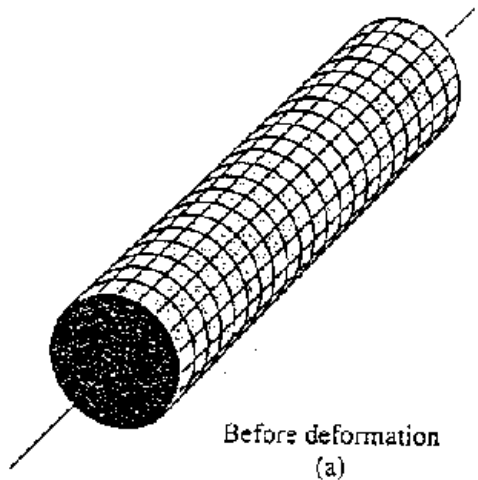


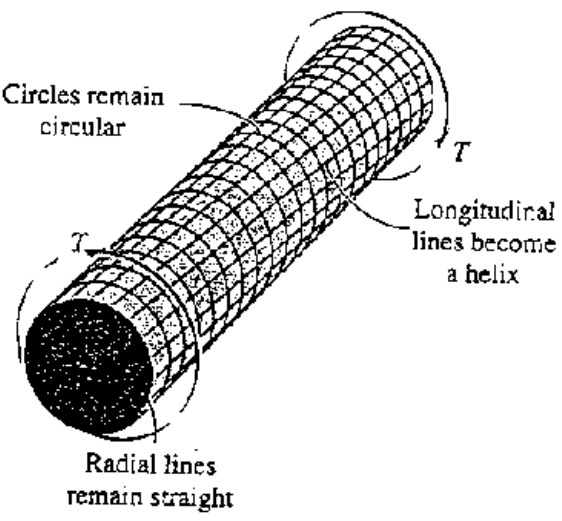
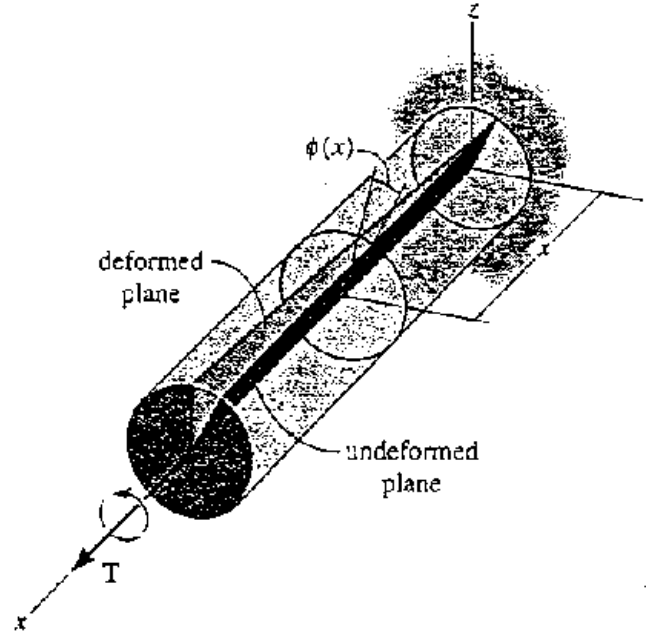
Chapter 4.

# Torsion

# TORSION



Before deformation  
(a)



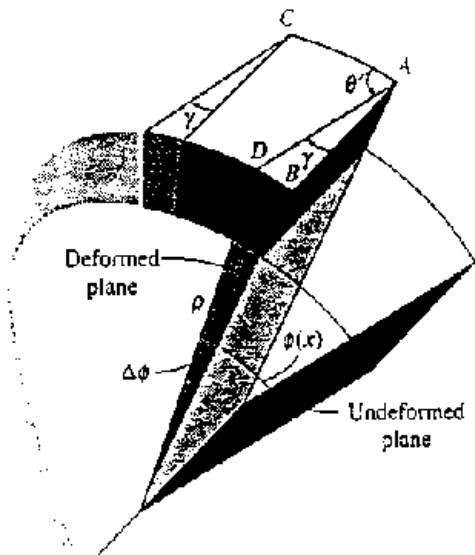
Circles remain circular

Longitudinal lines become a helix

Radial lines remain straight

After deformation  
(b)

