

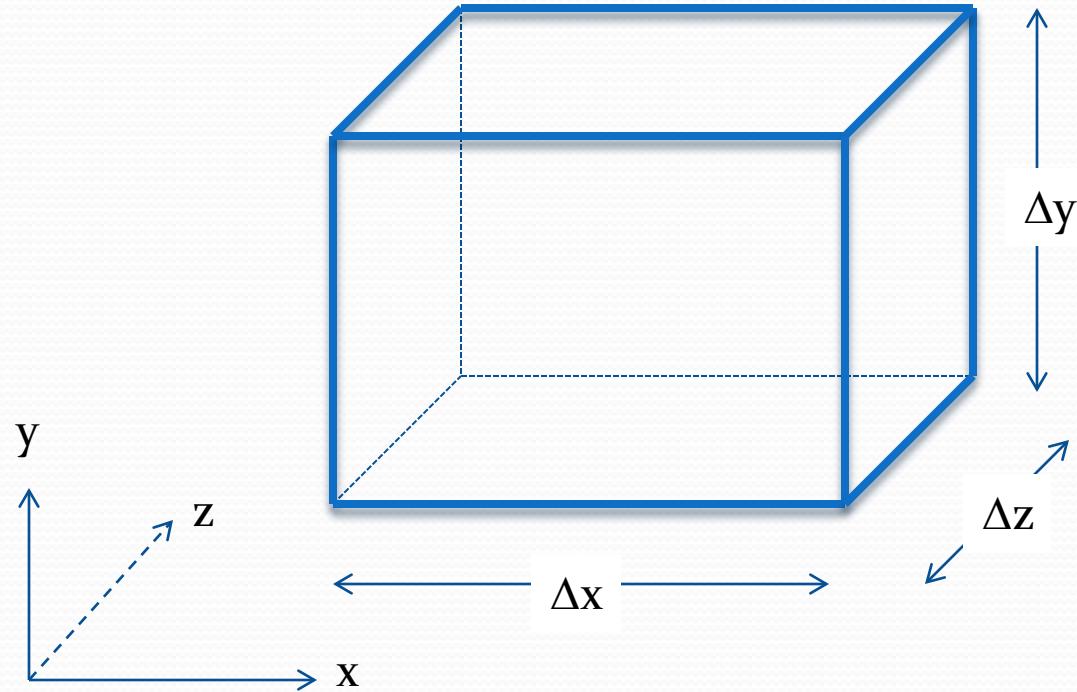
Microscopic Mass Balance

CHE204

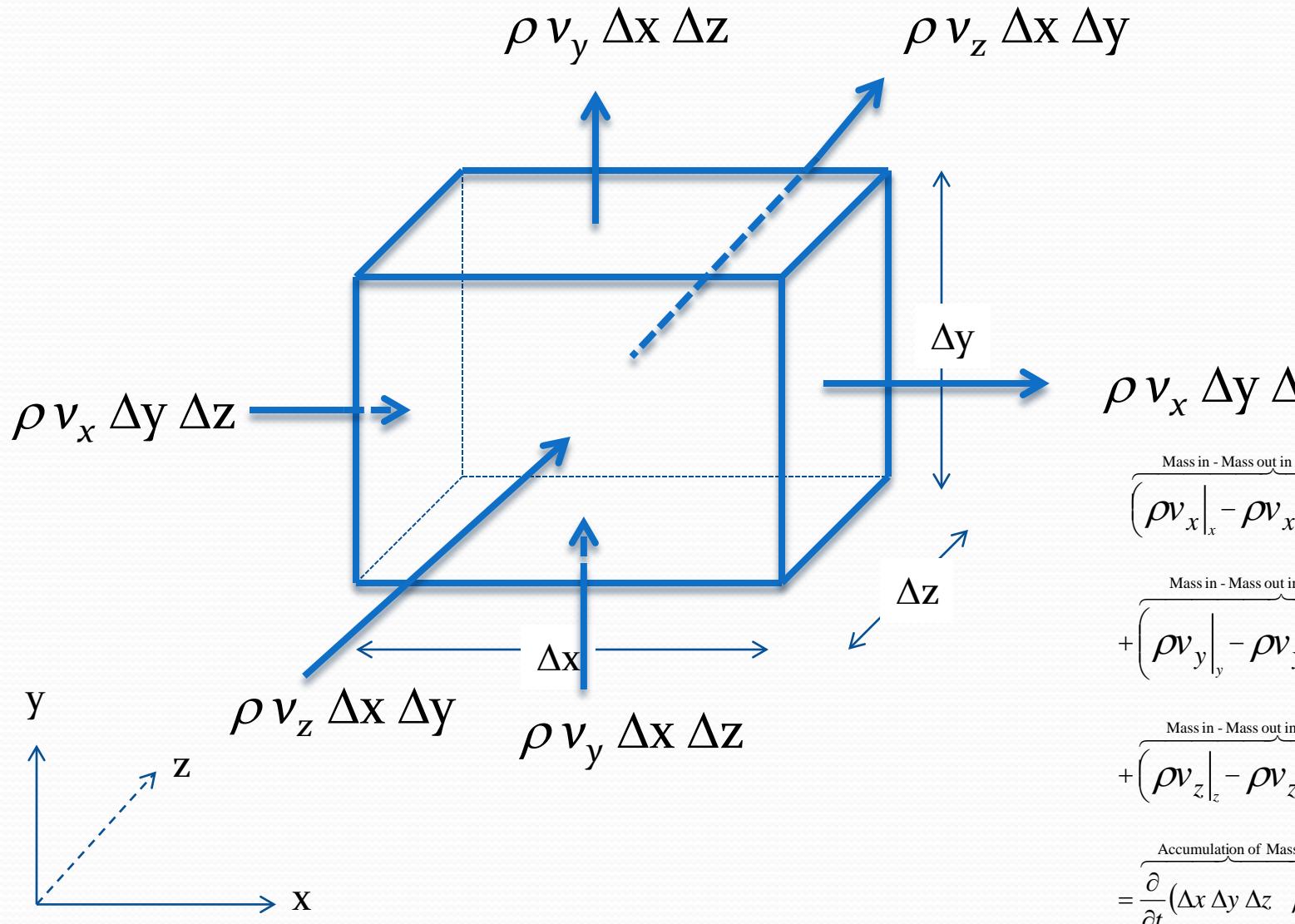
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Introduce the x y z coordinate system

Introduce a control volume (microscopic system)
of dimensions $\Delta x \Delta y \Delta z$



Consider the mass that enters and leaves out of the six surfaces of the control volume



$$\overbrace{(\rho v_x|_x - \rho v_x|_{x+\Delta x}) \Delta y \Delta z}^{\text{Mass in - Mass out in the } x \text{ direction}}$$

$$+ \overbrace{(\rho v_y|_y - \rho v_y|_{y+\Delta y}) \Delta x \Delta z}^{\text{Mass in - Mass out in the } y \text{ direction}}$$

$$+ \overbrace{(\rho v_z|_z - \rho v_z|_{z+\Delta z}) \Delta x \Delta y}^{\text{Mass in - Mass out in the } z \text{ direction}}$$

$$= \overbrace{\frac{\partial}{\partial t} (\Delta x \Delta y \Delta z \rho)}^{\text{Accumulation of Mass}}$$

Mass Balance on Control Volume:

