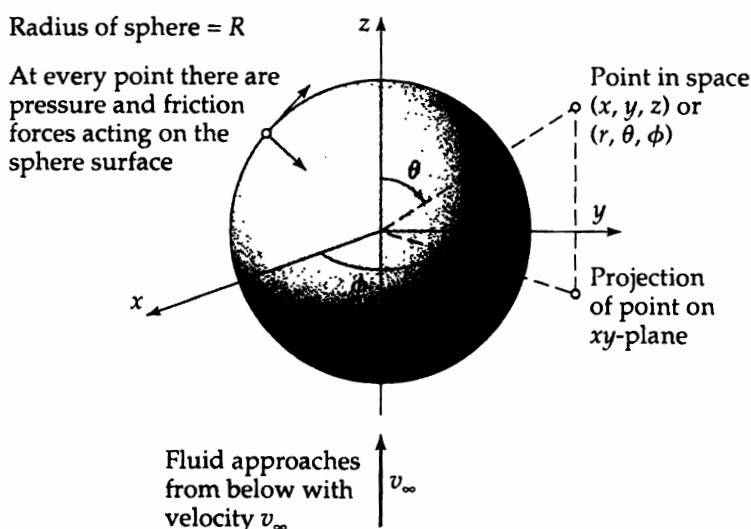


Example: Creeping Flow around A Sphere

Use Table 4.2-1 to set up the differential equation for the stream function for the flow of a Newtonian fluid around a stationary sphere of radius R at $Re \ll 1$. Obtain the velocity and pressure distributions when the fluid approaches the sphere in the positive z direction, as in Fig. 2.6-1.

Solution:

In this problem we consider the flow of an incompressible fluid about a solid sphere of radius R . The fluid approaches the fixed sphere vertically upwards in the z -direction with a uniform velocity v_∞ . The flow considered here is "creeping flow" means that the Reynolds number $Re = \frac{\rho v_\infty D}{\mu} < 0.1$.

For the flow considered here we have two velocity component close to the sphere:

v_r and v_θ . $v_\phi = 0$, moreover, the flow is axisymmetric i.e. independent of ϕ .

For creeping flow (laminar flow, Stokes flow) the ^{of table 4.2-1} L.H.S. of Equation D \uparrow cancels out and hence

$$E^4 \psi = 0$$

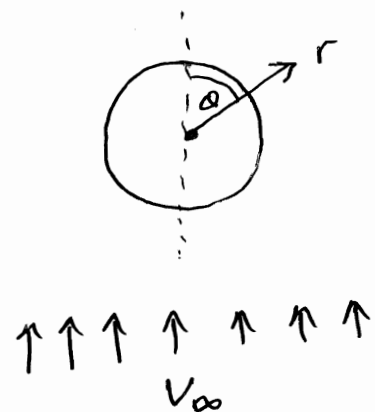
where $E^2 = \frac{\partial^2}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \right)$

$$\Rightarrow \left[\frac{\partial}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \right) \right]^2 \psi = 0 \quad \dots \textcircled{1}$$

as shown in table 4.2-1 :

$$V_r = - \frac{1}{r^2 \sin \theta} \frac{\partial \psi}{\partial \theta}$$

$$V_\theta = \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial r}$$



Boundary Conditions:

BC1 $r=R$ $V_r=0 \Rightarrow - \frac{1}{r^2 \sin \theta} \frac{\partial \psi}{\partial \theta} = 0$

BC2 $r=R$ $V_\theta=0 \Rightarrow \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial r} = 0$

BC3 $r \rightarrow \infty$ $V_r = v_\infty \cos \theta$ $\Rightarrow \psi = -\frac{1}{2} v_\infty r^2 \sin^2 \theta$
 $V_\theta = -v_\infty \sin \theta$

BC3 suggests that we can postulate a solution^② for the stream function of the form:

$$\psi(r, \theta) = f(r) \sin^2(\theta)$$

substitution in equation ① yields:

$$\left[\frac{d^2}{dr^2} - \frac{2}{r^2} \right]^2 f = 0$$

$$\Rightarrow \frac{d^4 f}{dr^4} - \frac{4}{r^2} \frac{d^2 f}{dr^2} + \frac{8}{r^3} \frac{df}{dr} - 8 \frac{f}{r^4} = 0$$