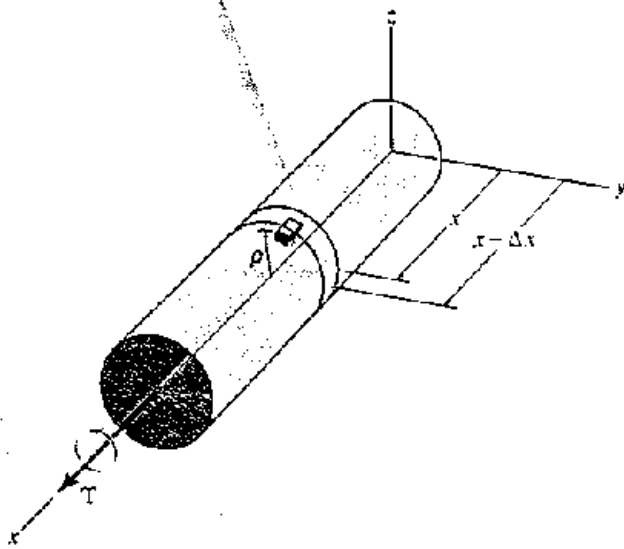
Fig. 5-1



$$BD = \rho d\phi = dx \gamma$$

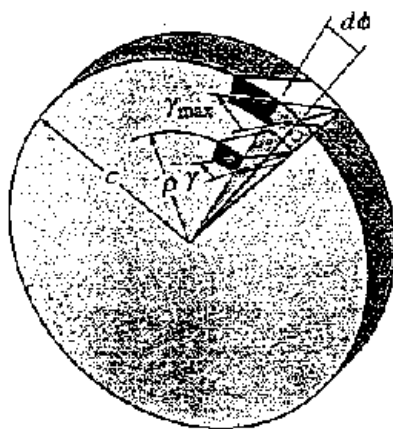
$$\gamma = \rho \frac{d\phi}{dx}$$

Shear strain of element



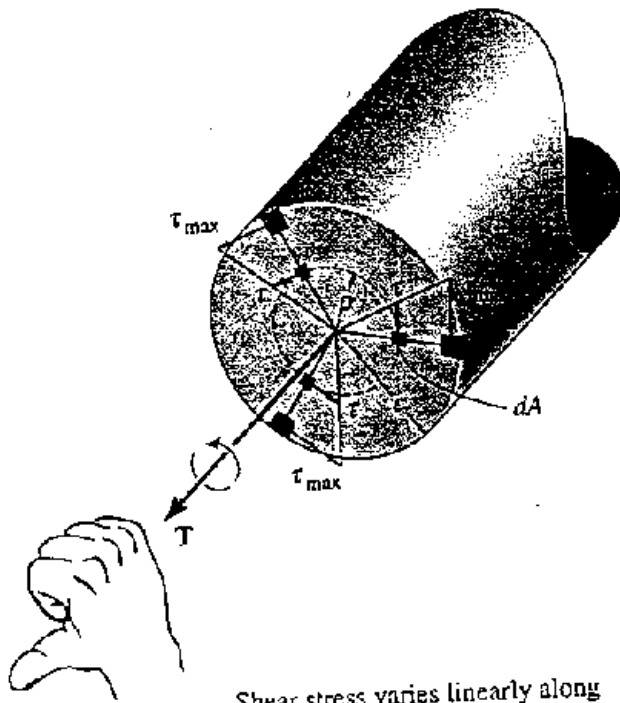
$$\gamma = \left(\frac{\rho}{c}\right) \gamma_{\max}$$

Fig. 5-3



The shear strain for the material increases linearly with  $\rho$ , i.e.,  $\gamma = (\rho/c) \gamma_{\max}$ .

Fig. 5-4



Shear stress varies linearly along each radial line of the cross section.

