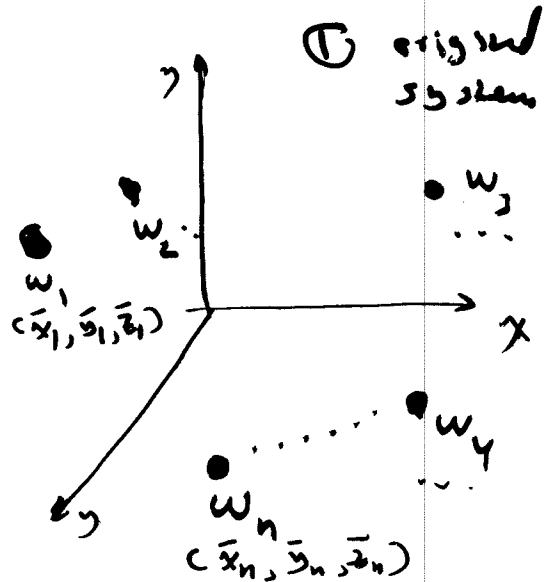


# Center of Gravity

## Centroid

To replace the system of particles / bodies by a simple system composed of only one body, two conditions must be satisfied



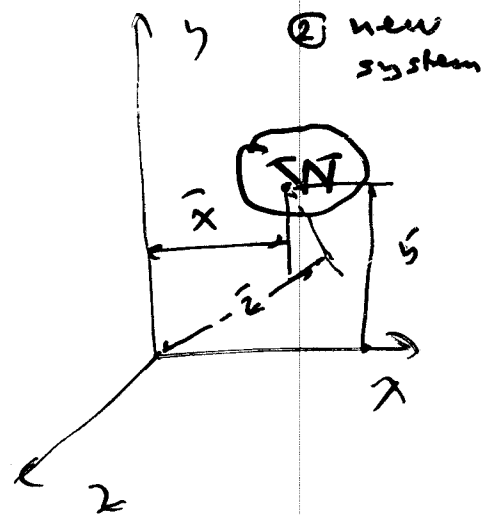
(as far as Statics is concerned). Thus the two systems will be equivalent.

①  $\Sigma$  Forces in the two systems must be equal.  $\Rightarrow$

$$\Sigma F_y :$$

$$\overline{W} = \sum_{i=1}^n w_i$$

②  $\Sigma$  Moments in the two systems must be equal.



$$\Sigma M_x :$$

$$\bar{z} \overline{W} = \sum_{i=1}^n \bar{z}_i w_i$$

$$\Rightarrow \bar{z} = \frac{\sum_{i=1}^n \bar{z}_i w_i}{\underbrace{\sum_{i=1}^n w_i}_{\overline{W}}}$$

similarly :

$$M_z \Rightarrow \bar{x} = \frac{\sum_{i=1}^n x_i w_i}{\overline{W}}$$

If  $w_i$  gets smaller and smaller, then  $w_i \rightarrow \Delta w_i \rightarrow dw_i$

$$\Rightarrow \overline{W} = \sum (\Delta w)_i \Rightarrow \overline{W} = \int dw; \text{ similarly, } \bar{x} = \frac{\int x dw}{\int dw}, \bar{z} = \dots$$

C. for "Particles"

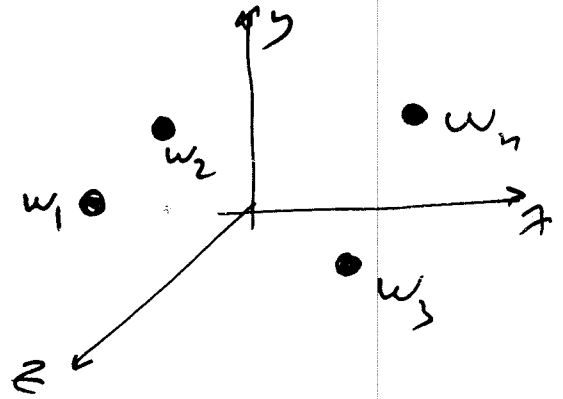
# Centroid

$$\bar{x} \sum w_i = \sum_{i=1}^n \bar{x}_i w_i$$

$$\Rightarrow \bar{x} = \frac{\sum \bar{x}_i w_i}{\sum w_i}$$

$$\bar{y} = \dots$$

$$\bar{z} = \dots$$

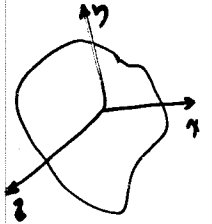


C.G. for bodies:

$$\bar{x} = \frac{\int \bar{x} dw}{\int dw}$$

$$\bar{y} = \dots$$

$$\bar{z} = \dots$$



C.M.

$$\bar{x} = \frac{\int \bar{x} \rho dv}{\int \rho dv}$$

$$\bar{y} = \dots$$

$$\bar{z} = \dots$$

## Centroid

$$\bar{x} = \frac{\int \bar{x} dv}{\int dv}$$

$$\bar{y} = \dots$$

$$\bar{z} = \dots$$



$$\bar{x} = \frac{\int_A \bar{x} dA}{\int_A dA}$$

$$\bar{y} = \dots$$

$$\bar{z} = \dots$$

$$\bar{x} = \frac{\int_L \bar{x} dL}{\int_L dL}$$

$$\bar{y} = \dots$$

$$\bar{z} = \dots$$



# Centroid for Composite Bodies

Volumes  
Areas

We can come back to the original definition.  $\Rightarrow$

Use  $\boxed{\Sigma \Delta}$  instead of  $\boxed{\int}$ .  $\Rightarrow$

$$\bar{X} = \frac{\Sigma \bar{x}_i V_i}{\Sigma V_i}$$

⋮

$$\bar{X} = \frac{\Sigma \bar{x}_i A_i}{\Sigma A_i}$$

⋮