The above equation is similar to C.1-14 but in this case it is fourth order. It admits a solution

$$f(r) = \frac{c_1}{r} + c_2 r + c_3 r^3 + c_4 r^4$$

BC3

$$r \rightarrow \infty \quad \psi = f \sin^2 \theta = -\frac{1}{2} v_\infty r^2 \sin^2 \theta$$

$$\Rightarrow \left(\frac{c_1}{r} + c_2 r + c_3 r^2 + c_4 r^4 \right) \Big|_{r=\infty} \sin^2 \theta = -\frac{1}{2} v_\infty r^2 \Big|_{r=\infty} \sin^2 \theta \cdot \frac{1}{r^2}$$

$$\Rightarrow \left(\frac{c_2}{r^3} + \frac{c_1}{r} + c_3 + c_4 r^2 \right) \Big|_{r=\infty} = -\frac{1}{2} v_\infty$$

$$\Rightarrow c_4 = 0 \quad \text{and} \quad c_3 = -\frac{1}{2} v_\infty$$

B.6-7 and

$$\Rightarrow \psi(r, \theta) = \left(\frac{c_1}{r} + c_2 r - \frac{1}{2} v_\infty r^2 \right) \sin^2(\theta) \quad (4)$$

recall,

$$v_r = - \frac{1}{r^2 \sin(\theta)} \frac{\partial \psi}{\partial \theta} = - \left(\frac{c_1}{r^3} + \frac{c_2}{r} - \frac{1}{2} v_\infty \right) \frac{1}{\sin(\theta)} \frac{\partial}{\partial \theta} (\sin^2(\theta))$$

$$= - \left(\frac{c_1}{r^3} + \frac{c_2}{r} - \frac{1}{2} v_\infty \right) \frac{1}{\sin(\theta)} 2 \sin(\theta) \cos(\theta)$$

$$\Rightarrow v_r = \left(v_\infty - 2 \frac{c_2}{r} - 2 \frac{c_1}{r^3} \right) \cos(\theta)$$

$$v_\theta = \frac{1}{r \sin(\theta)} \frac{\partial \psi}{\partial r} = \frac{1}{r} \sin(\theta) \left(-\frac{c_1}{r^2} + c_2 + v_\infty r \right)$$

$$\Rightarrow v_\theta = \left(-v_\infty + \frac{c_2}{r} - \frac{c_1}{r^3} \right) \sin(\theta)$$

$$\text{BC 1 \& 2} \Rightarrow v_\infty - 2 \frac{c_2}{R} - 2 \frac{c_1}{R^3} = 0$$

$$-v_\infty + \frac{c_2}{R} - \frac{c_1}{R^3} = 0$$

$$\Rightarrow c_1 = -\frac{1}{4} v_\infty R^3 \quad \& \quad c_2 = \frac{3}{4} v_\infty R$$

$$\Rightarrow v_r = v_\infty \left[1 - \frac{3}{2} \left(\frac{R}{r} \right) + \frac{1}{2} \left(\frac{R}{r} \right)^3 \right] \cos(\theta)$$

$$v_\theta = -v_\infty \left[1 - \frac{3}{4} \left(\frac{R}{r} \right) - \frac{1}{4} \left(\frac{R}{r} \right)^3 \right] \sin(\theta)$$

substitution of v_r and v_θ into equation

B.6-7 and B.6-8 yields:

Creeping flow

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) = -\frac{\partial p}{\partial r} + \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2} \right] + \rho g_r \quad (\text{B.6-7})^a$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{2 \cot \theta}{r^2} \frac{\partial v_\phi}{\partial \phi} \right] + \rho g_\theta \quad (\text{B.6-8})$$

$$\frac{\partial P}{\partial r} = \mu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 v_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) \right]$$

$$= 3 \left(\frac{\mu v_\infty}{R^2} \right) \left(\frac{R}{r} \right)^3 \cos(\theta) \quad \dots \quad (2)$$

$$\frac{\partial P}{\partial \theta} = r \mu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_r}{\partial r} \right) + \frac{1}{r^2} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (v_r \sin \theta) + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} \right]$$

$$= \frac{3}{2} \left(\frac{\mu v_\infty}{R} \right) \left(\frac{R}{r} \right)^2 \sin(\theta) \quad \dots \quad (3)$$

Try to do the above manipulations using Mathematical software!

Integration of (2) & (3) with the condition $r \rightarrow \infty \quad p = p_0$

$$\Rightarrow p = p_0 - \rho g z - \frac{3}{2} \left(\frac{\mu v_\infty}{R} \right) \left(\frac{R}{r} \right)^2 \cos(\theta)$$

The kinetic force F_K is evaluated by (6)
 calculation of work done on sphere surface

$$\text{work} = F_K v_\infty = \text{force} \times \text{velocity}$$

$$F_K v_\infty = - \int_0^{2\pi} \int_0^\pi \int_R^\infty (\mathbf{e} : \nabla \mathbf{v}) r^2 dr \sin\theta d\theta d\phi \quad \text{--- (A.8-6)}$$

$$= - \int_0^{2\pi} \int_0^\pi \int_R^\infty \left[2 \left(\frac{\partial v_r}{\partial r} \right)^2 + 2 \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right)^2 + \right. \\ \left. 2 \left(\frac{v_r}{r} + \frac{v_\theta \cot\theta}{r} \right)^2 + \left(r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)^2 \right] r^2 dr \sin\theta d\theta d\phi \quad \text{--- (B.7-3)}$$

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$$F_K = 6\pi\mu v_\infty R$$