Fig. 5-5

$$\tau = \left( \frac{\rho}{c} \right) \tau_{\max}$$

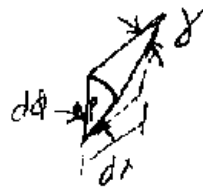
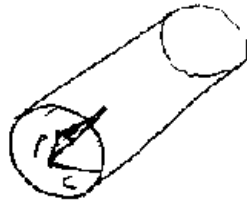
$$\tau_{\max} = \frac{Tc}{J}$$

$$J = \frac{\pi}{2} c^4$$

$$\tau = \frac{T\rho}{J}$$

$$J = \frac{\pi}{2} (c_o^4 - c_i^4)$$

# shear stress formula & angle of twist

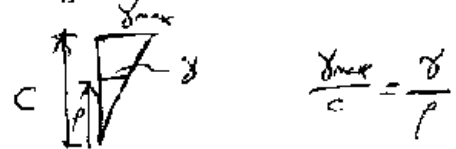


$$\rho d\phi = \gamma dx$$

$$\gamma = \rho \frac{d\phi}{dx}$$

for a given  $x$ ,  $\frac{d\phi}{dx} = \text{constant}$

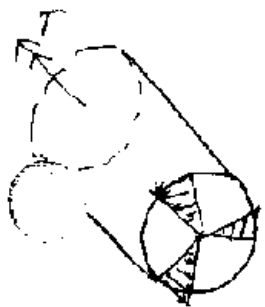
therefore  $\gamma$  is proportional to  $\rho$



$$\frac{\gamma_{max}}{c} = \frac{\gamma}{\rho}$$

$$\therefore \gamma = \rho \frac{\gamma_{max}}{c}, \quad \text{since } \tau \propto \gamma$$

$$\therefore \tau = \rho \frac{\tau_{max}}{c}$$



$$T = \int dT = \int \rho (\tau dA)$$

$$= \int \rho \left( \rho \frac{\tau_{max}}{c} \right) dA$$

$$= \frac{\tau_{max}}{c} \int \rho^2 dA$$

$$T = \frac{\tau_{max}}{c} \cdot J$$

$$\tau_{max} = \frac{Tc}{J}$$

or

$$\tau = \frac{Tr}{J}$$

$$J = \frac{\pi c^4}{2}$$

for



1) polar moment of inertia

$$J = \frac{\pi}{2} (c_o^4 - c_i^4)$$



# Angle of Twist $\phi$

$$\begin{aligned} d\phi &= \gamma \frac{dx}{\rho} \\ &= \frac{\tau}{G} \frac{dx}{\rho} \\ &= \frac{1}{G} \left( \frac{T\rho}{J} \right) \frac{dx}{\rho} \end{aligned}$$

$$d\phi = \frac{T}{GJ} dx$$

$$\phi = \int_0^L \frac{T}{GJ} dx$$

For constant  $T$ ,  $G$ , and  $J$ , the above can be integrated to yield.

$$\phi = \frac{TL}{GJ} \quad \text{and for many segments,}$$

$$\phi = \sum_{i=1}^n \frac{T_i L_i}{G_i J_i}$$

angular velocity,  
(angular distance  
per unit time)

5.3

## Power Transmission

$$\begin{aligned} W &= Fd \quad \text{or} \quad W = T\theta \quad \text{work} \\ P &= \frac{dW}{dt} \quad \left( P = FV \quad \text{or} \quad P = T \frac{d\theta}{dt} = T\omega \right) \end{aligned}$$

$$P = T [2\pi f] \quad \text{where } f = \text{frequency} \left( \frac{\# \text{ of revolutions}}{\text{second}} \right)$$

$$P = \text{Watt} \quad \left( \text{hp} = 550 \frac{\text{lb-ft}}{\text{second}} \right)$$

$$T = \text{N-m} \quad (\text{ft-lb})$$

$$\omega = \text{rad/s}$$

From table:  $G = 11.0 \times 10^3 \text{ ksi}$

$$A = \pi r^2 \Rightarrow r = 1.6925$$

$$\tau_c = \frac{TS}{J} = \frac{(4000)(1.692568)}{(\pi/2)(1.692568)^4} = 525 \text{ psi} \quad \text{Circle}$$

$$\tau_f = \frac{4.81 T}{a^3} = \frac{(4.81)(4000)}{(3)^3} = 713 \text{ psi}$$

$$\phi_c = \frac{TL}{GJ} = \frac{(4000)(36)}{(11.0 \times 10^6)(\pi/2)(1.692568)^4} = 1.0456 \times 10^{-3} \text{ rad}$$

$$\phi_f = \frac{7.10 TL}{a^4 G} = \frac{(7.10)(4000)(36)}{(3^4)(11.0 \times 10^6)} = 1.1474 \times 10^{-3} \text{ rad}$$