Mass_{in} – Mass_{out} = Accumulation of Mass

$$\underbrace{\left(\rho v_x \Big|_x - \rho v_x \Big|_{x+\Delta x} \right) \Delta y \Delta z}_{\text{Mass in - Mass out in the } x \text{ direction}} + \underbrace{\left(\rho v_y \Big|_y - \rho v_y \Big|_{y+\Delta y} \right) \Delta x \Delta z}_{\text{Mass in - Mass out in the } y \text{ direction}} + \underbrace{\left(\rho v_z \Big|_z - \rho v_z \Big|_{z+\Delta z} \right) \Delta x \Delta y}_{\text{Mass in - Mass out in the } z \text{ direction}} = \underbrace{\frac{\partial}{\partial t} (\Delta x \Delta y \Delta z \rho)}_{\text{Accumulation of Mass}}$$

$$\Delta x \Delta y \Delta z = \text{Constant}$$



$$\left(\rho v_x \Big|_x - \rho v_x \Big|_{x+\Delta x} \right) \Delta y \Delta z + \left(\rho v_y \Big|_y - \rho v_y \Big|_{y+\Delta y} \right) \Delta x \Delta z + \left(\rho v_z \Big|_z - \rho v_z \Big|_{z+\Delta z} \right) \Delta x \Delta y = \Delta x \Delta y \Delta z \frac{\partial}{\partial t} (\rho)$$

