

2-31. Express \mathbf{F}_1 , and \mathbf{F}_3 as Cartesian vectors.

2-32. Determine the magnitude of the resultant force and its orientation measured counterclockwise from the positive x axis.

2-49 The crate is to be hoisted using two chains. Determine the magnitudes of forces \mathbf{F}_A and \mathbf{F}_B acting on each chain in order to develop a resultant force of 600 N directed along the positive y axis. Set $\theta = 45^\circ$.

2-31

$$\mathbf{F}_1 = \{15 \cos 50^\circ \mathbf{i} + 15 \sin 50^\circ \mathbf{j}\} \text{ kN} = \{9.64 \mathbf{i} + 11.5 \mathbf{j}\} \text{ kN} \quad \text{Ans}$$

$$\mathbf{F}_2 = \left\{-\frac{12}{13}(26) \mathbf{i} + \frac{5}{13}(26) \mathbf{j}\right\} \text{ kN} = \{-24 \mathbf{i} + 10 \mathbf{j}\} \text{ kN} \quad \text{Ans}$$

$$\mathbf{F}_3 = \{36 \cos 30^\circ \mathbf{i} - 36 \sin 30^\circ \mathbf{j}\} \text{ kN} = \{31.2 \mathbf{i} - 18 \mathbf{j}\} \text{ kN} \quad \text{Ans}$$

2-32

$$\begin{aligned} \xrightarrow{+} F_{Rx} &= \sum F_x ; & F_{Rx} &= 15 \cos 50^\circ - \frac{12}{13}(26) + 36 \cos 30^\circ \\ & & &= 16.82 \text{ kN} \rightarrow \end{aligned}$$

$$\begin{aligned} + \uparrow F_{Ry} &= \sum F_y ; & F_{Ry} &= 15 \sin 50^\circ + \frac{5}{13}(26) - 36 \sin 30^\circ \\ & & &= 3.491 \text{ kN} \uparrow \end{aligned}$$

Magnitude

$$F_R = \sqrt{F_{Rx}^2 + F_{Ry}^2} = \sqrt{16.82^2 + 3.491^2} = 17.2 \text{ kN} \quad \text{Ans}$$

Direction

$$\theta = \tan^{-1} \frac{F_{Ry}}{F_{Rx}} = \tan^{-1} \frac{3.491}{16.82} = 11.7^\circ \quad \text{Ans}$$

Vector Analysis:

$$\mathbf{F}_1 = \{15 \cos 50^\circ \mathbf{i} + 15 \sin 50^\circ \mathbf{j}\} \text{ kN} = \{9.64 \mathbf{i} + 11.5 \mathbf{j}\} \text{ kN}$$

$$\mathbf{F}_2 = \{-\frac{12}{13}(26) \mathbf{i} + \frac{5}{13}(26) \mathbf{j}\} \text{ kN} = \{-24 \mathbf{i} + 10 \mathbf{j}\} \text{ kN}$$

$$\mathbf{F}_3 = \{36 \cos 30^\circ \mathbf{i} - 36 \sin 30^\circ \mathbf{j}\} \text{ kN} = \{31.2 \mathbf{i} - 18 \mathbf{j}\} \text{ kN}$$

$$\mathbf{F}_R = \mathbf{F}_1 + \mathbf{F}_2 + \mathbf{F}_3$$

$$= \{9.64 \mathbf{i} + 11.5 \mathbf{j}\} + \{-24 \mathbf{i} + 10 \mathbf{j}\} + \{31.2 \mathbf{i} - 18 \mathbf{j}\}$$

$$= \{16.8 \mathbf{i} + 3.49 \mathbf{j}\} \text{ kN}$$

$$\mathbf{F}_R = \sum F_x \hat{\mathbf{i}} + \sum F_y \hat{\mathbf{j}}$$

$$= F_{Rx} \hat{\mathbf{i}} + F_{Ry} \hat{\mathbf{j}}$$

2-49

$$\overset{+}{\rightarrow} F_{Rx} = \sum F_x ; \quad 0 = F_A \sin 30^\circ - F_B \sin 45^\circ \quad [1]$$

$$+ \uparrow F_{Ry} = \sum F_y ; \quad 600 = F_A \cos 30^\circ + F_B \cos 45^\circ \quad [2]$$