∴ As a conclusion stress is smaller and angle twist is also smaller for the circular shaft compared to square one

$$G = 26 \times 10^9 \text{ pa}$$

$$\tau_{all} = \tau_{cd} : 125 \times 10^6 = \frac{T}{2A_m t} = \frac{75000}{2[4a(2a) + \pi a^2] \cdot 0.007} \Rightarrow a = 62 \text{ mm}$$

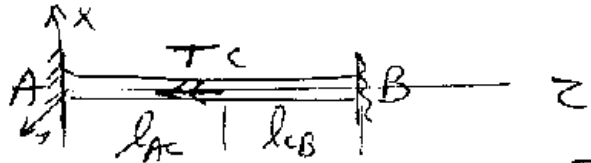
$$\phi = \frac{TL}{4G A_m^2 t} = \frac{(75000)(2)(4 + \pi)2a}{(4)(26 \times 10^9) \{8 + \pi\}^2 (0.007)(a^4)}$$

$$= 0.0994 \text{ rad}$$

$$= 5.69^\circ$$

## 5.5 Statically Indeterminate Members

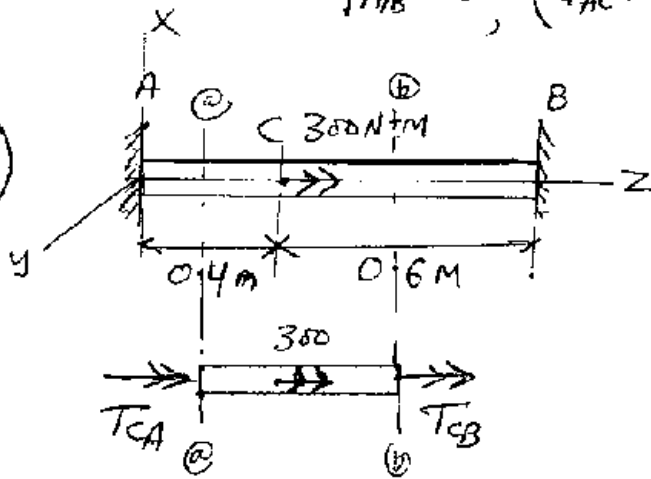
like statically indeterminate of axially loaded members, one needs both equations of equilibrium and compatibility equations.



① Equilibrium:  $T_A \rightarrow \leftarrow T \rightarrow T_B$   $T_B + T_A - T = 0$  *T is given*

② Compatibility:  $\phi_{A/B} = 0$ ,  $(\phi_{AC} + \phi_{CB} = 0)$ ,  $\left(\frac{T_{AC} l_{AC}}{GJ} + \frac{T_{CB} l_{CB}}{GJ} = 0\right)$

$\frac{5-73}{220}$



$$T = (3 \times 10^3) \left(\frac{100}{1000}\right) = 300 \text{ N-m}$$

positive torque is pointing in the positive z-axis

① Equilibrium:  $T_{CB} + T_{CA} + 300 = 0$

② Compatibility:  $\phi_{A/B} = 0 \left(\frac{T_{CA}(0.4)}{GJ} + \frac{T_{CB}(0.6)}{GJ} = 0\right)$

$$\therefore T_{CA} + T_{CB} = -300 \quad \text{--- (1)}$$

$$0.4 T_{CA} + 0.6 T_{CB} = 0 \quad \text{--- (2)}$$

$$\therefore T_{CA} = -180 \text{ N-m} \Rightarrow \tau_{AC} = \frac{T}{J} = \frac{-180(0.02)}{\left(\frac{\pi}{2}\right)(0.02)^4} = -14.3 \text{ MPa}$$

$$T_{CB} = -120 \Rightarrow \tau_{CB} = \frac{T}{J} = \frac{-120(0.02)}{\frac{\pi}{2}(0.02)^4} = -9.55 \text{ MPa}$$