$$\left(\rho v_x \Big|_x - \rho v_x \Big|_{x+\Delta x} \right) \Delta y \Delta z + \left(\rho v_y \Big|_y - \rho v_y \Big|_{y+\Delta y} \right) \Delta x \Delta z + \left(\rho v_z \Big|_z - \rho v_z \Big|_{z+\Delta z} \right) \Delta x \Delta y = \Delta x \Delta y \Delta z \frac{\partial}{\partial t}(\rho)$$

Divide the whole equation by $\Delta x \Delta y \Delta z$
then take the limit when $\Delta x \Delta y \Delta z$ approaches zero

$$\lim_{\Delta x \Delta y \Delta z \rightarrow 0} \left[\frac{\left(\rho v_x \Big|_x - \rho v_x \Big|_{x+\Delta x} \right)}{\Delta x} + \frac{\left(\rho v_y \Big|_y - \rho v_y \Big|_{y+\Delta y} \right)}{\Delta y} + \frac{\left(\rho v_z \Big|_z - \rho v_z \Big|_{z+\Delta z} \right)}{\Delta z} \right] = \frac{\partial}{\partial t}(\rho)$$

$$-\frac{\partial}{\partial x}(\rho v_x) - \frac{\partial}{\partial y}(\rho v_y) - \frac{\partial}{\partial z}(\rho v_z) = \frac{\partial}{\partial t}(\rho)$$

Divergence Operator

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho v_x)}{\partial x} + \frac{\partial(\rho v_y)}{\partial y} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

Velocity vector

$$\vec{v} = (v_x \hat{i} + v_y \hat{j} + v_z \hat{k})$$

Dell operator

$$\vec{\nabla} = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right)$$

Divergence

$$\vec{\nabla} \cdot \text{Vector} \quad (\text{Dot product between two vectors})$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho v) = 0$$

Microscopic Continuity Equation For Incompressible Fluid

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho v_x)}{\partial x} + \frac{\partial(\rho v_y)}{\partial y} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

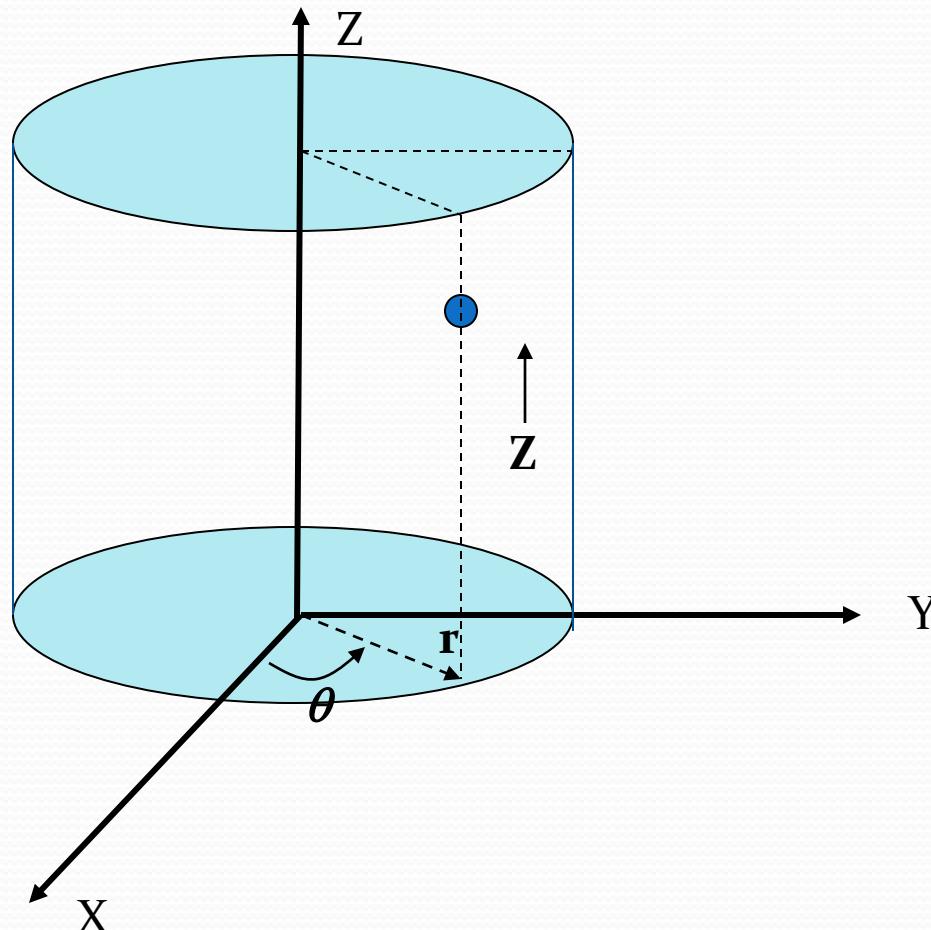
Incompressible Fluid \rightarrow Constant Density