Solving Eqs. [1] and [2] yields:

$$F_B = 311 \text{ N} \quad F_A = 439 \text{ N} \quad \text{Ans}$$

$$F_A \cdot \frac{1}{2} = F_B \cdot \frac{1}{\sqrt{2}} \quad F_A = F_B \cdot \frac{2}{\sqrt{2}} = \sqrt{2} F_B \quad (3)$$

$$600 = F_A \cdot \frac{\sqrt{3}}{2} + F_B \cdot \frac{1}{\sqrt{2}}$$

$$600 = \sqrt{2} \cdot F_B \cdot \frac{\sqrt{3}}{\sqrt{2}} + F_B \cdot \frac{1}{\sqrt{2}} = F_B \left(\sqrt{\frac{3}{2}} + \frac{1}{\sqrt{2}} \right) = F_B \frac{1}{\sqrt{2}} (\sqrt{3} + 1)$$

$$F_B = 310.58 \approx 311 \text{ N}$$

$$F_A = \sqrt{2} \cdot 310.58 = 439.23 \\ = 439 \text{ N}$$

2.5 Cartesian Vectors:

- Representing 3-D vectors in Cartesian vector form
- Right-hand coordinate system

- Rectangular components of a vector

\vec{A} is directed within an octant of x, y, z frame

- Two successive application of the parallelogram law

$$\vec{A} = \vec{A}' + \vec{A}_z$$

$$\vec{A}' = \vec{A}_x + \vec{A}_y$$

$$\therefore \vec{A} = \vec{A}_x + \vec{A}_y + \vec{A}_z$$

- Unit vector

A vector having a mag of 1

$$\vec{A}, |\vec{A}| \neq 0$$

$$\therefore \vec{u}_A = \frac{\vec{A}}{|\vec{A}|}$$

$$\vec{A} = A \cdot \vec{u}_A$$

positive scalar

dimensionless vector

Component & direction of each vector is separated.

Cartesian Unit vectors

$\hat{i}, \hat{j}, \hat{k}$ in x, y, z direction

Sense : \pm positive x, y, z axes
negative

Cartesian Vector Representation

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

- Magnitude of Cartesian vector

$$A = \sqrt{A'^2 + A_z^2}, \quad A'^2 = A_x^2 + A_y^2$$

$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$ positive square root of the sum of the squares of its components.

- Direction of Cartesian vector

Orientation of \vec{A} is defined by the coordinate direction angles (α - alpha; β - beta; γ - gamma) measured between tail of \vec{A}

and the positive (x, y, z) axes located at the tail of \vec{A} .

- values of α, β, γ is between 0 & 180° .

$$\left. \begin{aligned} \text{Cos } \alpha &= \frac{A_x}{A} \\ \text{Cos } \beta &= \frac{A_y}{A} \\ \text{Cos } \gamma &= \frac{A_z}{A} \end{aligned} \right\} \text{ direction of cosines of } \vec{A}$$

$$\alpha = \cos^{-1} \frac{A_x}{A}, \quad \beta = \cos^{-1} \frac{A_y}{A}, \quad \gamma = \cos^{-1} \frac{A_z}{A}$$

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{u}_A = \frac{\vec{A}}{A} = \frac{A_x}{A} \hat{i} + \frac{A_y}{A} \hat{j} + \frac{A_z}{A} \hat{k} \quad \text{represents the direction of } A$$

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

$$|\vec{u}_A| = 1 = \sqrt{\text{Cos}^2 \alpha + \text{Cos}^2 \beta + \text{Cos}^2 \gamma}$$

$$\text{or } \text{Cos}^2 \alpha + \text{Cos}^2 \beta + \text{Cos}^2 \gamma = 1$$

$$\vec{A} = A \vec{u}_A, \quad \vec{u}_A = \text{Cos } \alpha \hat{i} + \text{Cos } \beta \hat{j} + \text{Cos } \gamma \hat{k}$$

$$= A \text{Cos } \alpha \hat{i} + A \text{Cos } \beta \hat{j} + A \text{Cos } \gamma \hat{k}$$

$$= A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

2.6 Addition & subtraction of Cartesian vectors

\vec{A} , \vec{B} vectors within the positive octant of x, y, z frame

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\vec{R} = \vec{A} + \vec{B} = (A_x + B_x) \hat{i} + (A_y + B_y) \hat{j} + (A_z + B_z) \hat{k}$$

$$\vec{R}' = \vec{A} - \vec{B} = (A_x - B_x) \hat{i} + (A_y - B_y) \hat{j} + (A_z - B_z) \hat{k}$$

- Concurrent force systems

$$\vec{F}_1, \vec{F}_2, \vec{F}_3, \dots$$

$$\vec{F}_R = \sum \vec{F} = \sum F_x \hat{i} + \sum F_y \hat{j} + \sum F_z \hat{k}$$

$$\sum F_x, \sum F_y, \sum F_z : \text{Algebraic sum of } x, y, z \text{ components}$$