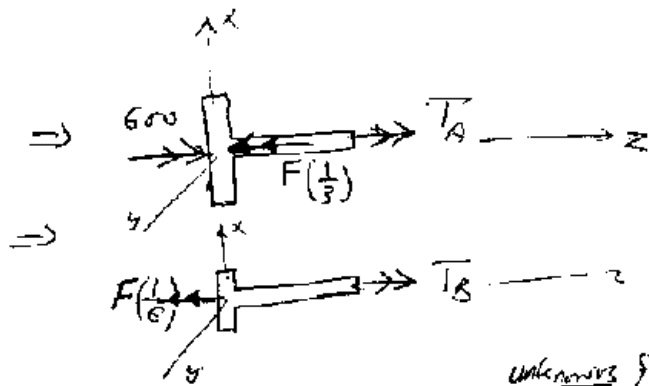
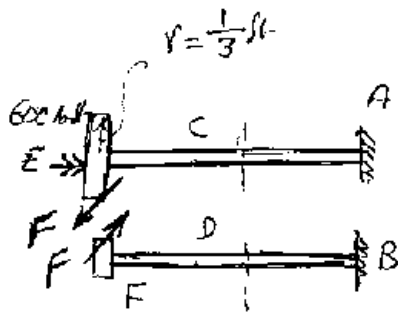
Section a-a



Section b-b



5-80  
221



unknowns  $\{T_A, T_B, F\}$

shaft A :  $T_A + 600 - \frac{F}{3} = 0$  — (1)

shaft B :  $T_B - \frac{F}{6} = 0$  — (2)

combine (1) & (2)  $\Rightarrow$

$$T_A + 2T_B + 600 = 0$$

Equilibrium Eq. (A)

Compatibility Equation

$r_E \phi_E = r_F \phi_F$  (same angular distance  $\phi$ )

$4 \phi_E = 2 \phi_F$

$\phi_E = \frac{1}{2} \phi_F$

$\frac{T_A L}{GJ} = \frac{1}{2} \frac{T_B L}{GJ}$

$2T_A = T_B$  — (B)

solving equations (A) & (B)  $\Rightarrow$

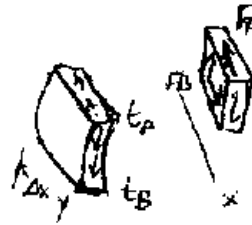
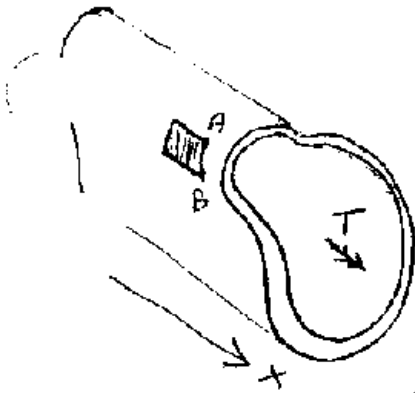
$T_A = 120 \text{ lb-ft}$

$T_B = 240 \text{ lb-ft}$

$(\tau_{BD})^{\max} = \frac{T_B C}{J} = \frac{(240)(12)(0.75)}{(\frac{\pi}{2})(0.75)^4} = 4.35 \text{ ksi}$

$(\tau_{AC})^{\max} = \frac{T_A C}{J} = \frac{(120)(12)(0.75)}{(\frac{\pi}{2})(0.75)^4} = 2.17 \text{ ksi}$

# 5-7 Thin-Walled Tubes Having Closed Cross Sections



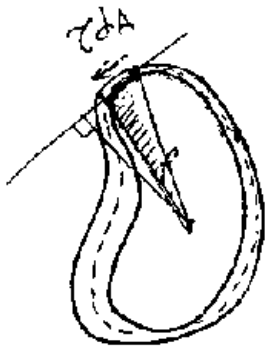
shear stress acting in all four faces meet by tails or heads.