$$\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} = 0$$

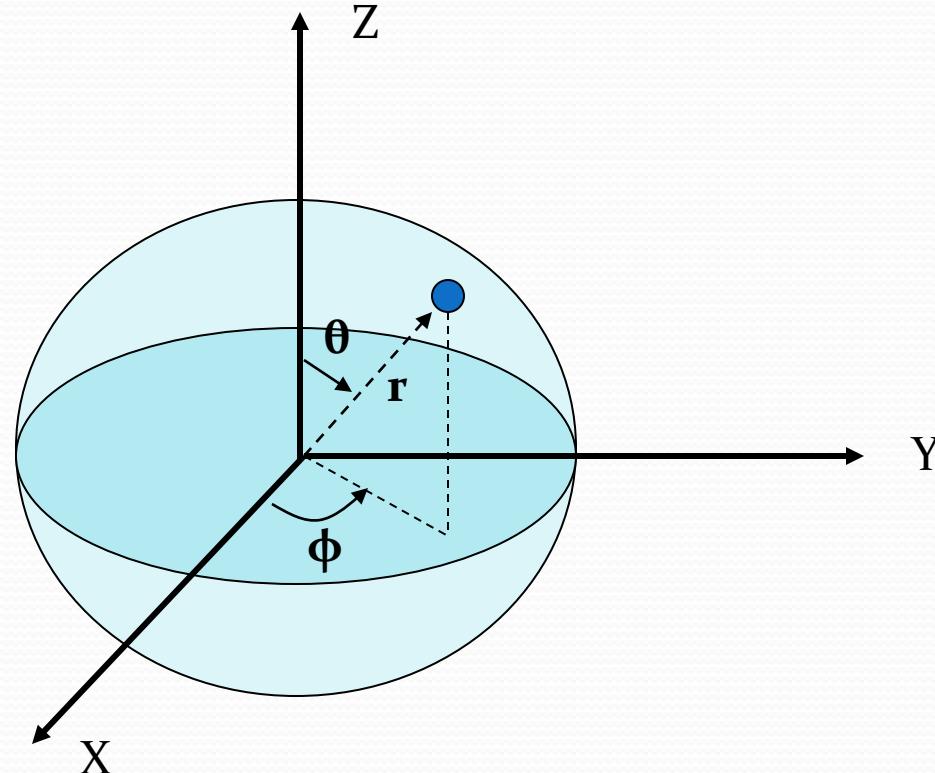
$$\nabla \cdot v = 0$$

For Incompressible Fluid:
The divergence of the velocity is equal to zero

Cylindrical Coordinates



Spherical Coordinates



Divergence Operator in Different Coordinate Systems

Rectangular Coordinates :

$$\nabla \cdot v = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

Cylindrical Coordinates :

$$\nabla \cdot v = \frac{1}{r} \frac{\partial(rv_r)}{\partial r} + \frac{1}{r} \frac{\partial(rv_\theta)}{\partial \theta} + \frac{\partial v_z}{\partial z}$$

Spherical Coordinates :

$$\nabla \cdot v = \frac{1}{r^2} \frac{\partial(r^2 v_r)}{\partial r} + \frac{1}{r \sin\theta} \frac{\partial(v_\theta \sin\theta)}{\partial \theta} + \frac{1}{r \sin\theta} \frac{\partial v_\phi}{\partial \phi}$$