6, x_7, x_4, x_5)$
- **Cluster function: $f = abc$.**
 - Symmetries: $\{(a, b, c)\} - 3$ unate.
- **Pattern functions**
 - $g_1 = a+b+c$
 - Symmetries: $\{(a, b, c)\} - 3$ unate.
 - $g_2 = ab+c$
 - Symmetries: $\{(a, b) (c)\} -- 3$ unate.
 - $g_3 = abc + a'b'c'$
 - Symmetries: $\{(a, b, c)\} -- 3$ binate.

... Signatures and Filters

- Taking advantage of both symmetric classes and unate-binate properties

$$\text{Let } C_i = C_i^b + C_i^u$$

$$|C_i| = |C_i^b| + |C_i^u|$$

- Number of non-redundant permutations

$$\prod_{i=1}^n |C_i^b|! * |C_i^u|!$$