$$\sum F_x = 0 \quad F_A = F_B$$

$$\tau_A t_A \Delta x = \tau_B t_B \Delta x = \text{const.}$$

$$q = \tau t$$

$$\tau_A t_A = \tau_B t_B = q \quad (\text{shear flow})$$



$$\begin{aligned} T &= \int dT = \int dF \rho = \int \tau dA \rho = \int \tau t ds \rho = \int q ds \rho \\ &= \int q (2d\rho) = 2q \int dA = 2qA \end{aligned}$$

$$q = T/2A$$

where  $T$  is the applied torque and  $A$  is the area enclosed by center line

$$\begin{aligned} d\rho &= \frac{1}{2} ds \rho \\ dA &= \rho ds \end{aligned}$$

$$\phi = \frac{TL}{4A^2 G} \int \frac{ds}{t}$$

, The angle of twist

# TORSION

## ① Solid/Hollow Circular Sections



$$\tau = \frac{Tr}{J}, \quad \tau^{\max} = \frac{Tc}{J}, \quad J = \frac{\pi d^4}{32}$$

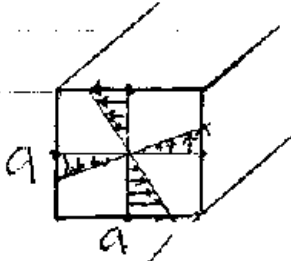


$$\tau^{\max} = \frac{Tc_o}{J}, \quad J = \frac{\pi}{32} (d_o^4 - d_i^4)$$

$$\phi = \frac{TL}{GJ}$$

## ② Solid Non-Circular Sections

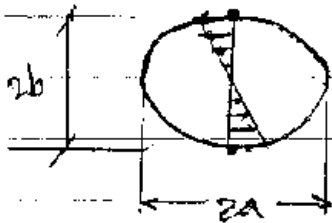
See table 5-1 page 221



• points of  $\tau^{\max} = \frac{4.81T}{a^3}$   
at corners  $\tau = 0$ ,  $\phi = \frac{7.10TL}{a^4 G}$



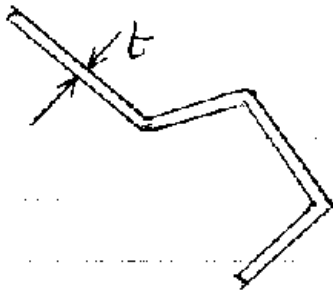
$$\tau^{\max} = \frac{20T}{a^3}, \quad \phi = \frac{46TL}{a^4 G}$$



$$\tau^{\max} = \frac{2T}{\pi ab^2}, \quad \phi = \frac{a^2 + b^2}{\pi a^3 b^3 G} TL$$

$$\phi = \frac{TL}{GJ}$$

### ③ Thin-walled Open Sections

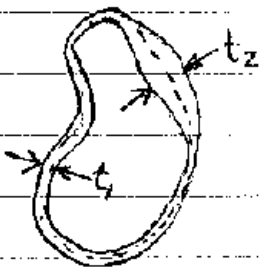


$$\tau = \frac{Tt}{J}, \quad J = \frac{1}{3}Lt^3$$

$L$  = length  
 $t$  = thickness

$$\phi = \frac{TL}{GJ}$$

### ④ Thin-walled Closed Sections



$$\tau = \frac{q}{t}, \quad q = \text{shear flow}$$

$$\tau^{\max} = \frac{q}{t_{\min}}, \quad q = \frac{T}{2A_m}$$

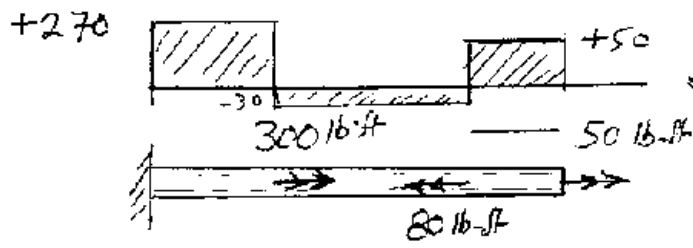
$A_m$  = area enclosed  
 by the center  
 line

$$\phi = \frac{TL}{G} \left( \frac{1}{4A_m^2} \int \frac{ds}{t} \right)$$

where  $s$  = the length of central line  
 $t$  = thickness

when  $t = \text{constant}$ , 
$$\phi = \frac{TLs}{4GA_m^2t}$$

5-105  
232



Thin-walled closed section

$$\tau = \frac{\max q}{t} = \frac{T^{\max}}{2[\pi b(0.5b)]t} = \tau_{\text{all}}$$

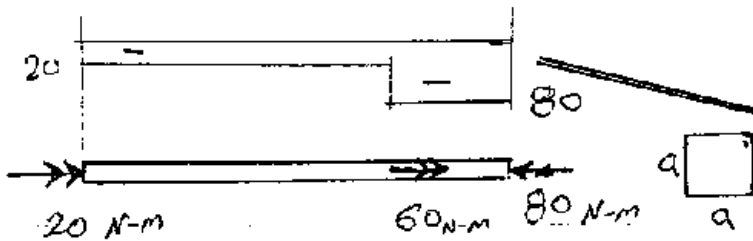
$$= \frac{(270)(12) \text{ lb-in}}{2\pi(b)(0.5b)(0.2)} = 8.0 \times 10^3$$

$T^{\max} = 270 \text{ lb-ft}$

$q = \text{shear flow}$

$\Rightarrow b = 0.803 \text{ in}$

5-91  
230



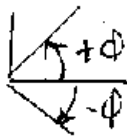
$T^{\max} = 80 \text{ N-m}$

$G = 26 \text{ GPa}$  (from table)

Solid  
Non-circular  
sections

$$\tau^{\max} = \frac{4.81 T^{\max}}{a^3} \quad (\text{Formula from table 5-1 page 221})$$

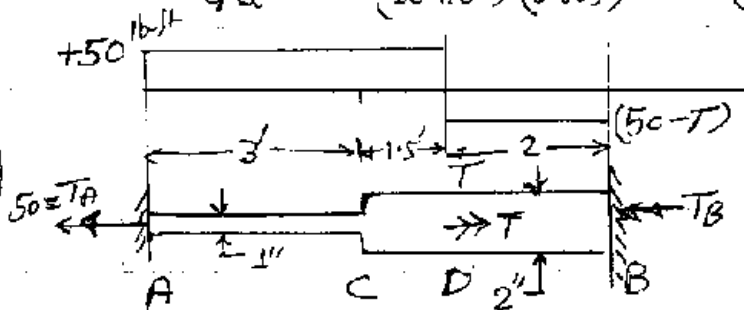
$$= \frac{(4.81)(80)}{(0.025)^3} = 24.6 \text{ MPa}$$



$$\phi = \frac{T_1 D T_1 L}{G D^4} = \frac{(710)(-20)(1.5)}{(26 \times 10^9)(0.025)^4} + \frac{(710)(-80)(0.5)}{(26 \times 10^9)(0.025)^4} = -0.0489$$

$$= -1.4^\circ = 1.4^\circ$$

5-83  
219



Two unknowns ( $T$  &  $T_B$ )  
Need two equations.  
( $G = 11 \times 10^6 \text{ psi}$ ) from table

1. Equilibrium Equation:  $T = 50 = T_B = 0 \Rightarrow T_B = T - 50 = T_{OB}$

2. Compatibility Equation:  $\frac{T_{AC} L_{AC}}{G J_{AC}} + \frac{T_{CD} L_{CD}}{G J_{CD}} + \frac{T_{DB} L_{DB}}{G J_{DB}} = 0 \quad (\phi_{A/B} = 0)$

$$\frac{[(50)(12)][3 \times 12]}{11 \times 10^6 \left(\frac{\pi}{2}\right)^4} + \frac{[(50)(12)][1.5 \times 12]}{(11 \times 10^6) \left(\frac{\pi}{2}\right)^4} + \frac{(50-T)(12)(2 \times 12)}{(11 \times 10^6) \left(\frac{\pi}{2}\right)^4} = 0$$

Solving for  $T = 1287 \text{ lb-ft}$   
 $T = 1.29 \text{ kip-ft}$